• CASA homepage: http://casa.nrao.edu

• For help, comments, or corrections, please visit the NRAO helpdesk: http://help.nrao.edu or http://help.almaScience.org for ALMA related questions.

• Data reduction guides are available at http://casaguides.nrao.edu

• For news, updates, critical bugs, subscribe to our CASA mailing lists: http://casa.nrao.edu/mail_list.shtml

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# Contents

1 Introduction .................................................. 28
   1.0.1 Reference for Publications .............................. 30
   1.1 About This Release ........................................ 30
   1.2 Obtaining CASA ............................................ 31
      1.2.1 What's New in Release 4.1.0 ......................... 31
   1.3 CASA Basics — Information for First-Time Users ............ 33
      1.3.1 Before Starting CASA ................................... 34
         1.3.1.1 Environment Variables ............................. 34
         1.3.1.2 Where is CASA? .................................. 35
      1.3.2 Starting CASA .......................................... 35
      1.3.3 Ending CASA ........................................... 36
      1.3.4 What happens if something goes wrong? ................. 36
      1.3.5 Aborting CASA execution ............................... 36
      1.3.6 What happens if CASA crashes? ......................... 37
      1.3.7 Python Basics for CASA ................................. 37
         1.3.7.1 Variables ......................................... 37
         1.3.7.2 Lists and Ranges .................................. 38
         1.3.7.3 Indexes ............................................ 38
         1.3.7.4 Indentation ........................................ 39
         1.3.7.5 System shell access ............................... 39
         1.3.7.6 Executing Python scripts .......................... 39
      1.3.8 Getting Help in CASA .................................... 40
         1.3.8.1 TAB key ........................................... 40
         1.3.8.2 help <taskname> .................................... 40
         1.3.8.3 help and PAGER .................................... 42
         1.3.8.4 help par.<parameter> ............................... 43
         1.3.8.5 Python help ........................................ 43
   1.4 Tasks and Tools in CASA .................................... 44
      1.4.1 What Tasks are Available? .............................. 44
      1.4.2 Running Tasks and Tools ................................. 49
         1.4.2.1 Aborting Synchronous Tasks ......................... 51
      1.4.3 Getting Return Values ................................... 51
      1.4.4 Running Tasks Asynchronously .......................... 52
         1.4.4.1 Monitoring Asynchronous Tasks ...................... 52
1.4.4.2 Aborting Asynchronous Tasks .................................................. 54
1.4.5 Setting Parameters and Invoking Tasks ........................................ 54
  1.4.5.1 The scope of parameters in CASA ............................................ 55
  1.4.5.2 The default Command .......................................................... 56
  1.4.5.3 The go Command ................................................................ 57
  1.4.5.4 The inp Command ................................................................. 58
  1.4.5.5 The saveinputs Command ...................................................... 60
  1.4.5.6 The tget Command ............................................................... 63
  1.4.5.7 The tput Command ............................................................... 63
  1.4.5.8 The .last file ....................................................................... 64
1.4.6 Tools in CASA ............................................................................ 64
1.5 Getting the most out of CASA ......................................................... 66
  1.5.1 Your command line history ....................................................... 66
  1.5.2 Logging your session .................................................................. 66
    1.5.2.1 Startup options for the logger .............................................. 69
    1.5.2.2 Setting priority levels in the logger ....................................... 70
  1.5.3 Where are my data in CASA? ...................................................... 71
    1.5.3.1 How do I get rid of my data in CASA? .................................. 71
  1.5.4 What’s in my data? .................................................................... 72
  1.5.5 Data Selection in CASA ............................................................. 72
1.6 From Loading Data to Images .......................................................... 73
  1.6.1 Loading Data into CASA ............................................................ 73
    1.6.1.1 VLA: Filling data from VLA archive format ............................ 74
    1.6.1.2 Filling data from UVFITS format .......................................... 75
    1.6.1.3 Loading FITS images ........................................................... 75
    1.6.1.4 Concatenation of multiple MS .............................................. 75
  1.6.2 Data Examination, Editing, and Flagging ..................................... 75
    1.6.2.1 Interactive X-Y Plotting and Flagging .................................. 76
    1.6.2.2 Flag the Data Non-interactively .......................................... 76
    1.6.2.3 Viewing and Flagging the MS ............................................. 76
  1.6.3 Calibration .............................................................................. 76
    1.6.3.1 Prior Calibration ................................................................. 77
    1.6.3.2 Bandpass Calibration .......................................................... 77
    1.6.3.3 Gain Calibration ................................................................ 78
    1.6.3.4 Polarization Calibration ....................................................... 78
    1.6.3.5 Examining Calibration Solutions ......................................... 78
    1.6.3.6 Bootstrapping Flux Calibration .......................................... 78
    1.6.3.7 Correcting the Data ............................................................. 79
    1.6.3.8 Splitting the Data ............................................................... 79
    1.6.3.9 UV Continuum subtraction ................................................. 79
    1.6.3.10 Transforming the Data to a new frame ............................... 79
  1.6.4 Synthesis Imaging .................................................................... 79
    1.6.4.1 Cleaning a single-field image or a mosaic ............................ 80
    1.6.4.2 Feathering in a Single-Dish image ....................................... 80
  1.6.5 Self Calibration ....................................................................... 80
1.6.6 Data and Image Analysis

1.6.6.1 What’s in an image? ................................. 81
1.6.6.2 Image statistics ..................................... 81
1.6.6.3 Image values ........................................ 81
1.6.6.4 Moments of an image cube .................. 81
1.6.6.5 Image math .......................................... 82
1.6.6.6 Regridding an Image ......................... 82
1.6.6.7 Displaying Images ............................... 82

1.6.7 Getting data and images out of CASA 82

2 Visibility Data Import, Export, and Selection

2.1 CASA Measurement Sets ................................. 84
2.1.1 Under the Hood: Structure of the Measurement Set 84
2.2 Data Import and Export ................................. 88
2.2.1 ALMA: Filling of Science Data Model (ASDM) data 88
  2.2.1.1 Filling SDM v0 data using importoldasdm ... 92
2.2.2 Jansky VLA: Filling of Science Data Model (ASDM) data 93
  2.2.3 VLA: Filling data from archive format (importvla) ... 94
    2.2.3.1 Parameter applytsys ........................ 96
    2.2.3.2 Parameter bandname .......................... 96
    2.2.3.3 Parameter frequencytol ...................... 96
    2.2.3.4 Parameter project ............................ 97
    2.2.3.5 Parameters starttime and stoptime ....... 97
    2.2.3.6 Parameter autocorr ........................... 97
    2.2.3.7 Parameter antnamescheme .................... 97
    2.2.3.8 Parameter evlabands .......................... 97
  2.2.4 UVFITS Import and Export ........................ 98
    2.2.4.1 Import using importuvfits .................. 98
    2.2.4.2 Import using importfitsidi ............... 98
    2.2.4.3 Export using exportuvfits ................. 99
  2.2.5 Handling Measurement Set metadata and data ...... 100
  2.2.6 Summarizing your MS (listobs) .................. 100
  2.2.7 MMS summary (listpartition) .................... 103
  2.2.8 Listing MS data (listvis) ....................... 103
  2.2.9 Listing and manipulating MS metadata (vishead) .... 103
  2.2.10 MS statistics (visstat) ....................... 105
  2.2.11 Concatenating multiple datasets (concat) ...... 106

2.3 Data Selection ................................. 108
  2.3.1 General selection syntax ...................... 109
    2.3.1.1 String Matching ........................... 109
  2.3.2 The field Parameter ............................. 111
  2.3.3 The spw Parameter ............................... 111
    2.3.3.1 Channel selection in the spw parameter .... 112
  2.3.4 The selectdata Parameters ..................... 113
    2.3.4.1 The antenna Parameter ...................... 113
2.3.4.2 The scan Parameter ......................................... 115
2.3.4.3 The timerange Parameter .................................. 116
2.3.4.4 The uvrange Parameter .................................... 117
2.3.4.5 The observation Parameter ................................. 118
2.3.4.6 The msselect Parameter .................................... 118

3 Data Examination and Editing ................................... 119
3.1 Plotting and Flagging Visibility Data in CASA .................. 119
3.2 Managing flag versions with flagmanager ...................... 120
3.3 X-Y Plotting and Editing of the Data ......................... 121
3.3.1 MS Plotting and Editing using plotms ....................... 121
3.3.1.1 Loading and Selecting Data ............................... 122
3.3.1.2 A Brief Note Regarding plotms Memory Usage ...... 124
3.3.1.3 Plot Axes .................................................... 125
3.3.1.4 Tools ....................................................... 128
3.3.1.5 Interactive Flagging in plotms ......................... 129
3.3.1.6 Averaging Data ........................................... 131
3.3.1.7 Plot Symbols ............................................... 132
3.3.1.8 Summarizing Data ......................................... 133
3.3.1.9 Defining Frequency and Velocity ....................... 133
3.3.1.10 Shifting the Phase Center ............................... 134
3.3.1.11 Plot Ranges ............................................... 134
3.3.1.12 Plot Labels ............................................... 134
3.3.1.13 Grid Lines ............................................... 135
3.3.1.14 Legend ..................................................... 135
3.3.1.15 The Options Tab ......................................... 135
3.3.1.16 Iteration .................................................. 136
3.3.1.17 Saving your plot ......................................... 136
3.3.1.18 exiting plotms ........................................... 137
3.3.2 Plotting and Editing using plotxy ......................... 137
3.3.2.1 GUI Plot Control ......................................... 141
3.3.2.2 The selectplot Parameters ............................... 142
3.3.2.3 The iteration parameter ................................ 143
3.3.2.4 The overplot parameter ................................ 143
3.3.2.5 The plotrange parameter ................................ 143
3.3.2.6 The plotsymbol parameter .............................. 144
3.3.2.7 The showflags parameter ............................... 145
3.3.2.8 The subplot parameter ................................. 146
3.3.2.9 Averaging in plotxy .................................... 146
3.3.2.10 Interactive Flagging in plotxy ....................... 148
3.3.2.11 Flag extension in plotxy ............................... 149
3.3.2.12 Setting rest frequencies in plotxy .................. 150
3.3.2.13 Printing from plotxy .................................. 151
3.3.2.14 Exiting plotxy ......................................... 152
3.3.2.15 Example session using plotxy ....................... 152
3.3.3 Plotting antenna positions using `plotants` .................................................. 155
3.3.4 Plotting uv-coverages `plotuv` ........................................................................ 155
3.4 Data Flagging using `flagdata` ............................................................................ 156
   3.4.1 The `action` parameter .................................................................................. 157
   3.4.2 Flagging Modes .............................................................................................. 158
      3.4.2.1 Manual Flag/Unflag ................................................................................ 158
      3.4.2.2 List .......................................................................................................... 159
      3.4.2.3 Clip ........................................................................................................... 160
      3.4.2.4 Shadow ................................................................................................... 160
      3.4.2.5 Quack ....................................................................................................... 161
      3.4.2.6 Elevation .................................................................................................. 161
      3.4.2.7 Tfcrop ...................................................................................................... 161
      3.4.2.8 Rflag ......................................................................................................... 163
      3.4.2.9 Extend ....................................................................................................... 165
      3.4.2.10 Unflag .................................................................................................... 166
      3.4.2.11 Summary ............................................................................................... 166
3.5 Command-based flagging using `flagcmd` ............................................................... 167
   3.5.1 Input modes `inpmode` ................................................................................. 168
      3.5.1.1 Input mode 'table' .................................................................................. 168
      3.5.1.2 Input flag mode 'list' ............................................................................. 168
      3.5.1.3 Input flag mode 'xml' .......................................................................... 169
   3.5.2 Operation types `action` .................................................................................. 170
      3.5.2.1 Apply flags — `optype option 'apply'` .................................................... 170
      3.5.2.2 Unapply flags — `action option 'unapply'` .......................................... 170
      3.5.2.3 List flags — `action='list'` .................................................................. 171
      3.5.2.4 Plot flags — `action='plot'` ................................................................. 171
      3.5.2.5 Clear flags — `action='clear'` .............................................................. 172
      3.5.2.6 Extract Flag Commands—`action='extract'` ...................................... 172
3.5.3 Flagging command syntax ................................................................................. 172
3.6 Browse the Data .................................................................................................... 175

4 Synthesis Calibration .................................................................................................. 179
   4.1 Calibration Tasks ............................................................................................... 179
   4.2 The Calibration Process — Outline and Philosophy ............................................. 181
      4.2.1 The Philosophy of Calibration in CASA ..................................................... 183
      4.2.2 Keeping Track of Calibration Tables .......................................................... 184
      4.2.3 The Calibration of traditional VLA data in CASA ...................................... 184
      4.2.4 Loading Jansky VLA data in CASA ........................................................... 186
   4.3 Preparing for Calibration .................................................................................... 186
      4.3.1 System Temperature Correction .................................................................. 187
      4.3.2 Antenna Gain-Elevation Curve Calibration ............................................... 187
      4.3.3 Atmospheric Optical Depth Correction ....................................................... 187
         4.3.3.1 Determining opacity corrections for VLA data .................................... 188
         4.3.3.2 Determining opacity corrections for VLA data .................................... 189
      4.3.4 Setting the Flux Density Scale using (setjy) ............................................. 189
4.3.4.1 Using Calibration Models for Resolved Sources ........................................ 194
4.3.5 Correction for delay and antenna position offsets using gencal .......................... 196
4.3.6 Applying Jansky VLA switched power or ALMA Tsys using gencal ......................... 200
4.3.7 Generate a gain table based on Water Vapor Radiometer data wvrgcal ..................... 200
4.3.7.1 Statistical parameters shown in the logger output of wvrgcal .......................... 202
4.3.8 Other a priori Calibrations and Corrections .................................................... 203

4.4 Solving for Calibration — Bandpass, Gain, Polarization ........................................ 203

4.4.1 Common Calibration Solver Parameters .......................................................... 203

4.4.2 Spectral Bandpass Calibration (bandpass) ....................................................... 209

4.4.3 Complex Gain Calibration (gaincal) ............................................................... 213

4.4.4 Establishing the Flux Density Scale (fluxscale) .............................................. 217

4.5 Plotting and Manipulating Calibration Tables ...................................................... 228

4.5.1 Plotting Calibration Solutions (plotcal) ......................................................... 229

4.5.2 Calibration Smoothing (smoothcal) ............................................................... 236

4.5.3 Calibration Interpolation and Accumulation (accum) ...................................... 238

4.6 Application of Calibration to the Data ............................................................... 243

4.6.1 Application of Calibration (applycal) ............................................................. 244
### 4.6.2 Examine the Calibrated Data .............................................. 247
### 4.6.3 Resetting the Calibration Models (delmod and clearcal) .......... 247
### 4.7 Other Calibration and UV-Plane Analysis Options ................. 248
#### 4.7.1 Splitting out Calibrated uv data (split) ......................... 248
##### 4.7.1.1 Averaging in split ............................................. 249
#### 4.7.2 Recalculation of uvw values (fixvis) .......................... 250
#### 4.7.3 Hanning smoothing of uv data (hanningsmooth) .............. 250
#### 4.7.4 Model subtraction from uv data (uvsub) ....................... 251
#### 4.7.5 UV-Plane Continuum Subtraction (uvcontsub) ............... 252
#### 4.7.6 Spectral regridding of the MS (cvel) .......................... 254
#### 4.7.7 UV-Plane Model Fitting (uvmodelfit) ......................... 256
#### 4.7.8 Reweighing visibilities based on their scatter (statwgt) .... 258
#### 4.7.9 Change the signs of visibility phases (conjugatevis) ....... 260
### 4.8 Examples of Calibration .................................................. 260

### 5 Synthesis Imaging ............................................................ 261
#### 5.1 Imaging Tasks Overview ................................................ 261
#### 5.2 Common Imaging Task Parameters .................................... 262
##### 5.2.1 Parameter cell ...................................................... 262
##### 5.2.2 Parameter field ..................................................... 263
##### 5.2.3 Parameter imagename .............................................. 263
##### 5.2.4 Parameter imsize .................................................. 263
##### 5.2.5 Parameter mode ..................................................... 264
###### 5.2.5.1 Mode mfs ......................................................... 264
###### 5.2.5.2 Mode channel ................................................... 266
###### 5.2.5.3 Mode frequency ............................................... 267
###### 5.2.5.4 Mode velocity .................................................. 268
###### 5.2.5.5 Sub-parameter interpolation .................................. 269
##### 5.2.6 Parameter phasecenter ............................................ 269
##### 5.2.7 Parameter restfreq ................................................ 269
##### 5.2.8 Parameter spw ...................................................... 270
##### 5.2.9 Parameter stokes .................................................. 270
##### 5.2.10 Parameter uvtaper ............................................... 271
##### 5.2.11 Parameter weighting .............................................. 271
###### 5.2.11.1 'natural' weighting .......................................... 272
###### 5.2.11.2 'uniform' weighting ........................................... 272
###### 5.2.11.3 'superuniform' weighting .................................... 273
###### 5.2.11.4 'radial' weighting ............................................. 273
###### 5.2.11.5 'briggs' weighting ............................................ 273
###### 5.2.11.6 'briggsabs' weighting ....................................... 274
##### 5.2.12 Parameter vis ...................................................... 274
##### 5.2.13 Primary beams in imaging ....................................... 275
#### 5.3 Deconvolution using CLEAN (clean) ............................... 276
##### 5.3.1 Parameter psfmode ............................................... 279
###### 5.3.1.1 The clark algorithm .......................................... 279
5.3.1.2 The hogbom algorithm ......................................................... 279
5.3.1.3 The clarkstokes algorithm ...................................................... 279
5.3.2 The multiscale parameter ........................................................ 279
5.3.3 Parameter gain ........................................................................... 280
5.3.4 Parameter imagermode ................................................................. 280
  5.3.4.1 Sub-parameter cyclefactor .................................................... 282
  5.3.4.2 Sub-parameter cyclespeedup .................................................. 283
  5.3.4.3 Sub-parameter ftmachine ....................................................... 283
  5.3.4.4 Sub-parameter mosweight ..................................................... 284
  5.3.4.5 Sub-parameter scaletype ....................................................... 284
  5.3.4.6 The threshold revisited .......................................................... 285
5.3.5 Parameter interactive ................................................................. 285
5.3.6 Parameter mask .......................................................................... 286
  5.3.6.1 Setting clean boxes ............................................................... 286
  5.3.6.2 Using clean mask images ...................................................... 286
5.3.7 Parameter minpb ......................................................................... 286
5.3.8 Parameter modelimage ................................................................. 287
5.3.9 Parameter niter .......................................................................... 287
5.3.10 Parameter pbcor ........................................................................ 287
5.3.11 Parameter restoringbeam ........................................................... 287
5.3.12 Parameter threshold ................................................................. 288
5.3.13 Parameter gridmode ................................................................. 288
5.3.14 Interactive Cleaning — Example ................................................ 289
5.3.15 Mosaic imaging ................................................................. 292
5.3.16 Heterogeneous imaging ......................................................... 295
5.3.17 Polarization imaging ................................................................. 295
5.3.18 Wide-field imaging and deconvolution in clean ......................... 295
  5.3.18.1 Outlier fields ................................................................. 296
  5.3.18.2 Setting up w-projection ..................................................... 298
  5.3.18.3 Setting up faceting ............................................................ 298
  5.3.18.4 Combination of w-projection and faceting ............................ 298
5.4 Primary Beam Correction (impbcor, widebandpbcor) ..................... 299
5.5 Combined Single Dish and Interferometric Imaging (feather) ............ 300
  5.5.1 Visual Interface for feather (casafeather) .................................. 301
5.6 Making Deconvolution Masks or Box Regions ................................ 302
  5.6.1 Making Deconvolution Regions from an Image (boxit) .............. 302
5.7 Insert an Image Model (ft) ............................................................. 304
5.8 Image-plane deconvolution (deconvolve) ...................................... 305
5.9 Self-Calibration ............................................................................ 305
5.10 Parallel Cleaning (pclean) .......................................................... 306
5.11 Examples of Imaging ................................................................. 307
## 6 Image Analysis

### 6.1 Common Image Analysis Task Parameters

<table>
<thead>
<tr>
<th>Task</th>
<th>Page</th>
</tr>
</thead>
<tbody>
<tr>
<td>Region Selection (box)</td>
<td>310</td>
</tr>
<tr>
<td>Plane Selection ([chans, stokes])</td>
<td>310</td>
</tr>
<tr>
<td>Lattice Expressions ([expr])</td>
<td>311</td>
</tr>
<tr>
<td>Masks ([mask])</td>
<td>312</td>
</tr>
<tr>
<td>Regions ([region])</td>
<td>313</td>
</tr>
</tbody>
</table>

### 6.2 Image Header Manipulation ([imhead])

- Examples for [imhead]                      | 313  |

### 6.3 Extracting sub-images ([imsubimage])

- Examples for [imsubimage]                  | 314  |

### 6.4 Continuum Subtraction on an Image Cube ([imcontsub])

- Examples for [imcontsub]                   | 314  |

### 6.5 Image-plane Component Fitting ([imfit])

- Examples for [imfit]                      | 319  |

### 6.6 Mathematical Operations on an Image ([immath])

- Simple math                               | 323  |
- Using masks in [immath]                   | 326  |

### 6.7 Computing the Moments of an Image Cube ([immoments])

- Hints for using ([immoments])              | 329  |
- Examples using ([immoments])               | 329  |

### 6.8 Generating Position-Velocity Diagrams ([impv])

- Computing image statistics ([imstat])     | 331  |
- Using the task return value               | 333  |
- Examples for [imstat]                     | 335  |

### 6.9 Extracting data from an image ([imval])

- Reordering the Axes of an Image Cube ([imtrans]) | 336  |
- Collapsing an Image Along an Axis ([imcollapse]) | 339  |
- Regridding an Image ([imregrid])             | 340  |
- Regridding an Image ([imreframe])            | 341  |
- Image Convolution ([imsmooth])               | 342  |
- Spectral Line fitting with [specfit]         | 343  |
- Polynomial Fits                             | 345  |
- Lorentzian and Gaussian Fits                | 345  |
- One or more single Gaussian/Lorentzian      | 345  |
- Gaussian Multiplets                         | 347  |
- Pixel-by-pixel fits                         | 348  |
- Image Mask Handling ([makemask])            | 348  |
- Search for Spectral Line Rest Frequencies ([slsearch]) | 349  |
- Convert Exported Splatalogue Catalogs to CASA Tables ([splattotable]) | 350  |
- Image Import/Export to FITS                 | 351  |
- FITS Image Export ([exportfits])            | 351  |
- FITS Image Import ([importfits])            | 352  |
- Using the CASA Toolkit for Image Analysis   | 352  |
7 Visualization With The CASA Viewer

7.1 Starting the Viewer

7.1.1 Running the CASA Viewer outside casapy

7.2 The Viewer Display Panel

7.2.1 The Main Toolbar

7.2.2 The Mouse Toolbar

7.2.3 The Display Area

7.2.3.1 The Animator Panel

7.2.3.2 The Position Tracking Panel

7.2.3.3 The Region Manager Panel

7.2.4 Saving and Restoring the Display Panel State

7.3 The Data Manager Panel — Saving and Loading Data

7.3.1 Loading Data

7.3.2 Registered vs. Open Datasets

7.3.3 Saving Data or Regions

7.4 Viewing Images

7.4.1 Viewing a Raster Map

7.4.1.1 Data Display Options — display and hidden axes

7.4.1.2 Data Display Options — basic settings

7.4.1.3 Graphical Specification of the Intensity Scale

7.4.1.4 Data Display Options — other settings

7.4.1.5 Viewer Canvas Manager — Panels, Margins, and Backgrounds

7.4.2 Viewing a Contour Map

7.4.2.1 Overlay Contours on a Raster Map

7.4.3 Regions and the Region Manager

7.4.3.1 Region Creation, Selection, and Deletion

7.4.3.2 Region Positioning

7.4.3.3 Region Statistics

7.4.3.4 Saving and Loading Regions

7.4.3.5 The Region Fit

7.4.3.6 The Region Histogram

7.4.4 The Spectral Profile Tool

7.4.4.1 Spectral Profile Toolbar

7.4.4.2 Main Spectral Profile Window

7.4.4.3 Spectral-Line Fitting

7.4.4.4 Line Overlays

7.4.5 The Brightness Profile Tool

7.4.6 The Collapse/Moments Tool

7.4.7 The Histogram Tool

7.4.8 The Two-D Fitting Tool

7.4.9 Interactive Position-Velocity Diagram Creation

7.5 Viewing Measurement Sets

7.5.1 Data Display Options Panel for Measurement Sets
## 8 Single Dish Data Processing

### 8.1 Guidelines for Use of ASAP and SDtasks in CASA

8.1.1 Environment Variables .................................................. 411
8.1.2 Assignment .................................................................... 412
8.1.3 Lists .............................................................................. 412
8.1.4 Dictionaries ................................................................. 413
8.1.5 Line Formatting .............................................................. 413
8.1.6 Logging ........................................................................ 413

### 8.2 Single Dish Analysis Tasks

8.2.1 SDtask Summaries ............................................................ 417
8.2.1.1 sdcal ..................................................................... 417
8.2.1.2 sdcal2 ................................................................. 421
8.2.1.3 sdsmoothing ......................................................... 424
8.2.1.4 sdbaseline ............................................................ 425
8.2.1.5 sdreduce .............................................................. 431
8.2.1.6 sdcoadd ............................................................... 437
8.2.1.7 sdflag ................................................................. 439
8.2.1.8 sdflagmanager ...................................................... 444
8.2.1.9 sdfit ................................................................... 445
8.2.1.10 sdgrid ............................................................... 449
8.2.1.11 sdimaging .......................................................... 451
8.2.1.12 sdlist .................................................................. 454
8.2.1.13 sdmath .............................................................. 455
8.2.1.14 sdplot ............................................................... 457
8.2.1.15 sdsave .............................................................. 465
8.2.1.16 sdscale .............................................................. 467
8.2.1.17 sdstat ............................................................... 468
8.2.1.18 sdtpimaging ....................................................... 471
8.2.1.19 sdimprocess ...................................................... 473
8.2.1.20 msnmoments ...................................................... 475

### 8.2.2 Single Dish Analysis Use Cases With SDTasks

8.2.2.1 GBT Position Switched Data Analysis ......................... 476
8.2.2.2 Imaging of Total Power Raster Scans ......................... 488

### 8.3 Using The ASAP Toolkit within CASA

8.3.1 Environment Variables .................................................... 491
# Appendix: Obtaining, Installing, and Customizing CASA

## A.1 Installation On Linux
- A.1.1 Installation
- A.1.1.1 Using more than one Linux version of CASA
- A.1.2 Unsupported platforms
- A.1.3 Download & Unpack

## A.2 Installation on Mac OS
- A.2.0.1 Using more than one Mac version of CASA

## A.3 Startup

## A.4 Startup Customization

## A.5 Updating the data repository

# Appendix: Python and CASA

## B.1 Python Packages

## B.2 Automatic parentheses

## B.3 Indentation

## B.4 Lists and Ranges

## B.5 Dictionaries
- B.5.1 Saving and Reading Dictionaries

## B.6 Control Flow: Conditionals, Loops, and Exceptions
- B.6.1 Conditionals
- B.6.2 Loops

## B.7 System shell access
- B.7.1 Using the `os.system` methods
- B.7.2 Directory Navigation
- B.7.3 Shell Command and Capture

## B.8 Logging

## B.9 History and Searching

## B.10 Macros

## B.11 On-line editing

## B.12 Executing Python scripts

## B.13 How do I exit from CASA?

# Appendix: Models, Conventions and Reference Frames

## C.1 Flux Density Models for setjy
- C.1.1 Long wavelength calibration
  - C.1.1.1 Baars
  - C.1.1.2 Perley 90
  - C.1.1.3 Perley-Taylor 95
  - C.1.1.4 Perley-Taylor 99
  - C.1.1.5 Perley-Butler 2010
  - C.1.1.6 Perley-Butler 2013
- C.1.2 Short wavelength calibration

## C.2 Velocity Reference Frames
# List of Tables

<table>
<thead>
<tr>
<th>Table</th>
<th>Title</th>
<th>Page</th>
</tr>
</thead>
<tbody>
<tr>
<td>2.1</td>
<td>Common MS Columns</td>
<td>87</td>
</tr>
<tr>
<td>2.2</td>
<td>Commonly accessed MAIN Table columns</td>
<td>87</td>
</tr>
<tr>
<td>4.1</td>
<td>Recognized Flux Density Calibrators. Note that the VLA uses J2000 calibrator names. CASA accepts all strings that contain the names below. E.g. 'PKS 1934-638' will be recognized</td>
<td>191</td>
</tr>
<tr>
<td>4.2</td>
<td>'Butler-JPL-Horizons 2012' recognized Solar System Objects for Flux Calibration</td>
<td>192</td>
</tr>
<tr>
<td>5.1</td>
<td>Combinations of observing band (wavelength,) and antenna array configurations that require w-projection.</td>
<td>296</td>
</tr>
<tr>
<td>C.1</td>
<td>Recognized Flux Density Calibrators. Note that the VLA uses J2000 calibrator names. CASA accepts all strings that contain the names below. E.g. 'PKS 1934-638' will be recognized</td>
<td>554</td>
</tr>
<tr>
<td>C.2</td>
<td>Velocity frames in CASA</td>
<td>556</td>
</tr>
<tr>
<td>C.3</td>
<td>Doppler types in CASA</td>
<td>556</td>
</tr>
<tr>
<td>C.4</td>
<td>Time reference frames in CASA</td>
<td>557</td>
</tr>
<tr>
<td>C.5</td>
<td>Coordinate frames in CASA</td>
<td>558</td>
</tr>
<tr>
<td>C.6</td>
<td>Prefixes</td>
<td>559</td>
</tr>
<tr>
<td>C.7</td>
<td>SI Units</td>
<td>560</td>
</tr>
<tr>
<td>C.7</td>
<td>SI Units – continued</td>
<td>561</td>
</tr>
<tr>
<td>C.8</td>
<td>Custom Units</td>
<td>562</td>
</tr>
<tr>
<td>C.8</td>
<td>Custom Units – continued</td>
<td>563</td>
</tr>
<tr>
<td>C.8</td>
<td>Custom Units – continued</td>
<td>564</td>
</tr>
<tr>
<td>C.9</td>
<td>Physical Constants</td>
<td>565</td>
</tr>
<tr>
<td>G.1</td>
<td>AIPS – CASA dictionary</td>
<td>582</td>
</tr>
<tr>
<td>G.2</td>
<td>MIRIAD – CASA dictionary</td>
<td>583</td>
</tr>
<tr>
<td>G.3</td>
<td>CLIC–CASA dictionary</td>
<td>584</td>
</tr>
</tbody>
</table>
List of Figures

1.1 Screen shot of the default CASA inputs for task clean. .......................... 60
1.2 The clean inputs after setting values away from their defaults (blue text). Note that some of the boldface ones have opened up new dependent sub-parameters (indented and green). .................................................. 61
1.3 The clean inputs where one parameter has been set to an invalid value. This is drawn in red to draw attention to the problem. This hapless user probably confused the ’hogbom’ clean algorithm with Harry Potter. .............................. 62
1.4 The CASA Logger GUI window under Linux. Note that under MacOSX a stripped down logger will instead appear as a Console. .......................... 66
1.5 Using the Search facility in the casalogger. Here we have specified the string ’apply’ and it has highlighted all instances in green. .......................... 67
1.6 Using the casalogger Filter facility. The log output can be sorted by Priority, Time, Origin, and Message. In this example we are filtering by Origin using ’clean’, and it now shows all the log output from the clean task. .......................... 68
1.7 CASA Logger - Insert facility: The log output can be augmented by adding notes or comments during the reduction. The file should then be saved to disk to retain these changes. .................................................. 69
1.8 Flow chart of the data processing operations that a general user will carry out in an end-to-end CASA reduction session. .......................... 74

2.1 The contents of a Measurement Set. These tables compose a Measurement Set named ngc5921.demo.ms on disk. This display is obtained by using the File:Open menu in browsetable and left double-clicking on the ngc5921.demo.ms directory. .... 86

3.1 A freshly-started plotms GUI window. Note that the Plots > Data tab is selected, which is discussed in §3.3.1.1, 3.3.1.6, and 3.3.1.8] .......................... 123
3.2 The Plots > Axes tab in the plotms GUI window, used to make a plot of Amp versus Channel. .................................................. 125
3.3 Plot of amplitude versus time, before (left) and after (right) flagging two marked regions. To unflag these regions, mark the two same regions and click the Unflag button. .................................................. 130
3.4 The plotxy plotter, showing the Jupiter data versus uv-distance. You can see bad
data in this plot. The **bottom set of buttons** on the lower left are: 1,2,3) **Home,**
**Back,** and **Forward.** Click to navigate between previously defined views (akin to
web navigation). 4) **Pan.** Click and drag to pan to a new position. 5) **Zoom.** Click
to define a rectangular region for zooming. 6) **Subplot Configuration.** Click to
configure the parameters of the subplot and spaces for the figures. 7) **Save.** Click
to launch a file save dialog box. The **upper set of buttons in the lower left**
are: 1) **Mark Region.** Press this to begin marking regions (rather than zooming or
panning). 2,3,4) **Flag, Unflag, Locate.** Click on these to flag, unflag, or list the
data within the marked regions. 5) **Next.** Click to move to the next in a series of
iterated plots. Finally, the **cursor readout** is on the bottom right.

3.5 The plotxy iteration plot. The first set of plots from the example in §3.3.2.3 with
**iteration=’antenna’.** Each time you press the **Next** button, you get the next
series of plots.

3.6 Multi-panel display of visibility versus channel (**top**), antenna array configuration
(**bottom left**) and the resulting uv coverage (**bottom right**). The commands to
make these three panels respectively are: 1) `plotxy('ngc5921.ms', xaxis='channel',
datacolumn='data', field='0', subplot=211, plotcolor='', plot_symbol='go')`
2) `plotxy('ngc5921.ms', xaxis='x', field='0', subplot=223, plotcolor='r.',
plot_symbol='r.')`
3) `plotxy('ngc5921.ms', xaxis='u', yaxis='v', field='0', subplot=224, plotcolor='b',
plot_symbol='b,')`

3.7 Plot of amplitude versus uv distance, before (left) and after (right) flagging two
marked regions. The call was: `plotxy(vis='ngc5921.ms', xaxis='uvdist',
field='1445*')`.

3.8 **browsetable:** The browser displays the main table within a frame. You can scroll
through the data (x=columns of the MAIN table, and y=the rows) or select a specific
page or row as desired. By default, 1000 rows of the table are loaded at a time, but
you can step through the MS in batches.

3.9 **browsetable:** You can use the tab for **Table Keywords** to look at other tables within
an MS. You can then double-click on a table to view its contents.

3.10 **browsetable:** Viewing the **SOURCE** table of the MS.

4.1 Flow chart of synthesis calibration operations. Not shown are use of table manipu-
lation and plotting tasks **accum, plotcal,** and **smoothcal** (see Figure 4.2).

4.2 Chart of the table flow during calibration. The parameter names for input or output
of the tasks are shown on the connectors. Note that from the output solver through
the accumulator only a single calibration type (e.g. ‘B’, ‘G’) can be smoothed,
interpolated or accumulated at a time. **accum** is optional (and not recommended as
of v4.0). The final set of cumulative calibration tables of all types (accumulated
or as a list of caltables) are then input to **applycal** as shown in Figure 4.1.

4.3 The weather information for a MS as plotted by the task **plotweather.**

4.4 Display of the amplitude (upper) and phase (lower) gain solutions for all antennas
and polarizations in the **ngc5921** post-fluxscale table.
4.5 Display of the amplitude (upper), phase (middle), and signal-to-noise ratio (lower) of the bandpass 'B' solutions for antenna='0' and both polarizations for ngc5921. Note the falloff of the SNR at the band edges in the lower panel.  

4.6 Display of the amplitude of the bandpass 'B' solutions. Iteration over antennas was turned on using iteration='antenna'. The first page is shown. The user would use the Next button to advance to the next set of antennas.  

4.7 The 'amp' of gain solutions for NGC4826 before (top) and after (bottom) smoothing with a 7200 sec smoothtime and smoothtype='mean'. Note that the first solution is in a different spw and on a different source, and is not smoothed together with the subsequent solutions.  

4.8 The 'phase' of gain solutions for NGC4826 before (top) and after (bottom) 'linear' interpolation onto a 20 sec accumtime grid. The first scan was 3C273 in spw='0' while the calibrator scans on 1331+305 were in spw='1'. The use of spwmap was necessary to transfer the interpolation correctly onto the NGC4826 scans.  

4.9 The final 'amp' (top) and 'phase' (bottom) of the self-calibration gain solutions for Jupiter. An initial phase calibration on 10s solint was followed by an incremental gain solution on each scan. These were accumulated into the cumulative solution shown here.  

4.10 The final 'amp' versus 'uvdist' plot of the self-calibrated Jupiter data, as shown in plotxy. The 'RR LL' correlations are selected. No outliers that need flagging are seen.  

4.11 Use of plotxy to display corrected data (red and blue points) and uv model fit data (green circles).  

5.1 Close-up of the top of the interactive clean window. Note the boxes at the left (where the iterations, cycles, and threshold can be changed), the buttons that control add/erase, the application of mask to channels, and whether to stop, complete, or continue cleaning, and the row of Mouse-button tool assignment icons.  

5.2 Screen-shots of the interactive clean window during deconvolution of the VLA 6m Jupiter dataset. We start from the calibrated data, but before any self-calibration. In the initial stage (left), the window pops up and you can see it dominated by a bright source in the center. Next (right), we zoom in and draw a box around this emission. We have also at this stage dismissed the tape deck and Position Tracking parts of the display (§ 7.2) as they are not used here. We have also changed the iterations to 30 for this boxed clean. We will now hit the Next Action Continue Cleaning button (the green clockwise arrow) to start cleaning.  

5.3 We continue in our interactive cleaning of Jupiter from where Figure 5.2 left off. In the first (left) panel, we have cleaned 30 iterations in the region previously marked, and are zoomed in again ready to extend the mask to pick up the newly revealed emission. Next (right), we have used the Polygon tool to redraw the mask around the emission, and are ready toContinue Cleaning for another 100 iterations.
5.4 We continue in our interactive cleaning of Jupiter from where Figure 5.3 left off. In the first (left) panel, it has cleaned deeper, and we come back and zoom in to see that our current mask is good and we should clean further. We change \texttt{npertcycle} to 500 (from 100) in the box at upper right of the window. In the final panel (right), we see the results after this clean. The residuals are such that we should terminate the \texttt{clean} using the red X button and use our model for self-calibration.

5.5 After clean and self-calibration using the intensity image, we arrive at the final polarization image of Jupiter. Shown in the \texttt{viewer} superimposed on the intensity raster is the linear polarization intensity (green contours) and linear polarization B-vectors (vectors). The color of the contours and the sampling and rotation by 90 degrees of the vectors was set in the Display Options panel. A LEL expression was used in the Load Data panel to mask the vectors on the polarized intensity.

5.6 Screen-shot of the interactive \texttt{clean} window during deconvolution of the NGC5921 spectral line dataset. Note where we have selected the mask to apply to the \texttt{Displayed Plane} rather than \texttt{All Channels}. We have just used the Polygon tool to draw a mask region around the emission in this channel, which will apply to this channel only.

5.7 Visual “casafeather” interface to the \texttt{feather} task.

6.1 NGC2403 VLA moment zero (left) and NGC4826 BIMA moment one (right) images as shown in the \texttt{viewer}.

7.1 The \texttt{Viewer Display Panel} (left) and the \texttt{Data Display Options} (right) panel for a regular image or data cube.

7.2 The \texttt{Viewer Display Panel} (left) and \texttt{Data Display Options} (right) panels with a Measurement Set open.

7.3 The display panel’s \texttt{Main Toolbar} appears directly below the menus and contains 'shortcut' buttons for most of the frequently-used menu items.

7.4 The \texttt{’Mouse Tool’ Bar} allows you to assign how mouse buttons behave in the image display area. Initially, zooming, color adjustment, and rectangular regions are assigned to the left, middle and right mouse buttons. Click on a tool with a mouse button to assign that tool to that mouse button.

7.5 "Preferences" dialog to manually change the docking and size of the viewer panel.

7.6 The animator panel, which allows one to scroll along the \texttt{z} axis of a data cube (using the Channels tape deck) or cycle among open Images. The panel can be undocked from the main display panel.

7.7 The position tracking panel, which gives information about the open data cube at the current location of the cursor. Freeze the position tracking panel using the \texttt{SPACE} bar.

7.8 The \texttt{load} tab of the \texttt{Data Manager} panel. This appears if you open the \texttt{viewer} without any \texttt{infile} specified, if you use select \texttt{Open} from the \texttt{Data} drop down menu, or click the Open (Folder) icon. You can access the \texttt{save image} or \texttt{save region} tabs from this view or by selecting \texttt{Save as...} from the \texttt{Data} drop down menu. The load tab shows all files in the current directory that can be loaded into the viewer — images, MS, CASA region files, and Display Panel State files.
7.9 The Save Data panel that appears when selecting the ’Save as...’ (Figure 7.3). . .
7.10 The basic settings category of the Data Display Options panel and the interactive tool for setting the mapping from intensity to color. . . . . . . . . . . . . . .
7.11 Example curves for scaling power cycles. . . . . . . . . . . . . . . . . . . . . . .
7.12 A multi-panel display set up through the Viewer Canvas Manager. . . . . . . .
7.13 The Viewer Display Panel (left) and Data Display Options panel (right) after
choosing contour map from the Load Data panel. The image shown is for channel
11 of the NGC5921 cube, selected using the Animator tape deck, and zoomed in
using the tool bar icon. Note the different options in the open basic settings
category of the Data Display Options panel (as compared to raster image in
Figure 7.1). . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . .
7.14 The Viewer Display Panel (left) and Data Display Options panel (right) after
overlaying a Contour Map of velocity on a Raster Image of intensity. The image
shown is for the moments of the NGC5921 cube, zoomed in using the tool bar icon.
The tab for the contour plot is open in the Data Display Options panel. . . . .
7.15 The Region Manager Panel, which becomes active once at least one region is created.
Cycle through available regions using the slider bar at the bottom and use the various
tabs to adjust, analyze, load, and save regions. . . . . . . . . . . . . . . . . . . . .
7.16 Selecting an image region (done with SHIFT+click). The region can be resized by
dragging the handles or deleted by hitting ESCAPE. . . . . . . . . . . . . . . . . .
7.17 The positioning tab in the Region Manager. Use it to manually adjust the location,
width, and display style of the selected region. . . . . . . . . . . . . . . . . . . . .
7.18 The statistics tab in the Region Manager. . . . . . . . . . . . . . . . . . . . . . . .
7.19 The save/load tab in the Region Manager. . . . . . . . . . . . . . . . . . . . . . . .
7.20 The histogram tab in the Region Manager. Right click to zoom. Hit SHIFT +
Right Click to adjust the details of the histogram display. . . . . . . . . . . . . .
7.21 The Spectral Profile panel (right) that appears when pressing the button Open
the Spectrum Profiler in the Main Toolbar and then use the tools to select a
region in the image, such as the rectangular region on the left panel. The Spectral
Profile tool shows the spectrum of the most recent region highlighted and updates
to track movements of the region if moved by dragging with the mouse. . . . . . .
7.22 The toolbar for the Spectral Profile tool allows the user to save the spectrum, print
or save the tool as an image, edit preferences (general, tool, legend), pan or zoom
around the spectrum, select a range of interest, jump to a channel, or add a label.
7.23 Preferences options in the Spectral Profile Tool. From the toolbar, one can access
dialogs to set overall viewer preferences, colors for plotting, and how the plot legend
is displayed. . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . .
7.24 The main panel for the Spectral Profile tool. Buttons along the bottom row allow
the axes to be set. Arrow keys pan and dragging out an area with the mouse zooms.
Holding CTRL and right clicking in the spectrum will jump the main Viewer Display
panel to display that frequency channel. . . . . . . . . . . . . . . . . . . . . . . . .

. 368
. 371
. 372
. 374

. 375

. 377

. 377
. 378
. 379
. 380
. 381
. 382

. 383

. 384

. 385

. 386


The Spectral Line Fitting tab in the Spectral Profile Tool. The user can fit a combination of a polynomial and multiple Gaussian components, specifying the range to be fit (gray region) manually or with a shift+click+drag. Initial estimates for each component may be entered by hand or specified via an initial estimates GUI. The results are output to a dialog and text file with the fit overplotted (here in blue) on the spectrum (with the possibility to save it to disk).

The left panel shows the graphical specification of initial estimates for Gaussian fitting. Slider bars specify the center, FWHM, and peak intensity for the initial estimate. The right panel shows the verbose output of the fitting.

Line Overlays in the Spectral Profile Tool. The Line Overlay tab, shown at the bottom, allows users to query the CASA copy of the Spaltalogue spectral line database. Enter the redshift of your source (right panel), select and Astronomical Filter from the drop down menu, and use shift+click+drag to select a frequency range (or do so manually). The "Search" button will bring up the dialog seen at the left top part of the image, which can in turn be used to graph the candidate lines in the main Spectral Profile window (here CO v=0).

1-dimensional slice of an image. The 1D slicer tool shows the brightness distribution along line segments.

The Collapse/Moments tool, accessed from the Main Toolbar or the Tools drop down menu. The mean spectrum from the region in the Main Display Panel appears in the top part of the tool. After selecting a range, a moment to calculate, and optionally data to exclude, click collapse to calculate a new image.

The Histogram tool, accessed from the Main Toolbar or the Tools drop down menu. Details of the display and included pixels can be manipulated via the menus along the top of the window. The right hand panel allows one to attempt to fit a distribution to the histogram.

Interactive creation of position-velocity cuts in the viewer. Use the P/V tool from the Mouse Toolbar to define a cut, then use the pV tool from the Region Manager Panel to adjust the cut (including the width). Click Generate P/V to build the position velocity cut and open it in a new Viewer Display Panel (from which it can be saved to disk).

The Load Data - Viewer panel as it appears if you select an MS. The only option available is to load this as a Raster Image. In this example, clicking on the Raster Image button would bring up the displays shown in Figure 7.2.

The MS for NGC4826 BIMA observations has been loaded into the viewer. We see the first of the spw in the Display Panel, and have opened up MS and Visibility Selections in the Data Display Options panel. The display panel raster is not full of visibilities because spw 0 is continuum and was only observed for the first few scans. This is a case where the different spectral windows have different numbers of channels also.
7.35 The MS for NGC4826 from Figure 7.34, now with the Display Axes open in the Data Display Options panel. By default, channels are on the Animation Axis and thus in the tapedeck, while spectral window and polarization are on the Display Axes sliders.

7.36 The MS for NGC4826, continuing from Figure 7.35. We have now put spectral window on the Animation Axis and used the tapedeck to step to spw 2, where we see the data from the rest of the scans. Now channels is on a Display Axes slider, which has been dragged to show Channel 33.

7.37 Printing the display to a hardcopy of a file. From the Viewer Print Manager, located in top right here and accessed by the print icon or from the Data drop down menu, you can use the Save button to save an image or Print directly to a printer. To achieve the best results, it is often helpful to adjust the settings in the Data Display Options and Viewer Canvas Manager, shown at right.

7.38 Data selection in msview.

8.1 Wiring diagram for the SDtask sdreduce. The stages of processing within the task are shown, along with the parameters that control them.

8.2 The Flag plotter. The bottom set of buttons are the standard matplotlib toolbar. See the caption of Figure 3.4 for detailed descriptions. The upper set of buttons in the lower left are: 1) region. Press this to begin marking regions (rather than zooming or panning). 2) panel. Press this to begin marking panels to select the whole spectrum. 3,4,5,6) clear, flag, unflag, statistics. Click on these to clear, flag, unflag, or calculate statistics of the data within the marked regions and spectra. 7) notation. Press this to begin editing notes on the plotter. 8,9) +, −. Click to move to the next or previous page in a series of iterated plots. The page counter on their left shows the current page number. Finally, the Quit is on the bottom right.

8.3 The toolbars on ASAP plotter. The bottom set of buttons are the standard matplotlib toolbar. See the caption of Figure 3.4 for detailed descriptions. The upper set of buttons are: 1) notation. Press this to begin editing notes on the plotter. 2) statistics. Press this to begin printing statistics to the logger. 3,4) +, −. Click to move to the next or previous page in a series of iterated plots. The page counter on their left shows the current page number. Finally, the Quit is on the bottom right.

8.4 The Notation widget.

8.5 Total power data display using sdtpimaging, with calmode='baseline'. The top panel shows uncalibrated data versus row numbers. The middle panel shows baseline fitting of each scan (only shown here the last scan). The bottom panel shows the calibrated (baseline subtracted) data.

8.6 Multi-panel display of the scantable. Subpanels are displayed per scan. There are two spectra in each scan indicating two polarization (RR and LL).

8.7 Two panel plot of the calibrated spectra. The GBT data have a separate scan for the SOURCE and REFERENCE positions so scans 20,21,22 and 23 result in these two spectra.

8.8 Calibrated spectrum with a line at zero (using histograms).
8.9 FLS3a HI emission. The display illustrates the visualization of the data cube (left) and the profile display of the cube at the cursor location (right); the Tools menu of the Viewer Display Panel has a Spectral Profile button which brings up this display. By default, it grabs the left-mouse button. Pressing down the button and moving in the display will show the profile variations.
Chapter 1

Introduction

This document describes how to calibrate and image interferometric and single-dish radio astronomical data using the CASA (Common Astronomy Software Application) package. CASA is a suite of astronomical data reduction tools and tasks that can be run via the IPython interface to Python. CASA is being developed in order to fulfill the data post-processing requirements of the ALMA and EVLA projects, but also provides basic and advanced capabilities useful for the analysis of data from other radio, millimeter, and submillimeter telescopes.

You have in your hands the latest release of CASA. This package is under active development, and thus there are a number of caveats and limitations for the use of this package. See the release notes (§ 1.1) below for more information, and pay heed to the numerous ALERTs placed throughout this reference. You can expect regular updates and patches, as well as increasing functionality.

This user reference and cookbook is a task-based walkthrough of interferometric data reduction and analysis. In CASA, tasks represent the more streamlined operations that a typical user would carry out. The idea for having tasks is that they are simple to use, provide a more familiar interface, and are easy to learn for most astronomers who are familiar with radio interferometric data reduction (and hopefully for novice users as well). In CASA, the tools provide the full capability of the package, and are the atomic functions that form the basis of data reduction. These tools augment the tasks, or fill in gaps left by tasks that are under development but not yet available. See the CASA Toolkit Manual for more details on the tools (available from casa.nrao.edu). Note that in most cases, the tasks are Python interface scripts to the tools, but with specific, limited access to them and a standardized interface for parameter setting. The tasks and tools can be used together to carry out more advanced data reduction operations.

For the moment, the audience is assumed to have some basic grasp of the fundamentals of synthesis imaging, so details of how a radio interferometer or telescope works and why the data needs to undergo calibration in order to make synthesis images are left to other documentation — a good

This reference is broken down by the main phases of data analysis:

- data import, export, and selection (Chapter 2),
- examination and flagging of data (Chapter 3),
- interferometric calibration (Chapter 4),
- interferometric imaging (Chapter 5),
- image analysis (Chapter 6), and
- data and image visualization (Chapter 7).

These are included for users that will be doing EVLA and ALMA telescope commissioning and software development.

The general appendices provide more details on what’s happening under the hood of CASA, as well as supplementary material on tasks, scripts, and relating CASA to other packages. These appendices include:

- obtaining and installing CASA (Appendix A),
- more details about Python and CASA (Appendix B),
- a discussion of the Hamaker-Bregman-Sault Measurement Equation (Appendix E),
- annotated scripts for typical data reduction cases (Appendix F), and
- CASA dictionaries to AIPS, MIRIAD, and CLIC (Appendix G).

The CASA User Documentation includes:

- CASA User Reference & Cookbook — this document, a task-based data analysis walk-through and instructions;
- CASA in-line help — accessed using help in the casapy interface;
- The CASA Toolkit Reference Manual — details on a specific task or tool does and how to use it.
• The CASA Task Reference Manual — the information from the inline help and task documentation, available online in HTML.

The CASA home page can be found at:

http://casa.nrao.edu

From there you can find documentation and assistance for the use of the package, including the User Documentation. You will also find information on how to obtain the latest release and receive user support.

There is also a CASAGuides Wiki

http://casaguides.nrao.edu

that contains helpful information on CASA startup, AIPS-to-CASA cheat sheet, example scripts of processing your data in CASA, along with hints and tricks to best use this package.

1.0.1 Reference for Publications

If you use CASA for any of your data reduction or analysis, you may use the following reference:


1.1 About This Release

CASA 4.1.0 is now available and the main feature improvements are listed below. In addition to the new features, many bugs were addressed and fixed.

We occasionally issue patches and 'stable' versions of CASA. To get notified, please subscribe to the 'casa-users' mailing list. 'Stable' as well as CASA releases are available at http://casa.nrao.edu Releases will be announced via the 'casa-announce' mailing list. To subscribe, please visit http://casa.nrao.edu For feedback, and help please go to the NRAO helpdesk http://help.nrao.edu for ALMA questions please use the ALMA helpdesk http://help.almascience.org.

Note that in its current incarnation CASA is designed to support EVLA, ALMA, and VLA data, as well as single dish data from ALMA as well as Nobeyama. Data from other telescopes, be it single dish or interferometers can be imported from uvfits, FITS-IDI, or sdfits formats into measurements sets (ms) or scantables in CASA. Given the variety of non-standard fits formats, we cannot guarantee that CASA will fully support data from all telescopes. However, efforts are made to support data formats from other facilities.
1.2 Obtaining CASA

CASA is available for the following operating systems:

- Linux
  - RedHat 5.7 and 6.3 (64-bit)
- Mac OS
  - Mac OS 10.6 (Snow Leopard; 64-bit)
  - Mac OS 10.7 & 10.8 (Lion/Mountain Lion; 64-bit)

The latest and previous releases can be downloaded from our CASA home page: [http://casa.nrao.edu](http://casa.nrao.edu), following the 'Obtaining CASA' link (direct link: [http://casa.nrao.edu/casa_obtaining.shtml](http://casa.nrao.edu/casa_obtaining.shtml)).

1.2.1 What’s New in Release 4.1.0

Major improvements over the previous version of CASA include:

- **Imaging**
  - implementation of narrow-band A-projection algorithm
- **Data examination/editing/import/export**
  - `flagdata` and `flagcmd` can now flag based on calibration tables (e.g. on Tsys)
  - support for multiple input files in `flagdata`
  - `listobs` reports a larger number of data parameters, including flagged rows, integration times, spw names
  - new tool `msmd` with a large number of methods to access meta data information
  - `plotms` can now display calibration tables (this will eventually replace the current `plotcal` functionality
  - multi-panel plotting in `plotms`
  - new task `imreframe` to change the spectral frame in which the velocity/frequency is reported
  - disabling tool return in tasks to align with general task behavior in CASA and to prevent table locks
- **Calibration**
- expanded use of obsid in all calibration tasks. Calibration solving behavior at ObsId boundaries is now controlled by the combine parameter; by default solutions will not cross ObsId boundaries in CASA v4.1 and later. Interpolation of solutions across ObsId boundaries is controlled by extensions to the interp parameter. Note: Extended ObsId capabilities are available only in CASA 4.1 and higher. Most older caltables will be backward compatible, but without any ObsId capabilities.
- radial limit to the VLA flux calibrator models (used by setjy)
- calwt in applycal can now be a vector to enable/disable weight calibration for individual gain tables
- uvcontsub now allows for specification of corrupted channels to be excluded from the fit in addition to line free channels
- gencal function to support VLA switched power calibration is now caltype="swpwr", requantizer gains can be computed via caltype="rq" and veracity of switched power can be evaluated with caltype='swp/rq'
- wvrgcal allows a string for the timescale of temporal smoothing

- **Simulation**
  - Task simalma uses feather to combine interferometer and total power images.

- **Data and Image Manipulation**
  - A graphical interface "casafeather" (run on the Unix command line) to display the feathering weighting functions, scaling and visibility functions of the feather task
  - imregrid has now asvelocity=True as default

- **Data analysis**
  - new task impv to create position-velocity diagrams (also available as tool method ia.pv)
  - data analysis tasks now accept specification of channel ranges in the form of velocity ranges

- **Viewer**
  - histogram plotting of data values and Gaussian fitting of these
  - interactive creation of position-velocity diagrams
  - arbitrary spatial brightness profile slices across images
  - ability to visually set the color transfer function and data range based on intensity value histogram
  - global color option for multiple images
  - the docking behavior can now be set in the “Preferences” menu

- **Single Dish**
CHAPTER 1. INTRODUCTION

- new tool method `sd.scantable.sub_baselines` allows for independent specification of parameters and function for each baseline per spectrum
- Baseline fitting results can be stored as a CASA table and applied later
- new sd tool function `sd.scantable.calc_aic()` is available to calculate some major values of model selection criteria for a given spectrum and a baseline function.
- new task `sdcal2` for interferometry style calibration (generate caltable and apply caltabes)
- new grid functions GAUSS (Gaussian) and GJINC (Gaussian * Jinc) are available for `sdimaging`, `sdtpimaging`, and `sdgrid`
- `sdimaging`: auto calculation of map center when phasecenter is empty
- `sdsave` (and `sd.splitant`): frequency reference frame takes from input MS when data is imported
- `sdgrid`: grid positions without any data are flagged
- `sdplot`: `plottype='pointings'` allows overlaying the scan pattern and changing the colors of plot symbols by source type, scan ID, beam ID, polarization ID, or IF number.
- Nobeyama filler: options to control frequency reference frame, proper handling of dual polarization data, support for data from SAM45

- **Performance**

  - `sdbaseline` speed improvement (2-10 times faster)
  - new experimental task `mstransform`, which can be used to replace `split`, `cvel`, `hanningsmooth` and `partition`. The task optimizes the I/O so that all the transformations are applied in memory without the need to read and write multiple times. See [http://www.eso.org/~scastro/ALMA/casa/MST/MSTransformDocs](http://www.eso.org/~scastro/ALMA/casa/MST/MSTransformDocs) for details.
  - The `partition` task has been modified to use the new MSTransform framework. The interface of `partition` also changed. The parameters "calmsselection" and "timebin" have been removed. `partition` now supports channel selections and re-indexes spws after a selection.

- **Other**

  - ALMA ATM library upgraded to ALMA-9.4R4
  - added support for "chan" in the CASA CRTF region format

For known issues with this release please visit the CASA webpages: [http://casa.nrao.edu/release_ki.shtml](http://casa.nrao.edu/release_ki.shtml)

1.3 CASA Basics — Information for First-Time Users

This section assumes that CASA has been installed on your LINUX or OSX system. See Appendix A for instructions on how to obtain and install CASA.
1.3.1 Before Starting CASA

First, you will most likely be starting CASA running from a working directory that has your data in it, or at least where you want your output to go. It is easiest to start from there rather than changing directories inside casapy. ALERT: There is at least one task (plotxy) that fails if the path to your working directory contains spaces in its name, e.g. /users/smyers/MyTest/ is fine, but /users/smyers/My Test/ is not! Please use our new task plotms whenever possible and we may work on a better handling of spaces in path names.

If you have done a default installation under Linux using rpms, or on the Mac with the CASA application, then there should be a sh script called casapy in the /usr/bin area which is in your path. This shell will set up its environment and run the version of casapy that it points to. If this is how you set up the system, then you need to nothing further and can run casapy.

For internal NRAO users we keep different version of CASA, the latest “casapy” release, the “casapy-stable” “Stable” version that is more developed than the Release but without the full documentation (and no GUI testing). We also offer the “Test” version, “casapy-test”, which is produced on a roughly weekly basis with all the latest code but it underwent much less rigorous testing. Instructions how to run the different versions at NRAO can be found on our http://casa.nrao.edu webpages under the “CASA at NRAO” link for the different NRAO sites.

1.3.1.1 Environment Variables

Before starting up casapy, you should set or reset any environment variables needed, as CASA will adopt these on startup. For example, the PAGER environment variable determines how help is displayed in the CASA terminal window (see § 1.3.8.3). The choices are less, more, and cat.

In bash, pick one of

    PAGER=less
    PAGER=more
    PAGER=cat

followed by

    export PAGER

In csh or tcsh, pick one of

    setenv PAGER less
    setenv PAGER more
    setenv PAGER cat

The actions of these are as if you were using the equivalent Unix shell command to view the help material. See § 1.3.8.3 for more information on these choices. We recommend using the cat option for most users, as this works smoothly both interactively and in scripts.
1.3.1.2 Where is CASA?

Note that the path to the CASA installation, which contains the scripts and data repository, will also depend upon the installation. With a default installation under Linux this will probably be in

```
/usr/lib64/casapy/
```

or

while in a Mac OSX default install it will likely be an application in the Applications folder.

You can find the location after initialized by looking at the `CASAPATH` environment variable. You can find it within `casapy` by

```
pathname=os.environ.get('CASAPATH').split()[0]
print(pathname)
```

1.3.2 Starting CASA

After having run the appropriate casainit script, CASA is started by typing `casapy` on the UNIX command line, e.g.

```
casapy
```

After startup information, you should get an IPython CASA <1>: command prompt in the xterm window where you started CASA. CASA will take approximately 10 seconds to initialize at startup in a new working directory; subsequent startups are faster. CASA is active when you get a CASA <1> prompt in the command line interface. You will also see a logger GUI appear on your Desktop (usually near the upper left).

You also have the option of starting CASA with various logger options (see §1.5.2.1). For example, if you are running remotely in a terminal window without an X11 connection, or if you just do not want to see the logger GUI, and want the logger messages to come to your terminal, do

```
casapy --nologger --log2term
```

See §1.5.2 for information on the logger in general.
1.3.3 Ending CASA

You can exit CASA by typing `quit`. This will bring up the query

Do you really want to exit ([y]/n)?

to give you a chance in case you did not mean to exit. You can also quit using `%exit` or `CTRL-D`.

If you don’t want to see the question "Do you really want to exit [y]/n?", then just type `Exit` or `exit` and CASA will stop right then and there.

1.3.4 What happens if something goes wrong?

**ALERT:** Please check the CASA Home Page for Release Notes and FAQ information including a list of known problems. If you think you have encountered an unknown problem, please consult the CASA HelpDesk (contact information on the CASA Home Page). See also the caveats to this Release (§ 1.1) for pointers to our policy on User Support.

First, always check that your inputs are correct; use the

```
help <taskname>
```

(§ 1.3.8.2) or

```
help par.<parameter name>
```

(§ 1.3.8.4) to review the inputs/output.

1.3.5 Aborting CASA execution

If something has gone wrong and you want to stop what is executing, then typing `CNTL-C` (Control and C keys simultaneously) will usually cleanly abort the application. This will work if you are running a task synchronously. If this does not work on your system, or you are running a task asynchronously (§ 1.4.4) then try `CNTL-Z` to put the task or shell in the background, and then follow up with a `kill -9 <PID>` where you have found the relevant `casapy` process ID (PID) using `ps` (see § 1.3.6 below).

If the problem causes CASA to crash, see the next sub-section.

See § 1.4.2 for more information on running tasks.

**Alert:** CNTL-C while a tasks runs can corrupt your input data file, e.g. when a scratch column is filled while aborting. If in doubt, wait until the task has finished, delete the new files produced, and start again.
1.3.6 What happens if CASA crashes?

Usually, restarting casapy is sufficient to get you going again after a crash takes you out of the Python interface. Note that there may be spawned subprocesses still running, such as the casaviewer or the logger. These can be dismissed manually in the usual manner. After a crash, there may also be hidden processes. You can find these by listing processes, e.g. in linux:

```
ps -elf | grep casa
```
or on MacOSX (or other BSD Unix):

```
ps -aux | grep casa
```

You can then kill these, for example using the Unix kill or killall commands. This may be necessary if you are running remotely using ssh, as you cannot logout until all your background processes are terminated. For example,

```
killall ipcontroller
```
or

```
killall Python
```

will terminate the most common post-crash zombies.

1.3.7 Python Basics for CASA

Within CASA, you use Python to interact with the system. This does not mean an extensive Python course is necessary - basic interaction with the system (assigning parameters, running tasks) is straightforward. At the same time, the full potential of Python is at the more experienced user’s disposal. Some further details about Python, IPython, and the interaction between Python and CASA can be found in Appendix B.

The following are some examples of helpful hints and tricks on making Python work for you in CASA.

1.3.7.1 Variables

Python variables are set using the `<parameter> = <value>` syntax. Python assigns the type dynamically as you set the value, and thus you can easily give it a non-sensical value, e.g.

```
vis = 'ngc5921.ms'
vis = 1
```
CHAPTER 1. INTRODUCTION

The CASA parameter system will check types when you run a task or tool, or more helpfully when you set inputs using inp (see below). CASA will check and protect the assignments of the global parameters in its namespace.

Note that Python variable names are case-sensitive:

CASA <109>: Foo = 'bar'
CASA <110>: foo = 'Bar'
CASA <111>: foo
  Out[111]: 'Bar'
CASA <112>: Foo
  Out[112]: 'bar'

so be careful.

Also note that mis-spelling a variable assignment will not be noticed (as long as it is a valid Python variable name) by the interface. For example, if you wish to set correlation='RR' but instead type corellation='RR' you will find correlation unset and a new corellation variable set. Command completion (see §1.3.8.1) should help you avoid this.

1.3.7.2 Lists and Ranges

Sometimes, you need to give a task a list of indices. If these are consecutive, you can use the Python range function to generate this list:

CASA <1>: iflist=range(4,8)
CASA <2>: print iflist
  [4, 5, 6, 7]
CASA <3>: iflist=range(4)
CASA <4>: print iflist
  [0, 1, 2, 3]

See Appendix B.4 for more information.

1.3.7.3 Indexes

As in C, Python indices are 0-based. For example, the first element in a list antlist would be antlist[0]:

CASA <113>: antlist=range(5)
CASA <114>: antlist
  Out[114]: [0, 1, 2, 3, 4]
CASA <115>: antlist[0]
  Out[115]: 0
  Out[116]: 4
CASA also uses 0-based indexing internally for elements in the Measurement Set (MS – the basic construct that contains visibility and/or single dish data; see Chapter 2). Thus, we will often talk about Field or Antenna “ID”s which will be start at 0. For example, the first field in an MS would have FIELD_ID==0 in the MSselect syntax, and can be addressed as be indexed as field=’0’ in most tasks, as well as by name field=’0137+331’ (assuming thats the name of the first field). You will see these indices in the MS summary from the task listobs.

### 1.3.7.4 Indentation

Python pays attention to the indentation of lines, as it uses indentation to determine the level of nesting in loops. Be careful when cutting and pasting: if you get the wrong indentation, then unpredictable things can happen (usually it just gives an error).

See Appendix B.3 for more information.

### 1.3.7.5 System shell access

If you want to access system commands from a script, use the `os.system` command (Appendix B.7.1).

In interactive mode, any input line beginning with a ’!’ character is passed verbatim (minus the ’!’), of course) to the underlying operating system. Also, several common commands (`ls, pwd, less`) may be executed with or without the ’!’ , although the `cp` command must use ’! ’ and `cd` must be executed without the ’!’ . For example:

```
CASA <5>: !rm -r mydata.ms
```

Note that if you want to access a Unix environment variable, you will need to prefix with a double `$$` instead of a single `$` — for example, to print the value of the `PAGER` variable, you would use

```
CASA <6>: !echo $$PAGER
```

See Appendix B.7 for more information.

### 1.3.7.6 Executing Python scripts

You can execute Python scripts (ASCII text files containing Python or casapy commands) using the `execfile` command. For example, to execute the script contained in the file `myscript.py` (in the current directory), you would type

```
CASA <7>: execfile('myscript.py')
```

or

```
CASA <8>: execfile 'myscript.py'
```
which will invoke the IPython auto-parenthesis feature.

NOTE: in some cases, you can use the IPython run command instead, e.g.

```
CASA <9>: run myscript.py
```

In this case, you do not need the quotes around the filename. This is most useful for re-initializing
the task parameters, e.g.

```
CASA <10>: run clean.last
```

(see § 1.4.5.8).

See Appendix B.12 for more information.

### 1.3.8 Getting Help in CASA

#### 1.3.8.1 TAB key

At any time, hitting the `<TAB>` key will complete any available commands or variable names and
show you a list of the possible completions if there’s no unambiguous result. It will also complete
filenames in the current directory if no CASA or Python names match.

For example, it can be used to list the available functionality using minimum match; once you have
typed enough characters to make the command unique, `<TAB>` will complete it.

```
CASA <15>: cle<TAB>
clean clean_description clearcal_check_params
clearplot clearstat
clean_check_params clear clearcal_defaults
clearplot_defaults clearstat_defaults
clean_defaults clearcal clearcal_description
clearplot_description clearstat_description
```

#### 1.3.8.2 help <taskname>

Basic information on an application, including the parameters used and their defaults, can be
obtained by typing `pdoc task, help task, help 'task' or task?`. The `pdoc task` currently
gives the cleanest documentation format with the smallest amount of object-oriented (programmer)
output. This inline help provides a one line description of the task and then lists all parameters,
a brief description of the parameter, the parameter default, an example setting the parameter and
any options if there are limited allowed values for the parameter.

For example:
Import VLA archive file(s) to a measurement set

Imports an arbitrary number of VLA archive-format data sets into a casa measurement set. If more than one band is present, they will be put in the same measurement set but in a separate spectral window. The task will handle old style and new style VLA (after July 2007) archive data and apply the tsys to the data and to the weights.

Keyword arguments:
archivefiles -- Name of input VLA archive file(s)
  default: none. Must be supplied
  example: archivefiles = 'AP314_A959519.xp1'
  example: archivefiles=['AP314_A950519.xp1','AP314_A950519.xp2']
vis -- Name of output visibility file
  default: none. Must be supplied.
  example: vis='NGC7538.ms'
  Will not over-write existing ms of same name.
  A backup flag-file version 'Original' will be made in vis.flagversions. See help flagmanager
bandname -- VLA Frequency band
  default: => '' = all bands
  example: bandname='K'
  Options: '4'=48-96 MHz,'P'=298-345 MHz,'L'=1.15-1.75 GHz,
  'C'=4.2-5.1 GHz,'X'=6.8-9.6 GHz,'U'=13.5-16.3 GHz,
  'K'=20.8-25.8 GHz,'Q'=38-51 GHz
frequencytol -- Tolerance in frequency shift in making spectral windows
  default: => 150000 (Hz). For Doppler shifted data, <10000 Hz may
  may produce too many unnecessary spectral windows.
  example: frequencytol = 1500000.0 (units = Hz)
project -- Project name to import from archive files:
  default: '' => all projects in file
  example: project='AL519'
  project = 'al519' or AL519 will work. Do not include leading zeros; project = 'AL0519' will not work.
starttime -- Time after which data will be considered for importing
  default: '' => all: Date must be included.
  syntax: starttime = '2003/1/31/05:05:23'
stoptime -- Time before which data will be considered for importing
  default: '' => all: Date must be included.
  syntax: stoptime = '2003/1/31/08:05:23'
applytsys -- Apply data scaling and weight scaling by nominal sensitivity (~Tsys)
  default: True. Strongly recommended
autocorr -- import autocorrelations to ms
  default: => False (no autocorrelations)
antnamescheme -- 'old' or 'new' antenna names.
  default => 'new' gives antenenna names
  'VA04' or 'EA13 for VLA telescope 04 and 13 (EVLA)
  'old' gives names '04' or '13'
keepblanks -- Should sources with blank names be filled into the data base
default => false. Do not fill
These scans are tipping scans (as of June 1, 2009) and should not be filled in the visibility data set.
evlabands -- Use the EVLA's center frequency and bandwidths for frequencies specified via wavelength or band.
default => True.
async -- Run asynchronously
default = False; do not run asynchronously

You can also get the short help for a CASA tool method by typing 'help tool.method'.

CASA <46>: help ia.subimage
Help on built-in function subimage:

subimage(...)  
Create a (sub)image from a region of the image
--- --- --- --- --- --- Parameters --- --- --- --- --- ---
outfile: Output image file name. Default is unset.
region: Region of interest. Default is whole image.
mask: OTF mask, Boolean LEL expression or mask region. Default is none.
dropdeg: Drop degenerate axes false
overwrite: Overwrite (unprompted) pre-existing output file? false
list: List informative messages to the logger true
--- --- --- --- --- --- --- --- --- --- --- --- --- --- ---
outfile
region
mask
dropdeg = false
overwrite = false
list = true
----------------------------------------

For a full list of keywords associated with the various tools, see the CASA User Reference Manual.

1.3.8.3 help and PAGER

Your PAGER environment variable ([1.3.1]) determines how help is displayed in the terminal window where you start CASA. If you set your bash environment variable PAGER=less (setenv PAGER less in csh) then typing help <taskname> will show you the help but the text will vanish and return you to the command line when you are done viewing it. Setting PAGER=more (setenv PAGER more) will scroll the help onto your command window and then return you to your prompt (but leaving it on display). Setting PAGER=cat (setenv PAGER cat) will give you the more equivalent without some extra formatting baggage and is the recommended choice.

If you have set PAGER=more or PAGER=less, the help display will be fine, but the display of 'taskname?' will often have confusing formatting content at the beginning (lots of ESC surrounding
the text). This can be remedied by exiting casapy and doing an `unset PAGER` (unsetenv PAGER in [t]csh) at the Unix command line.

You can see the current value of the PAGER environment variable with CASA by typing:

```bash
!echo $$PAGER
```

(note the double $$). This will show what command paging is pointed to.

1.3.8.4 help par.<parameter>

Typing `help par.<parameter>` provides a brief description of a given parameter `<parameter>`.

```bash
CASA <46>: help par.robust
Help on function robust in module parameter_dictionary:
robust()
    Brigg's robustness parameter.

    Options: -2.0 (close to uniform) to 2.0 (close to natural)
```

1.3.8.5 Python help

Typing `help` at the casapy prompt with no arguments will bring up the native Python help facility, and give you the `help>` prompt for further information; hitting `<RETURN>` at the help prompt returns you to the CASA prompt.

```bash
CASA <2>: help
--------> help()
Welcome to Python 2.5! This is the online help utility.

If this is your first time using Python, you should definitely check out
the tutorial on the Internet at http://www.python.org/doc/tut/.

Enter the name of any module, keyword, or topic to get help on writing
Python programs and using Python modules. To quit this help utility and
return to the interpreter, just type "quit".

To get a list of available modules, keywords, or topics, type "modules",
"keywords", or "topics". Each module also comes with a one-line summary
of what it does; to list the modules whose summaries contain a given word
such as "spam", type "modules spam".

help> keywords

Here is a list of the Python keywords. Enter any keyword to get more
help.
1.4 Tasks and Tools in CASA

Originally, CASA consisted of a collection of tools, combined in the so-called toolkit. Since the majority of prospective users is far more familiar with the concept of tasks, an effort is underway to replace most - if not all - toolkit functionality by tasks.

While running CASA, you will have access to and be interacting with tasks, either indirectly by providing parameters to a task, or directly by running a task. Each task has a well defined purpose, and a number of associated parameters, the values of which are to be supplied by the user. Technically speaking, tasks are built on top of tools - when you are running a task, you are running tools in the toolkit, though this should be transparent.

As more tasks are being written, and the functionality of each task is enhanced, there will be less and less reason to run tools in the toolkit. We are working toward a system in which direct access to the underlying toolkit is unnecessary for all standard data processing.

1.4.1 What Tasks are Available?

As mentioned in the introduction, tasks in CASA are python interfaces to the more basic toolkit. Tasks are executed to perform a single job, such as loading, plotting, flagging, calibrating, and imaging the data.

Basic information on tasks, including the parameters used and their defaults, can be obtained by typing `help <taskname>` or `<taskname>?` at the CASA prompt, where `<taskname>` is the name...
of a given task. As described above in §1.3.8.2, help <taskname> provides a description of the
task and then lists all parameters, a brief description of the parameter, the parameter default, an
example setting the parameter and any options if there are limited allowed values for the parameter.

To see what tasks are available in CASA, use tasklist, e.g.

CASA <3>: tasklist
--------- tasklist()
Available tasks, organized by category (experimental tasks in parenthesis ()
deprecated tasks in curly brackets {}).

<table>
<thead>
<tr>
<th>Import/export</th>
<th>Information</th>
<th>Editing</th>
<th>Manipulation</th>
</tr>
</thead>
<tbody>
<tr>
<td>exportasdm</td>
<td>imhead</td>
<td>fixplanets</td>
<td>concat</td>
</tr>
<tr>
<td>exportfits</td>
<td>imreframe</td>
<td>fixvis</td>
<td>conjugatevis</td>
</tr>
<tr>
<td>exportuvfits</td>
<td>imstat</td>
<td>flagcmd</td>
<td>cvel</td>
</tr>
<tr>
<td>importasdm</td>
<td>imval</td>
<td>flagdata</td>
<td>fixvis</td>
</tr>
<tr>
<td>importfits</td>
<td>listcal</td>
<td>flagmanager</td>
<td>hanningsh</td>
</tr>
<tr>
<td>importfitsidi</td>
<td>listfits</td>
<td>msview</td>
<td>imhead</td>
</tr>
<tr>
<td>importuvfits</td>
<td>listhistory</td>
<td>plotms</td>
<td>msmoments</td>
</tr>
<tr>
<td>importvla</td>
<td>listobs</td>
<td>plotxy</td>
<td></td>
</tr>
<tr>
<td>(importevla)</td>
<td>listvis</td>
<td></td>
<td>plotxy</td>
</tr>
<tr>
<td>(importgma)</td>
<td>plotms</td>
<td></td>
<td>split</td>
</tr>
<tr>
<td></td>
<td>plotuv</td>
<td></td>
<td>testconcat</td>
</tr>
<tr>
<td></td>
<td>plotxy</td>
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<tr>
<th>Calibration</th>
<th>Modeling</th>
<th>Imaging</th>
<th>Analysis</th>
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<tbody>
<tr>
<td>accum</td>
<td>predictcomp</td>
<td>clean</td>
<td>imcollapse</td>
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<td>applycal</td>
<td>setjy</td>
<td>deconvolve</td>
<td>imcontsub</td>
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<tr>
<td>bandpass</td>
<td>uvcontsub</td>
<td>feather</td>
<td>imfit</td>
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<td>bcal</td>
<td>uvmodelfit</td>
<td>ft</td>
<td>imhead</td>
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<td>calstat</td>
<td>uvsb</td>
<td>imcontsub</td>
<td>immath</td>
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<td>clearcal</td>
<td>(uvcontsub3)</td>
<td>(boxit)</td>
<td>immoments</td>
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<td>delmod</td>
<td>{uvcontsub2}</td>
<td>(csvclean)</td>
<td>impbcor</td>
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<td>fixplanets</td>
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<td>(tclean)</td>
<td>impv</td>
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<td>fluxscale</td>
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<td>(widebandpbc)</td>
<td>imreframe</td>
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<td>ft</td>
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<td>{mosaic}</td>
<td>imregrid</td>
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<td>gaincal</td>
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<td>{widefield}</td>
<td>imsmooth</td>
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<td>imstat</td>
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<td>plotants</td>
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<td>imtrans</td>
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plotcal
polcal
predictcomp
setjy
smoothcal
uvmodelfit
uvsub
wvrgcal

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<thead>
<tr>
<th>Visualization</th>
<th>Simulation</th>
<th>Single dish</th>
<th>Utility</th>
</tr>
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<tr>
<td>clearplot</td>
<td>simanalyze</td>
<td>asap_init</td>
<td>browsetable</td>
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<tr>
<td>imview</td>
<td>simobserve</td>
<td>sdbaseline</td>
<td>caltabconvert</td>
</tr>
<tr>
<td>msvview</td>
<td>(simalma)</td>
<td>sdcal</td>
<td>clearplot</td>
</tr>
<tr>
<td>plotants</td>
<td></td>
<td>sdcal2</td>
<td>clearstat</td>
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<td>plotbandpass</td>
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<td>concat</td>
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<td>conjugatevis</td>
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<td>plots</td>
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<td>sdflag</td>
<td>find</td>
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<td>plotuv</td>
<td></td>
<td>sdflagmanager</td>
<td>help par.parameter</td>
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<tr>
<td>plotxy</td>
<td></td>
<td>sdgrid</td>
<td>help taskname</td>
</tr>
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<td>viewer</td>
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<td>sdimaging</td>
<td>imview</td>
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<td>(plotweather)</td>
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<td>sdimprocess</td>
<td>msvview</td>
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<td>sdlist</td>
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<td>sdpplot</td>
<td>startup</td>
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<td>sdreduce</td>
<td>taskhelp</td>
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<td>sdsave</td>
<td>tasklist</td>
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<td>testconcat</td>
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<td>toolhelp</td>
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<td>sdtPimaging</td>
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User defined tasks
-------------------

The tasks with name in parentheses are experimental, those in curly brackets are deprecated and will be removed in future releases. The functionality of deprecated tasks is usually available in some other task (e.g., instead of `mosaic` one should use `clean`). In the above case, the user has not defined any task him/herself.

Typing `taskhelp` provides a one line description of all available tasks.

CASA <4>: taskhelp
------- taskhelp()
Available tasks:
Available tasks:
accum : Accumulate incremental calibration solutions into a calibration table
applycal : Apply calibrations solutions(s) to data
asdmsummary : Summarized description of an ASDM dataset.
autoclean : CLEAN an image with automatically-chosen clean regions.
bic : Calculate a baselines-based calibration solution (gain or bandpass)
boxit : Box regions in image above given threshold value.
browsetable : Browse a table (MS, calibration table, image)
calstat : Displays statistical information on a calibration table
caltabconvert : Convert old-style caltables into new-style caltables.
clean : Invert and deconvolve images with selected algorithm
clearcal : Re-initializes the calibration for a visibility data set
clearplot : Clear the matplotlib plotter and all layers
clearstat : Clear all autolock locks
concat : Concatenate several visibility data sets.
conjugatevis : Change the sign of the phases in all visibility columns.
csvclean : This task does an invert of the visibilities and deconvolve in the image plane.
cvel : regrid an MS to a new spectral window / channel structure or frame
deconvolve : Image based deconvolver
delmod : Deletes model representations in the MS
eportasdm : Convert a CASA visibility file (MS) into an ALMA Science Data Model
exportfits : Convert a CASA image to a FITS file
exportuvfits : Convert a CASA visibility data set to a UVFITS file:
feather : Combine two images using their Fourier transforms
find : Find string in tasks, task names, parameter names:
fixplanets : Changes FIELD and SOURCE table entries based on user given direction or POINTING table, optionally fixes the UVW coordinates
fixvis : Recalculates (u, v, w) and/or changes Phase Center
flagcmd : Flagging task based on batches of flag-commands
flagdata : All-purpose flagging task based on data-selections and flagging modes/algorithms.
flagmanager : Enable list, save, restore, delete and rename flag version files.
fluxscale : Bootstrap the flux density scale from standard calibrators
ft : Insert a source model a visibility set:
gaincal : Determine temporal gains from calibrator observations
gencal : Specify Calibration Values of Various Types
hanningsmooth : Hanning smooth frequency channel data to remove Gibbs ringing
imcollapse : Collapse image along one axis, aggregating pixel values along that axis.
imcontsub : Estimates and subtracts continuum emission from an image cube
imfit : Fit one or more elliptical Gaussian components on an image region(s)
imhead : List, get and put image header parameters
immath : Perform math operations on images
immoments : Compute moments from an image
impbcor : Construct a primary beam corrected image from an image and a primary beam pattern.
importasdm : Convert an ALMA Science Data Model observation into a CASA visibility file (MS) or single-dish data format
importevla : Convert a Science Data Model observation into a CASA Measurement Set
importfits : Convert an image FITS file into a CASA image
importfitsidi : Convert a FITS-IDI file to a CASA visibility data set
importgmmrt : Convert a UVFITS file to a CASA visibility data set
importuvfits : Convert a UVFITS file to a CASA visibility data set
importvla : Import VLA archive file(s) to a measurement set
impv : Construct a position-velocity image by choosing two points in the direction plane.
imreframe : Change the frame in which the image reports its spectral values
imregrid : regrid an image onto a template image
imsmooth : Smooth an image or portion of an image
imstat : Displays statistical information from an image or image region
imsubimage : Create a (sub)image from a region of the image
imtrans : Reorder image axes
imval : Get the data value(s) and/or mask value in an image.
imview : View an image
listcal : List antenna gain solutions
listfits : List the HDU and typical data rows of a fits file:
listhistory : List the processing history of a dataset:
listobs : List the summary of a data set in the logger or in a file
listpartition : List the summary of a multi-MS data set in the logger or in a file
listedm : Lists observation information present in an SDM directory.
listvis : List measurement set visibilities.
makemask : Makes and manipulates image masks
mosaic : Create a multi-field deconvolved image with selected algorithm
mmsmoments : Compute moments from an MS
mstransform : Task to combine/separate/regrid spws and do channel and time averaging
msview : View a visibility data set
partition : Experimental task to produce multi-MSs using parallelism
pclean : Invert and deconvolve images with parallel engines
plotants : Plot the antenna distribution in the local reference frame:
plotbandpass : Makes detailed plots of Tsys and bandpass solutions.
plotcal : An all-purpose plotter for calibration results
plotms : A plotter/interactive flagger for visibility data.
plotuv : Plot the baseline distribution
plotweather : Plot elements of the weather table; estimate opacity.
plotxy : An X-Y plotter/interactive flagger for visibility data.
polcal : Determine instrumental polarization calibrations
predictcomp : Make a component list for a known calibrator
rmtables :
sdbaseline : ASAP SD task: fit/subtract a spectral baseline
sdcal : ASAP SD task: do data selection, calibration, and averaging
sdcal2 : ASAP SD task: generate and/or apply caltables
sdcoadd : ASAP SD task: coadd multiple scantables into one
sdfit : ASAP SD task: fit a spectral line
sdflag : ASAP SD spectral flagging task
sdflagmanager : ASAP SD task: enable list, save, restore, delete and rename flag version files
sdgrid : SD task: gridding single dish data
sdimaging : SD task: imaging for total power and spectral data
sdimprocess : SD task: task for single-dish image processing
sdlist : ASAP SD task: list summary of single dish data
sdmath : ASAP SD task: do simple arithmetic (subtraction, addition, multiplication, and division)
sdplot : ASAP SD plotting task
sdreduce : ASAP SD task: do sdcal, sdsmooth, and sdbaseline in one task
sdscale : ASAP SD task: save the sd spectra in various format
sdstat : ASAP SD task: scale the sd spectra
sdsmooth : ASAP SD task: do smoothing of spectra
sdscale : ASAP SD task: list statistics of spectral region
sdtpimaging : SD task: do a simple calibration and imaging for total power data
setjy : Fills the model column with the visibilities of a calibrator
CHAPTER 1. INTRODUCTION

Typing `startup` will provide the startup page displayed when entering CASA. The startup screen lists the various options to obtain help within CASA.

```
CASA <26>: startup
---------- startup()
```

For help use the following commands:
- `tasklist` - Task list organized by category
- `taskhelp` - One line summary of available tasks
- `help taskname` - Full help for task
- `toolhelp` - One line summary of available tools
- `help par.parametername` - Full help for parameter name

1.4.2 Running Tasks and Tools

Tools are functions linked to the Python interface which must be called by name with arguments. Tasks have higher-level capabilities than tools. Tasks require input parameters which maybe be specified when you call the task as a function, or be set as parameters in the interface. A task, like
a tool, is a function under Python and may be written in Python, C, or C++ (the CASA toolkit is made up of C++ functions).

There are two distinct ways to run tasks. You can either set the global CASA parameters relevant to the task and tell the task to “go”, or you can call the task as a function with one or more arguments specified. These two invocation methods differ in whether the global parameter values are used or not.

For example,

```python
default('plotxy')
vis='ngc5921.ms'
xaxis='channel'
yaxis='amp'
datacolumn='data'
go
```

will execute `plotxy` with the set values for the parameters (see §1.4.5). Instead of using `go` command (§1.4.5.3) to invoke the task, you can also call the task with no arguments, e.g.

```python
default('plotxy')
vis='ngc5921.ms'
xaxis='channel'
yaxis='amp'
datacolumn='data'
plotxy()
```

which will also use the global parameter values.

Second, one may call tasks and tools by name with parameters set on the same line. Parameters may be set either as explicit `<parameter>=<value>` arguments, or as a series of comma delimited `<value>`s in the correct order for that task or tool. Note that missing parameters will use the default values for that task. For example, the following are equivalent:

```python
# Specify parameter names for each keyword input:
plotxy(vis='ngc5921.ms',xaxis='channel',yaxis='amp',datacolumn='data')
# when specifying the parameter name, order doesn’t matter, e.g.:
plotxy(xaxis='channel',vis='ngc5921.ms',datacolumn='data',yaxis='amp')
# use parameter order for invoking tasks
plotxy('ngc5921.ms','channel','amp','data')
```

This non-use of globals when calling as a function is so that robust scripts can be written. One need only cut-and-paste the calls and need not worry about the state of the global variables or what has been run previously. It is also more like the standard behavior of function calls in Python and other languages.

Tools can only be called in this second manner by name, with arguments (§1.4.6). Tools never use the global parameters and the related mechanisms of `inp` and `go`. 
1.4.2.1 Aborting Synchronous Tasks

If you are running CASA tasks synchronously, then you can usually use CNTL-C to abort execution of the task. If this does not work, try CNTL-Z followed by a kill. See §1.3.5 for more on these methods to abort CASA execution.

You may have to quit and restart CASA after an abort, as the internal state can get mixed up.

1.4.3 Getting Return Values

Some tasks and tools return a record (usually a Python dictionary) to the interface. For example, the `imstat` task (§6.9) returns a dictionary with the image statistics in it. To catch these return values into a Python variable, you MUST assign that variable to the task call, e.g.

```python
xstat = imstat('ngc5921.clean.image')
```

or

```python
default('imstat')
    imagename = 'ngc5921.clean.image'
xstat = imstat()
```

Note that tools that return values work in the same way (§1.4.6).

You can print or use the return value in Python for controlling scripts. For example,

```python
CASA <1>: xstat = imstat('ngc5921.clean.image')
CASA <2>: xstat
```

```python
dict:
{'blc': array([0, 0, 0, 0]),
 'blcf': '15:24:08.404, +04.31.59.181, I, 1.41281e+09Hz',
 'flux': array([ 4.15292207]),
 'max': array([ 0.05240594]),
 'maxpos': array([134, 134, 0, 38]),
 'maxposf': '15:21:53.976, +05.05.29.998, I, 1.41374e+09Hz',
 'mean': array([ 1.62978083e-05]),
 'medabsdevmed': array([ 0.00127287]),
 'median': array([-1.10467618e-05]),
 'min': array([-0.005249]),
 'minpos': array([160, 1, 0, 30]),
 'minposf': '15:21:27.899, +05.05.29.998, I, 1.41374e+09Hz',
 'npts': array([ 3014656.]),
 'quartile': array([ 0.00254587]),
 'rms': array([ 0.00201818]),
 'sigma': array([ 0.00201811]),
 'sum': array([ 49.1322855]),
 'sumsq': array([ 12.27880404]),
 'trc': array([255, 255, 0, 45]),
```
CHAPTER 1. INTRODUCTION

If you do not catch the return variable, it will be lost

```python
imstat('ngc5921.clean.image')
```

or

```python
default('imstat')
imagename = 'ngc5921.clean.image'
imstat()
```

and spewed to terminal. Note that `go` will trap and lose the return value, e.g.

```python
default('imstat')
imagename = 'ngc5921.clean.image'
go
```

will not dump the return to the terminal either.

NOTE: You cannot currently catch a return value from a task run asynchronously (§ 1.4.4).

1.4.4 Running Tasks Asynchronously

By default, most tasks run synchronously in the foreground. Many tasks, particularly those that can take a long time to execute, have the `async` parameter. This allows the user to send the task to the background for execution.

1.4.4.1 Monitoring Asynchronous Tasks

There is a “taskmanager” tool `tm` that allows the user to retrieve the status of, and to abort the execution of, tasks running with `async=True` in the background. There are two methods of interest for the user, `tm.retrieve` and `tm.abort`.

If you run a task with `async=True` then several things will happen. First of all, the task returns a “handle” that is a number used to identify the process. This is printed to the screen, e.g.

**ALERT:**
You should not use the `go` command to run a task asynchronously, as the “handle” will be swallowed by the Python task wrapper and you will not be able to access it with `tm`. This is also true if you run in a Python script.
CHAPTER 1. INTRODUCTION

53

CASA <5>: inp()
# mosaic :: Calculate a multi-field deconvolved image with selected clean algorithm:
...
async = True # if True run in the background, prompt is freed

CASA <6>: mosaic()
Connecting to controller: ('127.0.0.1', 60775)
Out[6]: 0

where the output value 0 is the handle id.

You can also catch the return value in a variable, e.g.

CASA <7>: handle = mosaic()
...
CASA <8>: print handle
1

You should also see the usual messages from the task in the logger, with some extra lines of information

###########################################
### Begin Task: mosaic ###
Tue Oct 2 17:58:16 2007 NORMAL ::mosaic:
"
"Use: 
 tm.abort(return_value)  # to abort the asynchronous task
 tm.retrieve(return_value) # to retrieve the status
"
... usual messages here ...

### End Task: mosaic ###
###########################################
"

for the example above.

To show the current status of an asynchronous task, use the tm.retrieve method using the handle id as the argument. For example,

CASA <9>: tm.retrieve(handle)
Out[9]: {'result': None, 'status': 'pending'}

or

CASA <10>: tm.retrieve(1)
Out[10]: {'result': None, 'status': 'pending'}
which means its still running. You should be seeing output in the logger also while the task is running.

When a task is finished, you will see:

```python
CASA <11>: tm.retrieve(1)
Out[11]: {'result': None, 'status': 'done'}
```

which indicates completion.

### 1.4.4.2 Aborting Asynchronous Tasks

To abort a task while it is running in the background, use the `tm.abort` method, again with the task handle id as the argument. For example,

```python
CASA <12>: handle = mosaic()
...
CASA <13>: tm.abort(handle)
```

will abort the task if it is running.

If this does not work, try `CTRL-Z` followed by a `kill -9 <PID>` for the appropriate process ID. See §1.3.5 for more on these methods to abort CASA execution.

**ALERT:** Currently, this is only available with the `tm` tool. We are working on a `taskmanager` task.

### 1.4.5 Setting Parameters and Invoking Tasks

One can set parameters for tasks (but not for tools) by performing the assignment within the CASA shell and then inspecting them using the `inp` command:

```python
CASA <30>: default(bandpass)
CASA <31>: vis = 'ngc5921.demo.ms'
CASA <32>: caltable = 'ngc5921.demo.bcal'
CASA <33>: field = '0'
CASA <34>: refant = '15'
CASA <35>: inp('bandpass')
```

```
# bandpass :: Calculates a bandpass calibration solution
vis = 'ngc5921.demo.ms' # Name of input visibility file
caltab = 'ngc5921.demo.bcal' # Name of output gain calibration table
field = '0' # Select field using field id(s) or field name(s)
spw = '' # Select spectral window/channels
selectdata = False # Other data selection parameters
solint = 'inf' # Solution interval
combine = 'scan' # Data axes which to combine for solve (scan, spw, field)
refant = '15' # Reference antenna name
```

**Inside the Toolkit:**

In the current version of CASA, you cannot use the task parameter setting features, such as the `inp`, `default`, or `go` commands, for the tools.
CHAPTER 1. INTRODUCTION

minblperant = 4 # Minimum baselines _per antenna_ required for solve
solnorm = False # Normalize average solution amplitudes to 1.0 (G, T only)
bandtype = 'B' # Type of bandpass solution (B or BPOLY)
fillgaps = 0 # Fill flagged solution channels by interpolation
append = False # Append solutions to the (existing) table
gaintable = '' # Gain calibration table(s) to apply on the fly
gainfield = '' # Select a subset of calibrators from gaintable(s)
interp = '' # Interpolation mode (in time) to use for each gaintable
spwmap = [] # Spectral windows combinations to form for gaintables(s)
gaincurve = False # Apply internal VLA antenna gain curve correction
opacity = 0.0 # Opacity correction to apply (nepers)
parang = False # Apply parallactic angle correction
async = False #

See §1.4.5.4 below for more details on the use of the inputs command.

All task parameters have global scope within CASA: the parameter values are common to all tasks and also at the CASA command line. This allows the convenience of not changing parameters that are shared between tasks but does require care when chaining together sequences of task invocations (to ensure proper values are provided).

If you want to reset the input keywords for a single task, use the default command (§1.4.5.2). For example, to set the defaults for the bandpass task, type:

CASA <30>: default('bandpass')

as we did above.

To inspect a single parameter value just type it at the command line. Continuing the above example:

CASA <36>: combine
Out[14]: 'scan'

CASA parameters are just Python variables.

Parameters for a given task can be saved by using the saveinputs command (see §1.4.5.5) and restored using the execfile '<filename>' command. Note that if the task is successfully executed, then a <taskname>.last file is created in the working directory containing the parameter values (see §1.4.5.8).

We now describe the individual CASA task parameter interface commands and features in more detail.

1.4.5.1 The scope of parameters in CASA
All task parameters have global scope within CASA: the parameter values are common to all tasks and also at the CASA command line. This allows the convenience of not changing parameters that are shared between tasks but does require care when chaining together sequences of task invocations (to ensure proper values are provided). Tasks DO NOT change the values of the global parameters, nor does the invocation of tasks using the functional call with arguments change the globals.

This does mean that unless you do an explicit default of the task (§1.4.5.2), previously set values may be unexpectedly used if you do not inspect the inp carefully. For example, good practice is:

```
default('imhead')
    imagedata = 'ngc5921.demo.cleaning.image'
    mode = 'list'
    imhead()
```

If you supply the task call with arguments, then these will be used for the values of those parameters (see above). However, if some but not all arguments are supplied, then those parameters not given as arguments will default and NOT use the current global values. Thus,

```
imhead('ngc5921.demo.cleaning.image', mode='list')
```

will reproduce the above.

### 1.4.5.2 The default Command

Each task has a special set of default parameters defined for its parameters. You can use the default command to reset the parameters for a specified task (or the current task as defined by the taskname variable) to their default.

**Important Note:** The default command resets the values of the task parameters to a set of “defaults” as specified in the task code. Some defaults are blank strings ‘’ or empty lists [], others are specific numerical values, strings, or lists. It is important to understand that just setting a string parameter to an empty string ‘’ is not setting it to its default! Some parameters do not have a blank as an allowed value. See the help for a particular task to find out its default. If ‘’ is the default or an allowed value, it will say so explicitly.

For example, suppose we have been running CASA on a particular dataset, e.g.

```
CASA <40>: inp clean
----------> inp('clean')
# clean :: Deconvolve an image with selected algorithm
vis = 'ngc5921.demo.src.split.ms.contsub' # name of input visibility file
```
and now we wish to switch to a different one. We can reset the parameter values using default:

CASA <41>: default
----------> default()

CASA <42>: inp
----------> inp()
# clean :: Deconvolve an image with selected algorithm
vis = ''     # name of input visibility file
imagename = '' # Pre-name of output images
field = ''    # Field Name
spw = ''     # Spectral windows:channels: '' is all
selectdata = False  # Other data selection parameters
mode = 'channel'     # Type of selection (mfs, channel, velocity, frequency)
nchan = 46 # Number of channels (planes) in output image
start = 5  # first input channel to use
width = 1   # Number of input channels to average
interpolation = 'nearest'     # Spectral interpolation (nearest, linear, cubic)
niter = 6000  # Maximum number of iterations
...

It is good practice to use default before running a task if you are unsure what state the CASA global variables are in.

**ALERT:** You currently can only reset ALL of the parameters for a given task to their defaults. In an upcoming update we will allow the default command to take a second argument with a specific parameter to default its value.

### 1.4.5.3 The go Command

You can execute a task using the go command, either explicitly

CASA <44>: go listobs
----------> go(listobs)
Executing: listobs()
...

or implicitly if taskname is defined (e.g. by previous use of default or inp)
CHAPTER 1. INTRODUCTION

CASA <45>: taskname = 'clean'
CASA <46>: go
----------> go()
Executing: clean()
...

You can also execute a task simply by typing the taskname.

CASA <46>: clean
----------> clean()
Executing: clean()
...

The go command can also be used to launch a different task without changing the current taskname, without disrupting the inp process on the current task you are working on. For example

```plaintext
default 'gaincal' # set current task to gaincal and default
vis = 'n5921.ms' # set the working ms
... # set some more parameters
go listobs # launch listobs w/o chaning current task
inp # see the inputs for gaincal (not listobs!)
```

**ALERT:** Doing `go listobs(vis='foo.ms')` will currently change the taskname, and will change vis, which might not be what is desired.

1.4.5.4 The inp Command

You can set the values for the parameters for tasks (but currently not for tools) by performing the assignment within the CASA shell and then inspecting them using the inp command. This command can be invoked in any of three ways: via function call `inp('<taskname>')` or `inp(<taskname>)`, without parentheses `inp 'taskname'` or `inp <taskname>`, or using the current taskname variable setting with inp. For example,

CASA <1>: inp('clean')
...
CASA <2>: inp 'clean'
----------> inp('clean')
...
CASA <3>: inp(clean)
...
CASA <4>: inp clean
----------> inp(clean)
...
CASA <5>: taskname = 'clean'
CASA <6>: inp
----------> inp()
all do the same thing.

When you invoke the task inputs via \texttt{inp}, you see a list of the parameters, their current values, and a short description of what that parameters does. For example, starting from the default values,

\begin{verbatim}
CASA <18>: \texttt{inp('clean')}
# clean :: Deconvolve an image with selected algorithm
vis = '' # name of input visibility file
imagename = '' # Pre-name of output images
field = '' # Field Name
spw = '' # Spectral windows:channels: '' is all
selectdata = False # Other data selection parameters
mode = 'mfs' # Type of selection (mfs, channel, velocity, frequency)
niter = 500 # Maximum number of iterations
gain = 0.1 # Loop gain for cleaning
threshold = '0.0mJy' # Flux level to stop cleaning. Must include units
psfmode = 'clark' # method of PSF calculation to use during minor cycles
imagermode = '' # multi-scale deconvolution scales (pixels)
interactive = False # use interactive clean (with GUI viewer)
mask = [] # cleanbox(es), mask image(s), and/or region(s)
imsize = [256, 256] # x and y image size in pixels
cell = ['1.0arcsec', '1.0arcsec'] # x and y cell size. default unit arcsec
phcasecenter = '' # Image phase center: position or field index
restfreq = '' # rest frequency to assign to image (see help)
stokes = 'I' # Stokes params to image (eg I,IV, QU,QUV)
weighting = 'natural' # Weighting of uv (natural, uniform, briggs, ...)
uvtaper = False # Apply additional uv tapering of visibilities.
modelimage = '' # Name of model image(s) to initialize cleaning
restoringbeam = [''] # Output Gaussian restoring beam for CLEAN image
pbcor = False # Output primary beam-corrected image
minpb = 0.1 # Minimum PB level to use
async = False # If true the taskname must be started using clean(...)  
\end{verbatim}

Figure 1.1 shows how this will look to you on your terminal. Note that some parameters are in boldface with a gray background. This means that some values for this parameter will cause it to expand, revealing new sub-parameters to be set.

CASA uses color and font to indicate different properties of parameters and their values:

\texttt{Parameter and Values in CASA inp}  

\begin{verbatim}
Figure 1.1 shows how this will look to you on your terminal. Note that some parameters are in boldface with a gray background. This means that some values for this parameter will cause it to expand, revealing new sub-parameters to be set.

CASA uses color and font to indicate different properties of parameters and their values: 

\texttt{Parameter and Values in CASA inp}  
\end{verbatim}
CHAPTER 1. INTRODUCTION

Figure 1.1: Screen shot of the default CASA inputs for task clean.

<table>
<thead>
<tr>
<th>Text Font</th>
<th>Text Color</th>
<th>Highlight</th>
<th>Indentation</th>
<th>Meaning</th>
</tr>
</thead>
<tbody>
<tr>
<td>Parameters:</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>plain</td>
<td>black</td>
<td>none</td>
<td>none</td>
<td>standard parameter</td>
</tr>
<tr>
<td>bold</td>
<td>black</td>
<td>grey</td>
<td>none</td>
<td>expandable parameter</td>
</tr>
<tr>
<td>plain</td>
<td>green</td>
<td>none</td>
<td>yes</td>
<td>sub-parameter</td>
</tr>
<tr>
<td>Values:</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>plain</td>
<td>black</td>
<td>none</td>
<td>none</td>
<td>default value</td>
</tr>
<tr>
<td>plain</td>
<td>blue</td>
<td>none</td>
<td>none</td>
<td>non-default value</td>
</tr>
<tr>
<td>plain</td>
<td>red</td>
<td>none</td>
<td>none</td>
<td>invalid value</td>
</tr>
</tbody>
</table>

Figure 1.2 shows what happens when you set some of the clean parameters to non-default values. Some have opened up sub-parameters, which can now be seen and set. Figure 1.3 shows what happens when you set a parameter, in this case vis and mode, to an invalid value. Its value now appears in red. Reasons for invalidation include incorrect type, an invalid menu choice, or a filename that does not exist. For example, since vis expects a filename, it will be invalidated (red) if it is set to a non-string value, or a string that is not the name of a file that can be found. The mode='happy' is invalid because its not a supported choice ('mfs', 'channel', 'velocity', or 'frequency').

1.4.5.5 The saveinputs Command

The saveinputs command will save the current values of a given task parameters to a Python (plain ascii) file. It can take up to two arguments, e.g.

```
saveinputs(taskname, outfile)
```
CHAPTER 1. INTRODUCTION

Figure 1.2: The clean inputs after setting values away from their defaults (blue text). Note that some of the boldface ones have opened up new dependent sub-parameters (indented and green).

The first is the usual taskname parameter. The second is the name for the output Python file. If there is no second argument, for example,

```casa
saveinputs('clean')
```

a file with name <taskname>.saved (in this case 'clean.saved' will be created or overwritten if extant. If invoked with no arguments, e.g.

```casa
saveinputs
```

it will use the current values of the taskname variable (as set using inp <taskname> or default <taskname>). You can also use the taskname global parameter explicitly,

```casa
saveinputs(taskname, taskname+'_.save')
```

For example, starting from default values

```casa
CASA <1>: default('listobs')
CASA <2>: vis='ngc5921.demo.ms'
CASA <3>: saveinputs
CASA <4>: !more 'listobs.saved'
taskname = "listobs"
vis = "ngc5921.demo.ms"
```
CHAPTER 1. INTRODUCTION

Figure 1.3: The clean inputs where one parameter has been set to an invalid value. This is drawn in red to draw attention to the problem. This hapless user probably confused the 'hogbom' clean algorithm with Harry Potter.

```
selectdata = True
spw = ""
field = ""
antenna = ""
uvrange = ""
timerange = ""
correlation = ""
scan = ""
intent = ""
feed = ""
array = ""
observation = ""
verbose = True
listfile = ""

#listobs(vis="ngc5921.demo.ms", selectdata=True, spw="", field="", antenna="", uvrange="", timerange="", correlation="", scan="", intent="", feed="", array="", observation="", verbose=True, listfile="")
```

To read these back in, use the Python `execfile` command. For example,

```
CASA <5>: execfile('listobs.saved')
```

and we are back.
CHAPTER 1. INTRODUCTION

An example save to a custom named file:

CASA <6>: saveinputs('listobs','ngc5921_listobs.par')

You can also use the CASA tget command (see § 1.4.5.6 below) instead of the Python execfile to restore your inputs.

1.4.5.6 The tget Command

The tget command will recover saved values of the inputs of tasks. This is a convenient alternative to using the Python execfile command (see above).

Typing tget without a taskname will recover the saved values of the inputs for the current task as given in the current value of the taskname parameter.

Adding a task name, e.g. tget <taskname> will recover values for the specified task. This is done by searching for 1) a <taskname>.last file (see § 1.4.5.8 below), then for 2) a <taskname>.saved file (see § 1.4.5.5 above), and then executing the Python in these files.

For example,

```plaintext
default('gaincal')  # set current task to gaincal and default
tget                 # read saved inputs from gaincal.last (or gaincal.saved)
inp                  # see these inputs!
tget bandpass        # now get from bandpass.last (or bandpass.saved)
inp                  # task is now bandpass, with recovered inputs
```

1.4.5.7 The tput Command

The tput command will save the current parameter values of a task to its <taskname>.last file. This is a shorthand to saveinputs and is a counterpart to tget.

Typing tput without a taskname will save the values of the inputs for the current task as given in the current value of the taskname parameter.

Adding a task name, e.g. tput <taskname> will save the values for the specified task.

For example,

```plaintext
default('gaincal')  # set current task to gaincal and default
tget                 # read saved inputs from gaincal.last (or gaincal.saved)
inp                  # see these inputs!
vis = 'new.ms'       # change the vis parameter
tput                 # save back to the gaincal.last file for later use
```
### 1.4.5.8 The .last file

Whenever you successfully execute a CASA task, a Python script file called `<taskname>.last` will be written (or over-written) into the current working directory. For example, if you ran the `listobs` task as detailed above, then

```
CASA <14>: vis = 'ngc5921.ms'
CASA <15>: verbose = True
CASA <16>: listobs()
CASA <17>: !more 'listobs.last'
```

```
IPython system call: more listobs.last
taskname = "listobs"
vis = "ngc5921.ms"
verbose = True
listfile = ""
#listobs(vis="ngc5921.ms",verbose=False,listfile="")
```

You can restore the parameter values from the save file using

```
CASA <18>: execfile('listobs.last')
```

or

```
CASA <19>: run listobs.last
```

Note that the .last file is generally not created until the task actually finished (successfully), so it is often best to manually create a save file beforehand using the `saveinputs` command if you are running a critical task that you strongly desire to have the inputs saved for.

### 1.4.6 Tools in CASA

The CASA toolkit is the foundation of the functionality in the package, and consists of a suite of functions that are callable from Python. The tools are used by the tasks, and can be used by advanced users to perform operations that are not available through the tasks.

It is beyond the scope of this reference to describe the toolkit in detail. Occasionally, examples will be given that utilize the tools (e.g. §6.21). In short, tools are always called as functions, with any parameters that are not to be defaulted given as arguments. For example:

```python
ia.open('ngc5921.chan21.clean.cleanbox.mask')
ia.calcmask('ngc5921.chan21.clean.cleanbox[mask]">0.5', 'mymask')
ia.summary()
ia.close()
```
CHAPTER 1. INTRODUCTION

uses the image tool (ia) to turn a clean mask image into an image mask. Tools never use the CASA global parameters.

To find what tools are available, use the toolhelp command:

--------> toolhelp()

Available tools:

af : Agent flagger utilities
at : Juan Pardo ATM library
ca : Calibration analysis utilities
cb : Calibration utilities
cl : Component list utilities
cp : Cal solution plotting utilities
cs : Coordinate system utilities
cu : Class utilities
dc : Deconvolver utilities
fg : Flagging/Flag management utilities
fi : Fitting utilities
fn : Functional utilities
ia : Image analysis utilities
im : Imaging utilities
me : Measures utilities
ms : MeasurementSet (MS) utilities
msmd : MS metadata accessors
mp : MS plotting (data (amp/phase) versus other quantities)
mt : MS transformer utilities
qa : Quanta utilities
pm : PlotMS utilities
po : Imagepol utilities
rg : Region manipulation utilities
sl : Spectral line import and search
sm : Simulation utilities
tb : Table utilities (selection, extraction, etc)
tp : Table plotting utilities
vp : Voltage pattern/primary beam utilities
---
pl : pylab functions (e.g., pl.title, etc)
sd : Single dish utilities
---

You can find much more information about the toolkit in the CASA User Reference Manual:

http://casa.nrao.edu/docs/casaref/CasaRef.html
1.5 Getting the most out of CASA

There are some other general things you should know about using CASA in order to make things go smoothly during your data reduction.

1.5.1 Your command line history

Your command line history is automatically maintained and stored as `ipython.log` in your local directory. This file can be edited and re-executed as appropriate using the `execfile '<filename>'` feature.

You can also use the “up-arrow” and “down-arrow” keys for command line recall in the `casapy` interface. If you start typing text, and then use “up-arrow”, you will navigate back through commands matching what you typed.

1.5.2 Logging your session

The output from CASA commands is sent to the file `casapy-YYYYMMDD-HHmmSS.log` in your local directory, where YYYYMMDD-HHmmSS are the UT date and time when CASA was started up. New starts of CASA create new log files.

![Figure 1.4: The CASA Logger GUI window under Linux. Note that under MacOSX a stripped down logger will instead appear as a Console.](image)

The output contained in `casapy-YYYYMMDD-HHmmSS.log` is also displayed in a separate window using the `casalogger`. Generally, the logger window will be brought up when `casapy` is started. If you do not want the logger GUI to appear, then start `casapy` using the `--nologger` option,

```
casapy --nologger
```
which will run CASA in the terminal window. See §1.5.2.1 for more startup options.

**ALERT:** Due to problems with Qt under MacOSX, we had to replace the GUI `qtcasalogger` with a special stripped down one that uses the Mac Console. This still has the important capabilities such as showing the messages and cut/paste. The following description is for the Linux version and thus should mostly be disregarded on OSX. On the Mac, you treat this as just another console window and use the usual mouse and hot-key actions to do what is needed.

The CASA logger window for Linux is shown in Figure 1.4. The main feature is the display area for the log text, which is divided into columns. The columns are:

- **Time** — the time that the message was generated. Note that this will be in local computer time (usually UT) for casapy generated messages, and may be different for user generated messages;
- **Priority** — the *Priority Level* (see below) of the message;
- **Origin** — where within CASA the message came from. This is in the format `Task::Tool::Method` (one or more of the fields may be missing depending upon the message);
- **Message** — the actual text.

The `casalogger` GUI has a range of features, which include:

- **Search** — search messages by entering text in the Search window and clicking the search icon. The search currently just matches the exact text you type anywhere in the message. See Figure 1.5 for an example.
Figure 1.6: Using the **casalogger** Filter facility. The log output can be sorted by Priority, Time, Origin, and Message. In this example we are filtering by Origin using 'clean', and it now shows all the log output from the **clean** task.

- **Filter** — a filter to sort by message priority, time, task/tool of origin, and message contents. Enter text in the Filter window and click the filter icon to the right of the window. Use the pull-down at the left of the Filter window to choose what to filter. The matching is for the exact text currently (no regular expressions). See Figure 1.6 for an example.

- **View** — show and hide columns (Time, Priority, Origin, Message) by checking boxes under the **View** menu pull-down. You can also change the font here.

- **Insert Message** — insert additional comments as “notes” in the log. Enter the text into the “Insert Message” box at the bottom of the logger, and click on the Add (+) button, or choose to enter a longer message. The entered message will appear with a priority of “NOTE” with the Origin as your username. See Figure 1.7 for an example. **ALERT:** This message currently will not be inserted into the correct (or user controllable) order into the log.

- **Copy** — left-click on a row, or click-drag a range of rows, or click at the start and shift click at the end to select. Use the Copy button or **Edit** menu Copy to put the selected rows into the clipboard. You can then (usually) paste this where you wish. **ALERT:** this does not work routinely in the current version. You are best off going to the **casapy-YYYYMMDD-HHMMSS.log** file if you want to grab text.

- **Open** — There is an Open function in the **File** menu, and an Open button, that will allow you to load old casalogger files.

Other operations are also possible from the menu or buttons. Mouse “flyover” will reveal the operation of buttons, for example.

It is possible to change the file that the logging is directed to. Per default it is 'casapy-YYYYMMDD-HHMMSS.log'. But starting CASA with the option **--logfile**
Figure 1.7: CASA Logger - Insert facility: The log output can be augmented by adding notes or comments during the reduction. The file should then be saved to disk to retain these changes.

casapy --logfile otherfile.log

will redirect the output of the logger to the file 'otherfile.log' (see also Sect. 1.5.2.1). The log file can also be changed during a CASA session. Type

CASA <15>: casalog.setlogfile('otherfile.log')

and you will redirect the output to the 'otherfile.log' file. However, the logger GUI will still be monitoring the previous 'casapy-YYYYMMDD-HHMMSS.log' file. To change it to the new file, go on File - Open and select the new log file, in our case 'otherfile.log'.

1.5.2.1 Startup options for the logger

One can specify logger options at the startup of casapy on the command line:

    casapy <logger option>

These options are:

--log2term == logging message go to terminal
--nologfile == no casapy.log logfile is produced
--logfile <filename> == use specified name for logfile instead of casapy.log
--nologger == do not bring up GUI logger (see above)
--nolog (is deprecated use --nologger)

For example, to not bring up a GUI but send the message to your terminal, do
CHAPTER 1. INTRODUCTION

    casapy --nologger --log2term

while

    casapy --logfile mynewlogfile.log

will start casapy with logger messages going to the file mynewlogfile.log.

1.5.2.2 Setting priority levels in the logger

Logger messages are assigned a Priority Level when generated within CASA. The current levels of Priority are:

1. SEVERE — errors;
2. WARN — warnings;
3. INFO — basic information every user should be aware of or has requested;
4. INFO1 — information possibly helpful to the user;
5. INFO2 — details the power user might want to see;
6. INFO3 — even more details;
7. INFO4 — lowest level of non-debugging information;
8. DEBUGGING — most “important” debugging messages;
9. DEBUG1 — more details;
10. DEBUG2 — lowest level of debugging messages.

The “debugging” levels are intended for the developers use.

There is a threshold for which these messages are written to the casapy-YYYYMMDD-HHMMSS.log file and are thus visible in the logger. By default, only messages at level INFO and above are logged. The user can change the threshold using the casalog.filter method. This takes a single string argument of the level for the threshold. The level sets the lowest priority that will be generated, and all messages of this level or higher will go into the casapy-YYYYMMDD-HHMMSS.log file.

Some examples:

Inside the Toolkit:
The casalog tool can be used to control the logging. In particular, the casalog.filter method sets the priority threshold. This tool can also be used to change the output log file, and to post messages into the logger.
CHAPTER 1. INTRODUCTION

```
casalog.filter('INFO')  # the default
casalog.filter('INFO2') # should satisfy even advanced users
casalog.filter('INFO4') # all INFOx messages
casalog.filter('DEBUG2') # all messages including debugging
```

**WARNING:** Setting the threshold to **DEBUG2** will put lots of messages in the log!

### 1.5.3 Where are my data in CASA?

Interferometric data are filled into a so-called Measurement Set (or MS). In its logical structure, the MS looks like a generalized description of data from any interferometric or single dish telescope. Physically, the MS consists of several tables in a directory on disk.

Tables in CASA are actually directories containing files that are the sub-tables. For example, when you create a MS called `AM675.ms`, then the name of the directory where all the tables are stored will be called `AM675.ms/`. See Chapter 2 for more information on Measurement Set and Data Handling in CASA.

The data that you originally get from a telescope can be put in any directory that is convenient to you. Once you "fill" the data into a measurement set that can be accessed by CASA, it is generally best to keep that MS in the same directory where you started CASA so you can get access to it easily (rather than constantly having to specify a full path name).

When you generate calibration solutions or images (again these are in table format), these will also be written to disk. It is a good idea to keep them in the directory in which you started CASA.

#### 1.5.3.1 How do I get rid of my data in CASA?

Note that when you delete a measurement set, calibration table, or image, which are in fact directories, you must delete this and all underlying directories and files. If you are not running **casapy**, this is most simply done by using the file delete method of the operating system you started CASA from. For example, when running CASA on a Linux system, in order to delete the measurement set named `AM675.ms` type:

```
CASA <5>: !rm -r AM675.ms
```

from within CASA. The `!` tells CASA that a system command follows (see §1.3.7.5), and the `-r` makes sure that all subdirectories are deleted recursively.

It is convenient to prefix all MS, calibration tables, and output files produced in a run with a common string. For example, one might prefix all files from VLA project AM675 with `AM675`, e.g. `AM675.ms`, `AM675.cal`, `AM675.clean`. Then,

```
CASA <6>: !rm -r AM675*
```

will clean up all of these.

In scripts, the `!` escape to the OS will not work. Instead, use the `os.system()` function (Appendix B.7.1) to do the same thing:
os.system('rm -r AM675*')

If you are within casapy, then the CASA system is keeping a cache of tables that you have been using and using the OS to delete them will confuse things. For example, running a script that contains rm commands multiple times will often not run or crash the second time as the cache gets confused. The clean way of removing CASA tables (MS, caltables, images) inside casapy is to use the rmtables task:

```
rmtables('AM675.ms')
```

and this can also be wildcarded

```
rmtables('AM675*')
```

(though you may get warnings if it tries to delete files or directories that fit the name wildcard that are not CASA tables).

**Alert:** Some CASA processes lock the file and forget to give it up when they are done (plotxy is usually the culprit). You will get WARNING messages from rmtables and your script will probably crash second time around as the file isn’t removed. The safest thing is still to exit casapy and start a new session for multiple runs.

### 1.5.4 What’s in my data?

The actual data is in a large MAIN table that is organized in such a way that you can access different parts of the data easily. This table contains a number of “rows”, which are effectively a single timestamp for a single spectral window (like an IF from the VLA) and a single baseline (for an interferometer).

There are a number of “columns” in the MS, the most important of which for our purposes is the DATA column — this contains the original visibility data from when the MS was created or filled. There are other helpful “scratch” columns which hold useful versions of the data or weights for further processing: the CORRECTED_DATA column, which is used to hold calibrated data and an optional MODEL_DATA column, which may hold the Fourier inversion of a particular model image. The creation and use of the scratch columns is generally done behind the scenes, but you should be aware that they are there (and when they are used). We will occasionally refer to the rows and columns in the MS.

More on the contents of the MS can be found in § 2.1.

### 1.5.5 Data Selection in CASA

We have tried to make the CASA task interface as uniform as possible. If a given parameter appears in multiple tasks, it should, as far as is possible, mean the same thing and be used in the same way in each. There are groups of parameters that appear in a number of tasks to do the same thing, such as for data selection.
The parameters \texttt{field}, \texttt{spw}, and \texttt{selectdata} (which if \texttt{True} expands to a number of sub-parameters) are commonly used in tasks to select data on which to work. These common data selection parameters are described in §2.3.

### 1.6 From Loading Data to Images

The subsections below provide a brief overview of the steps you will need to load data into CASA and obtain a final, calibrated image. Each subject is covered in more detail in Chapters 2 through 6.

An end-to-end workflow diagram for CASA data reduction for interferometry data is shown in Figure 1.8. This might help you chart your course through the package. In the following subsections, we will chart a rough course through this process, with the later chapters filling in the individual boxes.

Note that single-dish data reduction (for example with the ALMA single-dish system) follows a similar course. This is detailed in Chapter 8.

#### 1.6.1 Loading Data into CASA

The key data and image import tasks are:

- \texttt{importuvfits} — import visibility data in UVFITS format (§2.2.4);
- \texttt{importvla} — import data from VLA that is in \texttt{export} format (§2.2.3);
- \texttt{importasdm} — import ALMA data in ASDM format (§2.2.1);
- \texttt{importevla} — import JVLA/EVLA data in SDM format (§2.2.2);
- \texttt{importfits} — import a FITS image into a CASA \texttt{image} format table (§6.20).

These are used to bring in your interferometer data, to be stored as a CASA Measurement set (MS), and any previously made images or models (to be stored as CASA image tables).

The data import tasks will create a MS with a path and name specified by the \texttt{vis} parameter. See §1.5.3 for more information on MS in CASA. The measurement set is the internal data format used by CASA, and conversion from any other native format is necessary for most of the data reduction tasks.

Once data is imported, there are other operations you can use to manipulate the datasets:

- \texttt{concat} — concatenate multiple MSs into a given or a new MS (§2.2.11)

Data import, export, concatenation, and selection detailed in Chapter 2.
1.6.1.1 VLA: Filling data from VLA archive format

VLA data in “archive” format are read into CASA from disk using the `importvla` task (see §2.2.3). This filler supports the new naming conventions of EVLA antennas when incorporated into the old VLA system.

Note that future data from the EVLA in ASDM format will use a different filler. This will be made available in a later release.
1.6.1.2 Filling data from UVFITS format

For UVFITS format, use the `importuvfits` task. A subset of popular flavors of UVFITS (in particular UVFITS as written by AIPS) is supported by the CASA filler. See §2.2.4 for details.

1.6.1.3 Loading FITS images

For FITS format images, such as those to be used as calibration models, use the `importfits` task. Most, though not all, types of FITS images written by astronomical software packages can be read in. See §6.20 for more information.

1.6.1.4 Concatenation of multiple MS

Once you have loaded data into measurement sets on disk, you can use the tasks `concat` or `virtualconcat` to combine them. See §2.2.11 for details.

1.6.2 Data Examination, Editing, and Flagging

The main data examination and flagging tasks are:

- `listobs` — summarize the contents of a MS (§2.2.6);
- `flagmanager` — save and manage versions of the flagging entries in the measurement set (§3.2);
- `plotms` — interactive X-Y plotting and flagging of visibility data (§3.3.1);
- `(plotxy` — interactive X-Y plotting and flagging of visibility data (§3.3.2), note: plotxy is slower than plotms and will eventually be phased out, plotxy is still useful to create scripted hardcopy output, this functionality will likely be available in plotms in the next release);
- `flagdata` — flagging (and unflagging) of specified data (§3.4);
- `viewer` — the CASA viewer can display (as a raster image) MS data, with some editing capabilities (§7);

These tasks allow you to list, plot, and/or flag data in a CASA MS.

There will eventually be tasks for “automatic” flagging to data based upon statistical criteria. Stay tuned.

Examination and editing of synthesis data is described in Chapter 3.

Visualization and editing of an MS using the `casaviewer` is described in Chapter 7.
1.6.2.1 Interactive X-Y Plotting and Flagging

The principal tool for making X-Y plots of visibility data is `plotms` (see §3.3.1). Amplitudes and phases (among other things) can be plotted against several x-axis options.

Interactive flagging (i.e., “see it – flag it”) is possible on the `plotms` X-Y displays of the data (§3.3.1.5). Since flags are inserted into the measurement set, it is useful to backup (or make a copy) of the current flags before further flagging is done, using `flagmanager` (§3.2). Copies of the flag table can also be restored to the MS in this way.

1.6.2.2 Flag the Data Non-interactively

The `flagdata` task (§3.4) will flag the visibility data set based on the specified data selections. The `listobs` task (§2.2.6) may be run (e.g. with `verbose=True`) to provide some of the information needed to specify the flagging scope. `flagdata` also contains autoflagging routines.

1.6.2.3 Viewing and Flagging the MS

The CASA `viewer` can be used to display the data in the MS as a (grayscale or color) raster image. The MS can also be edited. Use of the `viewer` on an MS is detailed in §7.5.

1.6.3 Calibration

The major calibration tasks are:

- `setjy` — Computes the model visibilities for a specified source given a flux density or model image, knows about standard calibrator sources (§4.3.4);
- `gencal` — Creates a calibration table for known delay and antenna position offsets (§4.3.5);
- `bandpass` — Solves for frequency-dependent (bandpass) complex gains (§4.4.2);
- `gaincal` — Solves for time-dependent (frequency-independent) complex gains (§4.4.3);
- `fluxscale` — Bootstraps the flux density scale from standard calibrators (§4.4.4);
- `polcal` — polarization calibration (§4.4.5);
- `applycal` — Applies calculated calibration solutions (§4.6.1);
- `clearcal` — Re-initializes calibrated visibility data in a given measurement set (§4.6.3);
- `listcal` — Lists calibration solutions (§4.5.2);
- `plotcal` — Plots (and optionally flags) calibration solutions (§4.5.1);
- `uvcontsub` — carry out uv-plane continuum subtraction for spectral-line data (§4.7.5);
• **split** — write out a new (calibrated) MS for specified sources (§4.7.1);
• **cvel** — Regrid a spectral MS onto a new frequency channel system (§4.7.6).

During the course of calibration, the user will specify a set of calibrations to pre-apply before solving for a particular type of effect, for example gain or bandpass or polarization. The solutions are stored in a calibration table (subdirectory) which is specified by the user, not by the task: care must be taken in naming the table for future use. The user then has the option, as the calibration process proceeds, to accumulate the current state of calibration in a new cumulative table. Finally, the calibration can be applied to the dataset.

Synthesis data calibration is described in detail in Chapter 4.

### 1.6.3.1 Prior Calibration

The **setjy** task calculates absolute fluxes for measurement set base on known calibrator sources. This can then be used in later calibration tasks. Currently, **setjy** knows the flux density as a function of frequency for several standard EVLA flux calibrators and solar system objects, and the value of the flux density can be manually inserted for any other source. If the source is not well-modeled as a point source, then a model image of that source structure can be used (with the total flux density scaled by the values given or calculated above for the flux density). Models are provided for the standard VLA calibrators.

Antenna gain-elevation curves (e.g. for the EVLA antennas) and atmospheric optical depth corrections (applied as an elevation-dependent function) may be pre-applied before solving for the bandpass and gains. This was previously done by setting the **gaincurve** and **opacity** parameters in the various calibration solving tasks. We now suggest to create these tables ahead of the calibration with **gencal** and to carry them through the calibration tasks just like any other calibration table.

See §4.3 for more details.

### 1.6.3.2 Bandpass Calibration

The **bandpass** task calculates a bandpass calibration solution: that is, it solves for gain variations in frequency as well as in time. Since the bandpass (relative gain as a function of frequency) generally varies much more slowly than the changes in overall (mean) gain solved for by **gaincal**, one generally uses a long time scale when solving for the bandpass. The default ’B’ solution mode solves for the gains in frequency slots consisting of channels or averages of channels.

A polynomial fit for the solution (solution type ’BPOLY’) may be carried out instead of the default frequency-slot based ’B’ solutions. This single solution will span (combine) multiple spectral windows.

Bandpass calibration is discussed in detail in §4.4.2.

If the gains of the system are changing over the time that the bandpass calibrator is observed, then you may need to do an initial gain calibration (see next step).
1.6.3.3 Gain Calibration

The `gaincal` task determines solutions for the time-based complex antenna gains, for each spectral window, from the specified calibration sources. A solution interval may be specified. The default 'G' solution mode solves for antenna-based gains in each polarization in specified time solution intervals. The 'T' solution mode is the same as 'G' except that it solves for a single solution shared by both polarizations.

A spline fit for the solution (solution type 'GSPLINE') may be carried out instead of the default time-slot based 'G' solutions.

See §4.4.3 for more on gain calibration.

1.6.3.4 Polarization Calibration

The `polcal` task will solve for any unknown polarization leakage and cross-hand phase terms ('D' and 'X' solutions). The 'D' leakage solutions will work on sources with no polarization and sources with known (and supplied, e.g., using `smodel`) polarization. For sources with unknown polarization tracked through a range in parallactic angle on the sky, using poltype 'D+QU', which will first estimate the calibrator polarization for you.

The solution for the unknown cross-hand polarization phase difference 'X' term requires a polarized source with known linear polarization (Q,U).

Frequency-dependent (i.e., per channel) versions of all of these modes are also supported (poltypes 'Df', 'Df+QU', and 'Xf').

See §4.4.5 for more on polarization calibration.

1.6.3.5 Examining Calibration Solutions

The `plotcal` task (§4.5.1) will plot the solutions in a calibration table. The `xaxis` choices include time (for `gaincal` solutions) and channel (e.g. for `bandpass` calibration). The `plotcal` interface and plotting surface is similar to that in `plotxy`. Eventually, `plotcal` will allow you to flag and unflag calibration solutions in the same way that data can be edited in `plotxy`.

The `listcal` task (§4.5.2) will print out the calibration solutions in a specified table.

1.6.3.6 Bootstrapping Flux Calibration

The `fluxscale` task bootstraps the flux density scale from “primary” standard calibrators to the “secondary” calibration sources. Note that the flux density scale must have been previously established on the “primary” calibrator(s), typically using `setjy`, and of course a calibration table containing valid solutions for all calibrators must be available.

See §4.4.4 for more.
1.6.3.7 Correcting the Data

The final step in the calibration process, `applycal` may be used to apply several calibration tables (e.g., from `gaincal` or `bandpass`). The corrections are applied to the `DATA` column of the visibility, writing the `CORRECTED_DATA` column which can then be plotted (e.g. in `plotxy`), `split` out as the `DATA` column of a new MS, or imaged (e.g. using `clean`). Any existing corrected data are overwritten.

See §4.6.1 for details.

1.6.3.8 Splitting the Data

After a suitable calibration is achieved, it may be desirable to create one or more new measurement sets containing the data for selected sources. This can be done using the `split` task (§4.7.1).

Further imaging and calibration (e.g. self-calibration) can be carried out on these split Measurement Sets.

1.6.3.9 UV Continuum subtraction

For spectral line data, continuum subtraction can be performed in the image domain (`imcontsub`) or in the uv domain. For the latter, there are two tasks available: `uvcontsub` subtracts polynomial of desired order from each baseline, defined by line-free channels.

1.6.3.10 Transforming the Data to a new frame

If you want to transform your dataset to a different frequency and velocity frame than the one it was observed in, then you can use the `cvel` task (§4.7.6). Alternatively, you can do the regridding during the imaging process in `clean` without running `cvel` before.

1.6.4 Synthesis Imaging

The key synthesis imaging tasks are:

- `clean` — Calculates a deconvolved image based on the visibility data, using one of several clean algorithms (§5.3);
- `feather` — Combines a single dish and synthesis image in the Fourier plane (§5.5).

Most of these tasks are used to take calibrated interferometer data, with the possible addition of a single-dish image, and reconstruct a model image of the sky. **Alert:** The `clean` task is now even more powerful and incorporates the functionality of previous specialized tasks such as `mosaic` and `widefield`.

See Chapter 5 for more on synthesis imaging.
1.6.4.1 Cleaning a single-field image or a mosaic

The CLEAN algorithm is the most popular and widely-studied method for reconstructing a model image based on interferometer data. It iteratively removes at each step a fraction of the flux in the brightest pixel in a defined region of the current “dirty” image, and places this in the model image. The clean task implements the CLEAN algorithm for single-field data. The user can choose from a number of options for the particular flavor of CLEAN to use.

Often, the first step in imaging is to make a simple gridded Fourier inversion of the calibrated data to make a “dirty” image. This can then be examined to look for the presence of noticeable emission above the noise, and to assess the quality of the calibration by searching for artifacts in the image. This is done using clean with niter=0.

The clean task can jointly deconvolve mosaics as well as single fields, and also has options to do wide-field and wide-band multi-frequency synthesis imaging.

See § 5.3 for an in-depth discussion of the clean task.

1.6.4.2 Feathering in a Single-Dish image

If you have a single-dish image of the large-scale emission in the field, this can be “feathered” in to the image obtained from the interferometer data. This is carried out using the feather tasks as the weighted sum in the uv-plane of the gridded transforms of these two images. While not as accurate as a true joint reconstruction of an image from the synthesis and single-dish data together, it is sufficient for most purposes.

See § 5.5 for details on the use of the feather task.

1.6.5 Self Calibration

Once a calibrated dataset is obtained, and a first deconvolved model image is computed, a “self-calibration” loop can be performed. Effectively, the model (not restored) image is passed back to another calibration process (on the target data). This refines the calibration of the target source, which up to this point has had (usually) only external calibration applied. This process follows the regular calibration procedure outlined above.

Any number of self-calibration loops can be performed. As long as the images are improving, it is usually prudent to continue the self-calibration iterations.

This process is described in § 5.9.

1.6.6 Data and Image Analysis

The key data and image analysis tasks are:

- imhead — summarize and manipulate the “header” information in a CASA image (§ 6.2);
CHAPTER 1. INTRODUCTION

• **imcontsub** — perform continuum subtraction on a spectral-line image cube (§ 6.4);
• **immath** — perform mathematical operations on or between images (§ 6.6);
• **immoments** — compute the moments of an image cube (§ 6.7);
• **imstat** — calculate statistics on an image or part of an image (§ 6.9);
• **imval** — extract values of one or more pixels, as a spectrum for cubes, from an image (§ 6.10);
• **imfit** — simple 2D Gaussian fitting of single components to a region of an image (§ 6.5);
• **imregrid** — regrid an image onto the coordinate system of another image (§ 6.13);
• **viewer** — there are useful region statistics and image cube plotting capabilities in the viewer (§ 7).

1.6.6.1 What’s in an image?

The **imhead** task will print out a summary of image “header” keywords and values. This task can also be used to retrieve and change the header values.

See § 6.2 for more.

1.6.6.2 Image statistics

The **imstat** task will print image statistics. There are options to restrict this to a box region, and to specified channels and Stokes of the cube. This task will return the statistics in a Python dictionary return variable.

See § 6.9 for more.

1.6.6.3 Image values

The **imval** task will values from an image. There are options to restrict this to a box region, and to return specified channels and Stokes of the cube as a spectrum. This task will return these values in a Python dictionary return variable which can then be operated on in the **casapy** environment.

See § 6.9 for more.

1.6.6.4 Moments of an image cube

The **immoments** task will compute a “moments” image of an input image cube. A number of options are available, from the traditional true moments (zero, first, second) and variations thereof, to other images such as median, minimum, or maximum along the moment axis.

See § 6.7 for details.
CHAPTER 1. INTRODUCTION

1.6.6.5 Image math

The \texttt{immath} task will allow you to form a new image by mathematical combinations of other images (or parts of images). This is a powerful, but tricky, task to use.

See \S 6.6 for more.

1.6.6.6 Regridding an Image

It is occasionally necessary to regrid an image onto a new coordinate system. The \texttt{imregrid} task can be used to regrid an input image onto the coordinate system of an existing template image, creating a new output image.

See \S 6.13 for a description of this task.

1.6.6.7 Displaying Images

To display an image use the \texttt{viewer} task. The viewer will display images in raster, contour, or vector form. Blinking and movies are available for spectral-line image cubes. To start the viewer, type:

\begin{verbatim}
viewer
\end{verbatim}

Executing the \texttt{viewer} task will bring up two windows: a viewer screen showing the data or image, and a file catalog list. Click on an image or ms from the file catalog list, choose the proper display, and the image should pop up on the screen. Clicking on the wrench tool (second from left on upper left) will obtain the data display options. Most functions are self-documenting.

The viewer can be run outside of casapy by typing \texttt{casaviewer}.

See \S 7 for more on viewing images.

1.6.7 Getting data and images out of CASA

The key data and image export tasks are:

- \texttt{exportuvfits} — export a CASA MS in UVFITS format (\S 2.2.4);
- \texttt{exportfits} — export a CASA image table as FITS (\S 6.20).

These tasks can be used to export a CASA MS or image to UVFITS or FITS respectively. See the individual sections referred to above for more on each.
Chapter 2

Visibility Data Import, Export, and Selection

To use CASA to process your data, you first will need to get it into a form that is understood by the package. These are “measurement sets” for synthesis (and single dish) data, and “image tables” for images.

There are a number of tasks used to fill telescope-specific data, to import/export standard formats, to list data contents, and to concatenate multiple datasets. These are:

- `asdmsummary` — list the contents of a archive file in ASDM format (§2.2.1)
- `importasdm` — import of ALMA data in ASDM format (§2.2.1)
- `importevla` — import of Jansky VLA data and flags in ASDM format (§2.2.2)
- `importuvfits` — import visibility data in UVFITS format (§2.2.4.1)
- `importfitsidi` — import visibility data in the FITS-IDI format (§2.2.4.2)
- `importvla` — import data from VLA that is in export format (§2.2.3)
- `exportuvfits` — export a CASA MS in UVFITS format (§2.2.4.3)
- `listobs` — summarize the contents of a MS (§2.2.6)
- `listpartition` — List the summary of a multi-MS data set in the logger or in a file (§2.2.7)
- `listvis` — list the data in a MS (§2.2.8)
- `vishead` — list and change the metadata contents of a MS (§2.2.9)
- `visstat` — statistics on data in a MS (§2.2.10)
- `concat` — concatenate two or more MS into a new MS (§2.2.11)
• **virtualconcat** — concatenate two or more MS or multi-MS into a new multi-MS (§ 2.2.11 and chapter 10)

In CASA, there is a standard syntax for selection of data that is employed by multiple tasks. This is described in § 2.3.

There are also tasks for the import and export of image data using FITS:

• **listfits** — show the header content of any FITS file (§ 2.1)
• **importfits** — import a FITS image into a CASA image format table (§ 6.20)
• **exportfits** — export a CASA image table as FITS (§ 6.20)

## 2.1 CASA Measurement Sets

Data is handled in CASA via the **table** system. In particular, visibility data are stored in a CASA table known as a Measurement Set (MS). Details of the physical and logical MS structure are given below, but for our purposes here an MS is just a construct that contains the data. An MS can also store single dish data (essentially a set of auto-correlations of a 1-element interferometer), though there are also data formats more suitable for single-dish spectra (see § 8).

Note that images are handled through special **image** tables, although standard FITS I/O is also supported. Images and image data are described in a separate chapter.

The headers of any FITS files can be displayed in the logger with the **listfits** task:

```plaintext
# listfits :: List the HDU and typical data rows of a fits file:
fitsfile = '' # Name of input fits file
async = False # If true the taskname must be started using
# listfits(...)  
```

Inside the Toolkit:
Measurement sets are handled in the **ms** tool. Import and export methods include **ms.fromfits** and **ms.tofits**.

Unless your data was previously processed by CASA or software based upon its predecessor **aips++**, you will need to import it into CASA as an MS. Supported formats include some “standard” flavors of UVFITS, the VLA “Export” archive format, and most recently, the ALMA Science Data Model (ASDM) format. These are described below in § 2.2.

Once in Measurement Set form, your data can be accessed through various tools and tasks with a common interface. The most important of these is the **data selection interface** (§ 2.3) which allows you to specify the subset of the data on which the tasks and tools will operate.

### 2.1.1 Under the Hood: Structure of the Measurement Set
CHAPTER 2. VISIBILITY DATA IMPORT, EXPORT, AND SELECTION

It is not necessary that a casual CASA user know the specific details on how the data in the MS is stored and the contents of all the sub-tables. However, we will occasionally refer to specific “columns” of the MS when describing the actions of various tasks, and thus we provide the following synopsis to familiarize the user with the necessary nomenclature. You may skip ahead to subsequent sections if you like!

All CASA data files, including Measurement Sets, are written into the current working directory by default, with each CASA table represented as a separate sub-directory. MS names therefore need only comply with UNIX file or directory naming conventions, and can be referred to from within CASA directly, or via full path names.

An MS consists of a MAIN table containing the visibility data, and associated sub-tables containing auxiliary or secondary information. The tables are logical constructs, with contents located in the physical table.* files on disk. The MAIN table consists of the table.* files in the main directory of the ms-file itself, and the other tables are in the respective subdirectories. The various MS tables and sub-tables can be seen by listing the contents of the MS directory itself (e.g. using Unix ls), or via the browsetable task (§3.6).

See Fig 2.1 for an example of the contents of a MS directory. Or, from the casapy prompt,

CASA <1>: ls ngc5921.ms
IPython system call: ls -F ngc5921.ms
ANTENNA POLARIZATION table.f1 table.f3_TSM1 table.f8
DATA_DESCRIPTION PROCESSOR table.f10 table.f4 table.f8_TSM1
FEED SORTED_TABLE table.f10_TSM1 table.f5 table.f9
FIELD SOURCE table.f11 table.f5_TSM1 table.f9_TSM1
FLAG_CMD SPECTRAL_WINDOW table.f11_TSM1 table.f6 table.info
HISTORY STATE table.f2 table.f6_TSM0 table.lock
OBSERVATION table.dat table.f2_TSM1 table.f7
POINTING table.f0 table.f3_TSM1

Note that the MAIN table information is contained in the table.* files in this directory. Each of the sub-table sub-directories contain their own table.dat and other files, e.g.

CASA <2>: ls ngc5921.ms/SOURCE
IPython system call: ls -F ngc5921.ms/SOURCE
table.dat table.f0 table.f0i table.info table.lock

Each “row” in a table contains entries for a number of specified “columns”. For example, in the MAIN table of the MS, the original visibility data is contained in the DATA column — each “cell” contains a matrix of observed complex visibilities for that row at a single time stamp, for a single baseline in a single spectral window. The shape of the data matrix is given by the number of channels and the number of correlations (voltage-products) formed by the correlator for an array.

Table 2.1 lists the non-data columns of the MAIN table that are most important during a typical data reduction session. Table 2.2 lists the key data columns of the MAIN table of an interferometer MS. The MS produced by fillers for specific instruments may insert special columns, such as

Inside the Toolkit:
Generic CASA tables are handled in the tb tool. You have direct access to keywords, rows and columns of the tables with the methods of this tool.
CHAPTER 2. VISIBILITY DATA IMPORT, EXPORT, AND SELECTION

Figure 2.1: The contents of a Measurement Set. These tables compose a Measurement Set named ngc5921.demo.ms on disk. This display is obtained by using the File:Open menu in browsetable and left double-clicking on the ngc5921.demo.ms directory.

ALMA_PHASE_CORR, ALMA_NO_PHAS_CORR and ALMA_PHAS_CORR_FLAG_ROW for ALMA data filled using the importasdm filler (§2.2.1). These columns are visible in browsetable and are accessible from the toolkit in the ms tool (e.g. the ms.getdata method) and from the tb “table” tool (e.g. using tb.getcol).

Note that when you examine table entries for IDs such as FIELD_ID or DATA_DESC_ID, you will see 0-based numbers.

The MS can contain a number of “scratch” columns, which are used to hold useful versions of other columns such as the data or weights for further processing. The most common scratch columns are:

- **CORRECTED_DATA** — used to hold calibrated data for imaging or display;
- **MODEL_DATA** — holds the Fourier inversion of a particular model image for calibration or imaging. This column is optional from CASA 3.4 and higher and typically not required anymore.
Table 2.1: Common columns in the MAIN table of the MS.

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Contents</th>
</tr>
</thead>
<tbody>
<tr>
<td>ANTENNA1</td>
<td>First antenna in baseline</td>
</tr>
<tr>
<td>ANTENNA2</td>
<td>Second antenna in baseline</td>
</tr>
<tr>
<td>FIELD_ID</td>
<td>Field (source no.) identification</td>
</tr>
<tr>
<td>DATA_DESC_ID</td>
<td>Spectral window number, polarization identifier pair (IF no.)</td>
</tr>
<tr>
<td>ARRAY_ID</td>
<td>Subarray number</td>
</tr>
<tr>
<td>OBSERVATION_ID</td>
<td>Observation identification</td>
</tr>
<tr>
<td>POLARIZATION_ID</td>
<td>Polarization identification</td>
</tr>
<tr>
<td>SCAN_NUMBER</td>
<td>Scan number</td>
</tr>
<tr>
<td>TIME</td>
<td>Integration midpoint time</td>
</tr>
<tr>
<td>UVW</td>
<td>UVW coordinates</td>
</tr>
</tbody>
</table>

The creation and use of the scratch columns is generally done behind the scenes, but you should be aware that they are there (and when they are used).

Table 2.2: Commonly accessed MAIN Table data-related columns. Note that the columns ALMA_PHASE_CORR, ALMA_NO_PHAS_CORR and ALMA_PHAS_CORR_FLAG_ROW are specific to ALMA data filled using the importasdm filler.

<table>
<thead>
<tr>
<th>Column</th>
<th>Format</th>
<th>Contents</th>
</tr>
</thead>
<tbody>
<tr>
<td>DATA</td>
<td>Complex(N\textsubscript{c}, N\textsubscript{f})</td>
<td>complex visibility data matrix (= ALMA_PHASE_CORR by default)</td>
</tr>
<tr>
<td>FLAG</td>
<td>Bool(N\textsubscript{c}, N\textsubscript{f})</td>
<td>cumulative data flags</td>
</tr>
<tr>
<td>WEIGHT</td>
<td>Float(N\textsubscript{c})</td>
<td>weight for a row</td>
</tr>
<tr>
<td>WEIGHT_SPECTRUM</td>
<td>Float(N\textsubscript{c}, N\textsubscript{f})</td>
<td>individual weights for a data matrix</td>
</tr>
<tr>
<td>ALMA_PHASE_CORR</td>
<td>Complex(N\textsubscript{c}, N\textsubscript{f})</td>
<td>on-line phase corrected data (Not in VLA data)</td>
</tr>
<tr>
<td>ALMA_NO_PHAS_CORR</td>
<td>Bool(N\textsubscript{c}, N\textsubscript{f})</td>
<td>data that has not been phase corrected (Not in VLA data)</td>
</tr>
<tr>
<td>ALMA_PHAS_CORR_FLAG_ROW</td>
<td>Bool(N\textsubscript{c}, N\textsubscript{f})</td>
<td>flag to use phase-corrected data or not (not in VLA data)</td>
</tr>
<tr>
<td>MODEL_DATA</td>
<td>Complex(N\textsubscript{c}, N\textsubscript{f})</td>
<td>Scratch: created by calibrator or imager tools</td>
</tr>
<tr>
<td>CORRECTED_DATA</td>
<td>Complex(N\textsubscript{c}, N\textsubscript{f})</td>
<td>Scratch: created by calibrator or imager tools</td>
</tr>
</tbody>
</table>

The most recent specification for the MS is Aips++ MeasurementSet definition version 2.0 (http://casa.nrao.edu/Memos/229.html).
2.2 Data Import and Export

There are a number of tasks available to bring data in various forms into CASA as a Measurement Set:

- ALMA Science Data Model format data can be imported into CASA (importasdm)
- JVLA Science Data Model format data, including online flags, can imported into CASA (importevla)
- VLA Archive format data can be imported into CASA (importvla)
- UVFITS format can be imported into and exported from CASA (importuvfits, importfitsidi, and exportuvfits)

2.2.1 ALMA: Filling of Science Data Model (ASDM) data

The ALMA and JVLA projects have agreed upon a common archival science data model (ASDM) format, and have jointly developed the software to fill this data into CASA. In the ASDM format, the bulk of the data is contained in large binary data format (BDF) tables, with the meta-data and ancillary information in XML tables. This is structured as a directory, like the MS, and was designed to be similar to the MS to facilitate conversion.

The content of an ASDM can be listed with the task asdmsummary:

```bash
# asdmsummary :: Summarized description of an ASDM dataset.
asdm     = ''    # Name of input ASDM directory
async    = False # If true the taskname must be started using
               # asdmsummary(...) with an output that contains the list and positions of the antennas, followed by the parameters of each scan like observation time, source name, frequency and polarization setup:

Input ASDM dataset : TDEM0008.sb3373760.eb3580330.55661.22790537037
========================================================================================
ASDM dataset : TDEM0008.sb3373760.eb3580330.55661.22790537037
========================================================================================
Exec Block : ExecBlock_0
Telescope : JVLA
Configuration name : B
Observer name : Dr. Juergen Ott
```

Under the Hood:
The importasdm task is just an interface to the stand-alone asdm2MS_v3 and asdm2MS applications. To find out the command-line arguments to this application, do asdm2MS_v3 --help or asdm2MS --help respectively.
CHAPTER 2. VISIBILITY DATA IMPORT, EXPORT, AND SELECTION


27 antennas have been used in this exec block.

<table>
<thead>
<tr>
<th>Id</th>
<th>Name</th>
<th>Make</th>
<th>Station</th>
<th>Diameter</th>
<th>X</th>
<th>Y</th>
<th>Z</th>
</tr>
</thead>
<tbody>
<tr>
<td>Antenna_0</td>
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<td>Antenna_1</td>
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<td>E20</td>
<td>25</td>
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<td>-5043150.965</td>
<td>3554065.219</td>
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<tr>
<td>Antenna_2</td>
<td>ea03</td>
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<td>E36</td>
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<td>-5045193.751</td>
<td>3552652.421</td>
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<td>3552962.365</td>
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<td>ea05</td>
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<td>-5042001.653</td>
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<td>-5040316.397</td>
<td>3557330.397</td>
</tr>
<tr>
<td>Antenna_6</td>
<td>ea07</td>
<td>UNDEFINED</td>
<td>E32</td>
<td>25</td>
<td>-1597053.116</td>
<td>-5044604.687</td>
<td>3553058.987</td>
</tr>
<tr>
<td>Antenna_7</td>
<td>ea08</td>
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<td>N28</td>
<td>25</td>
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<td>-5039885.318</td>
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<tr>
<td>Antenna_8</td>
<td>ea09</td>
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<td>E24</td>
<td>25</td>
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<td>-5043581.392</td>
<td>3553767.029</td>
</tr>
<tr>
<td>Antenna_9</td>
<td>ea10</td>
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<td>25</td>
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<td>-5039347.465</td>
<td>3558761.542</td>
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<tr>
<td>Antenna_10</td>
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<td>UNDEFINED</td>
<td>E04</td>
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<td>3554824.835</td>
</tr>
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<td>E08</td>
<td>25</td>
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<td>-5042219.366</td>
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</tr>
<tr>
<td>Antenna_12</td>
<td>ea14</td>
<td>UNDEFINED</td>
<td>W12</td>
<td>25</td>
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<td>-5042025.824</td>
<td>3554427.832</td>
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<tr>
<td>Antenna_13</td>
<td>ea15</td>
<td>UNDEFINED</td>
<td>W24</td>
<td>25</td>
<td>-1604008.742</td>
<td>-5042135.828</td>
<td>3553403.707</td>
</tr>
<tr>
<td>Antenna_14</td>
<td>ea16</td>
<td>UNDEFINED</td>
<td>N12</td>
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<td>-5041488.079</td>
<td>3555597.439</td>
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<tr>
<td>Antenna_15</td>
<td>ea17</td>
<td>UNDEFINED</td>
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<td>25</td>
<td>-1605808.656</td>
<td>-5042230.082</td>
<td>3552459.202</td>
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<tr>
<td>Antenna_16</td>
<td>ea18</td>
<td>UNDEFINED</td>
<td>N16</td>
<td>25</td>
<td>-1601061.961</td>
<td>-5041175.88</td>
<td>3556058.022</td>
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<tr>
<td>Antenna_17</td>
<td>ea19</td>
<td>UNDEFINED</td>
<td>W04</td>
<td>25</td>
<td>-1601315.893</td>
<td>-5041985.32</td>
<td>3554808.305</td>
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<tr>
<td>Antenna_18</td>
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<td>-5038758.734</td>
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<tr>
<td>Antenna_19</td>
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<td>-5042462.45</td>
<td>3554536.041</td>
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<tr>
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<td>UNDEFINED</td>
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<td>25</td>
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<td>-5041902.658</td>
<td>3554987.518</td>
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<tr>
<td>Antenna_21</td>
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<td>W16</td>
<td>25</td>
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<td>-5042054.997</td>
<td>3554140.7</td>
</tr>
<tr>
<td>Antenna_22</td>
<td>ea24</td>
<td>UNDEFINED</td>
<td>N20</td>
<td>25</td>
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<tr>
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<td>W20</td>
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<tr>
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<td>ea27</td>
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<td>25</td>
<td>-1601147.94</td>
<td>-5041733.837</td>
<td>3555235.956</td>
</tr>
</tbody>
</table>

Number of scans in this exec Block : 234

scan #1 from 2011-04-10T05:28:13.200000000 to 2011-04-10T05:33:35.500000256
  Intents : OBSERVE_TARGET
  Sources : 1331+305=3C286
  Subscan #1 from 2011-04-10T05:28:13.200000000 to 2011-04-10T05:33:35.500000256
    Intent : UNSPECIFIED
    Number of integrations : 322

    Binary data in uid:///evla/bdf/1302413292901
    Number of integrations : 322
    Time sampling : INTEGRATION
    Correlation Mode : CROSS_AND_AUTO
    Spectral resolution type : FULL_RESOLUTION
    Atmospheric phase correction : AP_UNCORRECTED
    SpectralWindow_0 : numChan = 256, frame = TOPO, firstChan = 8484000000, chandWidth = 125000

scan #2 from 2011-04-10T05:33:35.500000256 to 2011-04-10T05:35.200000000
  Intents : OBSERVE_TARGET
CHAPTER 2. VISIBILITY DATA IMPORT, EXPORT, AND SELECTION

Sources: 1331+305=3C286
Subscan #1 from 2011-04-10T05:33:35.500000256 to 2011-04-10T05:35:35.200000000
Intent: UNSPECIFIED
Number of integrations: 119

Binary data in uid:///evla/bdf/1302413293280
Number of integrations: 119
Time sampling: INTEGRATION
Correlation Mode: CROSS_AND_AUTO
Spectral resolution type: FULL_RESOLUTION
Atmospheric phase correction: AP_UNCORRECTED
SpectralWindow_0: numChan = 256, frame = TOP0, firstChan = 8484000000, chandWidth = 125000

scan #3 from 2011-04-10T05:35:35.200000000 to 2011-04-10T05:36:34.999999488
Intents: OBSERVE_TARGET
Sources: 1331+305=3C286
Subscan #1 from 2011-04-10T05:35:35.200000000 to 2011-04-10T05:36:34.999999488
...

The `importasdm` task will fill SDM1.2 and SDM1.3 format data into a CASA visibility data set (MS). ALMA data was recorded in SDM1.2 format from October 2009 until May 2011. Since May 2011, ALMA is using the SDM 1.3 format. In particular all science data from cycle 0 will be in SDM1.3. The JVLA also started using SDM1.2 in October 2009 and continues to use this format as of October 2011. The parameter `useversion` can be used to select between `asdm2MW_v3` and `asdm2MS`, `asdm2MW_v3` is the default.

The default inputs of `importasdm` are:

```python
# importasdm :: Convert an ALMA Science Data Model observation into a CASA visibility file (MS) or single-dish data format (Scantable)

asdm = ''  # Name of input asdm directory (on disk)
vis = ''    # Root name of the ms to be created. Note the .ms is NOT added
 singledish = False  # Set true to output single-dish data format
 corr_mode = 'all'  # specifies the correlation mode to be considered on input. A quoted string containing a sequence of ao, co, ac, or all separated by whitespaces is expected
 srt = 'all'  # specifies the spectral resolution type to be considered on input. A quoted string containing a sequence of fr, ca, bw, or all separated by whitespaces is expected
 time_sampling = 'all'  # specifies the time sampling (INTEGRATION and/or SUBINTEGRATION) to be considered on input. A quoted string containing a sequence of i, si, or all separated by whitespaces is expected
 ocorr_mode = 'co'  # output data for correlation mode AUTO_ONLY (ao) or CROSS_ONLY (co) or CROSS_AND_AUTO (ca)
 compression = False  # Flag for turning on data compression
```
asis = ''
# Creates verbatim copies of the ASDMtables in
# the output measurement set. Value given must
# be a string of table names separated by
# spaces; A * wildcard is allowed.

wvr_corrected_data = 'no'
# Specifies which values are considered in the
# SDM binary data to fill the DATA column in
# the MAIN table of the MS. Expected values
# for this option are: no, for uncorrected
# data (default), yes, for the corrected data,
# and both, for for corrected and uncorrected
# data. Note if both is selected two
# measurement sets are created, one with
# uncorrected data and the other with
# corrected data.

scans = ''
# processes only the specified scans. This
# value is a semicolon separated list of scan
# specifications. A scan specification
# consists in an exec block index followed by
# the : character; followed by a comma
# separated list of scan indexes or scan index
# ranges. A scan index is relative to the exec
# block it belongs to. Scan indexes are
# 1-based while exec blocks are 0-based. "0:1"
# or "2:2~6" or "0:1,1:2~6,2:3:24~30" "1,2"
# are valid values for the option. "3:" alone
# will be interpreted as, all the scans of the
# exec block#3. An scan index or a scan index
# range not preceded by an exec block index
# will be interpreted as, all the scans with
# such indexes in all the exec blocks. By
# default all the scans are considered.

ignore_time = False
# All the rows of the tables Feed, History,
# Pointing, Source, SysCal, CalDevice,
# SysPower, and Weather are processed
# independently of the time range of the
# selected exec block / scan.

process_syspower = True
# The SysPower table is processed if and only
# if this parameter is set to true.

process_caldevice = True
# The CalDevice table is processed if and only
# if this parameter is set to true.

process_pointing = True
# The Pointing table is processed if and only
# if this parameter is set to true.

process_flags = True
# Create online flags in the FLAG_CMD sub-
# table.

tbuff = 0.0
# Time padding buffer (seconds)

applyflags = False
# Apply the flags to the MS.

savecmds = False
# Save flag commands to an ASCII file

outfile = ''
# Name of ASCII file to save flag commands

verbose = False
# Output lots of information while the filler
# is working
If `scans` is set, then `importasdm` processes only the scans specified in the option’s value. This value is a semicolon separated list of scan specifications. A scan specification consists in an exec block index followed by the character `:` followed by a comma separated list of scan indexes or scan index ranges. A scan index is relative to the exec block it belongs to. Scan indexes are 1-based while exec blocks’ are 0-based. The expressions

```
"0:1"
"2:2~6"
"0:1,1:2~6;8:2:,3:24~30"
"1,2"
"3:"
```

are all valid values for the selection. The "3:" selector will be interpreted as ‘all the scans of the exec block 3’. An scan index or a scan index range not preceded by an exec block index will be interpreted as ‘all the scans with such indexes in all the exec blocks’. By default all the scans are considered.

When `process_flags=True` the task will create online flags based on the `Flag.xml`, `Antenna.xml` and `SpectralWindow.xml` files and copy them to the `FLAG_CMD` sub-table of the MS. The flags will NOT be applied unless the parameter `applyflags` is set to True. Optionally, the flags can also be saved to an external ASCII file if `savecmds` is set to True.

If `singledish=True`, output data format is scantable (single-dish data format, see [8]) instead of MS. In that case, you must specify name or id of the antenna that you want to obtain data. This can be done by using antenna parameter that is defined as a subparameter of singledish. For single-dish mode, only auto-correlation data are filled, i.e. `ocorr_mode` is forcibly set to ‘ao’.

### 2.2.1.1 Filling SDM v0 data using `importoldasdm`

If you are filling old test data taken before October 2009 in the SDM0 format, then you should use the `importoldasdm` task to fill this.

```python
# importoldasdm :: Convert a Science Data Model v0 observation into a CASA visibility file
asdm = '' # Name of input asdm directory (on disk)
corr_mode = 'all' # correlation mode to be considered on input
srt = 'all' # specifies the spectral resolution type to be considered on input
time_sampling = 'all' # time sampling (INTEGRATION and/or SUBINTEGRATION)
ocorr_mode = 'co' # AUTO_ONLY (ao) or CROSS_ONLY (co) or CROSS_AND_AUTO (ca)
compression = False # Flag for turning on data compression
async = False # If true the taskname must be started using importoldasdm(...)```
2.2.2 Janksy VLA: Filling of Science Data Model (ASDM) data

The importevla task will fill SDM data from the Jansky VLA (or ALMA) into a MS, along with online flagging data contained in the Flag.xml SDM table. Otherwise, it behaves as importasdm but with a streamlined parameter set.

The default inputs are:

```
# importevla :: Convert an Science Data Model observation into a CASA Measurement Set

asdm = '' # Name of input asdm directory (on disk)
vis = '' # Root name of the ms to be created. Note the .ms
# is NOT added
ocorr_mode = 'co' # Fill correlation mode AUTO_ONLY (ao),
# CROSSONLY (co) or CROSS_ANDAUTO (ca)
compression = False # Flag for turning on data compression
asis = '' # Create verbatim copies of these SDM tables in
# the MS.
scans = '' # List of scans to fill (default is all scans).
verbose = False # Output lots of information while the filler is
# working
overwrite = False # Over write an existing MS
online = True # Create online flags
tbuff = 0.0 # Time padding buffer (in seconds)
flagzero = True # Create flag commands for zero points
flagpol = True # Create flag commands for cross-hand
correlations
shadow = True # Create flag commands for shadowed data
tolerance = 0.0 # Amount of shadow allowed (in meters)
addantenna = '' # File name or dictionary with additional antenna
# names, positions and diameters
applyflags = False # Apply flag commands to MS
savecmds = False # Save flag commands to an ASCII file
flagbackup = True # Back up flag column before applying flags
async = False # If true the taskname must be started using
# importevla(...)
```

**Under the Hood:**
The importevla task is a modified version of the importasdm task, that includes import of online flags from the Flag.xml table into the FLAG_CMD MS table, and a streamlined set of parameters.

The default action of importevla is to construct the FLAG_CMD MS table based on the settings of online, flagzero, and shadow (and sub-parameters). If applyflags=True then these flags will be applied after filling. We recommend you use the flagcmd task after filling to examine these flags and then apply.

**ALERT:** If you want to use your JVLA online flags then you must use importevla rather than importasdm. The flagcmd task will process these flags. Also, if you have run importevla in CASA 3.3 or earlier, the flag syntax will be processed by the task oldflagcmd.
CHAPTER 2. VISIBILITY DATA IMPORT, EXPORT, AND SELECTION

See importasdm (§2.2.1) for a description of the common parameters. Some differences:

Note that importevla automatically loads in VLA switched power information (unlike in previous versions).

The online parameter controls creation of online flags from the Flag.xml SDM table. The tbuff parameter adds a time “buffer” padding for these flags in both directions to deal with timing mismatches. ALERT: For JVLA data taken before April 2011, you should set tbuff to a value (in seconds) equal to $1.5 \times$ the integration time.

The flagzero parameter controls creation of clipping commands to flag visibilities with amplitudes that are exact zeros. If flagpol=True then it will flag the cross-hands (e.g. RL and LR) as well, which might result in low but correct values of these correlations being thrown out (but can catch erroneous zeros also). ALERT: This facility is provided as the JVLA correlator, particularly in 2010, occasionally produces visibilities with zero or very small values that need to get flagged out.

The shadow parameter turns on creation of flag commands to remove antenna time ranges where they are shadowed by other antennas in the array. By default it will flag based on the antenna diameter, but if you want more lenient or conservative flagging then set the tolerance sub-parameter, where the shadowed antennas are flagged for all baselines that are shorter than radius1 + radius2 − tolerance (the radii are those for the antennas as listed in the ANTENNA sub-table). addantenna can be a file that defines the positions of antennas that are on the ground but do not appear in the MS. They can still shadow antennas in the array.

savecmds will save all flagging commands in the flagdata and flagcmd syntax (§3.4 and 3.5) to a file to be applied later or for bookkeeping.

A flag backup can be performed using the flagbackup parameter. It saves all current flags to the ‘*.flagversions’ file of the MS, before all new flags are applied.

2.2.3 VLA: Filling data from archive format (importvla)

VLA data in archive format (i.e., as downloaded from the VLA data archive) are read into CASA from disk using the importvla task. The inputs are:

```
# importvla :: import VLA archive file(s) to a measurement set:

archivefiles = '' # Name of input VLA archive file(s)
vis = '' # Name of output visibility file
bandname = '' # VLA frequency band name: '' => obtain all bands in archive files
frequencytol = 150000.0 # Frequency shift to define a unique spectral window (Hz)
project = '' # Project name: '' => all projects in file
starttime = '' # start time to search for data
stoptime = '' # end time to search for data
applytsys = True # apply nominal sensitivity scaling to data & weights
autocorr = False # import autocorrelations to ms, if set to True
antnamescheme = 'new' # 'old' or 'new'; 'VA04' or '4' for ant 4
keepblanks = False # Fill scans with empty source names (e.g. tipping scans)?
evlabands = False # Use updated eVLA frequencies and bandwidths
async = False
```

The main parameters are `archivefiles` to specify the input VLA Archive format file names, and `vis` to specify the output MS name.

**ALERT:** The scaling of VLA data both before and after the June 2007 Modcomp-turnoff is fully supported, based on the value of `applytsys`.

The NRAO Archive is located at:

- [https://archive.nrao.edu](https://archive.nrao.edu)

Note that `archivefiles` takes a string or list of strings, as there are often multiple files for a project in the archive.

For example:

```python
archivefiles = ['AP314_A950519.xp1', 'AP314_A950519.xp2']
vis = 'NGC7538.ms'
```

The `importvla` task allows selection on the frequency band. Suppose that you have 1.3 cm line observations in K-band and you have copied the archive data files `AP314_A95019.xp*` to your working directory and started `casapy`. Then,

```python
default('importvla')
archivefiles = ['AP314_A950519.xp1', 'AP314_A950519.xp2', 'AP314_A950519.xp3']
vis = 'ngc7538.ms'
bandname = 'K'
frequencytol = 10e6
importvla()
```

If the data is located in a different directory on disk, then use the full path name to specify each archive file, e.g.:

```python
archivefiles=['/home/rohir2/jmcnulli/ALMATST1/Data/N7538/AP314_A950519.xp1',
'/home/rohir2/jmcnulli/ALMATST1/Data/N7538/AP314_A950519.xp2',
'/home/rohir2/jmcnulli/ALMATST1/Data/N7538/AP314_A950519.xp3']
```

**Important Note:** `importvla` will import the on-line flags (from the VLA system) along with the data. Shadowed antennas will also be flagged. The flags will be put in the `MAIN` table and thus available to subsequent tasks and tools. If you wish to revert to unflagged data, use `flagmanager` (§ 3.2) to save the flags (if you wish), and then use `flagdata` (§ 3.4) with `mode='manualflag'` and `unflag=True` to toggle off the flags.

The other parameters are:
CHAPTER 2. VISIBILITY DATA IMPORT, EXPORT, AND SELECTION

2.2.3.1 Parameter applytsys

The `applytsys` parameter controls whether the nominal sensitivity scaling (based on the measured TSYS, with the weights scaled accordingly using the integration time) is applied to the visibility amplitudes or not. If `True`, then it will be scaled so as to be the same as AIPS FILLM (i.e. approximately in deciJanskys). Note that post-Modcomp data is in raw correlation coefficient and will be scaled using the TSYS values, while Modcomp-era data had this applied online. In all cases `importvla` will do the correct thing to data and weights based on an internal flag in the VLA Archive file, either scaling it or unscaling based on your choice for `applytsys`.

If `applytsys=True` and you see strange behavior in data amplitudes, it may be due to erroneous TSYS values from the online system. You might want to then fill with `applytsys=False` and look at the correlation coefficients to see if the behavior is as expected.

2.2.3.2 Parameter bandname

The `bandname` indicates the VLA Frequency band(s) to load, using the traditional bandname codes. These are:

- `'4'` = 48-96 MHz
- `'P'` = 298-345 MHz
- `'L'` = 1.15-1.75 GHz
- `'C'` = 4.2-5.1 GHz
- `'X'` = 6.8-9.6 GHz
- `'U'` = 13.5-16.3 GHz
- `'K'` = 20.8-25.8 GHz
- `'Q'` = 38-51 GHz
- `'` = all bands (default)

Note that as the transition from the VLA to JVLA progresses, the actual frequency ranges covered by the bands will expand, and additional bands will be added (namely `'S'` from 1-2 GHz and `'A'` from 26.4-40 GHz).

2.2.3.3 Parameter frequencytol

The `frequencytol` parameter specifies the frequency separation tolerated when assigning data to spectral windows. The default is `frequencytol=150000` (Hz). For Doppler tracked data, where the sky frequency changes with time, a `frequencytol < 10000` Hz may may produce too many unnecessary spectral windows.
2.2.3.4 Parameter project

You can specify a specific project name to import from archive files. The default ‘ ’ will import data from all projects in file(s) archivefiles.

For example for VLA Project AL519:

```python
project = 'AL519'  # this will work
project = 'al519'  # this will also work
```

while project='AL0519' will NOT work (even though that is what queries to the VLA Archive will print it as - sorry!).

2.2.3.5 Parameters starttime and stoptime

You can specify start and stop times for the data, e.g.:

```python
starttime = '1970/1/31/00:00:00'
stoptime = '2199/1/31/23:59:59'
```

Note that the blank defaults will load all data fitting other criteria.

2.2.3.6 Parameter autocorr

Note that autocorrelations are filled into the data set if autocorr=True. Generally for the VLA, autocorrelation data is not useful, and furthermore the imaging routine will try to image the autocorrelation data (it assumes it is single dish data) which will swamp any real signal. Thus, if you do fill the autocorrelations, you will have to flag them before imaging.

2.2.3.7 Parameter antnamescheme

The antnamescheme parameter controls whether importvla will try to use a naming scheme where JVLA antennas are prefixed with EA (e.g. 'EA16') and old VLA antennas have names prefixed with VA (e.g. 'VA11'). Our method to detect whether an antenna is JVLA is not yet perfected, and thus unless you require this feature, simply use antnamescheme='old'.

2.2.3.8 Parameter evlabands

The evlabands=True option is provided to allow users to access JVLA frequencies outside the standard VLA tuninings (e.g. the extended C-band above 6 GHz). ALERT: use of this option for standard VLA data will cause unexpected associations, such as X-band data below 8 GHz being extracted to C-band (as the JVLA C-band is 4–8 GHz). Use with care.
CHAPTER 2. VISIBILITY DATA IMPORT, EXPORT, AND SELECTION

2.2.4 UVFITS Import and Export

The UVFITS format is not exactly a standard, but is a popular archive and transport format nonetheless. CASA supports UVFITS files written by the AIPS FITTP task, and others.

UVFITS is supported for both import and export.

2.2.4.1 Import using importuvfits

To import UVFITS format data into CASA, use the importuvfits task:

```
CASA <1>: inp(importuvfits)
fitsfile = '' # Name of input UVFITS file
vis = '' # Name of output visibility file (MS)
antnamescheme = 'old' # For VLA only; 'new' or 'old'; 'VA04' or '04' for VLA ant 4
async = False # if True run in the background, prompt is freed
```

This is straightforward, since all it does is read in a UVFITS file and convert it as best it can into a MS.

For example:

```
importuvfits(fitsfile='NGC5921.fits',vis='ngc5921.ms')
```

**ALERT:** CARMA data can be loaded into CASA. However,

```
tb.open("c0104I/ANTENNA",nomodify=False)
namelist=tb.getcol("NAME").tolist()
for i in range(len(namelist)):
    name = 'CA'+namelist[i]
    print ' Changing '+namelist[i]+' to '+name
    namelist[i]=name

    tb.putcol("NAME",namelist)
    tb.close()
```

2.2.4.2 Import using importfitsidi

Some uvfits data is written in the FITS-IDI standard. Those files can be imported into CASA with the importfitsidi task:

```
# importfitsidi :: Convert a FITS-IDI file to a CASA visibility data set
fitsidifile = [''] # Name(s) of input FITS-IDI file(s)
vis = '' # Name of output visibility file (MS)
async = False # If true the taskname must be started using importfitsidi(...)"'
```

Example:

```
importuvfits(fitsidifile='NGC1300.fits',vis='NGC1300.ms')
```
2.2.4.3 Export using exportuvfits

The `exportuvfits` task will take a MS and write it out in UVFITS format. The defaults are:

```plaintext
# exportuvfits :: Convert a CASA visibility data set (MS) to a UVFITS file

vis = '' # Name of input visibility file
fitsfile = '' # Name of output UVFITS file
datacolumn = 'corrected' # which data to write (data, corrected, model)
field = '' # Field name list
spw = '' # Spectral window and channel selection
antenna = '' # antenna list to select
time = '' # time range selection
nchan = -1 # Number of channels to select
start = 0 # Start channel
width = 1 # Channel averaging width (value>1 indicates averaging)
writesyscal = False # Write GC and TY tables
multisource = True # Write in multi-source format
combinespw = True # Combine spectral windows (True for AIPS)
writestation = True # Write station name instead of antenna name
async = False # if True run in the background, prompt is freed
```

For example:

```plaintext
exportuvfits(vis='ngc5921.split.ms',
             fitsfile='NGC5921.split.fits',
             multisource=False)
```

The MS selection parameters `field`, `spw`, `antenna`, and `timerange` follow the standard selection syntax described in §2.3.

**ALERT:** The `nchan`, `start`, and `width` parameters will be superseded by channel selection in `spw`. Currently, there is a `time` parameter rather than `timerange`.

The `datacolumn` parameter chooses which data-containing column of the MS (see §2.1.1) is to be written out to the UV FITS file. Choices are: 'data', 'corrected', and 'model'.

There are a number of special parameters that control what is written out. These are mostly here for compatibility with AIPS.

The `writesyscal` parameter toggles whether GC and TY extension tables are written. These are important for VLBA data, and for JVLA data. **ALERT:** Not yet available.

The `multisource` parameter determines whether the UV FITS file is a multi-source file or a single-source file, if you have a single-source MS or choose only a single source. Note: the difference between a single-source and multi-source UVFITS file here is whether it has a source (SU) table and the source ID in the random parameters. Some programs (i.e. difmap) only accept single-source files. If you select more than one source in fields, then the multisource parameter will be overridden to be True regardless.
The \texttt{combinespw} parameter allows, if some conditions are met, exporting all of spectral windows (SpW) as a set of "IF"s in a single "FREQID" setup instead of giving each SpW its own FREQID in the FITS file. In this context an IF (Intermediate Frequency) is a specialization of an SpW, where each IF in a UV FITS file must have the same number of channels and polarizations, each channel must have the same width, and each IF must be present (even if flagged) throughout the entire observation. If these conditions are not met the data must be exported using multiple FREQIDs, the UV FITS equivalent of a general SpW. This matters since many (sub)programs will work with multiple IFs, but not multiple FREQIDs. For example, a UV FITS file with multiple FREQIDs can be read by AIPS, but you may find that you have to separate the FREQIDs with \texttt{SPLIT} before you can do very much with them. Therefore \texttt{combinespw=True} should be \texttt{True} if possible. Typically MSes where each band was observed simultaneously can be exported with \texttt{combinespw=True}. MSes where the tuning changed with time, e.g. 10 minutes at 4.8 GHz followed by 15 minutes at 8.4 GHz, should be exported to multiple UV FITS files using \texttt{spw} to select one tuning (set of simultaneous SpWs) per file.

The \texttt{multisource} parameter determines whether the UV FITS file is a multi-source file or a single-source file, if you have a \texttt{single-source} MS or choose only a single source. Note: the difference between a single-source and multi-source UVFITS file here is whether it has a source (SU) table and the source ID in the random parameters. If you select more than one source in \texttt{fields}, then the \texttt{multisource} parameter will be overridden to be \texttt{True} regardless.

The \texttt{combinespw} parameter allows combination of all spectral windows at one time. If \texttt{True}, then all spectral windows must have the same shape. For AIPS to read an exported file, then set \texttt{combinespw=True}.

The \texttt{writestation} parameter toggles the writing of the station name instead of antenna name.

### 2.2.5 Handling Measurement Set metadata and data

There are tasks provided for basic listing and manipulation of Measurement Set data and metadata. These include:

- \texttt{listobs} — summarize the contents of a MS (§2.2.6)
- \texttt{vishead} — list and change the metadata contents of a MS (§2.2.9)
- \texttt{visstat} — statistics on data in a MS (§2.2.10)
- \texttt{concat} — concatenate two or more MS into a new MS (§2.2.11)

#### 2.2.6 Summarizing your MS (listobs)

Once you import your data into a CASA Measurement Set, you can get a summary of the MS contents with the \texttt{listobs} task.

The inputs are:
# listobs :: List the summary of a data set in the logger or in a file

```python
vis = 'day2_TDEM0003_10s_norx' # Name of input visibility file (MS)
selectdata = True # Data selection parameters
field = '' # Field names or field index numbers: '}'.==]**all, field='0,2,3C286
spw = '' # spectral-window/frequency/channel
antenna = '' # antenna/baselines: '}'.==]**all, antenna = 'ZVA04
timerange = '' # time range: '}'.==]**all,timerange='09:14:0~09:54:0'
correlation = '' # Select data based on correlation
scan = '' # scan numbers: '}'.==]**all
intent = '' # Select data based on observation intent: '}'.==]**all
feed = '' # multi-feed numbers: Not yet implemented
array = '' # (sub)array numbers: '}'.==]**all
uvrange = '' # uv range: '}'.==]**all; uvrange = '0~100klambda, default units=meters
observation = '' # Select data based on observation ID: '}'.==]**all
verbose = True
listfile = '' # Name of disk file to write output: '}'.==]**terminal
listunfl = False # List unflagged row counts? If true, it can have significant negative performance impact.
async = False # If true the taskname must be started using listobs(...)
```

The summary (of the selected data) will be written to the logger, to the `casapy-YYYYMMDD-HHMMSS.log` file, and optionally to a file specified in the `listfile` parameter. For example,

```python
listobs('n5921.ms')
```

results in the logger messages:

```python
listobs(vis="day2_TDEM0003_10s_norx",selectdata=True,spw="",field="",
antenna="",uvrange="",timerange="",correlation="",scan="",
intent="",feed="",array="",observation="",verbose=True,
listfile="",listunfl=False)
```

---

MeasurementSet Name: /Users/jott/casa/casatest/casa4.0/irc/day2_TDEM0003_10s_norx MS Version 2

Observer: Mark J. Mark Claussen Project: T.B.D.

Observation: EVLA

Data records: 290218 Total integration time = 10016 seconds

Observed from 26-Apr-2010/03:21:56.0 to 26-Apr-2010/06:08:52.0 (UTC)

<table>
<thead>
<tr>
<th>ObservationID</th>
<th>ArrayID</th>
<th>Date</th>
<th>Timerange (UTC)</th>
<th>Scan</th>
<th>FldId</th>
<th>FieldName</th>
<th>nRows</th>
<th>SpwIds</th>
<th>Average Interval</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>0</td>
<td>26-Apr-2010/03:21:51.0 - 03:23:21.0</td>
<td>5</td>
<td>2</td>
<td>J0954+1743</td>
<td>2720</td>
<td>[0, 1]</td>
<td>[10, 10]</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>03:23:39.0 - 03:28:25.0</td>
<td>6</td>
<td>3</td>
<td>IRC+10216</td>
<td>9918</td>
<td>[0, 1]</td>
<td>[10, 10]</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>03:28:38.0 - 03:29:54.0</td>
<td>7</td>
<td>2</td>
<td>J0954+1743</td>
<td>2700</td>
<td>[0, 1]</td>
<td>[10, 10]</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>03:30:08.0 - 03:34:53.5</td>
<td>8</td>
<td>3</td>
<td>IRC+10216</td>
<td>9918</td>
<td>[0, 1]</td>
<td>[10, 10]</td>
<td></td>
</tr>
</tbody>
</table>
```

(nRows = Total number of rows per scan)
Fields: 4

<table>
<thead>
<tr>
<th>ID</th>
<th>Code</th>
<th>Name</th>
<th>RA</th>
<th>Decl</th>
<th>Epoch</th>
<th>SrcId</th>
<th>nRows</th>
</tr>
</thead>
<tbody>
<tr>
<td>2</td>
<td>D</td>
<td>J0954+1743</td>
<td>09:54:56.823626 +17.43.31.22243</td>
<td>J2000</td>
<td>2</td>
<td>65326</td>
<td></td>
</tr>
<tr>
<td>3</td>
<td>NONE</td>
<td>IRC+10216</td>
<td>09:47:57.382000 +13.16.40.65999</td>
<td>J2000</td>
<td>3</td>
<td>208242</td>
<td></td>
</tr>
<tr>
<td>5</td>
<td>F</td>
<td>J1229+0203</td>
<td>12:29:06.99729 +02.03.08.59820</td>
<td>J2000</td>
<td>5</td>
<td>10836</td>
<td></td>
</tr>
<tr>
<td>7</td>
<td>E</td>
<td>J1331+3030</td>
<td>13:31:08.287984 +30.30.32.95886</td>
<td>J2000</td>
<td>7</td>
<td>5814</td>
<td></td>
</tr>
</tbody>
</table>

Spectral Windows: (2 unique spectral windows and 1 unique polarization setups)

<table>
<thead>
<tr>
<th>SpwID</th>
<th>Name</th>
<th>#Chans</th>
<th>Frame</th>
<th>Ch1(MHz)</th>
<th>ChanWid(kHz)</th>
<th>TotBW(kHz)</th>
<th>Corrs</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>Subband:0</td>
<td>64</td>
<td>TOP0</td>
<td>36387.229</td>
<td>125.000</td>
<td>8000.0</td>
<td>RR</td>
</tr>
<tr>
<td>1</td>
<td>Subband:0</td>
<td>64</td>
<td>TOP0</td>
<td>36304.542</td>
<td>125.000</td>
<td>8000.0</td>
<td>RL</td>
</tr>
</tbody>
</table>

Sources: 10

<table>
<thead>
<tr>
<th>ID</th>
<th>Name</th>
<th>SpwId</th>
<th>RestFreq(MHz)</th>
<th>SysVel(km/s)</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>J1008+0730</td>
<td>0</td>
<td>0.03639232</td>
<td>~0.026</td>
</tr>
<tr>
<td>0</td>
<td>J1008+0730</td>
<td>1</td>
<td>0.03639232</td>
<td>~0.026</td>
</tr>
<tr>
<td>2</td>
<td>J0954+1743</td>
<td>0</td>
<td>0.03639232</td>
<td>~0.026</td>
</tr>
<tr>
<td>2</td>
<td>J0954+1743</td>
<td>1</td>
<td>0.03639232</td>
<td>~0.026</td>
</tr>
<tr>
<td>3</td>
<td>IRC+10216</td>
<td>0</td>
<td>0.03639232</td>
<td>~0.026</td>
</tr>
<tr>
<td>3</td>
<td>IRC+10216</td>
<td>1</td>
<td>0.03639232</td>
<td>~0.026</td>
</tr>
<tr>
<td>5</td>
<td>J1229+0203</td>
<td>0</td>
<td>0.03639232</td>
<td>~0.026</td>
</tr>
<tr>
<td>5</td>
<td>J1229+0203</td>
<td>1</td>
<td>0.03639232</td>
<td>~0.026</td>
</tr>
<tr>
<td>7</td>
<td>J1331+3030</td>
<td>0</td>
<td>0.03639232</td>
<td>~0.026</td>
</tr>
<tr>
<td>7</td>
<td>J1331+3030</td>
<td>1</td>
<td>0.03639232</td>
<td>~0.026</td>
</tr>
</tbody>
</table>

Antennas: 19:

<table>
<thead>
<tr>
<th>ID</th>
<th>Name</th>
<th>Station</th>
<th>Diam.</th>
<th>Long.</th>
<th>Lat.</th>
<th>Offset from array center (m)</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>East</td>
</tr>
<tr>
<td>0</td>
<td>ea01</td>
<td>W09</td>
<td>25.0 m</td>
<td>-107.37.25.2</td>
<td>+33.53.51.0</td>
<td>-521.9407</td>
</tr>
<tr>
<td>1</td>
<td>ea02</td>
<td>E02</td>
<td>25.0 m</td>
<td>-107.37.04.4</td>
<td>+33.54.01.1</td>
<td>9.8247</td>
</tr>
<tr>
<td>2</td>
<td>ea03</td>
<td>E09</td>
<td>25.0 m</td>
<td>-107.36.45.1</td>
<td>+33.53.53.6</td>
<td>506.0591</td>
</tr>
<tr>
<td>3</td>
<td>ea04</td>
<td>W01</td>
<td>25.0 m</td>
<td>-107.37.05.9</td>
<td>+33.54.00.6</td>
<td>-27.3562</td>
</tr>
<tr>
<td>4</td>
<td>ea05</td>
<td>W08</td>
<td>25.0 m</td>
<td>-107.37.21.6</td>
<td>+33.53.53.0</td>
<td>-432.1158</td>
</tr>
<tr>
<td>5</td>
<td>ea07</td>
<td>N06</td>
<td>25.0 m</td>
<td>-107.37.06.9</td>
<td>+33.54.10.3</td>
<td>54.0678</td>
</tr>
<tr>
<td>6</td>
<td>ea08</td>
<td>N01</td>
<td>25.0 m</td>
<td>-107.37.06.0</td>
<td>+33.54.01.8</td>
<td>30.8810</td>
</tr>
<tr>
<td>7</td>
<td>ea09</td>
<td>E06</td>
<td>25.0 m</td>
<td>-107.36.55.6</td>
<td>+33.53.57.7</td>
<td>236.9058</td>
</tr>
<tr>
<td>8</td>
<td>ea12</td>
<td>E08</td>
<td>25.0 m</td>
<td>-107.36.48.9</td>
<td>+33.53.55.1</td>
<td>407.8394</td>
</tr>
<tr>
<td>9</td>
<td>ea15</td>
<td>W06</td>
<td>25.0 m</td>
<td>-107.37.15.6</td>
<td>+33.53.56.4</td>
<td>-275.8288</td>
</tr>
<tr>
<td>10</td>
<td>ea19</td>
<td>W04</td>
<td>25.0 m</td>
<td>-107.37.10.8</td>
<td>+33.53.59.1</td>
<td>152.8599</td>
</tr>
<tr>
<td>11</td>
<td>ea20</td>
<td>N05</td>
<td>25.0 m</td>
<td>-107.37.06.7</td>
<td>+33.54.08.0</td>
<td>-47.8454</td>
</tr>
<tr>
<td>12</td>
<td>ea21</td>
<td>E01</td>
<td>25.0 m</td>
<td>-107.37.05.7</td>
<td>+33.53.59.2</td>
<td>-23.8638</td>
</tr>
<tr>
<td>13</td>
<td>ea22</td>
<td>N04</td>
<td>25.0 m</td>
<td>-107.37.06.5</td>
<td>+33.54.06.1</td>
<td>-42.5986</td>
</tr>
<tr>
<td>14</td>
<td>ea23</td>
<td>E07</td>
<td>25.0 m</td>
<td>-107.36.52.4</td>
<td>+33.53.56.5</td>
<td>318.0523</td>
</tr>
<tr>
<td>15</td>
<td>ea24</td>
<td>W05</td>
<td>25.0 m</td>
<td>-107.37.13.0</td>
<td>+33.53.57.8</td>
<td>-210.0944</td>
</tr>
<tr>
<td>16</td>
<td>ea25</td>
<td>N02</td>
<td>25.0 m</td>
<td>-107.37.06.2</td>
<td>+33.54.03.5</td>
<td>-35.6245</td>
</tr>
<tr>
<td>17</td>
<td>ea27</td>
<td>E03</td>
<td>25.0 m</td>
<td>-107.37.02.8</td>
<td>+33.54.00.5</td>
<td>50.6647</td>
</tr>
<tr>
<td>18</td>
<td>ea28</td>
<td>N08</td>
<td>25.0 m</td>
<td>-107.37.07.5</td>
<td>+33.54.15.8</td>
<td>-68.9057</td>
</tr>
</tbody>
</table>

using the (default) verbose=True option. The most useful extra information that verbose=True gives is the list of the scans in the dataset.
2.2.7 MMS summary (listpartition)

Similar to listobs, listpartition shows the summary of a multi-measurement set (MMS).

2.2.8 Listing MS data (listvis)

The listvis task will print to the terminal (or file) listing of the data in your MS. The inputs are:

```
# listvis :: List measurement set visibilities.
vis = '' # Name of input visibility file
options = 'ap' # List options: ap only
datacolumn = 'data' # Column to list: data, float_data, corrected, model, residual
field = '' # Field names or index to be listed: 'all
spw = '*' # Spectral window: channels: '*all, spw='1:5-57'
selectdata = False # Other data selection parameters
observation = '' # Select by observation ID(s)
average = '' # Averaging mode: none (Not yet implemented)
showflags = False # Show flagged data (Not yet implemented)
pagerows = 50 # Rows per page
listfile = '' # Output file
async = False # If true the taskname must be started using listvis(...)```

For example:

Units of columns are: Date/Time(YYMMDD/HH:MM:SS UT), UVDist(wavelength), Phase(deg), UVW(m)

| WEIGHT: 7 |
| FIELD: 2 |
| SPW: 0 |

<table>
<thead>
<tr>
<th>Date/Time: 2010/04/26/</th>
<th>Intrf</th>
<th>UVDist</th>
<th>Chn</th>
<th>Amp</th>
<th>Phs</th>
<th>Wt F</th>
<th>Amp</th>
<th>Phs</th>
<th>Wt F</th>
<th>Amp</th>
<th>Phs</th>
<th>Wt F</th>
<th>Amp</th>
</tr>
</thead>
<tbody>
<tr>
<td>03:21:56.0 ea01-ea02 72363</td>
<td>0: 0.005</td>
<td>-124.5</td>
<td>7</td>
<td>0.005</td>
<td>25.7</td>
<td>7</td>
<td>0.001</td>
<td>104.6</td>
<td>7</td>
<td>0.000</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>03:21:56.0 ea01-ea02 72363</td>
<td>1: 0.001</td>
<td>-4.7</td>
<td>7</td>
<td>0.001</td>
<td>-135.1</td>
<td>7</td>
<td>0.004</td>
<td>-14.6</td>
<td>7</td>
<td>0.001</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>03:21:56.0 ea01-ea02 72363</td>
<td>2: 0.002</td>
<td>17.8</td>
<td>7</td>
<td>0.002</td>
<td>34.3</td>
<td>7</td>
<td>0.005</td>
<td>-114.3</td>
<td>7</td>
<td>0.005</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>03:21:56.0 ea01-ea02 72363</td>
<td>3: 0.004</td>
<td>-19.4</td>
<td>7</td>
<td>0.003</td>
<td>-79.2</td>
<td>7</td>
<td>0.002</td>
<td>-89.0</td>
<td>7</td>
<td>0.004</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>03:21:56.0 ea01-ea02 72363</td>
<td>4: 0.001</td>
<td>-16.8</td>
<td>7</td>
<td>0.004</td>
<td>-141.5</td>
<td>7</td>
<td>0.005</td>
<td>114.9</td>
<td>7</td>
<td>0.006</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>03:21:56.0 ea01-ea02 72363</td>
<td>5: 0.001</td>
<td>-29.8</td>
<td>7</td>
<td>0.009</td>
<td>-96.4</td>
<td>7</td>
<td>0.002</td>
<td>-125.0</td>
<td>7</td>
<td>0.002</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

Type Q to quit, A to toggle long/short list, or RETURN to continue [continue]:

**ALERT:** We are working on improving the format of the listvis output.

2.2.9 Listing and manipulating MS metadata (vishead)

The vishead task is provided to access keyword information in the Measurement Set. The default inputs are:
CHAPTER 2. VISIBILITY DATA IMPORT, EXPORT, AND SELECTION

# vishead :: List, get, and put metadata in a measurement set
vis = ''  # Name of input visibility file
mode = 'list'  # options: list, summary, get, put
listitems = []  # items to list ([]) for all
async = False #

The mode = 'summary' option just gives the same output as listobs.

For mode = 'list' the options are: 'telescope', 'observer', 'project', 'field', 'freq_group_name', 'spw_name', 'schedule', 'schedule_type', 'release_date'.

CASA <29>: vishead('ngc5921.demo.ms',mode='list',listitems=[])  
Out[29]:
{'cal_grp': (array([-1, -1, -1], dtype=int32), {}),
 'field': (array(['1331+30500002_0', '1445+09900002_0', 'N5921_2'],
   dtype='|S16'),
   {}),
 'fld_code': (array(['C', 'A', ''],
   dtype='|S2'), {}),
 'freq_group_name': (array(['none'],
   dtype='|S5'), {}),
 'log': ({'r1': False}, {}),
 'observer': (array(['TEST'],
   dtype='|S5'), {}),
 'project': (array([''],
   dtype='|S1'), {}),
 'ptcs': ({'r1': array([[-2.74392758],
   [0.53248521]],
   'r2': array([[-2.42044692],
   [0.17412604]],
   'r3': array([[-2.26020138],
   [0.08843002]]),
   {'MEASINFO': {'Ref': 'J2000', 'type': 'direction'},
   'QuantumUnits': array(['rad', 'rad'],
   dtype='|S4')},),
 'release_date': (array([4.30444800e+09],
   {'MEASINFO': {'Ref': 'TAI', 'type': 'epoch'},
   'QuantumUnits': array(['s'],
   dtype='|S2'))},
 'schedule': ({'r1': False}, {}),
 'schedule_type': (array([''],
   dtype='|S1'), {}),
 'source_name': (array(['1331+30500002_0', '1445+09900002_0', 'N5921_2'],
   dtype='|S16'),
   {}),
 'spw_name': (array(['none'],
   dtype='|S5'), {}),
You can use mode='get' to retrieve the values of specific keywords, and likewise mode='put' to change them. The inputs are:

mode = 'get'  # options: list, summary, get, put
hdkey = ''  # keyword to get/put
hdindex = ''  # keyword index to get/put, counting from zero. ==>all

and

# vishead :: List, summary, get, and put metadata in a measurement set
mode = 'put'  # options: list, summary, get, put
hdkey = ''  # keyword to get/put
hdindex = ''  # keyword index to get/put, counting from zero. ==>all
hdvalue = ''  # value of hdkey

For example, a common operation is to change the Telescope name (e.g. if it is unrecognized), e.g.

CASA <36>: vishead('ngc5921.demo.ms',mode='get',hdkey='telescope')
Out[36]:
(array(['VLA'],
dtype='|S4'), {})

CASA <37>: vishead('ngc5921.demo.ms',mode='put',hdkey='telescope',hdvalue='JVLA')

CASA <38>: vishead('ngc5921.demo.ms',mode='get',hdkey='telescope')
Out[38]:
(array(['JVLA'],
dtype='|S5'), {})

2.2.10 MS statistics (visstat)

ALERT: This is still a prototype task.

The visstat task is provided to obtain simple statistics for a Measurement Set, useful in regression tests.

The inputs are:

# visstat :: Displays statistical information from a measurement set
vis = ''  # Name of input visibility file
axis = 'amp'  # Which values to use
datacolumn = 'data'  # Which data column to use (data, corrected, model)
useflags = True  # Take flagging into account?
spw = ''  # spectral-window/frequency/channel
Field names or field index numbers: 'all', field='0~2,3C286'
More data selection parameters (antenna, timerange etc)
antenna: all, antenna = '3,VA04'
time range: 'all', timerange='09:14:0~09:54:0'
Select data based on correlation
scan: all
(array numbers: 'all'; array = '0~100klambda', default units=meters)
If true the taskname must be started using visstat(...)
Running this task returns a record (Python dictionary) with the statistics, which can be captured in a Python variable. For example,
```
CASA <42>: mystat = visstat('ngc5921.demo.ms',axis='amp',datacolumn='corrected',field='0')
```
```
CASA <43>: mystat
Out[43]:
{'CORRECTED': {'max': 51.938671112060547,
'mean': 14.796444141750133,
'medabsdevmed': 0.28020858764648438,
'median': 14.764373779296875,
'min': 0.81362706422805786,
'npts': 514916.0,
'quartile': 0.56053066253662109,
'rms': 14.829294204711914,
'stddev': 0.986508366091,
'sum': 7618925.8316934109,
'sumsq': 113234125.12642419,
'var': 0.97319875636846753}}
```
```
CASA <44>: print mystat['CORRECTED']['stddev']
0.986508366091
```
The options for axis are:
```
axis='amplitude' # or ('amp')
axis='phase'
axis='imag'
axis='scan_number'
axis='flag'
```
The phase of a complex number is in radians with range \((−\pi, \pi)\).

2.2.11 Concatenating multiple datasets (concat)

Once you have your data in the form of CASA Measurement Sets, you can go ahead and process your data using the editing, calibration, and imaging tasks. In some cases, you will most efficiently
operate on single MS for a particular session (such as calibration). Other tasks will (eventually) take multiple Measurement Sets as input. For others, it is easiest to combine your multiple data files into one.

If you need to combine multiple datasets, you can use the **concat** task. The default inputs are:

```python
# concat :: Concatenate several visibility data sets.
vis = '' # Name of input visibility files to be concatenated
concatvis = '' # Name of output visibility file
freqtol = '' # Frequency shift tolerance for considering data as the same spwid
dirtol = '' # Direction shift tolerance for considering data as the same field
respectname = False # If true, fields with a different name are not merged even if their direction agrees
timesort = False # If true, sort by TIME in ascending order
copypointing = True # Copy all rows of the POINTING table.
visweightscale = [] # List of the weight scaling factors to be applied to the individual MSs
createmms = False # Should this create a multi-MS output
async = False # If true the taskname must be started using concat(...)
```

The **vis** parameter will take a list of one or more MS. Usually, this will contain all the MS to combine.

With **visweightscale**, a list of weights can be manually specified for the respective input data sets. They will be applied at the time of the combination. To determine the appropriate weights for this procedure, one can inspect the weights (Wt axis parameter) of the input datasets in **plotms**.

The **concatvis** parameter contains the name of the output MS. If this points to an existing file on disk, then the MS in **vis** will appended to it, otherwise a new MS file is created to contain the concatenated data. Be careful here!

The **timesort** parameter can be used to make sure the output MS is in time order (e.g. if your input MS have concurrent times). This can possibly speed up some subsequent calibration operations.

Furthermore, the parameter **copypointing** can be used to control whether the POINTING table will be carried along in the concatenation process or if the output MS should not contain a POINTING table. This table is quite large for some data (e.g. ALMA) and is mainly needed for mosaic imaging. If you are certain that you will not need it, you can save time and disk space by setting **copypointing** to False.

The parameters **freqtol** and **dirtol** control how close together in frequency and angle on the sky spectral windows or field locations need to be before calling them the same.

**ALERT:** Note that if multiple frequencies or pointings are combined using **freqtol** or **dirtol**, then the data are not changed (ie. not rephased to the single phase center). Use of these parameters is intended to be tolerant of small offsets (e.g. planets tracked which move slightly in J2000 over the course of observations, or combining epochs observed with slightly different positions).
For example:

```python
default('concat')
vis = ['n4826_16apr.split.ms','n4826_22apr.split.ms']
concatvis = 'n4826_tboth.ms'
freqtol = '50MHz'
visweightscale=['1',2']
concat()
```

combines the two days in `n4826_16apr.split.ms` and `n4826_22apr.split.ms` into a new output MS called `n4826_tboth.ms`, and the second MS is weighted twice the first one.

**ALERT:** Note that if you are concatenating MSs which use antennas which were moved between observations, the MS definition does only foresee a unique antenna ID, but not a unique name(!). The moved antenna will appear twice in the antenna list under the same name but on different stations and with two different IDs. The pair ('NAME@STATION') will be the unique identifier.

If you would like to only concatenate the subtables of several MSs, not the bulk visibility data, you can use the task `testconcat` instead of `concat` to save time and disk space. `testconcat` has the same parameters as `concat`. It produces an output MS with the concatenated subtables and an empty Main table.

Furthermore, the new task `virtualconcat` permits to concatenate MSs into a multi-MS (MMS, see chapter 10) which is much faster as the data is moved into the MMS rather than copied and only some reindexing is done. The bulk data is not rewritten. If you want to keep a copy of the original MSs, set the parameter `keepcopy` of `virtualconcat` to True. The creation of that copy will of course consume some of the time you saved by doing a virtual concatenation. Otherwise `virtualconcat` offers the same functionality as `concat`.

## 2.3 Data Selection

Once in MS form, subsets of the data can be operated on using the tasks and tools. In CASA, there are three common data selection parameters used in the various tasks: `field`, `spw`, and `selectdata`. In addition, the `selectdata` parameter, if set to `True`, will open up a number of other sub-parameters for selection. The selection operation is unified across all the tasks. The available `selectdata` parameters may not be the same in all tasks. But if present, the same parameters mean the same thing and behave in the same manner when used in any task.

For example:

```python
field = ''  # field names or index of calibrators ''===>all
spw = ''  # spectral window:channels: ''===>all
selectdata = False  # Other data selection parameters
```
The following are the general syntax rules and descriptions of the individual selection parameters of particular interest for the tasks:

2.3.1 General selection syntax

Most of the selections are effected through the use of selection strings. This sub-section describes the general rules used in constructing and parsing these strings. Note that some selections are done though the use of numbers or lists. There are also parameter-specific rules that are described under each parameter.

All lists of basic selection specification-units are comma separated lists and can be of any length. White-spaces before and after the commas (e.g. '3C286, 3C48, 3C84') are ignored, while white-space within sub-strings is treated as part of the sub-string (e.g. '3C286, VIRGO A, 3C84').

All integers can be of any length (in terms of characters) composed of the characters 0–9. Floating point numbers can be in the standard format (DIGIT.DIGIT, DIGIT., or .DIGIT) or in the mantissa-exponent format (e.g. 1.4e9). Places where only integers make sense (e.g. IDs), if a floating point number is given, only the integer part is used (it is truncated).

Range of numbers (integers or real numbers) can be given in the format 'N0~N1'. For integer ranges, it is expanded into a list of integers starting from N0 (inclusive) to N1 (inclusive). For real numbers, it is used to select all values present for the appropriate parameter in the Measurement Set between N0 and N1 (including the boundaries). Note that the '~' character is used rather than the more obvious '-' in order to accommodate hyphens in strings and minus signs in numbers.

Wherever appropriate, units can be specified. The units are used to convert the values given to the units used in the Measurement Set. For ranges, the unit is specified only once (at the end) and applies to both the range boundaries.

2.3.1.1 String Matching

String matching can be done in three ways. Any component of a comma separated list that cannot be parsed as a number, a number range, or a physical quantity is treated as a regular expression or a literal string. If the string does not contain the characters '*', '{', '}' or '?', it is treated as a literal string and used for exact matching. If any of the above mentioned characters are part of the string, they are used as a regular expression. As a result, for most cases, the user does not need to supply any special delimiters for literal strings and/or regular expressions. For example:
field = '3'  # match field ID 3 and not select field named "3C286".

field = '3*'  # used as a pattern and matched against field names. If
# names like "3C84", "3C286", "3020+2207" are found,
# all will match. Field ID 3 will not be selected
# (unless of course one of the above mentioned field
# names also correspond to field ID 3!).

field = '30*'  # will match only with "3020+2207" in above set.

However if it is required that the string be matched exclusively as a regular expression, it can be
supplied within a pair of '/' as delimiters (e.g. '/.+BAND.+/'). A string enclosed within double
quotes ('"') is used exclusively for pattern matching (patterns are a simplified form of regular
expressions - used in most UNIX commands for string matching). Patterns are internally converted
to equivalent regular expressions before matching. See the Unix command "info regex", or visit
http://www.regular-expressions.info for details of regular expressions and patterns.

Strings can include any character except the following:

', ';' '"' '/' NEWLINE

(since these are part of the selection syntax). Strings that do not contain any of the characters
used to construct regular expressions or patterns are used for exact matches. Although it is highly
discouraged to have name in the MS containing the above mentioned reserved characters, if one
does choose to include the reserved characters as parts of names etc., those names can only be
matched against quoted strings (since regular expression and patterns are a super-set of literal
strings – i.e., a literal string is also a valid regular expression).

This leaves '"', '*', '{', '}' or '?' as the list of printable character that cannot be part of a
name (i.e., a name containing this character can never be matched in a MSSelection expression).
These will be treated as pattern-matching even inside double double quotes (""""). There is
currently no escape mechanism (e.g. via a backslash).

Some examples of strings, regular expressions, and patterns:

- The string 'LBAND' will be used as a literal string for exact match. It will match only the
  exact string LBAND.
- The wildcarded string '*BAND*' will be used as a string pattern for matching. This will
  match any string which has the sub-string BAND in it.
- The string '"*BAND*"' will also be used as a string pattern, matching any string which has
  the sub-string BAND in it.
- The string '/.BAND./' will be used as a regular expression. This will also match any string
  which as the sub-string BAND in it. (the .+ regex operator has the same meaning as the *
  wildcard operator of patterns).
2.3.2 The field Parameter

The field parameter is a string that specifies which field names or ids will be processed in the task or tool. The field selection expression consists of comma separated list of field specifications inside the string.

Field specifications can be literal field names, regular expressions or patterns (see § 2.3.1.1). Those fields for which the entry in the NAME column of the FIELD MS sub-table match the literal field name/regular expression/pattern are selected. If a field name/regular expression/pattern fails to match any field name, the given name/regular expression/pattern are matched against the field code. If still no field is selected, an exception is thrown.

Field specifications can also be given by their integer IDs. IDs can be a single or a range of IDs. Field ID selection can also be done as a boolean expression. For a field specification of the form '>ID', all field IDs greater than ID are selected. Similarly for '<ID' all field IDs less than the ID are selected.

For example, if the MS has the following observations:

<table>
<thead>
<tr>
<th>FIELDID</th>
<th>SPWID</th>
<th>NChan</th>
<th>Pol</th>
<th>NRows</th>
<th>Source Name</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>0</td>
<td>127</td>
<td>RR</td>
<td>10260</td>
<td>0530+135</td>
</tr>
<tr>
<td>1</td>
<td>0</td>
<td>127</td>
<td>RR</td>
<td>779139</td>
<td>05582+16320</td>
</tr>
<tr>
<td>2</td>
<td>0</td>
<td>127</td>
<td>RR</td>
<td>296190</td>
<td>05309+13319</td>
</tr>
<tr>
<td>3</td>
<td>0</td>
<td>127</td>
<td>RR</td>
<td>58266</td>
<td>0319+415</td>
</tr>
<tr>
<td>4</td>
<td>0</td>
<td>127</td>
<td>RR</td>
<td>32994</td>
<td>1331+305</td>
</tr>
<tr>
<td>5</td>
<td>1</td>
<td>1</td>
<td>RR,RL,LL,RR</td>
<td>23166</td>
<td>KTIP</td>
</tr>
</tbody>
</table>

one might select

field = '0~2,KTIP' # FIELDID 0,1,2 and field name KTIP
field = '0530+135' # field 0530+135
field = '05*' # fields 0530+135,05582+16320,05309+13319

2.3.3 The spw Parameter

The spw parameter is a string that indicates the specific spectral windows and the channels within them to be used in subsequent processing. Spectral window selection ('SPWSEL') can be given as a spectral window integer ID, a list of integer IDs, a spectral window name specified as a literal string (for exact match) or a regular expression or pattern.

The specification can be via frequency ranges or by indexes. A range of frequencies are used to select all spectral windows which contain channels within the given range. Frequencies can be specified with an optional unit — the default unit being Hz. Other common choices for radio and mm/sub-mm data are kHz, MHz, and GHz. You will get the entire spectral windows, not just the channels in the specified range. You will need to do channel selection (see below) to do that.
The `spw` can also be selected via comparison for integer IDs. For example, `'>ID'` will select all spectral windows with ID greater than the specified value, while `<ID' will select those with ID lesser than the specified value.

**ALERT:** In the current release, `<ID' and '>ID' are *inclusive* with the ID specified included in the selection, e.g. spw='<2' is equivalent to spw='0,1,2' and not spw='0,1' as was intended. This will be fixed in an upcoming release.

Spectral window selection using strings follows the standard rules:

```plaintext
spw = '1'       # SPWID 1
spw = '1,3,5'   # SPWID 1,3,5
spw = '0~3'     # SPWID 0,1,2,3
spw = '0~3,5'   # SPWID 0,1,2,3 and 5
spw = '<3,5'    # SPWID 0,1,2,3 and 5
spw = '*'       # All spectral windows
spw = '1412~1415MHz' # Spectral windows containing 1412-1415MHz
```

In some cases, the spectral windows may allow specification by name. For example,

```plaintext
spw = '3mmUSB, 3mmLSB'       # choose by names (if available)
```

might be meaningful for the dataset in question.

Note that the order in which multiple `spws` are given may be important for other parameters. For example, the `mode = 'channel'` in `clean` uses the first `spw` as the origin for the channelization of the resulting image cube.

### 2.3.3.1 Channel selection in the `spw` parameter

Channel selection can be included in the `spw` string in the form `SPWSEL:CHANSEL` where `CHANSEL` is the channel selector. In the end, the spectral selection within a given spectral window comes down to the selection of specific channels. We provide a number of shorthand selection options for this. These `CHANSEL` options include:

- **Channel ranges:** `START~STOP`
- **Frequency ranges:** `FSTART~FSTOP`
- **Velocity ranges:** `VSTART~VSTOP` (*not yet available*)
- **Bandwidth percentages:** `PSTART~PSTOP` or `PWIDTH` (*not yet available*)
- **Channel striding/stepping:** `START~STOP~STEP` or `FSTART~FSTOP~FSTEP`

The most common selection is via channel ranges `START~STOP` or frequency ranges `FSTART~FSTOP`:
spw = '0:13~53'  # spw 0, channels 13-53, inclusive
spw = '0:1413~1414MHz'  # spw 0, 1413-1414MHz section only

All ranges are inclusive, with the channel given by, or containing the frequency or velocity given by, \textsc{START} and \textsc{STOP} plus all channels between included in the selection. You can also select the spectral window via frequency ranges 'FSTART~FSTOP', as described above:

spw = '1413~1414MHz:1413~1414MHz'  # channels falling within 1413~1414MHz
spw = '*:1413~1414MHz'  # does the same thing

You can also specify multiple spectral window or channel ranges, e.g.

spw = '2:16, 3:32~34'  # spw 2, channel 16 plus spw 3 channels 32-34
spw = '2:1~3;57~63'  # spw 2, channels 1-3 and 57-63
spw = '1~3:10~20'  # spw 1-3, channels 10-20
spw = '*:4~56'  # all spw, channels 4-56

Note the use of the wildcard in the last example.

A step can be also be included using "^\textsc{STEP}" as a postfix:

spw = '0:10~100^2'  # chans 10,12,14,...,100 of spw 0
spw = ':^4'  # chans 0,4,8,... of all spw
spw = ':100~150GHz^10GHz'  # closest chans to 100,110,...,150GHz

A step in frequency or velocity will pick the channel in which that frequency or velocity falls, or the nearest channel.

2.3.4 The \textit{selectdata} Parameters

The \textit{selectdata} parameter, if set to \texttt{True}, will expand the inputs to include a number of sub-parameters, given below and in the individual task descriptions (if different). If \textit{selectdata} = \texttt{False}, then the sub-parameters are treated as blank for selection by the task.

The common \textit{selectdata} expanded sub-parameters are:

2.3.4.1 The \textit{antenna} Parameter

The \textit{antenna} selection string is a semi-colon (';;') separated list of baseline specifications. A baseline specification is of the form:

- \texttt{\'ANT1\'} — Select all baselines including the antenna(s) specified by the selector \texttt{ANT1}.
- \texttt{\'ANT1\&\'} — Select only baselines between the antennas specified by the selector \texttt{ANT1}.
• 'ANT1&ANT2' — Select only the cross-correlation baselines between the antennas specified by
   selector ANT1 and antennas specified by selector ANT2. Thus 'ANT1&' is an abbreviation for
   'ANT1&ANT1'.

• 'ANT1&&ANT2' — Select only auto-correlation and cross-correlation baselines between anten-
   nas specified by the selectors ANT1 and ANT2. Note that this is what the default antenna=''
   gives you.

• 'ANT1&&&' — Select only autocorrelations specified by the selector ANT1.

The selectors ANT1 and ANT2 are comma-separated lists of antenna integer-IDs or literal antenna
names, patterns, or regular expressions. The ANT strings are parsed and converted to a list of
antenna integer-IDs or IDs of antennas whose name match the given names/pattern/regular ex-
pression. Baselines corresponding to all combinations of the elements in lists on either side of
ampersand are selected.

Integer IDs can be specified as single values or a range of integers. When items of the list are parsed
as literal strings or regular expressions or patterns (see §[2,3,1] for more details on strings). All
antenna names that match the given string (exact match)/regular expression/pattern are selected.

**ALERT:** Just for antenna selection, a user supplied integer (or integer list) is converted to a string
and matched against the antenna name. If that fails, the normal logic of using an integer as an
integer and matching it with antenna index is done. Note that currently there is no method for
specifying a pure index (e.g. a number that will not first be checked against the name).

The comma is used only as a separator for the list of antenna specifications. The list of baselines
specifications is a semi-colon separated list, e.g.

\[
antenna = '1^3 & 4^6 ; 10&11'
\]

will select baselines between antennas 1,2,3 and 4,5,6 ('1&4', '1&5', ..., '3&6') plus baseline
'10&11'.

The wildcard operator ('*') will be the most often used pattern. To make it easy to use, the
wildcard (and only this operator) can be used without enclosing it in quotes. For example, the
selection

\[
antenna = 'VA*'
\]

will match all antenna names which have 'VA' as the first 2 characters in the name (irrespective
of what follows after these characters).

There is also a negation operator “!'” that can be used to de-select antennas or baselines.

Some examples:

```
antenna=''
# shows blank autocorr pages
antenna='*&&*'  # does not show the autocorrs
antenna='*&&&'  # show both auto and cross-cor (default)
```
antenna='*&&&' # shows only autocorrs
antenna='5&*' # shows non-auto baselines with AN 5
antenna='5,6&&&' # AN 5 and 6 autocor
antenna='5&&&;6&*' # AN 5 autocor plus cross-cors to AN 6
antenna='!5' # baselines not involving AN 5

Antenna numbers as names: Needless to say, naming antennas such that the names can also be parsed as a valid token of the syntax is a bad idea. Nevertheless, antenna names that contain any of the reserved characters and/or can be parsed as integers or integer ranges can still be used by enclosing the antenna names in double quotes ("ANT "). E.g. the string

antenna = '10~15,21,VA22'

will expand into an antenna ID list 10,11,12,13,14,15,21,22 (assuming the index of the antenna named 'VA22' is 22). If, however, the antenna with ID index 50 is named '21', then the string

antenna = '10~15,21,VA22'

will expand into an antenna ID list of 10,11,12,13,14,15,50,22.  *Keep in mind that numbers are FIRST matched against names, and only against indices if that matching fails.* There is currently no way to force a selection to use the index, and if there an antenna with that name it will select that.

Read elsewhere (e.g. info regex under Unix) for details of regular expression and patterns.

Antenna stations Instead of antenna names, the antenna station names are also accepted by the selection syntax., e.g. 'N15' for the JVLA.

ANT@STATION sections syntax Sometimes, data from multiple array configurations are stored in a single MS. But some antennas may have been moved during reconfiguration and the 'ANT@STATION' syntax can distinguish between them. 'ANT' is the antenna name or index and 'STATION' is the antenna station name, e.g., 'EA12@W03' selects antenna EA012 but only at times when it is positioned on station W03. Wildcards are accepted, e.g. 'EA12@*' selects all visibilities from antenna EA12, and '*@W03' would select all antennas that are located on station 'W03' during any observations included in the MS.

2.3.4.2 The scan Parameter

The scan parameter selects the scan ID numbers of the data. There is currently no naming convention for scans. The scan ID is filled into the MS depending on how the data was obtained, so use this with care.

Examples:
scan = '3' # scan number 3.
scan = '1~8' # scan numbers 1 through 8, inclusive
scan = '1,2,4,6' # scans 1,2,4,6
scan = '<9' # scans <9 (1-8)

NOTE: ALMA and VLA/JVLA number scans starting with 1 and not 0. You can see what the numbering is in your MS using the listobs task with verbose=True (see § 2.2.6).

### 2.3.4.3 The timerange Parameter

The time strings in the following (T0, T1 and dT) can be specified as YYYY/MM/DD/HH:MM:SS.FF. The time fields (i.e., YYYY, MM, DD, HH, MM, SS and FF), starting from left to right, may be omitted and they will be replaced by context sensitive defaults as explained below.

Some examples:

1. **timerange='T0~T1':** Select all time stamps from T0 to T1. For example:

   ```
   timerange = '2007/10/09/00:40:00 ~ 2007/10/09/03:30:00'
   ```

   Note that fields missing in T0 are replaced by the fields in the time stamp of the first valid row in the MS. For example,

   ```
   timerange = '09/00:40:00 ~ 09/03:30:00'
   ```

   where the YY/MM/ part of the selection has been defaulted to the start of the MS.

   Fields missing in T1, such as the date part of the string, are replaced by the corresponding fields of T0 (after its defaults are set). For example:

   ```
   timerange = '2007/10/09/23:41:00 ~ 03:30:00'
   ```

   does the same thing as above.

2. **timerange='T0':** Select all time stamps that are within an integration time of T0. For example,

   ```
   timerange = '2007/10/09/23:41:00'
   ```

   Integration time is determined from the first valid row (more rigorously, an average integration time should be computed). Default settings for the missing fields of T0 are as in (1).

3. **timerange='T0+dT':** Select all time stamps starting from T0 and ending with time stamp T0+dT. For example,

   ```
   timerange = '23:41:00+01:00:00'
   ```

   picks an hour-long chunk of time.

   Defaults of T0 are set as usual. Defaults for dT are set from the time corresponding to MJD=0. Thus, dT is a specification of length of time from the assumed nominal "start of time".
CHAPTER 2. VISIBILITY DATA IMPORT, EXPORT, AND SELECTION

4. timerange='>T0': Select all times greater than T0. For example,

\[
\text{timerange} = '2007/10/09/23:41:00' \\
\text{timerange} = '23:41:00'  # Same thing without day specification
\]

Default settings for T0 are as above.

5. timerange='<T1': Select all times less than T1. For example,

\[
\text{timerange} = '<2007/10/09/23:41:00'
\]

Default settings for T1 are as above.

An ultra-conservative selection might be:

\[
\text{timerange} = '1960/01/01/00:00:00~2020/12/31/23:59:59'
\]

which would choose all possible data!

2.3.4.4 The uvrange Parameter

Rows in the MS can also be selected based on the uv-distance or physical baseline length that the visibilities in each row correspond to. This \textit{uvrange} can be specified in various formats.

The basic building block of uv-distance specification is a valid number with optional units in the format N\text{[UNIT]} (the unit in square brackets is optional). We refer to this basic building block as \textit{UVDIST}. The default unit is meter. Units of length (such as \texttt{m} and \texttt{km}) select physical baseline distances (independent of wavelength). The other allowed units are in wavelengths (such as \texttt{lambda}, \texttt{klambda} and \texttt{Mlambda} and are true uv-plane radii

\[
r_{uv} = \sqrt{u^2 + v^2}.
\]

If only a single \textit{UVDIST} is specified, all rows, the uv-distance of which exactly matches the given \textit{UVDIST}, are selected.

\textit{UVDIST} can be specified as a range in the format \texttt{N0~N1\text{[UNIT]}} (where N0 and N1 are valid numbers). All rows corresponding to uv-distance between N0 and N1 (inclusive) when converted the specified units are selected.

\textit{UVDIST} can also be selected via comparison operators. When specified in the format \texttt{>UVDIST'}, all visibilities with uv-distances greater than the given \textit{UVDIST} are selected. Likewise, when specified in the format \texttt{<UVDIST'}, all rows with uv-distances less than the given \textit{UVDIST} are selected.

Any number of above mentioned uv-distance specifications can be given as a comma-separated list.

Examples:

\[
\begin{align*}
\text{uvrange} & = '100~200km' & \text{# an annulus in physical baseline length} \\
\text{uvrange} & = '24~35\text{Mlambda}, 40~45\text{Mlambda}' & \text{# two annuli in units of mega-wavelengths} \\
\text{uvrange} & = '< 45\text{klambda}' & \text{# less than 45 kilolambda} \\
\text{uvrange} & = '> 0\text{lambda}' & \text{# greater than zero length (no auto-corrs)} \\
\text{uvrange} & = '100\text{km}' & \text{# baselines of length 100km} \\
\text{uvrange} & = '100\text{klambda}' & \text{# uv-radius 100 kilolambda}
\end{align*}
\]
2.3.4.5 The observation Parameter

The observation parameter can select between different observation IDs. They will be assigned to parts of a combined data set during a run of concat. Each input MS will receive its own observation id in the process.

2.3.4.6 The msselect Parameter

More complicated selections within the MS structure are possible using the Table Query Language (TaQL). This is accessed through the msselect parameter.

Note that the TaQL syntax does not follow the rules given in §2.3.1 for our other selection strings. TaQL is explained in more detail in Aips++ NOTE 199 — Table Query Language (http://aips2.nrao.edu/docs/notes/199/199.html). This will eventually become a CASA document. The specific columns of the MS are given in the most recent MS specification document: Aips++ NOTE 229 — MeasurementSet definition version 2.0 (http://aips2.nrao.edu/docs/notes/229/229.html). This documentation will eventually be updated to the CASA document system.

Most selection can be carried out using the other selection parameters. However, these are merely shortcuts to the underlying TaQL selection. For example, field and spectral window selection can be done using msselect rather than through field or spw:

```
msselect='FIELD_ID == 0'       # Field id 0 only
msselect='FIELD_ID <= 1'       # Field id 0 and 1
msselect='FIELD_ID IN [1,2]'   # Field id 1 and 2
msselect='FIELD_ID==0 && DATA_DESC_ID==3' # Field id 0 in spw id 3 only
```

**ALERT:** The msselect style parameters will be phased out of the tasks. TaQL selection will still be available in the Toolkit.
Chapter 3

Data Examination and Editing

3.1 Plotting and Flagging Visibility Data in CASA

The tasks available for plotting and flagging of data are:

- **flagmanager** — manage versions of data flags (§ 3.2)
- **plotms** — create X-Y plots of data in MS and calibration tables, flag data (§ 3.3.1)
- **plotxy** — older X-Y plotter with some functionalities not yet implemented in plotms (§ 3.3.2)
- **flagdata** --- Data Flagging (§ 3.4)
- **flagcmd** --- manipulate and apply flags using FLAG_CMD table (§ 3.5)
- **browsetable** --- browse data in any CASA table (including a MS) (§ 3.6)
- **plotants** --- create simple plots of antenna positions (§ 3.3.3)
- **plotuv** --- plotting of uv-coverages (§ 3.3.4)

The following sections describe the use of these tasks.

Information on other related operations can be found in:

- **listobs** — list summary of a MS (§ 2.2.6)
- **listvis** — list data in a MS (§ 2.2.8)
- **selectdata** — general data selection syntax (§ 2.3)
- **viewer** — use the casaviewer to display the MS as a raster image, and flag it (§ 7)
3.2 Managing flag versions with flagmanager

The flagmanager task will allow you to manage different versions of flags in your data. These are stored inside a CASA flagversions table, under the name of the MS `<msname>.flagversions`. For example, for the MS `jupiter6cm.usecase.ms`, there will need to be `jupiter6cm.usecase.ms.flagversions` on disk. This is created on import (by importvla or importuvfits) or when flagging is first done on an MS without a .flagversions (e.g. with plotxy).

By default, when the .flagversions is created, this directory will contain a flags.Original in it containing a copy of the original flags in the MAIN table of the MS so that you have a backup. It will also contain a file called FLAG_VERSION_LIST that has the information on the various flag versions there. The flagversions are cumulative, i.e. a specific version number contains all the flags from the lower version numbers, too.

The inputs for flagmanager are:

```python
vis = '' # Name of input visibility file (MS)
mode = 'list' # Flag management operation (list,save,restore,delete)
```

The mode='list' option will list the available flagversions from the `<msname>.flagversions` file. For example:

```bash
CASA <102>: default('flagmanager')
CASA <103>: vis = 'jupiter6cm.usecase.ms'
CASA <104>: mode = 'list'
CASA <105>: flagmanager()
```

MS: `/home/imager-b/smyers/Oct07/jupiter6cm.usecase.ms`

main : working copy in main table
Original : Original flags at import into CASA
flagautocorr : flagged autocorr
xyflags : Plotxy flags

The mode parameter expands the options. For example, if you wish to save the current flagging state of vis= `<msname>`,

```python
mode = 'save' # Flag management operation (list,save,restore,delete)
versionname = '' # Name of flag version (no spaces)
comment = '' # Short description of flag version
merge = 'replace' # Merge option (replace, and, or)
```

with the output version name specified by versionname. For example, the above xyflags version was written using:

```python
default('flagmanager')
vis = 'jupiter6cm.usecase.ms'
mode = 'save'
versionname = 'xyflags'
comment = 'Plotxy flags'
flagmanager()
```
and you can see that there is now a sub-table in the flagversions directory

CASA <106>: ls jupiter6cm.usecase.ms.flagversions/
   IPython system call: ls -F jupiter6cm.usecase.ms.flagversions/
   flags.flagautocorr flags.Original flags.xyflags FLAG_VERSION_LIST

It is recommended that you use this facility regularly to save versions during flagging.
You can restore a previously saved set of flags using the mode='restore' option:

```
mode = 'restore'  # Flag management operation (list,save,restore,delete)
versionname = ''  # Name of flag version (no spaces)
merge = 'replace' # Merge option (replace, and, or)
```

The merge sub-parameter will control how the flags are restored. For merge='replace', the flags in versionname will replace those in the MAIN table of the MS. For merge='and', only data that is flagged in BOTH the current MAIN table and in versionname will be flagged. For merge='or', data flagged in EITHER the MAIN or in versionname will be flagged.

The mode='delete' option can be used to remove versionname from the flagversions:

```
mode = 'delete'  # Flag management operation (list,save,restore,delete)
versionname = ''  # Name of flag version (no spaces)
```

### 3.3 X-Y Plotting and Editing of the Data

There are three main X-Y plotting tasks in CASA:

- **plotms** — create X-Y plots of data in MS, flag data ([§ 3.3.1](#))
- **plotxy** — older X-Y plotter with some functionalities not yet implemented in plotms ([§ 3.3.2](#))
- **plotants** — create simple plots of antenna positions ([§ 3.3.3](#))

#### 3.3.1 MS Plotting and Editing using plotms

The principal way to get X-Y plots of visibility data and calibration tables is the plotms task. This task also provides editing capability. Plotms is a GUI-style plotter, based on Qt ([http://www.trolltech.com/qt](http://www.trolltech.com/qt)). It can either be started as a task within CASA (plotms) or from outside CASA (type casaplotms on the command line).

The current inputs to the plotms task are:
CHAPTER 3. DATA EXAMINATION AND EDITING

# plotms :: A plotter/interactive flagger for visibility data.
vis = '' # input visibility dataset (blank for none)
xaxis = '' # plot x-axis (blank for default/current)
yaxis = '' # plot y-axis (blank for default/current)
selectdata = False # data selection parameters
averagedata = True # data averaging parameters
avgchannel = '' # average over channel? (blank = False, otherwise value in channels)
avgtime = '' # average over time? (blank = False, other value in seconds)
avgscan = False # only valid if time averaging is turned on. average over scans?
avgfield = False # only valid if time averaging is turned on. average over fields?
avgbaseline = False # average over all baselines? (mutually exclusive with avgantenna)
avgantenna = False # average by per-antenna? (mutually exclusive with avgbaseline)
avgspw = False # average over all spectral windows?
scalar = False # Do scalar averaging?
transform = False # transform data in various ways?
extendflag = False # have flagging extend to other data points?
iterraxis = '' # the axis over which to iterate
customsymbol = False # set a custom symbol for unflagged points
coloraxis = '' # selects which data to use for colorizing
customflaggedsymbol = False # set a custom plot symbol for flagged points
plotrange = [] # plot axes ranges: [xmin,xmax,ymin,ymax]
title = '' # Title written along top of plot
xlabel = '' # Text for horizontal axis. Blank for default.
ylabel = '' # Text for vertical axis. Blank for default.
showmajorgrid = False # Show major grid lines (horiz and vert.)
showminorgrid = False # Show minor grid lines (horiz and vert.)
plotfile = '' # Name of plot file to save automatically.
async = False # If true the taskname must be started using plotms(...)

All of these parameters can also be set or modified from inside the plotms window. Note that, if the vis parameter is set to the name of a measurement or calibration table set here, when you start up plotms, the entire measurement set will be plotted, which can be time consuming. It is probably best to leave all parameters blank for now, setting them as needed inside the plotms GUI.

3.3.1.1 Loading and Selecting Data

When plotms is first started, a window will appear as in Figure 3.1. It will, by default, display the Plots tab (as chosen from the tabs at the top of the plotms window—e.g., Plots, Flagging, Tools...) and the Plots > Data tab (as chosen from the tabs on the far left side of the plotms window—e.g., Data, Axes, Trans, Iter...). First, a measurement set should be loaded by clicking
on **Browse** near the top of the **Plots** > **Data** tab, and selecting a .ms directory (just select the directory itself; do not descend into the .ms directory). A plot can now be made of the measurement set by clicking on **Plot**—but beware, this would plot the entire measurement set, and could take quite some time! It is probably better to select a subset of the measurement set using the **Selection** windows in the **Plots** > **Data** tab before clicking **Plot**.

The options for data selection are:

- **field**
- **spw**
- **timerange**
- **uvrange**
• antenna
• scan
• corr
• array
• msselect

These are described in §2.3. Note that, unlike when setting data selection parameters from the CASA command line, no quotation marks are needed around strings.

When a plotting parameter has been changed, it will turn red (for example, when a new measurement set is loaded, **File Location** turns red). This alerts the user that, if the **Plot** button is clicked, a change will be made to the displayed plot.

Once you have selected the desired subset of data, if you click **Plot**, **plotms** will by default plot amplitude versus time. See the next section for information about other possible axes.

For a given data selection, **plotms** will only load the data once. This speeds up plotting considerably when changing plot parameters such as different axes, colors etc. Sometimes, however, the data changes on disk, e.g., when other data processing tasks were applied. To force **plotms** to reload the data, checkmark the little **force reload** box left to the **Plot** button or press the **SHIFT** key while clicking the **Plot** button.

### 3.3.1.2 A Brief Note Regarding **plotms** Memory Usage

In order to provide a wide range of flexible interactive plotting options while minimizing the I/O burden, **plotms** caches the data values for the plot (along with a subset of relevant meta-info) in as efficient a manner as possible. For plots of large numbers of points, the total memory requirement can be quite large. **plotms** attempts to predict the memory it will require (typically 5 or 6 bytes per plotted point when only one axis is a data axis, depending upon the data shapes involved), and will complain if it believes there is insufficient memory to support the requested plot. For most practical interactive purposes (plots that load and draw in less than a few or a few 10s of minutes), there is usually not a problem on typical modern workstations (attempts to plot large datasets on small laptops might be more likely to encounter problems here).

The absolute upper limit on the number of simultaneously plotted points is currently set by the ability to index the points in the cache. For modern 64 bit machines, this is about 4.29 billion points (requiring around 25GB of memory). (Such plots are not especially useful interactively, since the I/O and draw become prohibitive.)

In general, it is usually most efficient to plot data in modest chunks of not more than a few hundred million points or less, either using selection or averaging. Note that all iterations are (currently) cached simultaneously for iterated plots, so iteration is not a way to manage memory use. A few hundred million points tends to be the practical limit of interactive **plotms** use w.r.t. information
content and utility in the resulting plots, especially when you consider the number of available pixels on your screen.

Since datasets are growing very large, options for plotting arbitrarily large numbers of points—probably in a non-interactive mode—are under consideration for a future release.

3.3.1.3 Plot Axes

The X and Y axes of a plot are selected by clicking on the **Plots > Axes** tab on the left side of the `plotms` window, and choosing an entry from the drop-down menus below **X Axis** and **Y Axis** (see Figure 3.2). Possible axes are:

- **Scan** — The scan number, as listed by `listobs` (§ 2.2.6) or the data summary in `plotms` (§ 3.3.1.8).
• **Field** — The field number, as listed by `listobs` (§ 2.2.6) or the `plotms` data summary (§ 3.3.1.8).

• **Time** — The time at which the visibility was observed, given in terms of calendar year (yyyy/mm/dd/hh:mm:ss.ss).

• **Time_interval** — The integration time in seconds.

• **Spw** — The spectral window number. The characteristics of each spectral window are listed in `listobs` (§ 2.2.6) or the `plotms` data summary (§ 3.3.1.8).

• **Channel** — The spectral channel number.

• **Frequency** — Frequency in units of GHz. The frame for the frequency (e.g., topocentric, barycentric, LSRK) can be set in the **Plots > Trans** tab (§ 3.3.1.9).

• **Velocity** — Velocity in units of km s\(^{-1}\), as defined by the **Frame**, **Velocity Defn**, and **Rest Freq** parameters in the **Plots > Trans** tab (§ 3.3.1.9).

• **Corr** — Correlations which have been assigned integer IDs: 5 = RR; 6 = RL; 7 = LR; and 8 = LL.

• **Antenna1** — The first antenna in a baseline pair; for example, for baseline 2-4, Antenna1 = 2. Antennae are numbered according to the antenna IDs listed in `listobs` (§ 2.2.6) or the `plotms` data summary (§ 3.3.1.8).

• **Antenna2** — The second antenna in a baseline pair; for baseline 2-4, Antenna2 = 4. Antennae are numbered according to the antenna IDs listed in `listobs` (§ 2.2.6) or the `plotms` data summary (§ 3.3.1.8).

• **Antenna** — Antenna ID for plotting antenna-based quantities. Antennae are numbered according to the antenna IDs listed in `listobs` (§ 2.2.6) or the `plotms` data summary (§ 3.3.1.8).

• **Baseline** — The baseline number.

• **UVDist** — Projected baseline separations in units of meters. Note that **UVDist** is not a function of frequency.

• **UVwave** — Projected baseline separations in units of the observing wavelength (lambda, not kilolambda). **UVDist\_L** is a function of frequency, and therefore, there will be a different data point for each frequency channel.

• **U**, **V**, and **W** — \( u, v, \) and \( w \) in units of meters.

• **Uwave**, **Vwave**, and **Wwave** — \( u, v, \) and \( w \) in units of wavelengths lambda.

• **Amp** — Data amplitudes in units which are proportional to Jansky (for data which are fully calibrated, the units should be in Jy).

• **Phase** — Data phases in units of degrees.
• **Real** and **Imag** — The real and imaginary parts of the visibility in units which are proportional to Jansky (for data which are fully calibrated, the units should be Jy).

• **Wt** and **Wt*Amp** — the weight of the visibility and the product of the weight and the amplitude

• **Flag** — Data which are flagged have Flag = 1, whereas unflagged data are set to Flag = 0. Note that, to display flagged data, you will have to click on the **Plots > Display** tab and choose a **Flagged Points Symbol** (§3.3.1.7).

• **Azimuth** and **Ant-Azimuth** — Azimuth in units of degrees. **Azimuth** plots a fiducial value for the entire array, while **Ant-Azimuth** plots the azimuth for each individual antenna (their azimuths will differ by small amounts, because each antenna is located at a slightly different longitude, latitude, and elevation).

• **Elevation** and **Ant-Elevation** — Elevation in units of degrees. **Elevation** is a representative value for the entire array, while **Ant-Elevation** is the elevation for each individual antenna (their elevations will differ by small amounts, because each antenna is located at a slightly different longitude, latitude, and elevation).

• **HourAngle** — Hour angle in units of hours. This is a fiducial value for the entire array.

• **ParAngle** and **Ant-ParAng** — Parallactic angle in units of degrees. **ParAngle** is the fiducial parallactic angle for all antennae in the array, while **Ant-ParAng** plots the parallactic angle for each individual antenna (their parallactic angles will differ by small amounts, because each antenna is located at a slightly different longitude, latitude, and elevation).

• **Row** — Data row number. A row number corresponds to a unique time, baseline, and spectral window in the measurement set.

• **FlagRow** — In some tasks, if a whole data row is flagged, then FlagRow will be set to 1 for that row. Unflagged rows have FlagRow = 0. However, note that some tasks (like plotms) may flag a row, but *not* set FlagRow = 1. It is probably better to plot Flag than FlagRow for most applications.

• **GainAmp, GainPhase, GainReal, GainImag** — are the amplitude, phase, real and imaginary part of the calibration tables for regular complex gain tables.

• **Delay** — The delay of a delay calibration table

• **Opac** — Opacity values of a Opacity calibration table

• **SwPower** — Switched Power values for VLA switched power calibration tables

• **Tsys** — Tsys for ALMA Tsys calibration tables

If the data axis selected from the drop-down menu is already stored in the cache (therefore implying that plotting will proceed relatively quickly), an “X” will appear in the checkbox next to **In Cache?**. If the data shall be reloaded from disk, the “force reload” checkmark should be set at the bottom of this display.
For relevant data axes like Amp and Phase, the user will be presented with the option to plot raw data or calibrated data. This can be selected via a drop-down menu called Data Column, located directly under the drop-down menu for X or Y Axis selection (see the Y axis in Figure 3.2). To plot raw data, select “data”; to plot calibrated data, select “corrected”. Note that this choice will only have an impact on a plot if a calibration table has been applied to the measurement set (see applycal, Sect. 4.6.1).

If a data model has been applied to the measurement set (e.g., with setjy, Sect. 4.3.4) it can be plotted by selecting “model” from the Data Column menu. Finally, to plot the differences between the calibrated data and the model, select “corrected-model” and for uncalibrated data/model differences “data-model” from Data Column.

### 3.3.1.4 Tools

Various tools—selectable as icon buttons at the bottom of the plotms window—can be used to zoom, edit, and locate data. The icon buttons can be seen at the bottom of Figures 3.1 and 3.2 and are, from left to right:

- **Zoom** — The “magnifying glass” button (1st on left) lets you draw a box around a region of the plot (left-click on one corner of the box, and drag the mouse to the opposite corner of the desired box), and then zooms in on this box.

- **Pan** — The “four-arrow” button (2nd from left) lets you pan around a zoomed plot.

- **Annotate** — The 3rd button from the left is chosen from a drop-down menu to either Annotate Text (“T with a green diamond” button) or Annotate Rectangle (“pencil” button). In the Annotate Text environment, click on a location in the plot where text is desired; a window will pop up, allowing you to type text in it. When you click the OK button, this text will appear on the plot. Annotate Rectangle simply lets you draw a box on the plot by left-clicking and dragging the mouse. By clicking on the Annotator tab near the top of the plotms window, different fonts, colors, line styles, etc. can be selected for annotations.

- **Home** — The “house” button (5th from left) returns to the original zoom level.

- **Stack Back** and **Stack Forward** — The left and right arrow buttons (4th and 6th from left) step through the zoom settings you’ve visited.

- **Mark Regions** — The “box with a green diamond” button (7th from left) lets you mark a region for flagging, unflagging, or locating. Left-click on one corner of the desired region, and then drag the mouse to set the opposite corner of the region. You can mark multiple boxes before performing an operation on them.

- **Clear Regions** — Clicking on the “box with a red circle” button (8th from left) will clear all regions which have been marked using Mark Regions.

- **Flag** — Click on the “flag” button (9th from left) to flag all points in the marked regions.
• **Unflag** — Click on the “crossed-out flag” button (10th from left) to unflag any flagged points that would be in the marked regions (even if invisible).

• **Locate** — The “magnifying glass on a sheet of paper” button (11th from left) will print out information to the command line about points in the marked regions.

• **Hold Drawing** — If the “hold drawing” button (rightmost, or 12th from left) is depressed, and if new plot axes are selected from the **Plots > Axes** tab, these new data will be cached but not plotted. When the button is clicked on again and un-depressed, it will automatically plot the data that was last requested. This can be particularly useful when changing the size of the **plotms** window.

There are two relevant options under the **Options** tab near the top of the **plotms** window. The **when changing plot axes, clear any existing regions or annotations** checkbox determines when regions and annotation are deleted from the plot. The **Tool Button Style** drop-down menu determines if icons and/or text represent the buttons at the bottom of the **plotms** window.

It is possible to hide these icons by going to the **View > Toolbars** menu at the top of the **plotms** window and un-depressing the **Tools** option (except for **Hide Drawing**, which is hidden by clicking on **View > Toolbars > Display**). In addition, the above tools can also be accessed by clicking on the **Tools** tab near the top of the **plotms** window (just below the **View** menu).

The **Tools** tab also enables one additional tool, the **Tracker**. To use **Tracker**, click on the **Hover** and/or **Display** checkbox, and place your mouse over the plot. **Tracker** will output the X and Y position of your mouse, either as text superimposed on the plot near your mouse (if **Hover** is selected) or in the blank window in the **Tools** tab (if **Display** is selected). Pressing the **SPACE** bar will copy the lines into the larger white box below to the right. This can be repeated many times and a log of positions and values will be created. The content in the box can then be easily copied and pasted into any other application that is used for data analysis. The **Clear** button wipes out the content of the box for a fresh start into new scientific adventures.

### 3.3.1.5 Interactive Flagging in **plotms**

Interactive flagging, on the principle of “see it — flag it”, is possible on the X-Y display of the data plotted by **plotms**. The user can use the cursor to mark one or more regions, and then flag, unflag, or list the data that falls in these zones of the display.

Using the row of icons buttons at the bottom of the **plotms** window (§3.3.1.4), click on the **Mark Regions** button (which will appear to depress), then mark a region by left-clicking and dragging the mouse (each click and drag will mark an additional region). You can get rid of all your regions by clicking on the **Clear Regions**. Once regions are marked, you can then click on one of the other buttons to take action:

1. **Flag** — flag the points in the region(s),
2. **Unflag** — unflag flagged points in the region(s),

3. **Locate** — spew out a list of the points in the region(s) to the command line (Warning: this could be a long list!).

Figure 3.3 shows an example of marking regions and then clicking the **Flag** button. Whenever you click on a button, that action occurs without requiring an explicit disk-write. If you quit **plotms** and re-enter, you will see your previous edits.

![Figure 3.3: Plot of amplitude versus time, before (left) and after (right) flagging two marked regions. To unflag these regions, mark the two same regions and click the **Unflag** button.](image)

A table with the name `<msname>.flagversions` (where `vis=<msname>`) will be created in the same directory if it does not exist already. It is recommended that you save important flagging stages using the **flagmanager** task (§ 3.2).

Flags can also be extended with options in the **Flagging** tab, found near the top of the **plotms** window. Flag extension enables the user to plot a subset of the data and extend the flagging to a wider set. In this release, the only functional extensions are over channel and correlation.

By checking the boxes next to **Extend Flags** and **Channel**, flagging will be extended to other channels in the same `spw` as the displayed point. For example, if `spw=’0:0’` and channel 0 is displayed, then flagging will extend to all channels in spw 0.

By checking the boxes next to **Extend Flags** and **Correlation**, flags will be extended beyond the correlations displayed. Currently the only option is to extend to All correlations, implying that all correlations will be flagged, e.g. with RR displayed, the correlations RR, RL, LR, and LL will all be flagged.

**WARNING:** use of flag extensions may lead to deletion of much more data than desired. Be careful!
3.3.1.6 Averaging Data

The Plots > Data tab enables averaging of the data in order to increase signal-to-noise of the plotted points or to increase plotting speed. The options for Averaging are:

- channel
- time
- all baselines or per antenna
- all spectral windows
- scalar

The box next to a given Averaging mode needs to be checked for that averaging to take effect.

For example, to average \( n \) channels together, the user would click on the box next to Channels so that an “X” appears in it, and then type the number \( n \) in the empty box. When the user next clicks on Plot, every \( n \) channels will then be averaged together and the total number of channels plotted will be decreased by a factor of \( n \).

Time averaging is a little trickier, as it is controlled by three fields. If the checkbox next to Time under Averaging is clicked on, a blank box with units of seconds will become active, along with two additional checkboxes: Scan and Field. If averaging is desired over a relatively short interval (say, 30 seconds, shorter than the scan length), a number can simply be entered into the blank box and, when the data are replotted, the data will be time averaged. Clicking on the Scan or Field checkbox in this case will have no impact on the time averaging.

These checkboxes become relevant if averaging over a relatively long time—say the entire observation, which consists of multiple scans—is desired. Regardless of how large a number is typed into the Time averaging blank box, only data within individual scans will be averaged together. In order to average data across scan boundaries, the Scan checkbox must be clicked on and the data replotted. Finally, clicking on the Field checkbox enables the averaging of multiple fields together in time.

Clicking on the All Baselines checkbox will average all baselines in the array together. Alternatively, the Per Antenna box may be checked, which will average all baselines for a given antenna together. In this case, all baselines are represented twice; baseline 3-24 will contribute to the averages for both antenna 3 and antenna 24. This can produce some rather strange-looking plots if the user also selects on antenna—say, if the user requests to plot only antenna 0 and then averages Per Antenna. In this case, an average of all baselines including antenna 0 will be plotted, but each individual baseline including antenna 0 will also be plotted (because the presence of baselines 0-1, 0-2, 0-3, etc. trigger Per Antenna averaging to try and compute averages for antennae 1, 2, 3, etc. Therefore, baseline 0-1 will contribute to the average for antenna 0, but it will also singlehandedly be the average for antenna 1.)

Spectral windows can be averaged together by checking the box next to All Spectral Windows. This will result in, for a given channel \( n \), all channels \( n \) from the individual spectral windows being averaged together.
Finally, the default mode is vector averaging, where the complex average is formed by averaging the real and imaginary parts of the relevant visibilities. If **Scalar** is chosen, then the amplitude of the average is formed by a scalar average of the individual visibility amplitudes.

When averaging, **plotms** will prefer unflagged data. I.e., if an averaging bin contains any unflagged data at all, only the average of the unflagged will be shown. For averaging bins that contain *only* unflagged data, the average of that unflagged data will be shown. When flagging on a plot of averaged data, the flags will be applied to the unaveraged data in the MS.

### 3.3.1.7 Plot Symbols

Plot symbols are selected in the **Plots > Display** tab. Most fundamentally, the user can choose to plot unflagged data and/or flagged data. By default, unflagged data is plotted (the circle next to **Default** is checked under **Unflagged Points Symbol**), and flagged data is not plotted (the circle next to **None** is checked under **Flagged Points Symbol**). We note here that plotting flagged data on an averaged plot is undertaken at the user’s own risk, as the distinction between flagged points and unflagged points becomes blurred if data are averaged over a dimension that is partially flagged. Take, for example, a plot of amplitude versus time where all channels are averaged together, but some channels have been flagged due to RFI spikes. In creating the average, **plotms** will skip over the flagged channels and only use the unflagged ones. The averaged points will be considered unflagged, and the flagged data will not appear on the plot at all.

A selection of **None** produces no data points, **Default** results in data points which are small circles (blue for unflagged data and red for flagged data), and **Custom** allows the user to define a plot symbol. If **Custom** plot symbols are chosen, the user can determine the symbol size by typing a number in the blank box next to **px** or by clicking on the adjacent up or down arrows. Symbol shape can be chosen from the drop-down menu to be either “circle”, “square”, “diamond”, or “pixel” (note than “pixel” only has one possible size). “autoscaling” attempts to adjust the size of the points from dots to circles of different sizes, depending on how many points are plotted. Symbol color can be chosen by typing a hex color code in the blank box next to **Fill** (e.g., “ff00ff”), or by clicking on the ... button and selecting a color from the pop-up GUI. The adjacent drop-down menu provides options for how heavily the plot symbol is shaded with this color, from heaviest to lightest: “fill”, “mesh1”, “mesh2”, “mesh3”, and “no fill”. Finally, the plot symbol can be outlined in black (if **Outline: Default** is checked) or not (if **Outline: None** is checked). Note that if “no fill” and **Outline: None** are selected, the plot symbols will be invisible.

Finally, unflagged data points can be given informative symbol colors using the **Colorize** parameter. By checking the box next to **Colorize** and selecting a data dimension from the drop-down menu, the data will be plotted with colors that vary along that dimension. For example, if “corr” is chosen from the **Colorize** menu, “RR”, “LL”, “RL”, and “LR” data will each be plotted with a different color. Note that, currently, **colorize** and plotting flagged data appear to be incompatible; a plot can only include one of these special features at a time.
3.3.1.8 Summarizing Data

Information about the measurement set can be obtained from within plotms by clicking on the Summary button, found at the bottom of the Plots > Data tab window. If “All” is chosen from the pull-down menu next to Summary, listobs-style output about scans, correlator configurations, and antennae will be written to the command line from which plotms was started. For more detail, click on the Verbose checkbox. For a specific subset of the data, choose a selection from the pull-down menu like “Antenna” or “Field”.

3.3.1.9 Defining Frequency and Velocity

If the user plans to plot Frequency, the reference frame must be defined. By default, the plotted frequency is simply that observed at the telescope. However, transformations can be made by choosing a Frame from the drop-down menu in the Plots > Trans tab. Frequency reference frames can be chosen to be:

- LSRK — local standard of rest (kinematic)
- LSRD — local standard of rest (dynamic)
- BARY — barycentric
- GEO — geocentric
- TOPO — topocentric
- GALACTO — galactocentric
- LGROUP — Local Group
- CMB — cosmic microwave background dipole

Velocity is affected by the user’s choice of Frame, but it is also impacted by the choice of velocity definition and spectral line rest frequency. The velocity definition is chosen from the Velocity Defn drop-down menu in the Plots > Trans tab, offering selections of Radio, True, or Optical.

For more information on frequency frames and spectral coordinate systems, see the paper by Greisen et al. (A&A, 446, 747, 2006).[1] Finally, the spectral line’s rest frequency in units of MHz should be typed into the blank box next to Rest Freq in the Plots > Trans tab. You can use the me.spectralline tool method to turn transition names into frequencies

CASA <16>: me.spectralline('HI')

Out[17]:
{'m0': {'unit': 'Hz', 'value': 1420405751.786},
 'refer': 'REST',
 'type': 'frequency'}

[1] Also at http://www.aoc.nrao.edu/~egreisen/scs.ps
For a list of known lines in the CASA measures system, use the toolkit command `me.linelist()`. For example:

```python
CASA <21>: me.linelist()
```

```
```

### 3.3.1.10 Shifting the Phase Center

The plot's phase center can be shifted in the `Plots > Trans` tab. Enter the X and Y shifts in units of arcseconds in the blank boxes under `Phase center shift`.

### 3.3.1.11 Plot Ranges

The X and Y ranges of the plot can be set in the `Plots > Axes` tab. By default, the circle next to `Automatic` will be checked, and the ranges will be auto-scaled. To define the range, click on the circle below `Automatic` and enter a minimum and maximum value in the blank boxes (as for the X Axis in Figure 3.2). Note that if identical values are placed in the blank boxes (`xmin=xmax` and/or `ymin=ymax`), then the values will be ignored and a best guess will be made to auto-range that axis.

### 3.3.1.12 Plot Labels

The plot and axes labels which are displayed in the plot window are set in the `Plots > Canvas` tab. To change the plot title, under `Canvas Title`, click on the circle next to the blank box and enter the desired text. To change the X- and Y-axis labels, similarly click on the circles next to the blank boxes under `Show X Axis` and `Show Y Axis` and type the desired text in the blank box. To display these new labels, simply click the `Plot` button.

The user can determine the locations of axis labels in the `Plots > Axes` tab. The X-axis label switches from the bottom to the top of the plot depending on what is selected for `Attach to:`.
Similarly for the Y-Axis, the user can choose to attach axis labels and tick marks to the **Top** or **Bottom** (note that the axis labels have been attached to the **Bottom** and **Right** in Figure 3.2).

Finally, axis labels can be removed all together by unchecking the boxes next to **Show X Axis** and **Show Y Axis** on the **Plots > Canvas** tab.

### 3.3.1.13 Grid Lines

A grid of lines can be superimposed on the plot using **Grid Lines** in the **Plots > Canvas** tab. “Major” grid lines are drawn at the locations of major tick marks, while “minor” grid lines are drawn at minor tick marks.

Grid line colors, thicknesses, and styles are selected independently for the “major” and “minor” grid lines. Desired line thickness should be typed into the blank boxes just to the right of the **Major** and **Minor** labels. Colors are set by clicking on the ... buttons. The blank boxes to the left of the ... buttons will then contain the hex codes for the selected colors (e.g., “808080”). Line styles can also be selected from the drop-down menus to the right of ... buttons.

### 3.3.1.14 Legend

A plot symbol legend can be added to the plot by clicking on the checkbox next to **Legend** in the **Plots > Canvas** tab. However, given the current functionalities of **plotms**, a symbol legend is of very limited use. This option will become more relevant when overplotting capabilities are included in **plotms**.

### 3.3.1.15 The Options Tab

A few miscellaneous options are available in the **Options** tab, the last tab at the top of the **plotms** window. The **Tool Button Style** drop-drop down menu determines if icons and/or text represent the buttons in the toolbar near the bottom of the **plotms** window.

The **Log Events** drop down menu determines how verbose **plotms** is in documenting its actions on the command line.

There is a checkbox that determines the persistence of regions and annotations on new plots, labelled **When changing plot axes, clear any existing regions and annotations**.

A useful option is the **fixed size for cached image** checkbox. It determines how large the dots in the panel are with respect to the screen resolution. The values influence how the data is redrawn on the panel. When the **Screen resolution** is selected, the **plotms** window can be resized without redrawing on the canvas – a considerable speedup for large data sets. The penalty is that the dots of the data points are the size of a pixel on the screen, which may be very small for high resolution monitors.

Finally, the **File chooser history limit** determines the number of remembered directories in the file loading pop-up of the **Browse** selection of the **Data** tab.
3.3.1.16 Iteration

In many cases, it is desirable to iterate through the data that were selected in the Data tab. A typical example is to display a single baseline in a time vs. amplitude plot and then proceed to the next baselines step by step. This can be done via the Iter tab on the left hand side of plotms. A drop-down menu allows you to select the parameter to be iterated on, such as baseline or spw (press plot after changing your selection). The plot titles in the main panel in plotms show which data slice is currently displayed. To proceed to the next plot use the green buttons below the main panel. The different button symbols let you to proceed panel by panel or to jump to the first or last panel directly.

There are two scaling options for the axes: Global and Self. Global will use a common axis range based on data loaded with the selection criteria specified in the Data tab. Self readjusts the axes scaling to the data for each individual panel of the iteration.

Below, one can invoke multiple panels per display by selecting the number of rows and columns to be displayed on the canvas.

Note that exporting iterated data only refers to the shown panel, the exported files do not (yet) collate all the iteration panels in say a multi-page pdf. So please export every panel separately.

3.3.1.17 Saving your plot

You can save a copy of a plot to file in the Plots > Export tab. Click the Browse button for a GUI-based selection of the directory and file name to which the plot will be saved. The file format can also be determined in this GUI by the suffix given to the filename: .png (PNG), .jpg (JPG), .ps (PS), .pdf (PDF), and txt (TEXT). Alternatively, the file format can be selected from the Format drop-down menu located just below the Browse button. In this case, plotms will add a suffix to the file name depending on the format chosen.

ALERT: The plot files produced by the PS and PDF options can be large and time-consuming to export. The JPG is the smallest.

The exported plot resolution can be manipulated using the High Resolution, DPI, and Size options.

Click on Export to create the file. Note that, if there is more than one plot displayed in the plotms window, it will only export the currently selected plot.

The TEXT format will not save an image but the data points themselves. This allows one to dump the current plot into a file that is used in other programs for further processing. The reported data is the same as when using the locate button in plotms and the format looks like:

```
# x y chan scan field ant1 ant2 antiname ant2name time freq spw corr offset currchunk irel
# Real Imag None None None None None None MJD(seconds) GHz None None None None None
0.282938 0.0387683 31 5 2 1 12 ea02@E02 ea21@E01 4778968956.000 36.308479452 1 RR 26 0 26
0.263241 -0.00806698 31 7 2 1 12 ea02@E02 ea21@E01 4778969356.000 36.308479452 1 RR 29 1 28
```
where \( x \) and \( y \) are the two plotted axes and the other columns contain additional information such as the baselines or frequencies. The three last columns \( \text{offset, corrchunk, and irel} \) are internal data management items for \texttt{plotms} and you most likely will never use them.

### 3.3.1.18 Exiting \texttt{plotms}

To exit the \texttt{plotms} GUI, select \texttt{Quit} from the \texttt{File} menu at the top of the \texttt{plotms} window. You can also dismiss the window by killing it with the “X” on the frame.

Alternatively, you can just leave it alone, and \texttt{plotms} will keep running in the background. If the data file changes in the background, you can force reloading the data via the 'force reload' checkbox next to the 'Plot' button. Alternatively, press \texttt{SHIFT} while clicking on 'Plot' for the same purpose.

### 3.3.2 Plotting and Editing using \texttt{plotxy}

\texttt{plotxy} is a tool for visualizing and editing visibility data. Unlike \texttt{plotms}, it is useful in scripting, as it can non-interactively produce a hardcopy plot (see §3.3.2.13). It also has multi-plot (§3.3.2.8) and iteration (§3.3.2.3) functionality—unlike \texttt{plotms} in the current release. \texttt{plotxy} uses the \texttt{matplotlib} plotting library to display its plots. You can find information on \texttt{matplotlib} at \url{http://matplotlib.sourceforge.net/}.

To bring up this plotter use the \texttt{plotxy} task. The inputs are:

```bash
# plotxy :: X-Y plotter/interactive flagger for visibility data
vis = ''          # Name of input visibility
xaxis = 'time'    # X-axis: def = 'time': see help for options
```
Figure 3.4: The plotxy plotter, showing the Jupiter data versus uv-distance. You can see bad data in this plot. The **bottom set of buttons** on the lower left are: 1,2,3) **Home, Back, and Forward**. Click to navigate between previously defined views (akin to web navigation). 4) **Pan**. Click and drag to pan to a new position. 5) **Zoom**. Click to define a rectangular region for zooming. 6) **Subplot Configuration**. Click to configure the parameters of the subplot and spaces for the figures. 7) **Save**. Click to launch a file save dialog box. The **upper set of buttons in the lower left** are: 1) **Mark Region**. Press this to begin marking regions (rather than zooming or panning). 2,3,4) **Flag, Unflag, Locate**. Click on these to flag, unflag, or list the data within the marked regions. 5) **Next**. Click to move to the next in a series of iterated plots. Finally, the **cursor readout** is on the bottom right.

```python
yaxis = 'amp' # Y-axis: def = 'amp': see help for options
datacolumn = 'data' # data (raw), corrected, model, residual (corrected - model)
selectdata = False # Other data selection parameters
spw = '' # spectral window:channels: ''==>all, spw='1:5~57'
field = '' # field names or index of calibrators: ''==>all
```
AVERAGEMODE = '' # Select averaging type: 'vector', 'scalar'
restfreq = '' # a frequency quanta or transition name. see help for options
extendflag = False # Have flagging extend to other data points?
subplot = 111 # Panel number on display screen (yxn)
plotsymbol = '.' # Options include . : , o ^ v > < s + x D d 2 3 4 h H | _
plotcolor = 'darkcyn' # Plot color
plotrange = [-1, -1, -1, -1] # The range of data to be plotted (see help)
multicolor = 'corr' # Plot in different colors: Options: none, both, chan, corr
selectplot = False # Select additional plotting options (e.g, fontsize, title, etc)
overplot = False # Overplot on current plot (if possible)
showflags = False # Show flagged data?
interactive = True # Show plot on gui?
figfile = '' # ''= no plot hardcopy, otherwise supply name
async = False # If true the taskname must be started using plotxy(...)

ALERT: The plotxy task expects all of the scratch columns to be present in the MS, even if it is not asked to plot the contents. If you get an error to the effect "Invalid Table operation: Table: cannot add a column" then use clearcal() to force these columns to be made in the MS. Note that this will clear anything in all scratch columns (in case some were actually there and being used).

Setting selectdata=True opens up the selection sub-parameters:

selectdata = True # Other data selection parameters
antenna = '' # antenna/baselines: ''==>all, antenna = '3,VA04'
timerange = '' # time range: ''==>all
correlation = '' # correlations: default = ''
scan = '' # scan numbers: Not yet implemented
feed = '' # multi-feed numbers: Not yet implemented
array = '' # array numbers: Not yet implemented
uvrange = '' # uv range''==>all; uvrange = '0^100kl' (default unit=meters)

These are described in §2.3.

Averaging is controlled with the set of parameters

averagemode = 'vector' # Select averaging type: vector, scalar
timebin = '0' # Length of time-interval in seconds to average
crossscans = False # Have time averaging cross scan boundaries?
crossbls = False # have averaging cross over baselines?
crossarrays = False # have averaging cross over arrays?
stackspw = False # stack multiple spw on top of each other?
width = '1' # Number of channels to average

See §3.3.2.9 below for more on averaging.

You can extend the flagging beyond the data cell plotted:

extendflag = True # Have flagging extend to other data points?
extendcorr = 'corr' # flagging correlation extension type
CHAPTER 3. DATA EXAMINATION AND EDITING

```
extendchan = '' # flagging channel extension type
extendspw = '' # flagging spectral window extension type
extendant = '' # flagging antenna extension type
extendtime = '' # flagging time extension type
```

See §3.3.2.11 below for more on flag extension.

The `restfreq` parameter can be set to a transition or frequency:

```
restfreq = 'HI' # a frequency quanta or transition name. see help for options
frame = 'LSRK' # frequency frame for spectral axis. see help for options
doppler = 'RADIO' # doppler mode. see help for options
```

See §3.3.2.12 below for more on setting rest frequencies and frames.

Setting `selectplot=True` will open up a set of plotting control sub-parameters. These are described in §3.3.2.2 below.

The `interactive` and `figfile` parameters allow non-interactive production of hardcopy plots. See §3.3.2.13 for more details on saving plots to disk.

The `iteration`, `overplot`, `plotrange`, `plotsymbol`, `showflags` and `subplot` parameters deserve extra explanation, and are described below.

For example:

```
plotxy(vis='jupiter6cm.ms', # jupiter 6cm dataset
       xaxis='uvdist', # plot uv-distance on x-axis
       yaxis='amp', # plot amplitude on y-axis
       field='JUPITER', # plot only JUPITER
       selectdata=True, # open data selection
       correlation='RR,LL', # plot RR and LL correlations
       selectplot=True, # open plot controls
       title = 'Jupiter 6cm uncalibrated') # give it a title
```

The plotter resulting from these settings is shown in figure 3.4.

**ALERT:** The `plotxy` task still has a number of issues. The averaging has been greatly speeded up in this release, but there are cases where the plots will be made incorrectly. In particular, there are problems plotting multiple `spw` at the same time. There are sometimes also cases where data that you have flagged in `plotxy` from averaged data is done so incorrectly. This task is under active development for the next cycle to fix these remaining problems, so users should be aware of this.

**ALERT:** Another know problem with (`plotxy`) is that it fails if the path to your working directory contains spaces in its name, e.g. `/users/smyers/MyTest/` is fine, but `/users/smyers/My Test/` is not!
3.3.2.1 GUI Plot Control

You can use the various buttons on the plotxy GUI to control its operation – in particular, to determine flagging and unflagging behaviors.

There is a standard row of buttons at the bottom. These include (left to right):

- **Home** — The “house” button (1st on left) returns to the original zoom level.
- **Step** — The left and right arrow buttons (2nd and 3rd from left) step through the zoom settings you’ve visited.
- **Pan** — The “four-arrow button” (4th from left) lets you pan in zoomed plot.
- **Zoom** — The most useful is the “magnifying glass” (5th from the left) which lets you draw a box and zoom in on the plot.
- **Panels** — The “window-thingy” button (second from right) brings up a menu to adjust the panel placement in the plot.
- **Save** — The “disk” button (last on right) saves a .png copy of the plot to a generically named file on disk.

In a row above these, there are a set of other buttons (left to right):

- **Mark Region** — If depressed lets you draw rectangles to mark points in the panels. This is done by left-clicking and dragging the mouse. You can Mark multiple boxes before doing something. Clicking the button again will un-depress it and forget the regions. ESC will remove the last region marked.
- **Flag** — Click this to Flag the points in a marked region.
- **Unflag** — Click this to Unflag any flagged point that would be in that region (even if invisible).
- **Locate** — Print out some information to the logger on points in the marked regions.
- **Next** — Step to the next plot in an iteration.
- **Quit** — Exit plotcal, clear the window and detach from the MS.

These buttons are shared with the plotcal tool.
3.3.2.2 The selectplot Parameters

These parameters work in concert with the native matplotlib functionality to enable flexible representations of data displays.

Setting `selectplot=True` will open up a set of plotting control sub-parameters:

```python
selectplot = True  # Select additional plotting options (e.g., fontsize, title, etc)
markersize = 5.0   # Size of plotted marks
linewidth = 1.0    # Width of plotted lines
skipnrows = 1      # Plot every nth point
newplot = False    # Replace the last plot or not when overplotting
clearpanel = 'Auto' # Specify if old plots are cleared or not
title = ''         # Plot title (above plot)
xlabels = ''       # Label for x-axis
ylabels = ''       # Label for y-axis
fontsize = 10.0    # Font size for labels
windowsize = 5.0   # Window size: not yet implemented
```

The `markersize` parameter will change the size of the plot symbols. Increasing it will help legibility when doing screen shots. Decreasing it can help in congested plots. The `linewidth` parameter will do similar things to the lines.

The `skipnrows` parameter, if set to an integer \( n \) greater than 1, will allow only every \( n \)th point to be plotted. It does this, as the name suggests, by skipping over whole rows of the MS, so beware (channels are all within the same row for a given \( \text{spw} \)). Be careful flagging on data where you have skipped points! Note that you can also reduce the number of points plotted via averaging (§3.3.2.9) or channel striding in the \( \text{spw} \) specification (§2.3.3).

The `newplot` toggle lets you choose whether or not the last layer plotted is replaced when `overplot=True`, or whether a new layer is added.

The `clearpanel` parameter turns on/off the clearing of plot panels that lie under the current panel layer being plotted. The options are: `none` (clear nothing), `auto` (automatically clear the plotting area), `current` (clear the current plot area only), and `all` (clear the whole plot panel).

The `title`, `xlabels`, and `ylabels` parameters can be used to change the plot title and axes labels.

The `fontsize` parameter is useful in order to enlarge the label fonts so as to be visible when making plots for screen capture, or just to improve legibility. Shrinking can help if you have lots of panels on the plot also.

The `windowsize` parameter is supposed to allow adjustments on the window size. **ALERT:** This currently does nothing, unless you set it below 1.0, in which case it will produce an error.
3.3.2.3 The iteration parameter

There are currently four iteration options available: 'field', 'antenna', and 'baseline'. If one of these options is chosen, the data will be split into separate plot displays for each value of the iteration axis (e.g., for the VLA, the 'antenna' option will get you 27 displays, one for each antenna).

An example use of iteration:

```python
# choose channel averaging, every 5 channels
plotxy('n5921.ms','channel',subplot=221,iteration='antenna',width='5')
```

The results of this are shown in Figure 3.5. Note that this example combines the use of width, iteration and subplot.

**NOTE:** If you use iteration='antenna' or 'baseline', be aware if you have set antenna selection. You can also control whether you see auto-correlations or not using the appropriate syntax, e.g. antenna='*&&*' or antenna='*&&&' (§2.3.4.1).

3.3.2.4 The overplot parameter

The overplot parameter toggles whether the current plot will be overlaid on the previous plot or subpanel (via the subplot setting, § section:edit.plot.plotxy.subplot) or will overwrite it. The default is False and the new plot will replace the old.

The overplot parameter interacts with the newplot sub-parameter (see §3.3.2.2). See §3.3.2.7 for an example using overplot.

3.3.2.5 The plotrange parameter

The plotrange parameter can be used to specify the size of the plot. The format is [xmin, xmax, ymin, ymax]. The units are those on the plot. For example,

```python
plotrange = [-20,100,15,30]
```

Note that if xmin=xmax and/or ymin=ymax, then the values will be ignored and a best guess will be made to auto-range that axis.

Unfortunately, the units for the time axis must be in Julian seconds. This is somewhat inconvenient as the usual time parameter is given in Julian days. To calculate the Julian seconds the me.epoch tool can be used. An example: For 02:00 UT on 2012/05/22, the value of MJD seconds can be calculated via

```python
86400*(me.epoch('utc','2012/05/22')['m0']['value']+2/24.)
```

which results in 4844368800.0.
Figure 3.5: The \texttt{plotxy} iteration plot. The first set of plots from the example in §3.3.2.3 with \texttt{iteration='antenna'}. Each time you press the \texttt{Next} button, you get the next series of plots.

\subsection*{3.3.2.6 The \texttt{plotsymbol} parameter}

The \texttt{plotsymbol} parameter defines both the line or symbol for the data being drawn as well as the color; from the matplotlib online documentation (e.g., type \texttt{plt.plot?} for help):

The following line styles are supported:
- \ : solid line
-- \ : dashed line
-. \ : dash-dot line
: \ : dotted line
. \ : points
The following color abbreviations are supported:

- b : blue
- g : green
- r : red
- c : cyan
- m : magenta
- y : yellow
- k : black
- w : white

In addition, you can specify colors in many weird and wonderful ways, including full names 'green', hex strings '#008000', RGB or RGBA tuples (0,1,0,1) or grayscale intensities as a string '0.8'.

Line styles and colors are combined in a single format string, as in 'bo' for blue circles.

### 3.3.2.7 The showflags parameter

The `showflags` parameter determines whether only unflagged data (showflags=False) or flagged (showflags=True) data is plotted by this execution. The default is `False` and will show only unflagged "good" data.

Note that if you want to plot both unflagged and flagged data, in different colors, then you need to run `plotxy` twice using `overplot` (see §3.3.4.3) the second time, e.g.

```python
> plotxy(vis="myfile", xaxis='uvdist', yaxis='amp')
> plotxy(vis="myfile", xaxis='uvdist', yaxis='amp', overplot=True, showflags=True)
```
3.3.2.8 The subplot parameter

The subplot parameter takes three numbers. The first is the number of y panels (stacking vertically), the second is the number of x panels (stacking horizontally) and the third is the number of the panel you want to draw into. For example, subplot=212 would draw into the lower of two panels stacked vertically in the figure.

An example use of subplot capability is shown in Fig 3.6. These were drawn with the commands (for the top, bottom left, and bottom right panels respectively):

*plotxy('n5921.ms','channel',
  field='0',
  datacolumn='corrected',
  plotcolor='g',
  plotsymbol='go',
  subplot=211) # plot to the top of two panels

plotxy('n5921.ms','x',
  field='0',
  datacolumn='corrected',
  subplot=223, # plot to 3rd panel (lower left) in 2x2 grid
  plotcolor='r.' # red dots

plotxy('n5921.ms','u','v',
  field='0',
  datacolumn='corrected',
  subplot=224, # plot to the lower right in a 2x2 grid
  plotcolor='b,', # blue, somewhat larger dots
  plotsymbol='b,' # the ny x nx grid.

See also § 3.3.2.3 above, and Figure 3.5 for an example of channel averaging using iteration and subplot.

3.3.2.9 Averaging in plotxy

The averaging parameters and sub-parameters are:

averagemode = 'vector' # Select averaging type: vector, scalar

timebin = '0' # length of time in seconds to average, default='0', or: 'all'
crossscans = False # have time averaging cross over scans?
crossbls = False # have averaging cross over baselines?
crossarrays = False # have averaging cross over arrays?
stackspw = False # stack multiple spw on top of each other?
width = '1' # number of channels to average, default: '1', or: 'all', 'allspw'
Figure 3.6: Multi-panel display of visibility versus channel (top), antenna array configuration (bottom left) and the resulting uv coverage (bottom right). The commands to make these three panels respectively are: 1) `plotxy('ngc5921.ms', xaxis='channel', datacolumn='data', field='0', subplot=211, plotcolor='', plotsymbol='go')` 2) `plotxy('ngc5921.ms', xaxis='x', field='0', subplot=223, plotsymbol='r.')`, 3) `plotxy('ngc5921.ms', xaxis='u', yaxis='v', field='0', subplot=224, plotsymbol='b', figfile='ngc5921_multiplot.png')`.

The choice of `averagemode` controls how the amplitudes are calculated in the average. The default mode is `vector`, where the complex average is formed by averaging the real and imaginary parts of the relevant visibilities. If `scalar` is chosen, then the amplitude of the average is formed by a scalar average of the individual visibility amplitudes.

Time averaging is effected by setting the `timebin` parameter to a value larger than the integration time. Currently, `timebin` takes a string containing the averaging time in seconds, e.g.
to plot one-minute averages.

Channel averaging is invoked by setting \texttt{width} to a value greater than 1. Currently, the averaging \texttt{width} is given as a number of channels.

By default, the averaging will not cross \texttt{scan} boundaries (as set in the import process). However, if \texttt{crossscans=True}, then averaging will cross scans.

Note that data taken in different sub-arrays are never averaged together. Likewise, there is no way to plot data averaged over \texttt{field}.

\subsection*{Interactive Flagging in \texttt{plotxy}}

Interactive flagging, on the principle of “see it — flag it”, is possible on the X-Y display of the data plotted by \texttt{plotxy}. The user can use the cursor to mark one or more regions, and then flag, unflag, or list the data that falls in these zones of the display.

There is a row of buttons below the plot in the window. You can punch the \textbf{Mark Region} button (which will appear to depress), then mark a region by left-clicking and dragging the mouse (each click and drag will mark an additional region). You can get rid of all your regions by clicking again on the \textbf{Mark Region} button (which will appear to un-depress), or you can use the \texttt{ESC} key to remove the last box you drew. Once regions are marked, you can then click on one of the other buttons to take action:

1. \textbf{Flag} — flag the points in the region(s),
2. \textbf{Unflag} — unflag flagged points in the region(s),
3. \textbf{Locate} — spew out a list of the points in the region(s) to the logger (Warning: this could be a long list!).

Whenever you click on a button, that action occurs without forcing a disk-write (unlike previous versions). If you quit \texttt{plotxy} and re-enter, you will see your previous edits.

A table with the name \texttt{<msname>.flagversions} (where \texttt{vis=<msname>}) will be created in the same directory if it does not exist already.

It is recommended that you save important flagging stages using the \texttt{flagmanager} task (§\ref{sec:flagmanager}).
3.3.2.11 Flag extension in plotxy

Flag extension is controlled using `extendflag=True` and its sub-parameters:

- `extendflag` = `True` # Have flagging extend to other data points?
- `extendcorr` = '' # flagging correlation extension type
- `extendchan` = '' # flagging channel extension type
- `extendspw` = '' # flagging spectral window extension type
- `extendant` = '' # flagging antenna extension type
- `extendtime` = '' # flagging time extension type

The use of `extendflag` enables the user to plot a subset of the data and extend the flagging to a wider set.

**ALERT:** Using the `extendflag` options will greatly slow down the flagging in `plotxy`. You will see a long delay after hitting the `Flag` button, with lots of logger messages as it goes through each flag. Fixing this requires a refactoring of `plotxy` which is underway starting in Patch 4 development.

Setting `extendchan='all'` will extend the flagging to other channels in the same `spw` as the displayed point. For example, if `spw='0:0'` and channel 0 is displayed, then flagging will extend to all channels in `spw` 0.

The `extendcorr` sub-parameter will extend the flagging beyond the correlations displayed. If `extendcorr='all'`, then all correlations will be flagged, e.g. with RR displayed then all RR,RL,LR,LL will be flagged. If `extendcorr='half'`, then the extension will be to those correlations in common with that show, e.g. with RR displayed then RR,RL,LR will be flagged.
CHAPTER 3. DATA EXAMINATION AND EDITING

Setting `extendspw='all'` will extend the flagging to all other spw for the selection. Using the same example as above, with `spw='0:0'` displayed, then channel 0 in ALL spw will be flagged. Note that use of `extendspw` could result in unintended behavior if the spw have different numbers of channels, or if it is used in conjunction with `extendchan`.

**WARNING:** use of the following options, particularly in conjunction with other flag extensions, may lead to deletion of much more data than desired. Be careful!

Setting `extendant='all'` will extend the flagging to all baselines that have antennas in common with those displayed and marked. For example, if `antenna='1&2'` is shown, then ALL baselines to BOTH antennas 1 and 2 will be flagged. Currently, there is no option to extend the flag to ONLY baselines to the first (or second) antenna in a displayed pair.

Setting `extendtime='all'` will extend the flagging to all times matching the other selection or extension for the data in the marked region.

### 3.3.2.12 Setting rest frequencies in `plotxy`

The `restfreq` parameter can be set to a transition or frequency and expands to allow setting of frame information. For example,

```plaintext
restfreq = 'HI'  # a frequency quanta or transition name. see help for options
frame = 'LSRK'  # frequency frame for spectral axis. see help for options
doppler = 'RADIO'  # doppler mode. see help for options
```

Examples of transitions include:

```plaintext
restfreq='1420405751.786Hz'  # 21cm HI frequency
restfreq='HI'  # 21cm HI transition name
restfreq='115.2712GHz'  # CO 1-0 line frequency
```

For a list of known lines in the CASA `measures` system, use the toolkit command `me.linelist()`.

For example:

```plaintext
CASA <14>: me.linelist()
```

**ALERT:** The list of known lines in CASA is currently very restricted, and will be increased in upcoming releases (to include lines in ALMA bands for example).

You can use the `me.spectralline` tool method to turn transition names into frequencies

```plaintext
CASA <16>: me.spectralline('HI')
Out[17]:
{'m0': {'unit': 'Hz', 'value': 1420405751.786},
 'refer': 'REST',
 'type': 'frequency'}
```
CHAPTER 3. DATA EXAMINATION AND EDITING

(not necessary for this task, but possibly useful).

The `frame` sub-parameter sets the frequency frame. The allowed options can be listed using the `me.listcodes` method on the `me.frequency()` method, e.g.

```
CASA <17>: me.listcodes(me.frequency())
```

```
Out[17]:
{"extra": array([], dtype=|S1
  dtype=|S8")
}
```

The `doppler` sub-parameter likewise sets the Doppler system. The allowed codes can be listed using the `me.listcodes` method on the `me.doppler()` method,

```
CASA <18>: me.listcodes(me.doppler())
```

```
Out[18]:
{"extra": array([], dtype=|S1
, 'normal': array(["RADIO", "Z", "RATIO", "BETA", "GAMMA", "OPTICAL", "TRUE", "RELATIVISTIC"],
  dtype=|S13")
}
```

For most cases the `"RADIO"` Doppler system is appropriate, but be aware of differences.

For more information on frequency frames and spectral coordinate systems, see the paper by Greisen et al. (A&A, 446, 747, 2006)

3.3.2.13 Printing from `plotxy`

There are two ways to get hardcopy plots in `plotxy`.

The first is to use the “disk save” icon from the interactive plot GUI to print the current plot. This will bring up a sub-menu GUI that will allow you to choose the filename and format. The allowed formats are `.png` (PNG), `.eps` (EPS), and `.svg` (SVG). If you give the filename with a suffix (`.png`, `.eps`, or `.svg`) it will make a plot of that type. Otherwise it will put a suffix on depending on the format chosen from the menu.

**ALERT:** The plot files produced by the EPS option can be large, and the SVG files can be very large. The PNG is the smallest.

The second is to specify a `figfile`. You probably want to disable the GUI using `interactive=False` in this case. The type of plot file that is made will depend upon the filename suffix. The allowed choices are `.png` (PNG), `.eps` (EPS), and `.svg` (SVG).

This latter option is most useful from scripts. For example,

default('plotxy')
vis = 'ngc5921.ms'
field = '2'
spw = '
xaxis = 'uvdist'
yaxis = 'amp'
interactive=False
figfile = 'ngc5921.uvplot.amp.png'
plotxy()

will plot amplitude versus uv-distance in PNG format. No plotxy GUI will appear.

**ALERT:** if you use this option to print to `figfile` with an *iteration* set, you will only get the first plot.

### 3.3.2.14 Exiting plotxy

You can use the Quit button to clear the plot from the window and detach from the MS. You can also dismiss the window by killing it with the X on the frame, which will also detach the MS.

You can also just leave it alone. The plotter pretty much keeps running in the background even when it looks like it’s done! You can keep doing stuff in the plotter window, which is where the overplot parameter comes in. Note that the plotcal task (§4.5.1) will use the same window, and can also overplot on the same panel.

If you leave plotxy running, beware of (for instance) deleting or writing over the MS without stopping. It may work from a memory version of the MS or crash.

### 3.3.2.15 Example session using plotxy

The following is an example of interactive plotting and flagging using plotxy on the Jupiter 6cm continuum VLA dataset. This is extracted from the script `jupiter6cm_usecase.py` available in the script area.

This assumes that the MS `jupiter6cm.usecase.ms` is on disk with `flagautocorr` already run.

default('plotxy')
vis = 'jupiter6cm.usecase.ms'

# The fields we are interested in: 1331+305, JUPITER, 0137+331
selectdata = True

# First we do the primary calibrator
field = '1331+305'

# Plot only the RR and LL for now
correlation = 'RR LL'
# Plot amplitude vs. uvdist
xaxis = 'uvdist'
yaxis = 'amp'
multicolor = 'both'

# The easiest thing is to iterate over antennas
iteration = 'antenna'

plotxy()

# You'll see lots of low points as you step through RR LL RL LR
# A basic clip at 0.75 for RR LL and 0.055 for RL LR will work
# If you want to do this interactively, set
iteration = ''

plotxy()

# You can also use flagdata to do this non-interactively
# (see below)

# Now look at the cross-polar products
correlation = 'RL LR'

plotxy()

#-------------------------------------------------------------
# Now do calibrator 0137+331
field = '0137+331'
correlation = 'RR LL'
xaxis = 'uvdist'
spw = ''
iteration = ''
antenna = ''

plotxy()

# You'll see a bunch of bad data along the bottom near zero amp
# Draw a box around some of it and use Locate
# Looks like much of it is Antenna 9 (ID=8) in spw=1
xaxis = 'time'
spw = '1'
correlation = ''

# Note that the strings like antenna='9' first try to match the
# NAME which we see in listobs was the number '9' for ID=8.
# So be careful here (why naming antennas as numbers is bad).
antenna = '9'

plotxy()
# YES! the last 4 scans are bad. Box 'em and flag.

# Go back and clean up
xaxis = 'uvdist'
spw = ''
antenna = ''
correlation = 'RR LL'
plotxy()

# Box up the bad low points (basically a clip below 0.52) and flag

# Note that RL,LR are too weak to clip on.

# Finally, do JUPITER
field = 'JUPITER'
correlation = ''
iteration = ''
xaxis = 'time'
plotxy()

# Here you will see that the final scan at 22:00:00 UT is bad
# Draw a box around it and flag it!

# Now look at what's left
correlation = 'RR LL'
xaxis = 'uvdist'
spw = '1'
antenna = ''
iteration = 'antenna'
plotxy()

# As you step through, you will see that Antenna 9 (ID=8) is often
# bad in this spw. If you box and do Locate (or remember from
# 0137+331) its probably a bad time.

# The easiest way to kill it:

antenna = '9'
iteration = ''
xaxis = 'time'
correlation = ''
plotxy()

# Draw a box around all points in the last bad scans and flag 'em!
# Now clean up the rest
xaxis = 'uvdist'
correlation = 'RR LL'
antenna = '',
spw = '',

# You will be drawing many tiny boxes, so remember you can
# use the ESC key to get rid of the most recent box if you
# make a mistake.
plotxy()

# Note that the end result is we've flagged lots of points
# in RR and LL. We will rely upon imager to ignore the
# RL LR for points with RR LL flagged!

3.3.3 Plotting antenna positions using plotants

This task is a simple plotting interface (to the plotxy functionality) to produce plots of the antenna positions (taken from the ANTEenna sub-table of the MS).

The inputs to plotants are:

# plotants :: Plot the antenna distribution in the local reference frame:
vis = '' # Name of input visibility file (MS)
figfile = '' # Save the plotted figure to this file
async = False #

3.3.4 Plotting uv-coverages plotuv

A simple way to plot uv-coverages is offered by the task plotuv:

# plotuv :: Plot the baseline distribution
vis = '', # Name of input visibility file (MS)
field = '', # Select field using ID(s) or name(s)
antenna = '', # Select data based on antenna/baseline
spw = '', # Select spectral window/channels
observation = '', # Select by observation ID(s)
array = '', # Select (sub)array(s) by array ID number
maxnpts = 100000 # Maximum number of points per plot.
colors = ['r', 'y', 'g', 'b'] # a list of matplotlib color codes
symb = ',' # A matplotlib plot symbol code
ncycles = 1 # How many times to cycle through colors per plot.
figfile = '', # Save the plotted figure(s) using this name
async = False # If true the taskname must be started using
# plotuv(...)

plotuv provides basic selection of data as well as plotting style options. The difference to plotms is that plotuv is also plotting the Hermitian conjugates of the visibilities which produces the familiar symmetric plots. This is a remedy to the restriction in plotms to allow flagging of data. This is achieved via a unambiguous link from a displayed data point to a visibility. Plotting Hermitian conjugates would break this rule in plotms and plotuv is used instead to plot Hermitian conjugates.

3.4 Data Flagging using flagdata

flagdata can flag measurement sets and calibration tables with an elaborate selection syntax. It also contains auto-flagging routines.

For a full description of flagdata please visit:

http://www.aoc.nrao.edu/~rurvashi/FlaggerDocs/FlaggerDocs.html

The inputs to flagdata are:

```python
# flagdata :: All-purpose flagging task based on data-selections and flagging modes/algorithms.
vis = '' # Name of MS file or calibration table to flag
mode = 'manual' # Flagging mode
field = '' # Field names or field index numbers: '' ==> all, field='0~2,3C286'
spw = '' # Spectral-window/frequency/channel: '' ==> all, spw='0:17~19'
antenna = '' # Antenna/baselines: '' ==> all, antenna='3,VA04'
timerange = '' # Time range: '' ==> all,timerange='09:14:0~09:54:0'
correlation = '' # Correlation: '' ==> all, correlation='XX,YY'
scan = '' # Scan numbers: '' ==> all
intent = '' # Observation intent: '' ==> all, intent='CAL*POINT*'
array = '' # (Sub)array numbers: '' ==> all
uvrange = '' # UV range: '' ==> all; uvrange = '0~100klambda', default units=meters
observation = '' # Observation ID: '' ==> all
feed = '' # Multi-feed numbers: Not yet implemented
autocorr = False # Flag auto-correlations
action = 'apply' # Action to perform in MS and/or in inpfile (none/apply/calculate)
display = '' # Display data and/or end-of-MS reports at runtime (data/report/both).
flagbackup = True # Back up the state of flags before the run
savepars = False # Save the current parameters to the FLAG_CMD table or to a file
async = False # If true the taskname must be started using flagdata(...)
```

vis can take a measurement set or calibration table. Data selection for calibration tables is limited to field, scan, time, antenna, spw, and observation. Since calibration tables do not have a FLAG_CMD table, parameter settings, if requested, can only be saved in external files.

The mode parameter (§3.4.2) selects the flagging algorithm and the following are available:
list = list of flagging commands to apply to MS
manual = flagging based on specific selection parameters
clip = clip data according to values
quack = remove/keep specific time range at scan beginning/end
shadow = remove antenna-shadowed data
elevation = remove data below/above given elevations
tfcrop = automatic identification of outliers on the time-freq plane
rflag = automatic detection of outliers based on sliding-window RMS filters
extend = extend and/or grow flags beyond what the basic algorithms detect
summary = report the amount of flagged data
unflag = unflag the specified data

Flagging will only be applied to the data selection that is performed with the usual selection parameters (§ 2.3). The dataset is iterated-through in chunks (small pieces of data) consisting of one field, one spw, and a user-defined timerange (default is one scan). In addition to the typical antenna, spw, timerange, etc. selections, we would like to point out some addition of the correlation syntax for modes clip, tfcrop, and rflag. One can combine correlation products with simple mathematical expressions

'ABS', 'ARG', 'RE', 'IM', 'NORM'

followed by the polarization products (using an underscore in between "_" )

'ALL', 'I', 'XX', 'YY', 'RR', 'LL', 'WVR'

'WVR' refers to the water vapour radiometer of ALMA data. Note that the operators ABS, ARG, RE, etc are written only once as the first value. if more than one correlation is given, the operator will be applied to all of them. An example would be

correlation='RE_XX,XY'

which would select all real XX and XY polarization for flagging.

3.4.1 The action parameter

The keyword action controls whether the actual flagging commands will be applied or not and the options are the empty string '', 'apply' and 'calculate'.

apply is likely the most popular one as it applies the flags to the MS:

action = 'apply' # Action to perform in MS and/or in inpfile
display = '' # Display data and/or end-of-MS reports at runtime
flagbackup = True # Back up the state of flags before the run
flagbackup specifies if a backup of the current flags should be saved in the ‘*.flagversions’ file. display can be ‘’, ‘data’, ‘report’, ‘both’ where the empty string ‘’ will report no individual flagging statistics, whereas ‘data’ launches an interactive GUI to display data and flags for each chunk to browse through. The plots are time-frequency planes and both old and new flags are being overlaid for all correlations per baseline. In the GUI, one can step through all chunks for inspection and if the flagging is unsatisfactory, one can exit without applying the flags. If the flagging is acceptable, it is also possible to continue flagging without viewing all chunks (the number of chunks can be very large for typical JVLA and ALMA data sets. display='report' lists the flagging statistics at the end of the procedure on the screen and both starts the GUI and reports all statistics at the end.

action='calculate' calculates the flags but does not write them to the MS or calibration table. This is useful if one would like to inspect the computed flags in the GUI without a straight application:

```
action = 'calculate' # Action to perform in MS and/or in inpfile
                   # (none/apply/calculate)
display = ''      # Display data and/or end-of-MS reports at runtime
                   # (data/report/both).
```

The empty string action=''' will do nothing and is useful when the commands themselves shall only be written to the FLAG_CMD sub-table or to an external file using the savepars parameter to specify the filename.

savepars will save the flagging commands to a file that can be later used for input in flagdata via mode='list'. It also shares the flagcmd syntax and can be used there. The file name is specified by outfile and, if empty, the FLAG_CMD table in the MS will be populated. A REASON can be given by the reason keyword which may be useful for bookkeeping as well as for unflagging data that are marked by specific REASON keywords.

### 3.4.2 Flagging Modes

#### 3.4.2.1 Manual Flag/Unflag

```
mode = 'manual'     # Flagging mode (list/manual/clip/shadow/quack/evaluate/tfcrop/rflag/extend/unflag/summary)
field = ''          # Field names or field index numbers: ‘’ ==> all, field='02,3C286'
spw = ''            # Spectral-window/frequency/channel: ‘’ ==> all, spw='0:17:19'
antenna = ''        # Antenna/baselines: ‘’ ==> all, antenna = '3,VA04'
timerange = ''      # Time range: ‘’ ==> all, timerange='09:14:0~09:54:0'
correlation = ''    # Correlation: ‘’ ==> all, correlation='XX,YY'
scan = ''           # Scan numbers: ‘’ ==> all
intent = ''         # Observation intent: ‘’ ==> all,
```
CHAPTER 3. DATA EXAMINATION AND EDITING

The 'manual' mode is the most straightforward of all modes. All visibilities that are selected by the various data selection parameters will be flagged or unflagged, depending on the action parameter. autocorr is a shorthand for antenna='*&*%' to flag all auto correlations in the data.

### 3.4.2.2 List

```python
mode = 'list'  # Flagging mode (list/manual/clip/shadow/quack/el
              # evation/tfcrop/rflag/extend/unflag/summary)
inpfile = ''  # Input ASCII file, list of files or Python list of strings with
              # flag commands.
reason = 'any'  # Select by REASON types
```

A list of ag commands can be provided through a le or a list of files, specied by the inpfile parameter. Each input line may contain a flagging mode with data selection parameters as well as parameters that are specific to that mode. All parameters that are not set will be reset to their default values (default mode is 'manual'). Each line of this file or list of strings will be taken as a command to the flagdata task. This mode=list is similar to the task flagcmd with the inpmode=list option.

An example for such a file would be:

```
mode='shadow'
mode='clip' clipminmax=[0,5] correlation='ABS_ALL'
mode='quack' quackmode='end' quackinterval=1.0
antenna='ea01' timerange='00:00:00~01:00:00'
antenna='ea11' timerange='00:00:00~03:00:00' spw='0~4'
```

Alternatively, this can be issued in the task directly like:

```python
flagdata(vis='vis',mode='list',
inpfile=['"mode='shadow''",
        "mode='clip' clipminmax=[0,5] correlation='ABS_ALL'",
        "mode='quack' quackmode='end' quackinterval=1.0"
        "antenna='ea01' timerange='00:00:00~01:00:00'",
        "antenna='ea11' timerange='00:00:00~03:00:00' spw='0~4'"])
```

or via a variable
cmds=["mode=shadow,"
    "mode=clip clipminmax=[0,5] correlation=ABS_ALL",
    "mode=quack quackmode=end quackinterval=1.0",
    "antenna=ea01 timerange=00:00:00~01:00:00",
    "antenna=ea11 timerange=00:00:00~03:00:00 spw=0~4"]

flagdata(vis='vis',mode='list', inpfile=cmds)

The syntax should be written with quotes e.g. mode='manual' antenna='ea10' but will usually also be accepted without the quotes (like mode=manual antenna=ea10). Spaces are only allowed to separate pairs of parameters, not adjacent to the equal '=' signs or inside strings and there are no commas between the subparameters on each line.

### 3.4.2.3 Clip

```python
mode = 'clip'  # Flagging mode (list/manual/clip/shadow/quack/
               # elevation/tfcrop/rflag/extend/unflag/summary)
...
datacolumn = 'DATA'  # Data column on which to operate
                    # (data,corrected,model,residual)
clipminmax = []  # Range to use for clipping
clipoutside = True  # Clip outside the range, or within it
channelavg = False  # Average over channels (scalar average)
clipzeros = False  # Clip zero-value data
```

In addition to the regular selection parameters, mode='clip' also has an option to select between the DATA, CORRECTED_DATA and other scratch columns for operation. clipminmax selects the range of values to be clipped – usually this is combined with clipoutside=True to clip everything but the values covered in clipminmax. The data can also be averaged over the selected spw channel ranges by setting channelavg=True. clip will also flag 'NaN', 'inf', and '-inf' values by default and can flag exact zero values (these are sometimes produced by the JVLA correlator) using the clipzeros parameter.

Note: For modes clip, tfcrop and rflag, channel-ranges can be excluded from flagging by selecting ranges such as spw='0:05;1063'. This is a way to protect known spectral-lines from being flagged by the autoflag algorithms.

### 3.4.2.4 Shadow

```python
mode = 'shadow'  # Flagging mode (list/manual/clip/shadow/quack/
                 # elevation/tfcrop/rflag/extend/unflag/summary)
...
tolerance = 0.0  # Amount of shadow allowed (in meters)
addantenna = ''  # File name or dictionary with additional antenna names,
                 # positions and diameters
```
CHAPTER 3. DATA EXAMINATION AND EDITING

This option flags shadowed antennas, i.e. when one antenna blocks part of the aperture of a second antenna that is behind the first one. Shadowing can be gradual and the criterion for a shadow flag is when a baseline is shorter than \( r_1 + r_2 - \text{tolerance} \) (where the radii of the antennae are taken from the MS antenna subtable). `addantenna` may be used to account for shadowing when antennas are not listed in the MS but are physically present. Please read the `flagdata` inline help for the syntax of this option.

3.4.2.5 Quack

```
mode = 'quack' # Flagging mode (list/manual/clip/shadow/quack/
               # elevation/tfcrop/rflag/extend/unflag/summary)

... quackinterval = 0.0 # Quack n seconds from scan beginning or end
quackmode = 'beg' # Quack mode. 'beg' ==> beginning of scan.'endb' ==> end of
                 # scan. 'end' ==> all but end of scan. 'tail' ==> all but
                 # beginning of scan
quackincrement = False # Flag incrementally in time?
```

`quack` is used to remove data at scan boundaries. `quackinterval` specifies the time in seconds to be flagged, and `quackmode` can be 'beg' to flag the `quackinterval` at the beginning of each selected scan, 'endb' at the end of scan. 'tail' flags all but the beginning of scan and 'end' all but the end of scan. The `quackincrement` is either True or False, depending if one wishes to flag the `quackinterval` from the first unflagged data in the scan, or from the scan boundaries independent of data being already flagged or not.

3.4.2.6 Elevation

```
mode = 'elevation' # Flagging mode (list/manual/clip/shadow/quack/
                   # elevation/tfcrop/rflag/extend/unflag/summary)

... lowerlimit = 0.0 # Lower limiting elevation (in degrees)
upperlimit = 90.0 # Upper limiting elevation (in degrees)
```

Flagging based on the elevation of the antennae. This may be useful to avoid data taken at very low elevations or close to transit and the `lowerlimit` and `upperlimit` parameters specify the range of good elevations.

3.4.2.7 Tfcrop

```
mode = 'tfcrop' # Flagging mode (list/manual/clip/shadow/quack/
                # elevation/tfcrop/rflag/extend/unflag/summary
                #
                #
                #

... ntime = 'scan' # Time-range to use for each chunk (in seconds
                 # or minutes)
```
CHAPTER 3. DATA EXAMINATION AND EDITING

```plaintext
combinescans = False  # Accumulate data across scans.
datacolumn = 'DATA'  # Data column on which to operate
# (data,corrected,model,residual)
timecutoff = 4.0  # Flagging thresholds in units of deviation
# from the fit
timefit = 'line'  # Fitting function for the time direction
# (poly/line)
freqcutoff = 3.0  # Flagging thresholds in units of deviation
# from the fit
freqfit = 'poly'  # Fitting function for the frequency direction
# (poly/line)
maxnpieces = 7  # Number of pieces in the polynomial-fits (for
# 'freqfit' or 'timefit' = 'poly')
flagdimension = 'freqtime'  # Dimensions along which to calculate fits
# (freq/time/freqtime/timefreq)
usewindowstats = 'none'  # Calculate additional flags using sliding
# window statistics (none,sum,std,both)
halfwin = 1  # Half-width of sliding window to use with
# 'usewindowstats' (1,2,3).
```

TFCrop is an autoflag algorithm that detects outliers on the 2D time-frequency plane, and can operate on un-calibrated data (non bandpass-corrected). The original implementation of this algorithm is described in NCRA Technical Report 202 (Oct 2003).

The algorithm iterates through the data in chunks of time. For each chunk, the result of user-specified visibility-expressions are organized as 2D time-frequency planes, one for each baseline and correlation-expression result, and the following steps are performed.

1. **Calculate a bandshape template**: Average the data across time, to construct an average bandpass. Construct an estimate of a clean bandpass (without RFI) via a robust piece-wise polynomial fit to the average bandpass shape.

   Note: A robust fit is computed in up to 5 iterations. It begins with a straight line fit across the full range, and gradually increases to 'maxnpieces' number of pieces with third-order polynomials in each piece. At each iteration, the stddev between the data and the fit is computed, values beyond N-stddev are flagged, and the fit and stddev are re-calculated with the remaining points. This stddev calculation is adaptive, and converges to a value that reflects only the data and no RFI. At each iteration, the same relative threshold is applied to detect flags, and this results in a varying set of flagging thresholds, that allows deep flagging only when the fit represents the true data best. Iterations stop when the stddev changes by less than 10%, or when 5 iterations are completed.

   The resulting clean bandpass is a fit across the base of RFI spikes.

2. **Divide out this clean bandpass function from all timesteps in the current chunk**. Now, any data points that deviate from a mean of 1 can be considered RFI. This step helps to separate narrow-band RFI spikes from a smooth but varying bandpass, in situations where a simple range-based clipping will flag good sections of the bandpass.
3. Perform iterative flagging (robust flagging) of points deviating from a value of 1.

Flagging is done in up to 5 iterations. In each iteration, for every timestep, calculate the stddev of the bandpass-flattened data, flag all points further than \( N \) times stddev from the fit, and recalculate the stddev. At each iteration, the same relative threshold is applied to detect flags. Optionally, use sliding-window based statistics to calculate additional flags.

4. Repeat steps 1 and 3, but in the other direction (i.e. average the data across frequency, calculate a piece-wise polynomial fit to the average time-series, and find flags based on deviations w.r.t. this fit.)

It is usually helpful to extend the flags along time, frequency and correlation using the "extend" mode in a second step within the same flagging run. See the example below:

```python
cmd=['mode="tfcrop" freqcutoff=3.0 usewindowstats="sum"',
     "mode='extend' extendpols=True growtime=50.0 growaround=True"]

flagdata(vis, mode='list', inpf=cmd)
```

The default parameters of the tfcrop implementation are optimized for strong narrow-band RFI. With broad-band RFI, the piece-wise polynomial can sometimes model it as part of the band-shape, and therefore not detect it as RFI. In this case, reducing the maximum number of pieces in the polynomial can help. This algorithm usually has trouble with noisy RFI that is also extended in time of frequency, and additional statistics-based flagging is recommended (via the 'usewindowstats' parameter). It is often required to set up parameters separately for each spectral-window.

If frequency ranges of known astronomical spectral lines are known \textit{a-priori}, they can be protected from automatic flagging by de-selecting those frequency-ranges via the 'spw' data-selection parameter.

For a detailed description of the \texttt{tfcrop parameters} and some examples, we refer to the inline help of \texttt{flagdata} and to \url{http://www.aoc.nrao.edu/~rurvashi/FlaggerDocs/FlaggerDocs.html}.

### 3.4.2.8 Rflag

```python
mode = 'rflag' # Flagging mode (list/manual/clip/shadow/quack/
elevation/tfcrop/rflag/extend/unflag/summary
# )

ntime = 'scan' # Time-range to use for each chunk (in seconds
# or minutes)
combinescans = False # Accumulate data across scans.
datacolumn = 'DATA' # Data column on which to operate
# (data,corrected,model,residual)
winsize = 3 # Number of timesteps in the sliding time
# window [aips:fparm(1)]
```
CHAPTER 3. DATA EXAMINATION AND EDITING

```plaintext
timedev = '' # Time-series noise estimate [aips:noise]
freqdev = '' # Spectral noise estimate [aips:scutoff]
timedevscale = 5.0 # Threshold scaling for timedev [aips:fparm(9)]
freqdevscale = 5.0 # Threshold scaling for freqdev
                     # [aips:fparm(10)]
spectralmax = 1000000.0 # Flag whole spectrum if freqdev is greater
                     # than spectralmax [aips:fparm(6)]
spectralmin = 0.0 # Flag whole spectrum if freqdev is less than
                     # spectralmin [aips:fparm(5)]
```

RFlag is an autoflag algorithm based on a sliding window statistical filter. The RFlag algorithm was originally developed by Eric Greisen in AIPS (31DEC11). AIPS documentation: Subsection E.5 of the AIPS cookbook (Appendix E: Special Considerations for JVLA data calibration and imaging in AIPS).

In RFlag, the data is iterated-through in chunks of time, statistics are accumulated across time-chunks, thresholds are calculated at the end, and applied during a second pass through the dataset.

The CASA implementation also optionally allows a single-pass operation where statistics and thresholds are computed and also used for flagging, within each time-chunk (defined by ‘ntime’ and ‘combinescans’).

For each chunk, calculate local statistics, and apply flags based on user supplied (or auto-calculated) thresholds.

1. Time analysis (for each channel)
   (a) Calculate local rms of real and imag visibilities, within a sliding time window
   (b) Calculate the median rms across time windows, deviations of local rms from this median, and the median deviation
   (c) Flag if local rms is larger than timedevscale x (medianRMS + medianDev)
2. Spectral analysis (for each time)
   (a) Calculate avg of real and imag visibilities and their rms across channels
   (b) Calculate the deviation of each channel from this avg, and the median-deviation
   (c) Flag if deviation is larger than freqdevscale x medianDev

It is usually helpful to extend the flags along time, frequency and correlation using the "extend" mode in a second step within the same flagging run. See the example below:

```plaintext
    cmd=['mode='tfcrop' freqcutoff=3.0 usewindowstats='sum''
        , "mode='extend' extendpols=True growtime=50.0 growaround=True"]

    flagdata(vis, mode='list', inpfile=cmd)
```

Again, we would like to refer to the inline help and to [http://www.aoc.nrao.edu/~ruvashi/FlaggerDocs/FlaggerDocs.html](http://www.aoc.nrao.edu/~ruvashi/FlaggerDocs/FlaggerDocs.html) for a more comprehensive description with examples.
3.4.2.9 Extend

mode = 'extend'  # Flagging mode (list/manual/clip/shadow/quack/ev
              #     tfcrop/rflag/extend/unflag/summary)
field = ''  # Field names or field index numbers: '' ==> all,
            # field='0~2,3C286'
spw = ''  # Spectral-window/frequency/channel: '' ==> all,
          # spw='0:17~19'
antenna = ''  # Antenna/baselines: '' ==> all, antenna
            # = '3,VA04'
timerange = ''  # Time range: '' ==>
               # all,timerange='09:14:0~09:54:0'
correlation = ''  # Correlation: '' ==> all, correlation='XX,YY'
scan = ''  # Scan numbers: '' ==> all
intent = ''  # Observation intent: '' ==> all,
            # intent='CAL*POINT*'
array = ''  # (Sub)array numbers: '' ==> all
uvrange = ''  # UV range: '' ==> all; uvrange = '0~100klambda',
             # default units=meters
observation = ''  # Observation ID: '' ==> all
feed = ''  # Multi-feed numbers: Not yet implemented
ntime = 'scan'  # Time-range to use for each chunk (in seconds or
                 # minutes)
combinescans = False  # Accumulate data across scans.
extendpols = True  # If any correlation is flagged, flag all
                    # correlations
growtime = 50.0  # Flag all 'ntime' integrations if more than X%
                 # of the timerange is flagged (0-100)
growfreq = 50.0  # Flag all selected channels if more than X% of
                 # the frequency range is flagged(0-100)
growaround = False  # Flag data based on surrounding flags
flagnearitime = False  # Flag one timestep before and after a flagged
                      # one (True/False)
flagnearfreq = False  # Flag one channel before and after a flagged one
                    # (True/False)

The extend mode may be most useful after running the tfcrop or rflag autoflagging procedures. Sometimes, these algorithms leave small islands of unflagged data behind, data that are surrounded by flagged visibilities in the time-frequency space. Although the algorithm may deem these visibilities as good ones, they are frequently affected by low-level RFI that spills from the adjacent, flagged points and one may wish to clean those up.

ntime specifies the time ranges over which to clean up, e.g. '1.5min' or 'scan' which checks on all data within a scan. To span time ranges larger than scans, one can set combinescans to True.

extendpols=True would extend all flags to all polarization products when at least one of them is flagged.

growtime flags the entire time range for a flagged channel, when a certain fraction of flagged time intervals is exceeded.
growfreq is similar but extends the flags in frequency when a given fraction of channels is already flagged.

growaround checks for flagged data points in the time-frequency domain that neighbor a datum. The threshold is four data points. If more surrounding points are flagged, the central datum will be flagged, too.

flagneartime flags adjacent data points along the time axis, around a flagged datum
flagnearfreq flags neighboring channels.

3.4.2.10 Unflag

mode = 'unflag'  \# Flagging mode (list/manual/clip/shadow/quack/
\# elevation/tfcrop/rflag/extend/unflag/summary
\# )
field = ''  \# Field names or field index numbers: ''==>all,
\# field='0\^2,3C286'
spw = ''  \# spectral-window/frequency/channel
antenna = 'ea01'  \# antenna/baselines: ''==>all, antenna
\# = '3,VA04'
timerange = ''  \# time range:
\# '':''==>all, timerange='09:14:0~09:54:0'
correlation = ''  \# Select data based on correlation
scan = ''  \# scan numbers: ''==>all
intent = ''  \# Select data based on observation intent:
\# '':''==>all
feed = ''  \# multi-feed numbers: Not yet implemented
array = ''  \# (sub)array numbers: ''==>all
uvrange = ''  \# uv range: ''==>all; uvrange = '0~100klambda',
\# default units=meters
observation = ''  \# Select data based on observation ID: ''==>all

The selection data will be unflagged.

3.4.2.11 Summary

mode = 'summary'  \# Flagging mode (list/manual/clip/shadow/quack/
\# elevation/tfcrop/rflag/extend/unflag/summary
\# )

minrel = 0.0  \# minimum number of flags (relative)
maxrel = 1.0  \# maximum number of flags (relative)
minabs = 0  \# minimum number of flags (absolute)
maxabs = -1  \# maximum number of flags (absolute). Use a
\# negative value to indicate infinity.
spwchan = False  \# Print summary of channels per spw
spwcorr = False  \# Print summary of correlation per spw
basecnt = False  \# Print summary counts per baseline
This mode reports the number of rows and data points that are flagged. The selection of reported points can be restricted (see inline help for details).

`mode='summary'` can also report back a dictionary if the task is run as

```python
s = flagdata(..., mode='summary')
```

with a variable assigned, here 's'.

### 3.5 Command-based flagging using `flagcmd`

The task `flagcmd` will flag the visibility data set or calibration table based on a specified set of flagging commands using a flagging syntax (see §3.5.3). These commands can be input from the `FLAG_CMD` MS table, from a `Flag.xml` SDM table, from an ascii file, or from input python strings. Facilities for manipulation, listing, or plotting of these flags are also provided.

The inputs to `flagcmd` are:

```bash
# flagcmd :: Flagging task based on batches of flag-commands
vis          = ''          # Name of MS file or calibration table to flag
inpmode      = 'table'    # Input mode for flag commands(table/list/xml)
infile       = ''          # Source of flag commands
tablerows    = []          # Rows of infile to read
reason       = 'any'      # Select by REASON types
useapplied   = False      # Select commands whose rows have APPLIED column set to True

action       = 'apply'   # Action to perform in MS and/or in infile
                # (apply/unapply/list/plot/clear/extract)
flagbackup   = True       # Automatically backup the FLAG column before execution
savepars     = False     # Save flag commands to the MS or to a file
async        = False     # If true the taskname must be started using flagcmd(...)```

The default input mode is `inpmode='table'` which directs the task to input flag commands from the `FLAG_CMD` internal MS table. See §3.5.1 for more options.

The default operation mode is `action='apply'` directing the task to apply relevant flagging commands to the MS data main table. See §3.5.2 for more options.

See §3.5.3 for a description of the flagging command syntax.

It is possible to flag calibration tables using `flagcmd`, although we recommend using the `flagdata` task for this.

When using `flagcmd` to flag calibration tables, only the `apply` and `list` actions are supported. Because calibration tables do not have a `FLAG_CMD` sub-table, the default `inpmode='table'` can only be used if an MS is given in the `infile` parameter so that flags from the MS are applied to the calibration table directly. Otherwise, the flag commands must be given using `inpmode='list'`, either from a file or from a list of strings.
3.5.1 Input modes inpmode

The inpmode parameter selects options for the input mode for the flagging commands.

Available inpmode options are:

- 'table' — input from MS table (§ 3.5.1.1)
- 'list' — input from ASCII file or from a list of strings (§ 3.5.1.2)
- 'xml' — input from XML table (§ 3.5.1.3)

3.5.1.1 Input mode 'table'

The default input mode is inpmode='table' which directs the task to input flag commands from a FLAG_CMD MS table. This has the sub-parameters:

```
inpmode = 'table' # Input mode for flag commands(table/list/xml)
inpfile = '' # Source of flag commands
tablerows = [] # Rows of inpfile to read
reason = 'any' # Select by REASON types
useapplied = False # Select commands whose rows have APPLIED column set to True
```

If inpfile = '' then it will look for the FLAG_CMD table in the MS given by vis. You can use this sub-parameter to direct the task to look directly at another table.

The tablerows sub-parameter is a simple Python list of the row numbers of the table to consider in processing flags. The default is all rows.

The useapplied sub-parameter toggles whether only flag commands marked as not having been applied are considered (the default), or to allow (re)processing using all commands.

The reason sub-parameter selects the REASON type to process. The default 'any' means all commands, note that reason='' would only select flags who have a blank REASON column entry.

One use case is to read the flag commands from the FLAG_CMD of an MS and apply them to a calibration table given in the parameter vis. Example:

```
flagcmd(vis='cal-X54.B1', inpmode='table', inpfile='uid___A002_X2a5c2f_X54.ms', action='apply')
```

3.5.1.2 Input flag mode 'list'

This mode allows one to insert a list of strings with flagging commands, the name of a file or a list of filenames that contains these commands equivalent to the mode='list' in flagdata (§ 3.4.2.2).

E.g. a file flags.txt that contains
3.5.1.3 Input flag mode 'xml'

The input mode `inpmode='xml'` directs the task to input flag commands from a XML SDM online flagging `Flag.xml` file. When set this opens the sub-parameters:

```plaintext
inpmode = 'xml'   # Input mode for flag commands(table/list/xml)
                 # Time buffer (sec) to pad flags
                 # Allowed flag antenna names to select by
                 # Select by REASON types
```

This mode will look for a file called `Flag.xml` inside the MS directory specified under `vis`. Note that if the data was filled from the SDM using `importevla` (§2.2.2) then the relevant XML file will have been copied to the MS already.

The `tbuff` sub-parameter sets a padding buffer (in seconds) to the begin and end times of the online flags in the XML file. As in `importevla`, the online flag time buffer `tbuff` is specified in seconds, but in fact should be keyed to the intrinsic online integration time to allow for events (like slewing) that occur within an integration period. This is particularly true for JVLA data, where a `tbuff` value of $0.5 \times$ to $1.5 \times$ the integration time is needed. For example, if data were taken with 1-second integrations, then at least `tbuff=0.5` should be used, likewise `tbuff=5` for 10-second integrations. **Note:** For JVLA data you should use $1.5 \times$ (e.g. `tbuff=15` for 10-second integrations) for data taken in early 2011 or before due to a timing error. We do not yet know what ALMA data will need for padding (if any).

The `ants` sub-parameter selects the antennas from which online flags will be selected (default is all antennas). For example, `ants='ea01'` is a valid choice for JVLA data.

The `reason` sub-parameter selects by the `REASON` field in the `Flag.xml` file. The default `'any'` means all commands. Note that `reason='''` would only select flags who have a blank `REASON` field entry.
3.5.2 Operation types action

The action selects options for operating on the selected flags and possibly the data. Available action options are:

- 'apply' — apply flag commands to data (§ 3.5.2.1)
- 'unapply' — unapply flags in data (§ 3.5.2.2)
- 'list' — list and/or save flag commands (§ 3.5.2.3)
- 'plot' — plot flag commands (§ 3.5.2.4)
- 'clear' — clear rows from FLAG_CMD table (§ 3.5.2.5)
- 'extract' — extract internal flag dictionary (§ 3.5.2.6)

3.5.2.1 Apply flags — optype option 'apply'

The default operation mode is action='apply' directing the task to apply relevant flagging commands to the vis data main table.

```
action = 'apply'                  # Action to perform in MS and/or in inpfile
flagbackup = True                # Automatically backup the FLAG column before execution
```

The flagbackup toggle sets whether a new copy of the MS main table FLAG column is written to the .flagversions backup directory for that MS before the requested flagging operation.

3.5.2.2 Unapply flags — action option 'unapply'

The unapply option allows unflagging of data based on the selected flag commands. This choice opens the sub-parameters:

```
action = 'unapply'                  # Action to perform in MS and/or in inpfile
flagbackup = True                # Automatically backup the FLAG column before execution
```

As in action='apply', it is possible to make a backup to the *.flagversions file by using flagbackup=True.

In order to guarantee that only the data selected in the command is unapplied, the framework will first unapply the selected rows and then re-apply the overlapping data that got unapplied in the first pass. This is a true unapply action, but it will take longer to process because it will re-apply all the remaining commands that have APPLIED = True!
3.5.2.3 List flags — action='list'

The 'list' option will give a listing of the flagging commands. This choice opens the sub-parameters:

```
action = 'list'  # Action to perform in MS and/or in inpfile
savepars = True  # Save flag commands to the MS or to a file
outfile = ''  # Name of output file to save commands
```

This action lists the commands on the screen without applying them. One can save the flagging script to an file specified in the `outfile` parameter when `savepars=True`. If `outfile` is empty, it will save the commands to the MS given in `vis`.

The format of the listing output depends on the source of the flagging commands. A set of flagging commands specified through `inpmode='list'` will be listed directly. The flagging commands extracted through `inpmode='table'` will reflect the columns in the table:

- 'Row', 'Timerange', 'Reason', 'Type', 'Applied', 'Lev', 'Sev', 'Command'

while commands from `inpmode='xml'` will be shown with the SDM XML table fields:

- 'Key', 'FlagID', 'Antenna', 'Reason', 'Timerange'

3.5.2.4 Plot flags — action='plot'

The 'plot' option will produce a graphical plot of flags of time versus antenna. This choice opens the sub-parameters:

```
action = 'plot'  # Action to perform in MS and/or in inpfile
plotfile = ''  # Name of output file to save plot
```

This is only useful for online flags or general flag commands that are specified by antenna plus timerange using the standard `REASON` codes that are known SDM `Flag.xml` enumerations.

If the `plotfile` sub-parameter is non-blank, then a plotfile will be made with that name instead of appearing in a matplotlib plotter window on the users workstation.

**ALERT:** The plotted enumerations are currently only those known to be allowed JVLA online flags as of 15 April 2011, and include:

- 'FOCUS', 'SUBREFLECTOR', 'OFF SOURCE', 'NOT IN SUBARRAY'

with all others being plotted as 'Other'.
3.5.2.5 Clear flags — action='clear'

The 'clear' action will delete selected rows from the FLAG_CMD MS table. This choice opens the sub-parameters:

```
action = 'clear' # Action to perform in MS and/or in infile

clearall = False # Delete all rows from FLAG_CMD
rowlist = [] # FLAG_CMD rows to clear
```

The `rowlist` sub-parameter is a simple Python list of the row numbers of the table to consider in processing flags. The default is a blank list which indicates the desire to clear all rows.

In either case, if `clearall=False` then nothing will happen by default as a safeguard. If `clearall=True`, then a blank list will direct the deletion of the selected rows from the table.

**ALERT:** Use this option with care. You can easily mess up the FLAG_CMD table.

3.5.2.6 Extract Flag Commands— action='extract'

The 'extract' option will return the internal flagging dictionary to python:

```
action = 'extract' # Action to perform in MS and/or in infile
```

The value can be returned to a variable like:

```python
myflagd = flagcmd(vis=msfile,useapplied=True,action='extract')
```

3.5.3 Flagging command syntax

A flagging command syntax has been devised to populate the COMMAND column of the FLAG_CMD table and to direct the operation of the flagcmd task.

The syntax is similar to flagdata, so please check help flagdata for more info.

You can also use help flagcmd inside casapy for this syntax guide also.

Commands are a string (which may contain internal "strings") consisting of KEY=VALUE pairs separated by whitespace (see examples below).

**NOTE:** There should be no whitespace between KEY=VALUE or within each KEY or VALUE, since the simple parser first breaks command lines on whitespace, then on "."

Each key should only appear once on a given command line/string

There is an implicit "mode" for each command, with the default being 'manual' if not given.

Comment lines can start with '#*' and will be ignored.
1. Data selection parameters (used by all flagging modes, see also §2.3)

\[
\begin{align*}
\text{timerange}= & '', \\
\text{antenna}= & '', \\
\text{spw}= & '', \\
\text{correlation}= & '', \\
\text{field}= & '', \\
\text{scan}= & '', \\
\text{feed}= & '', \\
\text{array}= & '', \\
\text{uvrange}= & '', \\
\text{intent}= & '', \\
\text{observation}= & ''
\end{align*}
\]

Note: a command consisting only of selection key-value pairs is a basic "manual" operation, ie. flag the data meeting the selection

2. Modes specific parameters with default values (for further details, refer to the task flagdata, §3.4.2).

(a) Mode manual

\[
\text{autocorr}=\text{False}
\]

(b) Mode clip

(c) Mode manual

\[
\begin{align*}
\text{datacolumn}= & \text{'DATA'} \\
\text{clipminmax}= & [] \\
\text{clipoutside}= & \text{True} \\
\text{channelavg}= & \text{False} \\
\text{clipzeros}= & \text{False}
\end{align*}
\]

(d) Mode shadow

\[
\begin{align*}
\text{tolerance}= & 0.0 \\
\text{addantenna}= & '',
\end{align*}
\]

(e) Mode quack

\[
\begin{align*}
\text{quackinterval}= & 0.0 \\
\text{quackmode}= & \text{'beg'} \\
\text{quackincrement}= & \text{False}
\end{align*}
\]

(f) Mode elevation

\[
\begin{align*}
\text{lowerlimit}= & 0.0 \\
\text{upperlimit}= & 90.0
\end{align*}
\]

(g) Mode tfcrop

\[
\begin{align*}
\text{ntime}= & \text{'scan'} \\
\text{combinescans}= & \text{False} \\
\text{datacolumn}= & \text{'DATA'} \\
\text{timecutoff}= & 4.0
\end{align*}
\]
freqcutoff=3.0
timefit='line'
freqfit='poly'
maxnpieces=7
flagdimension='freqtime'
usewindowstats='none'
halfwin=1

(h) Mode extend

ntime='scan'
combine scans=False
extendpols=True
growtime=50.0
growfreq=50.0
growaround=False
flagneartime=False
flagnearfreq=False

(i) Mode rflag

ntime='scan'
combine scans=False
datacolumn='DATA'
winsize=3
timedev='',
freqdev='',
timedevscale=5.0
freqdevscale=5.0
spectralmax=1000000.0
spectralmin=0.0

(j) Mode unflag

3. Basic elaboration options for online and interface use

id=''
reason=''
flagtime='' # flag ID tag (not necessary)
# reason string for flag
# a timestamp for when this flag was generated (for
# user history use)

NOTE: there is no flagtime column in FLAG_CMD at this time, but we will propose to add this as an optional column

NOTE: These are currently ignored and not used

4. Extended elaboration options for online and interface use Note: these are FLAG_CMD columns, but their use is not clear but included here for compatibility and future expansion

level=N
severity=N
# flagging "level" for flags with same reason
# Severity code for the flag, on a scale of 0-10 in order
# of increasing severity; user specified
3.6 Browse the Data

The `browsetable` task is available for viewing data directly (and handles all CASA tables, including Measurement Sets, calibration tables, and images). This task brings up the CASA Qt `casabrowser`, which is a separate program. You can launch this from outside `casapy`.

The default inputs are:

```
# browsetable :: Browse a table (MS, calibration table, image)

tablename = ''  # Name of input table
async = False   # If true the taskname must be started using browsetable(...)  
```

Currently, its single input is the `tablename`, so an example would be:

```
browsetable('ngc5921.ms')
```

For an MS such as this, it will come up with a browser of the `MAIN` table (see Fig 3.8). If you want to look at sub-tables, use the tab `table keywords` along the left side to bring up a panel with the sub-tables listed (Fig 3.9), then choose (left-click) a table and `View:Details` to bring it up (Fig 3.10). You can left-click on a cell in a table to view the contents.

Note that one useful feature is that you can Edit the table and its contents. Use the `Edit table` choice from the `Edit` menu, or click on the `Edit` button. Be careful with this, and make a backup copy of the table before editing!

Use the `Close Tables and Exit` option from the `Files` menu to quit the `casabrowser`.

There are a lot of features in the `casabrowser` that are not fully documented here. Feel free to explore the capabilities such as plotting and sorting!

**ALERT:** You are likely to find that the `casabrowser` needs to get a table lock before proceeding. Use the `clearstat` command to clear the lock status in this case.
Figure 3.8: **browsetable**: The browser displays the main table within a frame. You can scroll through the data (x=columns of the MAIN table, and y=the rows) or select a specific page or row as desired. By default, 1000 rows of the table are loaded at a time, but you can step through the MS in batches.
Figure 3.9: **browsetable**: You can use the tab for **Table Keywords** to look at other tables within an MS. You can then double-click on a table to view its contents.
Figure 3.10: **browsetable**: Viewing the **SOURCE** table of the MS.
Chapter 4

Synthesis Calibration

This chapter explains how to calibrate interferometer data within the CASA task system. Calibration is the process of determining the net complex correction factors that must be applied to each visibility in order to make them as close as possible to what an idealized interferometer would measure, such that when the data is imaged an accurate picture of the sky is obtained. This is not an arbitrary process, and there is a philosophy behind the CASA calibration methodology (see §4.2.1 for more on this). For the most part, calibration in CASA using the tasks is not too different than calibration in other packages such as AIPS or Miriad, so the user should not be alarmed by cosmetic differences such as task and parameter names!

4.1 Calibration Tasks

Alert: The calibration table format has changed in CASA 3.4. From now on, calibration tables are largely independent of the MS that they were created from and can be applied to any MS. We recommend using the new calibration table format throughout and recreate them when possible (only important when the user switches from CASA 3.3 to 3.4 or 4.1 during calibration). If absolutely necessary, old calibration tables can be converted to the new format using the task caltabconvert, but some information was not stored in the old tables and cannot be filled into the new tables. When old calibration tables were already applied with applycal, one can proceed with imaging as usual in any version of CASA and no action is needed. A second change has made to calibration tables in CASA 4.1, introducing obsID. Older calibration tables do not feature this keyword and will not support obsID-specific calibration operations. If required, these tables should be regenerated in CASA 4.1 or higher to access these new features.

: Alert: CASA v4.1 is the last version that will support use of the gaincurve and opacity parameters. These calibration types are now supported via the gencal task.

The standard set of calibration solving tasks (to produce calibration tables) are:

Inside the Toolkit:
The workhorse for synthesis calibration is the cb tool.
CHAPTER 4. SYNTHESIS CALIBRATION

- **bandpass** — complex bandpass (B) calibration solving, including options for channel-binned or polynomial solutions ($\S$ 4.4.2).
- **gaincal** — complex gain (G,T) calibration solving, including options for time-binned or spline solutions ($\S$ 4.4.3),
- **polcal** — polarization calibration including leakage and angle ($\S$ 4.4.5),
- **blcal** — *baseline-based* complex gain or bandpass calibration ($\S$ 4.4.6).

There are helper tasks to create, manipulate, and explore calibration tables:

- **accum** — Accumulate incremental calibration solutions into a cumulative cal table ($\S$ 4.5.5) *(ALERT: The *accum* task is generally no longer recommended for most calibration scenarios. Please write to the NRAO CASA helpdesk if you need support using *accum*.),
- **applycal** — Apply calculated calibration solutions ($\S$ 4.6.1),
- **clearcal** — Re-initialize the calibration for a visibility dataset ($\S$ 4.6.3),
- **fluxscale** — Bootstrap the flux density scale from standard calibration sources ($\S$ 4.4.4),
- **listcal** — List calibration solutions ($\S$ 4.5.2),
- **plotcal** — Plot calibration solutions ($\S$ 4.5.1),
- **setjy** — Compute model visibilities with the correct flux density for a specified source ($\S$ 4.3.4),
- **smoothcal** — Smooth calibration solutions derived from one or more sources ($\S$ 4.5.4),
- **split** — Write out new MS containing calibrated data from a subset of the original MS ($\S$ 4.7.1).

There are some development versions of calibration and utility tasks that are recently added to the suite:

- **calstat** — Statistics of calibration solutions ($\S$ 4.5.3),
- **cvel** — Regrid a spectral MS onto a new frequency channel system ($\S$ 4.7.6),
- **gencal** — Create a calibration tables from metadata such as antenna position offsets, gain-curves and opacities ($\S$ 4.3.5),
- **wvgcal** — Generate a gain table based on Water Vapour Radiometer data (for ALMA use - $\S$ 4.3.7),
- **hanningsmooth** — Apply a Hanning smoothing filter to spectral-line uv data ($\S$ 4.7.3),
- **uvcontsub** — Carry out uv-plane continuum fitting and subtraction ($\S$ 4.7.5),
CHAPTER 4. SYNTHESIS CALIBRATION

- **uvmodelfit** — Fit a component source model to the uv data (§4.7.7),
- **uvsub** — Subtract the transform of a model image from the uv data (§4.7.4),
- **statwt** — Recalculcate the data weights based on their scatter (§4.7.8),
- **conjugatevis** — Change the signs of visibility phases (§4.7.9).

These are not yet full-featured, and may have only rudimentary controls and options.

The following sections outline the use of these tasks in standard calibration processes.

Information on other useful tasks and parameter setting can be found in:

- **listobs** — summary of a MS (§2.2.6),
- **listvis** — list data in a MS (§2.2.8),
- **plotms** — prototype next-generation X-Y plotting and editing (§3.3.1),
- **plotxy** — previous generation X-Y plotting and editing (§3.3.2),
- **plotweather** — plot the weather information of an MS and calculate atmospheric opacities (§4.3.3.1),
- **flagdata** — non-interactive data flagging (§3.4),
- **data selection** — general data selection syntax (§2.3).

4.2 The Calibration Process — Outline and Philosophy

A work-flow diagram for CASA calibration of interferometry data is shown in Figure 4.1. This should help you chart your course through the complex set of calibration steps. In the following sections, we will detail the steps themselves and explain how to run the necessary tasks and tools.

This can be broken down into a number of discrete phases:

- **Calibrator Model Visibility Specification** — set model visibilities for calibrators, either unit point source visibilities for calibrators with unknown flux density or structure (generally, sources used for calibrators are approximately point-like), or visibilities derived from a priori images and/or known or standard flux density values.

- **Prior Calibration** — set up previously known calibration quantities that need to be pre-applied, such antenna gain-elevation curves, atmospheric models, delays, and antenna position offsets. Use the **setjy** task (§1.3.4) for calibrator flux densities and models, and use **gen cal** (§4.3.5) for antenna position offsets, gaincurves, antenna efficiencies, and opacities;
Figure 4.1: Flow chart of synthesis calibration operations. Not shown are use of table manipulation and plotting tasks `accum`, `plotcal`, and `smoothcal` (see Figure 4.2).
• **Bandpass Calibration** — solve for the relative gain of the system over the frequency channels in the dataset (if needed), having pre-applied the prior calibration. Use the `bandpass` task (§4.4.2);

• **Gain Calibration** — solve for the gain variations of the system as a function of time, having pre-applied the bandpass (if needed) and prior calibration. Use the `gaincal` task (§4.4.3);

• **Polarization Calibration** — solve for polarization leakage terms and linear polarization position angle (§4.4.5);

• **Establish Flux Density Scale** — if only some of the calibrators have known flux densities, then rescale gain solutions and derive flux densities of secondary calibrators. Use the `fluxscale` task (§4.4.4);

• **Manipulate, Accumulate, and Iterate** — if necessary, accumulate different calibration solutions (tables), smooth, and interpolate/extrapolate onto different sources, bands, and times. Use the `accum` (§4.5.5) and `smoothcal` (§4.5.4) tasks;

• **Examine Calibration** — at any point, you can (and should) use `plotcal` (§4.5.1) and/or `listcal` (§4.5.2) to look at the calibration tables that you have created;

• **Apply Calibration to the Data** — this can be forced explicitly by using the `applycal` task (§4.6.1), and can be undone using `clearcal` (§4.6.3);

• **Post-Calibration Activities** — this includes the determination and subtraction of continuum signal from line data, the splitting of data-sets into subsets (usually single-source), and other operations (such as model-fitting). Use the `uvcontsub` (§4.7.5), `split` (§4.7.1), and `uvmodelfit` (§4.7.7) tasks.

The flow chart and the above list are in a suggested order. However, the actual order in which you will carry out these operations is somewhat fluid, and will be determined by the specific data-reduction use cases you are following. For example, you may need to do an initial **Gain Calibration** on your bandpass calibrator before moving to the **Bandpass Calibration** stage. Or perhaps the polarization leakage calibration will be known from prior service observations, and can be applied as a constituent of Prior Calibration.

### 4.2.1 The Philosophy of Calibration in CASA

Calibration is not an arbitrary process, and there is a methodology that has been developed to carry out synthesis calibration and an algebra to describe the various corruptions that data might be subject to: the Hamaker-Bregman-Sault Measurement Equation (ME), described in Appendix E. The user need not worry about the details of this mathematics as the CASA software does that for you. Anyway, its just matrix algebra, and your familiar scalar methods of calibration (such as in AIPS) are encompassed in this more general approach.

There are a number of “physical” components to calibration in CASA:
• **data** — in the form of the Measurement Set (§2.1). The MS includes a number of columns that can hold calibrated data, model information, and weights;

• **calibration tables** — these are in the form of standard CASA tables, and hold the calibration solutions (or parameterizations thereof);

• **task parameters** — sometimes the calibration information is in the form of CASA task parameters that tell the calibration tasks to turn on or off various features, contain important values (such as flux densities), or list what should be done to the data.

At its most basic level, Calibration in CASA is the process of taking “uncalibrated” data, setting up the operation of calibration tasks using parameters, solving for new calibration tables, and then applying the calibration tables to form “calibrated” data. Iteration can occur as necessary, with the insertion of other non-calibration steps (e.g. imaging to generate improved source models for “self-calibration”).

### 4.2.2 Keeping Track of Calibration Tables

The calibration tables are the currency that is exchanged between the calibration tasks. The “solver” tasks (gaincal, bandpass, b1cal, polcal) take in the MS (which may have a calibration model attached) and previous calibration tables, and will output an “incremental” calibration table (it is incremental to the previous calibration, if any). This table can then be smoothed using smoothcal if desired.

You can optionally accumulate the incremental calibration onto previous calibration tables with accum, which will then output a cumulative calibration table. This task will also interpolate onto a different time scale. See §4.5.5 for more on accumulation and interpolation.

Figure 4.2 graphs the flow of these tables through the sequence

\[
\text{solve} \Rightarrow \text{smooth} \Rightarrow \text{accumulate}
\]

Note that this sequence applied to separate types of tables (e.g. ‘B’, ‘G’) although tables of other types can be previous calibration input to the solver.

The final set of cumulative calibration tables is what is applied to the data using applycal. You will have to keep track of which tables are the intermediate incremental tables, and which are cumulative, and which were previous to certain steps so that they can also be previous to later steps until accumulation. This can be a confusing business, and it will help if you adopt a consistent table naming scheme (see Figure 4.2 for an example naming scheme).

### 4.2.3 The Calibration of traditional VLA data in CASA

CASA supports the calibration of traditional VLA data that is imported from the Archive through the importvla task. See §2.2.3 for more information.
Figure 4.2: Chart of the table flow during calibration. The parameter names for input or output of the tasks are shown on the connectors. Note that from the output solver through the accumulator only a single calibration type (e.g. 'B', 'G') can be smoothed, interpolated or accumulated at a time. _accum_ is optional (and not recommended as of v4.0). The final set of cumulative calibration tables of all types (accumulated or as a list of caltables) are then input to _applycal_ as shown in Figure 4.1.

**ALER:** Data taken both before and after the Modcomp turn-off in late June 2007 will be handled automatically by _importvla_. You do not need to set special parameters to do so, and it will obey the scaling specified by _applytsys_.

You can also import VLA data in UVFITS format with the _importuvfits_ task (§2.2.4.1). However, in this case, you must be careful during calibration in that some prior or previous calibrations (see below) may or may not have been done in AIPS and applied (or not) before export.

For example, the default settings of AIPS _FILLM_ will apply VLA gaincurve and approximate (weather-based) atmospheric optical depth corrections when it generates the extension table _CL1_. If the data is exported immediately using _FITTP_, then this table is included in the UVFITS
file. However, CASA is not able to read or use the AIPS \texttt{SN} or \texttt{CL} tables, so that prior calibration information is lost and must be applied during calibration here (i.e., using \texttt{gaincurve=True} and setting the \texttt{opacity} parameter).

On the other hand, if you apply calibration in AIPS by using the \texttt{SPLIT} or \texttt{SPLAT} tasks to apply the \texttt{CL} tables before exporting with \texttt{FITTP}, then this calibration will be in the data itself. In this case, you do not want to re-apply these calibrations when processing in CASA.

### 4.2.4 Loading Jansky VLA data in CASA

Jansky VLA data can be loaded into CASA either via \texttt{importevla} or by using the task \texttt{importasdm}. Both tasks will convert ASDM raw data files into measurement sets. \texttt{importasdm} will convert the data itself and the majority of the metadata. \texttt{importevla} will run \texttt{importasdm} followed by Jansky VLA-specific corrections, like the application of the on-line flags (e.g., times when the subreflector was not in place or the an antenna was not on source), an option to clip values that are exactly zero (as of 2010, such values still may appear in the VLA raw data), and flagging for shadowing.

### 4.3 Preparing for Calibration

There are a number of “a priori” calibration quantities that may need to be applied to the data before further calibration is carried out. These include

- **system temperature correction** — turn correlation coefficient into correlated flux density (necessary for some telescopes),
- **gain curves** — antenna gain-elevation dependence,
- **atmospheric optical depth** — attenuation of the signal by the atmosphere, including correcting for its elevation dependence.
- **flux density models** — establish the flux density scale using “standard” calibrator sources, with models for resolved calibrators,
- **delays** — antenna-based delay offsets,
- **antenna position errors** — offsets in the positions of antennas assumed during correlation.

These are pre-determined effects and should be applied (if known) before solving for other calibration terms. If unknown, then they will need to be solved for (or subsumed in other calibration such as bandpass or gains).

We now deal with these in turn.
4.3.1 System Temperature Correction

Some telescopes, including the VLA and the VLBA, record the visibilities in the form of raw correlation coefficient with weights proportional to the number of bits correlated. The correlation coefficient is the fraction of the total signal that is correlated, and thus multiplication by the system temperature and the antenna gain (in Jy/K) will produce visibilities with units of correlated flux density. Note that the old VLA system did this initial calibration on-line, and ALMA will also provide some level of on-line calibration (TBD).

**ALERT:** There is as yet no mechanism available in importvla or in the calibration tasks to use the system temperature information provided by the VLA/Jansky VLA on-line system to calibrate Jansky VLA or VLBA data in raw form. This includes VLA data taken after the Modcomp turn-over in late June 2007. You may pass the data through AIPS first. You can also just forge ahead with standard calibration. The drawback to this is that short-term changes in $T_{sys}$ which are not tracked by calibrator observations or self-calibration will remain in the data.

4.3.2 Antenna Gain-Elevation Curve Calibration

Large antennas (such as the 25-meter antennas used in the VLA and VLBA) have a forward gain and efficiency that changes with elevation. Gain curve calibration involves compensating for the effects of elevation on the amplitude of the received signals at each antenna. Antennas are not absolutely rigid, and so their effective collecting area and net surface accuracy vary with elevation as gravity deforms the surface. This calibration is especially important at higher frequencies where the deformations represent a greater fraction of the observing wavelength. By design, this effect is usually minimized (i.e., gain maximized) for elevations between 45 and 60 degrees, with the gain decreasing at higher and lower elevations. Gain curves are most often described as 2nd- or 3rd-order polynomials in zenith angle.

Gain curve calibration has been implemented in CASA for the Jansky VLA and old VLA (only), with gain curve polynomial coefficients available directly from the CASA data repository. To make gain curve and antenna efficiency corrections for VLA data, use gencal with caltable='gceff'.

**ALERT:** If you are not using VLA data, do not use gaincurve corrections. A general mechanism for incorporating gaincurve information for other arrays will be made available in future releases. The gain-curve information available for the E/VLA is time-dependent (on timescales of months to years, at least for the higher frequencies), and CASA will automatically select the date-appropriate gain curve information. Note, however, that the time-dependence was poorly sampled prior to 2001, and so gain curve corrections prior to this time should be considered with caution.

4.3.3 Atmospheric Optical Depth Correction

The troposphere is not completely transparent. At high radio frequencies (>15 GHz), water vapor and molecular oxygen begin to have a substantial effect on radio observations. According to the physics of radiative transmission, the effect is threefold. First, radio waves from astronomical sources are absorbed (and therefore attenuated) before reaching the antenna. Second, since a good
absorber is also a good emitter, significant noise-like power will be added to the overall system noise. Finally, the optical path length through the troposphere introduces a time-dependent phase error. In all cases, the effects become worse at lower elevations due to the increased air mass through which the antenna is looking. In CASA, the opacity correction described here compensates only for the first of these effects, tropospheric attenuation, using a plane-parallel approximation for the troposphere to estimate the elevation dependence.

To make opacity corrections in CASA, an estimate of the zenith opacity is required (see observatory-specific chapters for how to measure zenith opacity). This is then supplied to the caltype='opac' parameter in gencal which creates a calibration table with all the information. E.g. for data with two spectral windows, the inputs are like:

```
gencal(vis='dataset.ms',
   caltable='opacity.cal',
   caltype='opac',
   spw=['0','1'],
   parameter=[0.0399,0.037])
```

If you do not have an externally supplied value for opacity, for example from a VLA tip procedure, then you should either use an average value for the telescope, or leave it at zero and let your gain calibration compensate as best it can (e.g. that your calibrator is at the same elevation as your target at approximately the same time. As noted above, there are no facilities yet to estimate this from the data (e.g. by plotting Tsys vs. elevation).

Below, we give instructions for determining opacity for Jansky VLA data from weather statistics and VLA observations where tip-curve data is available. It is beyond the scope of this cookbook to provide information for other telescopes.

### 4.3.3.1 Determining opacity corrections for VLA data

For the VLA site, weather statistics and/or seasonal models that average over many years of weather statistics prove to be reasonable good ways to estimate the opacity at the time of the observations. The task `plotweather` calculates the opacity as a mix of both actual weather data and seasonal model. It has the following inputs:

```
# plotweather :: Plot elements of the weather table; estimate opacity.
vis = '' # MS name
seasonal_weight = 0.5 # weight of the seasonal model
doPlot = True # set this to True to create a plot
async = False # If true the taskname must be started using plotweather(...)```

The task plots the weather statistics if `doPlot=T`, like shown in Figure 4.3. The bottom panel displays the calculated opacities for the run as well as a seasonal model. The parameter `seasonal_weight` can be adjusted to calculate the opacities as a function of the weather data alone `seasonal_weight=0`, only the seasonal model `seasonal_weight=1`, or a mix of the two (values between 0 and 1). Calculated opacities are shown in the logger output, one for each spectral window. `plotweather` can also assign a python variable to a list of calculated opacities (one entry for each spw) when run as:
myTau = plotweather(vis='..')

in that example, myTau will be returned with, e.g. $myTau=[0.02,0.03]$ and can later be used as input for the opacity parameter in a number of calibration tasks ($opacity=myTau$ or $opacity=[0.02,0.03]$).

### 4.3.3.2 Determining opacity corrections for VLA data

For VLA data, zenith opacity can be measured at the frequency and during the time observations are made using a VLA tipping scan in the observe file. Historical tipping data are available at:


Choose a year, and click Go to get a list of all tipping scans that have been made for that year.

If a tipping scan was made for your observation, then select the appropriate file. Go to the bottom of the page and click on the button that says Press here to continue. The results of the tipping scan will be displayed. Go to the section called 'Overall Fit Summary' to find the fit quality and the fitted zenith opacity in percent. If the zenith opacity is reported as 6%, then the actual zenith optical depth value is $opacity=0.060$ for gaincal and other calibration tasks.

If there were no tipping scans made for your observation, then look for others made in the same band around the same time and weather conditions. If nothing is available here, then at K and Q bands you might consider using an average value (e.g. 6% in reasonable weather). See the VLA memo:


for more on the atmospheric optical depth correction at the VLA, including plots of the seasonal variations.

### 4.3.4 Setting the Flux Density Scale using (setjy)

When solving for visibility-plane calibration, CASA calibration applications compare the observed DATA column with the Fourier transform of calibrator model when it is provided (if no model is specified, a point source at the phase center is assumed).

The setjy task is used to set the proper flux density and attaches a model image (if specified) of the calibrator to the MS. For sources that are recognized flux calibrators (listed in Tables 4.1 and 4.2, see also §C.1), setjy can calculate the flux densities as a function of frequency (and time, for Solar System objects). Otherwise, the flux densities should be manually specified.

For the VLA, the default source models are customarily point sources defined by the 'Baars', 'Perley 90', 'Perley-Taylor 99', 'Perley-Butler 2010', or 'Perley-Butler 2013' flux density scales (§C.1.1 'Perley-Butler 2010' is the current standard by default), or point sources of unit flux density.
Figure 4.3: The weather information for a MS as plotted by the task plotweather.
CHAPTER 4. SYNTHESIS CALIBRATION

if the flux density is unknown. In fact, the model can be any image in Jy/pixel units (models typically generated by the `clean` task).

Optionally, the MODEL column can be filled with the Fourier transform of (option `usescratch=T` is `setjy`, `ft`, and `clean`). But for most measurement sets, the performance and data storage requirements are less demanding without the MODEL_DATA column.

The inputs for `setjy` are:

```python
# setjy :: Fills the model column with the visibilities of a calibrator
vis = '' # Name of input visibility file
field = '' # Field name(s)
spw = '' # Spectral window identifier (list)
selectdata = False # Other data selection parameters
modimage = '' # File location for field model
listmodels = False # List the available models for VLA or calibrators or Tb models for Solar System objects
scalebychan = True # scale the flux density on a per channel basis or else on a per spw basis
fluxdensity = -1 # Specified flux density [I,Q,U,V]; -1 will lookup values
standard = 'Perley-Butler 2010' # Flux density standard
usescratch = False # Will create if necessary and use the MODEL_DATA
async = False # If true the taskname must be started using `setjy(...)`
```

Table 4.1: Recognized Flux Density Calibrators. Note that the VLA uses J2000 calibrator names. CASA accepts all strings that contain the names below. E.g. 'PKS 1934-638' will be recognized

<table>
<thead>
<tr>
<th>3C Name</th>
<th>B1950 Name</th>
<th>J2000 Name</th>
<th>Alt. J2000 Name</th>
<th>Standards</th>
</tr>
</thead>
<tbody>
<tr>
<td>3C48</td>
<td>0134+329</td>
<td>0137+331</td>
<td>J0137+3309</td>
<td>1,3,4,5,6</td>
</tr>
<tr>
<td>3C123</td>
<td>0433+295</td>
<td>0437+296</td>
<td>J0437+2940</td>
<td>2</td>
</tr>
<tr>
<td>3C138</td>
<td>0518+165</td>
<td>0521+166</td>
<td>J0521+1638</td>
<td>1,3,4,5,6</td>
</tr>
<tr>
<td>3C147</td>
<td>0538+498</td>
<td>0542+498</td>
<td>J0542+4951</td>
<td>1,3,4,5,6</td>
</tr>
<tr>
<td>3C196</td>
<td>0809+483</td>
<td>0813+482</td>
<td>J0813+4813</td>
<td>1,2</td>
</tr>
<tr>
<td>3C286</td>
<td>1328+307</td>
<td>1331+305</td>
<td>J1331+3030</td>
<td>1,2,3,4,5,6</td>
</tr>
<tr>
<td>3C295</td>
<td>1409+524</td>
<td>1411+522</td>
<td>J1411+5212</td>
<td>1,2,3,4,5,6</td>
</tr>
<tr>
<td>–</td>
<td>1934-638</td>
<td>–</td>
<td>J1939-6342</td>
<td>1,3,4,5,6</td>
</tr>
</tbody>
</table>


By default the `setjy` task will cycle through all fields spectral windows and channels, (one solution per spw with `scalebychan = False`), setting the flux density either to 1 Jy (unpolarized), or if
CHAPTER 4. SYNTHESIS CALIBRATION

Table 4.2: ’Butler-JPL-Horizons 2012’ recognized Solar System Objects for Flux Calibration

<table>
<thead>
<tr>
<th>Planets</th>
<th>Moons</th>
<th>Asteroids</th>
</tr>
</thead>
<tbody>
<tr>
<td>Venus(^1), Mars(^2), Jupiter(^3), Uranus(^4), Neptune(^5)</td>
<td>Jupiter: Io, Europa, Ganymede, Callisto</td>
<td>Ceres, Pallas(^8), Vesta(^8), Juno(^8)</td>
</tr>
</tbody>
</table>

1 Venus: model for \(\sim 300\) MHz to 350 GHz, no atmospheric lines (CO, H\(_2\)O, HDO, etc.)
2 Mars: tabulated as a function of time and frequency (30 - 1000 GHz) based on Rudy et al. (1988), no atmospheric lines (CO, H\(_2\)O, HDO, etc)
3 Jupiter: model for 30-1020 GHz, does not include synchrotron emission
4 Uranus: model for 60-1800 GHz, contains no rings or synchrotron.
5 Neptune: model for 2-2000 GHz, the broad CO absorption line is included, but contains no rings or synchrotron.
6 Titan: model for 53.3-1024.1 GHz, include many spectral lines
7 not recommended (The temperature is not yet adjusted for varying distance from the Sun. The model data can be scaled after running setjy, but it is an involved process.)

Details are described in ALMA Memo 594 available on [https://science.nrao.edu/facilities/alma/aboutALMA/Technology/ALMA_Memo_Series/alma594/abs594](https://science.nrao.edu/facilities/alma/aboutALMA/Technology/ALMA_Memo_Series/alma594/abs594).

the source is recognized as one of the calibrators in the above table, to the flux density (assumed unpolarized) appropriate to the observing frequency. For example, to run setjy on a measurement set called data.ms:

```python
setjy(vis='data.ms')  # This will set all fields and spectral windows
```

Models of available calibrator sources can be listed by setting listmodels=True. setjy will then come up with all images that are in the paths where calibrator models for known telescopes are stored. It will also show all images in the working directory - any image there could potentially be a calibrator model. If the calibrator model is found by listmodels it can be used in the modimage parameter without a path.

The fluxdensity parameter can be used to specify the flux of the calibrator in all Stokes parameters. Is is thus a list of values [I,Q,U,V], e.g. ['12Jy','13mJy','0Jy','0Jy']. In addition, a spectral index can be specified via spix and a reference frequency reffreq (using the definition: \(S = fluxdensity \times \frac{freq}{reffreq^{spix}}\)).

Most calibrator sources are based on radio emission from quasars and jets. The spectral indices of these sources are such that at (sub)mm wavelengths the majority of these sources become too weak and variable to be reliable flux estimators. Alternatives are thermal objects such as planets, moons, and asteroids. Those sources, however, are all Solar System objects, which implies that they move and may be (strongly) resolved. The standard='Butler-JPL-Horizons 2010’ and the recommended standard='Butler-JPL-Horizons 2012’ (for more information on the implemented models, see ALMA Memo 594 soon available on [https://science.nrao.edu/facilities/alma/](https://science.nrao.edu/facilities/alma/))
The setjy option of setjy includes flux density calibration using Solar System objects. For 'Butler-JPL-Horizons 2012' CASA currently supports the objects listed in Table 4.2 to be applied to ALMA data. These names are recognized when they are used in the 'field' parameter in setjy. In that case, setjy will obtain the geocentric distance and angular diameter at the time of the observation from a (JPL–Horizons) ephemeris and calculate model visibilities. Currently the objects are modeled as uniform temperature disks, but effects like primary beam attenuation and limb darkening will be accounted for soon. Note that this model may oversimplify the real structure, in particular asteroids.


```
setjy(vis='c0104I', field='MARS', spw='0 2', standard='Butler-JPL-Horizons 2012')
```

Tip: Running casalog.filter('INFO1') before running setjy with a Solar System object may send the logger a reference to the temperature measurement. Use casalog.filter('INFO') to restore the normal logging level.

The source model will be attached to the MS and applied to all calibration steps when usescratch=False. usescratch=True fills the MODEL_DATA column with the Fourier transform of the model. As of CASA 3.4. we found that under some circumstances, creation of the MODEL column may prevent memory issues and if tasks fail, we recommend to set usescratch=True. Note that currently setjy will not transform a full-Stokes model image such that all polarizations are applied correctly. You need to use ft for this.

To limit this operation to certain fields and spectral windows, use the field and/or spw parameters, which take the usual data selection strings (§2.3). For example, to set the flux density of the first field (all spectral windows)

```
setjy(vis='data.ms',field='0')
```

or to set the flux density of the second field in spectral window 17

```
setjy(vis='data.ms',field='1',spw='17')
```

The full-polarization flux density (I,Q,U,V) may also be explicitly provided:

```
setjy(vis='data.ms',
    field='1',spw='16', 
    fluxdensity=[3.5,0.2,0.13,0.0])   # Run setjy on field id 1, spw id 17
```

**ALERT:** The apparent brightness of objects in the Solar System will vary with time because of the Earth’s varying distance to them, if nothing else. If the field index of a flux calibrator spans several days, you should run setjy more than once, limiting each run to a suitable timerange by using the timerange, scan, and/or observation selection parameters. Note that it is the field index that matters, not the name. Typically concat assigns moving objects a new field index for each observation, so usually it is not necessary to select a time range in setjy. However, it is worth checking with listobs, especially for planets.
4.3.4.1 Using Calibration Models for Resolved Sources

For observations of solar system objects using the ’Butler-JPL-Horizons 2010’ and ’Butler-JPL-Horizons 2012’ models (§4.3.4) setjy will know and apply the flux distribution across the extended structure of the calibrators.

For other sources, namely VLA calibrator sources, a flux density calibrator can be resolved at the observing frequency and the point source model generated by setjy will not be appropriate. If available, a model image of the resolved source at the observing frequency may be used to generate the appropriate visibilities using the modimage parameter (or in older versions explicitly with the ft task). To use this, provide modimage with the path to the model image. Remember, if you just give the file name, it will assume that it is in the current working directory. Note also that setjy using a model image will only operate on that single source, thus you would run it multiple times (with different field settings) for different sources.

Otherwise, you may need to use the uvrangle selection (§4.4.1.2) in the calibration solving tasks to exclude the baselines where the resolution effect is significant. There is not hard and fast rule for this, though you should consider this if your calibrator is shows a drop of more than 10% on the longest baselines (use plotxy, §3.3.2, to look at this). You may need to do antenna selection also, if it is heavily resolved and there are few good baselines to the outer antennas. Note that uvrangle may also be needed to exclude the short baselines on some calibrators that have extended flux not accounted for in the model. Note: the calibrator guides for the specific telescopes usually indicate appropriate min and max for uvrangle. For example, see the VLA Calibration Manual at:

http://www.vla.nrao.edu/astro/calib/manual/

for details on the use of standard calibrators for the E/VLA.

Model images for some flux density calibrators are provided with CASA:

- Red Hat Linux RPMs 32bit (RHE4, Fedora 6): located in /usr/lib/casapy/data/nrao/VLA/CalModels
- Red Hat Linux RPMs 64bit (RHE4, Fedora 6): located in /usr/lib64/casapy/data/nrao/VLA/CalModels
- MAC OSX .dmg: located in /Applications/CASA.app/Contents/Resources/casa-data/nrao/VLA/CalModels
- NRAO-AOC casapy-test: /home/casa/data/nrao/VLA/CalModels

E.g., these are found in the data/nrao/VLA/CalModels sub-directory of the CASA installation. For example, just point to the repository copy, e.g.

    modimage = ’/usr/lib/casapy/data/nrao/VLA/CalModels/3C48_C.im’
or if you like, you can copy the ones you wish to use to your working directory.

The models available are:

- 3C138_L.im
- 3C147_L.im
- 3C286_L.im
- 3C48_L.im
- 3C138_C.im
- 3C147_C.im
- 3C286_C.im
- 3C48_C.im
- 3C138_X.im
- 3C147_X.im
- 3C286_X.im
- 3C48_X.im
- 3C138_U.im
- 3C147_U.im
- 3C286_U.im
- 3C48_U.im
- 3C138_K.im
- 3C147_K.im
- 3C286_K.im
- 3C48_K.im
- 3C138_Q.im
- 3C147_Q.im
- 3C286_Q.im
- 3C48_Q.im


These are all un-reconvolved images of AIPS CC lists. It is important that the model image not be one convolved with a finite beam; it must have units of Jy/pixel (not Jy/beam).

Note that setjy will rescale the flux in the models for known sources (e.g. those in Table 4.1) to match those it would have calculated. It will thus extrapolated the flux out of the frequency band of the model image to whatever spectral windows in the MS are specified (but will use the structure of the source in the model image).

**ALERT:** The reference position in the modimage is currently used by setjy when it does the Fourier transform, thus differences from the positions for the calibrator in the MS will show up as phase gradients in the uv-plane. If your model image position is significantly different but you don’t want this to affect your calibration, then you can doctor either the image header using imhead (§ 6.2) or in the MS (using the ms tool) as appropriate. In an upcoming release we will put in a toggle to use or ignore the position of the modimage. Note that this will not affect the flux scaling (only put in erroneous model phases); in any event small position differences, such as those arising by changing epoch from B1950 to J2000 using regridimage (§ 6.13), will be inconsequential to the calibration.

This illustrates the use of uvrange for a slightly resolved calibrator:

```python
# Import the data
importvla(archivefiles='AS776_A031015.xp2', vis='ngc7538_XBAND.ms',
          freqtol=10000000.0, bandname='X')

# Flag the ACs
flagautocorr('ngc7538_XBAND.ms')

# METHOD 1: Use point source model for 3C48, plus uvrange in solve

# Use point source model for 3C48
setjy(vis='ngc7538_XBAND.ms', fieldid='0');

# Limit 3C48 (fieldid=0) solutions to uvrange = 0-40 klambda
gaincal(vis='ngc7538_XBAND.ms', caltable='cal.G', field='0',
       solint=60.0, refant='10', selectdata=True, uvrange='0~40klambda',
       append=False)
```
# Append phase-calibrator’s solutions (no uvrange) to the same table
gaincal(vis='ngc7538_XBAND.ms', caltable='cal.G', field='2',
    solint=60.0, refant='10', selectdata=True, uvrange='',
    append=True)

# Fluxscale
fluxscale(vis='ngc7538_XBAND.ms', caltable='cal.G', reference=['0137+331'],
    transfer=['2230+697'], fluxtable='cal.Gflx', append=False)

while the following illustrates the use of of a model:

# METHOD 2: use a resolved model copied from the data repository
# for 3C48, and no uvrange
# (NB: detailed freq-dep flux scaling TBD)
# Copy the model image 3C48_X.im to the working directory first!
setjy(vis='ngc7538_XBAND.ms', field='0', modimage='3C48_X.im')

# Solutions on both calibrators with no uvrange
gaincal(vis='ngc7538_XBAND.ms', caltable='cal.G2', field='0,2',
    solint=60.0, refant='10',
    append=False)

# Fluxscale
fluxscale(vis='ngc7538_XBAND.ms', caltable='cal.G2', reference=['0137+331'],
    transfer=['2230+697'], fluxtable='cal.G2flx', append=False)

# Both methods give 2230 flux densities ~0.7 Jy, in good agreement with
# AIPS

4.3.5 Correction for delay and antenna position offsets using gencal

The gencal task provides a means of specifying antenna-based calibration values manually. The values are put in designated tables and can be applied to the data on-the-fly in solving tasks and using applycal.

The gencal task has the inputs:

# gencal :: Specify Calibration Values of Various Types
vis = ''  # Name of input visibility file
caltab = ''  # The new/existing calibration table
caltype = ''  # The calibration type: 'amp', 'ph', 'sbd', 'mbd',
    # 'antpos', 'antposvla', 'tsys', 'evlagain', 'opac',
    # 'gc', 'gceff', 'eff'
spw = ''  # Calibration spw(s) selection
antenna = ''  # Calibration antenna(s) selection
pol = ''  # Calibration polarizations(s) selection
**CHAPTER 4. SYNTHESIS CALIBRATION**

```python
parameter = [] # The calibration values
async = False # If true the taskname must be started using 
# gencal(...) 
```

Current antenna-based gencal options (caltype) are:

- `'amp'` — amplitude correction
- `'ph'` — phase correction
- `'sbd'` — single-band delay (phase-frequency slope for each spw)
- `'mbd'` — multi-band delay (phase-frequency slope over all spw)
- `'antpos'` — ITRF antenna position corrections for the Jansky VLA (automatic parameter lookup is supported)
- `'antposvla'` — old VLA-centric antenna position corrections
- `'tsys'` — Tsys from the SYSCAL table (ALMA)
- `'evlagain'` — VLA switched-power gains (experimental; equal to 'swpow')
- `'swpow'` — VLA switched power (equal to 'evlagain')
- `'rq'` — VLA requantizer gains only
- `'swp/rq'` — VLA switched-power gains divided by requantizer gain
- `'opac'` — Tropospheric opacity
- `'gc'` — Gain curve (zenith-angle-dependent gain) (VLA only) (auto-lookup only)
- `'gceff'` — Antenna efficiency (sqrt(K/Jy)) (VLA only) (auto-lookup only)
- `'eff'` — Gain curve and efficiency (VLA only) (auto-lookup only)

The calibration parameter specifications cannot be time-variable in the present implementation (though some of them will introduce implicit time-dependence upon evaluation in the apply). Calibration values can be assigned to each `spw`, `antenna` and `pol` selection, where applicable. The list of calibration values specified in `parameter` must conform to the range of spectral windows, antennas, and polarizations specified in `spw`, `antenna` and `pol`, with the values specified in order of the specified polarizations (fastest), antennas, and spectral windows (slowest). If any of `spw`, `antenna`, or `pol` are left unspecified (empty strings), the values specified in `parameter` will be assumed applicable to all values of the unspecified data axes. The output caltable will otherwise assume nominal calibration values for unspecified spectral windows, antennas, and polarizations. Note that antenna position corrections formally do not have spectral-window or polarization dependence; such specifications should not be used with `'antpos'`.
The same caltable can be specified for multiple runs of gencal, in which case the specified parameters will be incorporated cumulatively. E.g., amplitude parameters (caltype='amp') multiply and phase-like parameters ('ph', 'sbd', 'mbd', 'antpos') add. Parameters for 'amp' and 'ph' corrections can be incorporated into the same caltable (in separate runs), but each of the other types require their own unique caltable. A mechanism for specifying manual corrections via a text file will be provided in the future.

Two kinds of delay corrections are supported. For caltype='sbd', the specified delays (in nanoseconds) will be applied locally to each spectral window, referring the derived phase corrections to each spectral window's reference frequency (where the phase correction will be zero). The phases in each spectral window will nominally be flattened, but any phase offsets between spectral windows will remain. (These can be corrected using caltype='phase', or via ordinary spectral-window-dependent phase calibration.) For caltype='mbd', the evaluated phase corrections are referred to zero frequency. This causes a correction that is coherent over many spectral windows. If the data are already coherent over many spectral windows and share a common multi-band delay (e.g., VLA data, per baseband), caltype='mbd' corrections will maintain this coherence and flatten the frequency-dependent phase. Using caltype='sbd' in this instance will introduce phase offsets among spectral windows that reflect the multi-band delay.

For antenna position corrections (caltype='antpos'), the antenna position offsets are specified in the ITRF frame. If the antenna field is left empty, gencal will try to look up the appropriate antenna position offsets at the time of the observation from the VLA baseline webpage http://www.vla.nrao.edu/astro/archive/baselines/. For VLA position corrections in the VLA-centric frame, use caltype='antposvla', and gencal will rotate them to ITRF before storing them in the output caltable.

The sign and scale convention for gencal corrections (indeed for all CASA caltables) is such that the specified parameters (and as stored in caltables) are the factors that corrupt ideal data to yield the observed data. Thus, when applied to correct the data, their effective inverse will automatically be taken. I.e., amplitude factors will be divided into the data on correction. Phase-like parameters adopt the convention that the complex factor for the second antenna in the baseline is conjugated, and then both antenna factors are divided into the data on correction. (These conventions differ from AIPS in that multiplying correction factors are stored in AIPS calibration tables; however, the phase convention ends up being the same since AIPS conjugates the complex factor for the first antenna in the baseline.)

The following series of examples illustrate the use of gencal.

For the dataset 'data.ms', the following sequence of gencal runs introduces, into a single caltable ('test.G'), (1) an antenna-based amplitude scale correction of 3.0 for all polarizations, antennas, and spectral windows, (2) phase corrections for all spectral windows and polarizations of 45 and 120 degrees to antennas EA03 and EA04, respectively, (3) phase corrections for all spectral windows of 63 and -34 in R (only) for antennas EA05 and EA06, respectively, and (4) phase corrections for all spectral windows of 14, -23, -130, and 145 degrees for antenna/polarizations EA09/R, EA09/L, EA10/R, and EA10/L, respectively:

gencal(vis='data.ms', caltable='test.G', caltype='amp',


In the following example, delay corrections in both polarizations will be adjusted for antenna EA09 by 14 nsec in spw 2 and -130 nsec in spw 3, and for antenna EA10 by -23 nsec in spw 2 and 145 nsec in spw 3:

```
gencal(vis='test.ms', caltable='test.sbd', caltype='sbd', spw='2,3', antenna='EA09,EA10', pol='', parameter=[14,-23,-130,145])
```

In the following example, antenna position corrections in meters (in ITRF) for antenna EA09 (dBx=0.01, dBy=0.02, dBz=0.03) and for antenna EA10 (dBx=-0.03, dBy=-0.01, dBz=-0.02) are introduced. Note that three parameters are required for each antenna. The antenna offsets can be obtained for the 'Jansky VLA/old VLA Baseline Corrections' web page: [http://www.vla.nrao.edu/astro/archive/baselines](http://www.vla.nrao.edu/astro/archive/baselines).

The table given on this webpage has a format like:

```
; 2010 BASELINE CORRECTIONS IN METERS
;ANT ;MOVED OBSDATE Put_In_ MC(IAT) ANT PAD Bx By Bz
; JAN27 FEB12 FEB21 01:57 11 E04 0.0000 0.0000 0.0000
JAN27 FEB12 FEB21 01:57 26 W03 -0.0170 0.0204 0.0041
MAR24 MAR25 MAR26 18:28 17 W07 -0.0061 -0.0069 -0.0055
APR21 MAY02 MAY04 23:25 12 E08 -0.0072 0.0045 -0.0017
```

If your observations fall in between the 'Antenna Moved' and 'Put_In_' dates of a given antenna, you may choose to apply the offsets in that table; the 'Put_In_' time stamp marks the date where the more accurate solution was introduced in the data stream directly and no correction is required anymore. In `gencal` the offsets will be inserted as:

```
gencal(vis='test.ms', caltable='test.antpos', caltype='antpos', antenna='EA09,EA10', parameter=[0.01,0.02,0.03, -0.03,-0.01,-0.02])
```
In the following example, antenna position corrections (in the traditional VLA-centric frame) will
be introduced in meters for antenna EA09 (dBx=-0.01, dBy=-0.02, dBz=-0.03) and for antenna EA10
(dBx=-0.03, dBy=-0.01, dBz=-0.02) These offsets will be rotated to the ITRF frame before storing
them in the caltable.

\[
gencal(vis='test.ms', caltable='test.antposvla', caltype='antposvla', \ 
    antenna='EA09,EA10', \ 
    parameter=[[0.01,0.02,0.03, -0.03,-0.01,-0.02]])
\]

gencal is also the task to generate gaincurve, antenna efficiency, and opacity tables. The first two
items can be determined together with caltype='gceff' and the latter with caltype='opac'.
These tables are treated just like any other calibration table and will be carried through the
calibration steps. This method replaces the older method where 'gaincurve' and 'opacity' keywords
were present in calibration tasks such as gaincal, bandpass, or applycal.

4.3.6 Applying Jansky VLA switched power or ALMA Tsys using gencal

Noise diodes in the Jansky VLA antennas can be used to pre-calibrate the data. The diodes follow
an ON-OFF cycle and the power for both states is measured and recorded. This is called the 'VLA
switched power' calibration. To apply the switched power data, one needs to create a calibration
table with gencal using caltype='evlagain', like

\[
gencal(vis='test.ms', caltable='VLAswitchedpower.cal', caltype='evlagain')
\]

For ALMA the calibration of system temperature is done via hot loads and the data recorded
similar to the VLA in the measurement set (ALMA will provide measurement sets where these
data are available. To derive the calibration table from it, use caltype='tsys':

\[
gencal(vis='test.ms', caltable='ALMAtsys.cal', caltype='tsys')
\]

This calibration tables created for ALMA or VLA are then carried along all further calibration
steps in the gaintable parameter.

4.3.7 Generate a gain table based on Water Vapor Radiometer data wvrgcal

```bash
# wvrgcal :: Generate a gain table based on Water Vapour Radiometer data
vis = '' # Name of input visibility file
caltable = '' # Name of output gain calibration table
toffset = -1 # Time offset (sec) between interferometric and WVR data
segsource = True # Do a new coefficient calculation for each source
tie = [] # Prioritise tieing the phase of these sources as well as possible
    # (requires segsource=True)
sourceflag = [] # Flag the WVR data for these source(s) as bad and do not produce
```
The task `wvrgcal` generates a gain table based on Water Vapor Radiometer (WVR) data and is used for ALMA data reduction. It is an interface to the executable “wvrgcal” which is part of the CASA 4.0 distribution and can also be called from outside CASA. The wvrgcal software is based on the libair and libbnmin libraries which were developed by Bojan Nikolic at the University of Cambridge as part of EU FP6 ALMA Enhancement program.

CASA 4.0 contains version 1.2.1 of wvrgcal. Source code of the stand-alone package and links to documentation can be found at [http://www.mrao.cam.ac.uk/~bn204/alma/wvrsoft.html](http://www.mrao.cam.ac.uk/~bn204/alma/wvrsoft.html). In particular, there are three ALMA memos (number 587, 588, and 593 (submitted)) which describe the algorithms implemented in the software. They can be found at [http://www.alma.cl/almamemos](http://www.alma.cl/almamemos). The only recently submitted memo 593 can be found at [http://xxx.lanl.gov/pdf/1207.6069](http://xxx.lanl.gov/pdf/1207.6069).

Briefly, wvrgcal follows a Bayesian approach to calculate the coefficients that convert the outputs of the ALMA 183 GHz water-vapor radiometers (mounted on each antenna) into estimates of path fluctuations which can then be used to correct the observed interferometric visibilities.

The CASA task interface to wvrgcal follows closely the interface of the shell executable at the same time staying within the CASA task parameter conventions.

In ALMA data, the WVR measurements belonging to a given observation are contained in the ASDM for that observation. After conversion to an MS using `importasdm`, the WVR information can be found in separate spectral windows (as of September 2012, it is still spectral window id 0). This spectral window must be present in the MS for wvrgcal to work.

The various features of wvrgcal are then controlled by a number of task parameters (see the list above). They have default values which will work for ALMA data. An example for a typical wvrgcal call can be found in the ALMA CASA guide for the NGC 3256 analysis:

```python
wvrgcal(vis='uid___A002_X1d54a1_X5.ms', caltable='cal-wvr-uid___A002_X1d54a1_X5.W',
        toffset=-1, segsource=True, tie=['Titan,1037-295,NGC3256'],
        statsource='1037-295')
```

Here, `vis` is the name of input visibility file (which as mentioned above also contains the WVR data in spectral window 0) and `caltable` is the name of the output gain calibration table.
toffset is the known time offset in seconds between the WVR measurements and the visibility integrations they are valid for. For ALMA, this offset is presently -1 s (which is also the default value).

The parameter segsource (segregate source) controls whether separate coefficients are calculated for each source. The default value True is the recommended one for ALMA. When segsource is True, the subparameter tie is available. It permits to form groups of sources for which common coefficients are calculated as well as possible. The tie parameter ensures best possible phase transfer between a group of sources. In general it is recommended to tie together all of the sources in a single Science Goal (in ALMA speak) and their phase calibrator(s). The recommended maximum angular distance up to which two sources can be tied is 15°.

Finally, the parameter statsource controls for which sources statistics are calculated and displayed in the logger. This has no influence on the generated calibration table. See the online help of wvrgcal for a brief explanation of the other parameters.

4.3.7.1 Statistical parameters shown in the logger output of wvrgcal

wvrgcal writes out a variety of information to the logger, including various statistical measures of the performance. This allows the user to judge whether WVR correction is appropriate for the ms, to check whether any antennas have problematic WVR values, and to examine the predicted performance of the WVR correction when applied.

For each set of correction coefficients which are calculated (the number of coefficient sets are controlled by the parameters nsol, segsource and tie), the wvrgcal output to the logger first of all shows the time sample, the individual temperatures of each of the four WVR channels and the elevation of the source in question at that time.

For each of these coefficient sets, it then gives the evidence of the bayesian parameter estimation, the calculated precipitable water vapour (PWV) and its error in mm, and the correction coefficients found for each WVR channel (dTdL).

The output then shows the statistical information about the observation. First of all it gives the start and end times for the parts of the observation used to calculate these statistics (controlled by segsource). It then shows a break down for each of the antennas in the data set. This gives the antenna name and number; whether or not it has a WVR (column WVR); whether or not it has been flagged (column FLAG); the RMS of the path length variation with time towards that antenna (column RMS); and the discrepancy between the RMS path length calculated separately for different WVR channels (column Disc.). These values allow the user to see if an individual WVR appears to have been suffering from problems during the observation, and to flag that antenna using wvrflag if necessary.

This discrepancy value, Disc., can in addition be used as a simple diagnostic tool to evaluate whether or not the WVR correction caltable created by wvrgcal should be applied. In the event of the WVR observations being contaminated by strong cloud emission in the atmosphere, the attempt by wvrgcal to fit the water vapour line may not be successful, and applying the produced calibration table can in extremem cases reduce the quality of the data. However, these weather
conditions should identified by a high value in the discrepancy column produced when running `wvrgcal`.

Although there have not currently been enough cases checked to give definitive limits, the available data sets as of summer 2012 suggest that discrepancy values of greater than a 1000 microns usually indicate strong cloud contamination of the WVR data, and the output calibration table should probably not be applied. If the values are between 100 and 1000 microns, then the user should manually examine the phases before and after applying the caltable to decide if WVR correction is appropriate.

After the antenna-by-antenna statistics, the output then displays some estimates of the performance of the `wvrgcal` correction. These are the thermal contribution from the water vapour to the path fluctuations per antenna (in microns), the largest path fluctuation found on a baseline (in microns), and the expected error on the path length calculated for each baseline due to the error in the coefficients (in microns).

### 4.3.8 Other \textit{a priori} Calibrations and Corrections

Other \textit{a priori} calibrations will be added to the `calibrater` (cb) tool in the near future. These will include instrumental line-length corrections, ionospheric corrections, etc. Where appropriate, solving capabilities for these effects will also be added.

### 4.4 Solving for Calibration — Bandpass, Gain, Polarization

The `gaincal`, `bandpass`, `polcal`, and `blcal` tasks actually solve for the unknown calibration parameters from the visibility data obtained on calibrator sources, placing the results in a calibration table. They take as input an MS, and a number of parameters that specify any prior calibration or previous calibration tables to pre-apply before computing the solution. These are placed in the proper sequence of the Measurement Equation automatically.

We first discuss the parameters that are in common between many of the calibration tasks. Then we describe each solver in turn.

#### 4.4.1 Common Calibration Solver Parameters

There are a number of parameters that are in common between the calibration “solver” tasks. These also appear in some of the other calibration manipulation and application tasks.

##### 4.4.1.1 Parameters for Specification : \texttt{vis} and \texttt{caltable}

The input measurement set and output table are controlled by the following parameters:

```plaintext
vis       =       ''       # Name of input visibility file  
caltable  =       ''       # Name of output calibration table
```
The MS name is input in `vis`. If it is highlighted red in the inputs (§1.4.5.4) then it does not exist, and the task will not execute. Check the name and path in this case.

The output table name is placed in `caltable`. Be sure to give a unique name to the output table, or be careful. If the table exists, then what happens next will depend on the task and the values of other parameters (e.g. §4.4.1.6). The task may not execute giving a warning that the table already exists, or will go ahead and overwrite the solutions in that table, or append them. Be careful.

### 4.4.1.2 Selection: field, spw, selectdata, intent, and observation

Selection is controlled by the parameters:

```plaintext
field = '' # field names or index of calibrators: ''==>all
spw = '' # spectral window:channels: ''==>all
intent = '' # Select observing intent
selectdata = False # Other data selection parameters
```

Field and spectral window selection are so often used, that we have made these standard parameters `field` and `spw` respectively. `intent` is the scan intent that was specified when the observations were set up. They typically describe what was intended with a specific scan, i.e. a flux or phase calibration, a bandpass, a pointing, an observation of your target, or something else or a combination. The format for the scan intents of your observations are listed in the logger when you run `listobs`. Minimum matching with wildcards will work, like '*BANDPASS*'. This is especially useful when multiple intents are attached to scans. Finally, `observation` is an identifier to distinguish between different observing runs, mainly used for ALMA.

The `selectdata` parameter expands as usual, uncovering other selection sub-parameters:

```plaintext
selectdata = True # data selection parameters
field = '' # field names or field index numbers (blank for all)
spw = '' # spectral windows:channels (blank for all)
timerange = '' # time range (blank for all)
uvrange = '' # uv range (blank for all)
antenna = '' # antenna/baselines (blank for all)
scan = '' # scan numbers (blank for all)
correlation = '' # correlations (blank for all)
array = '' # (sub)array numbers (blank for all)
observation = '' # Select by observation ID(s)
msselect = '' # MS selection (blank for all)
```

Note that if `selectdata=False` these parameters are not used when the task is executed, even if set underneath.

The most common `selectdata` parameter to use is `uvrange`, which can be used to exclude longer baselines if the calibrator is resolved, or short baselines of the calibrator contains extended flux not accounted for in the model (e.g. §4.3.4.1).

See §2.3 for more on the selection parameters.
4.4.1.3 Prior Calibration and Correction: parang

These parameters control the on-the-fly application of various calibration or effect-based corrections prior to the solving process.

The `parang` parameter turns on the application of the antenna-based parallactic angle correction (\(P\)) in the measurement equation. This is necessary for polarization calibration and imaging, or for cases where the parallactic angles are different for geographically spaced antennas and it is desired that the ordinary gain calibration not absorb the inter-antenna parallactic angle phase. When dealing with only the parallel-hand data (e.g. RR, LL, XX, YY), and an unpolarized calibrator model for a co-located array (e.g. the VLA or ALMA), you can set `parang=False` and save some computational effort. Otherwise, set `parang=True` to apply this correction.

See §4.3 for more on Prior Calibration, including how to invoke `gaincurve` and `opacity` correction using `gencal`.

4.4.1.4 Previous Calibration: gaintable, gainfield, interp and spwmap

Calibration tables that have already been determined can also be applied before solving for the new table:

```python

gaintable = ''  # Prior gain calibration table(s) to apply
gainfield = ''  # Field selection on prior gaintable(s)
interp = ''     # Interpolation mode (in time) for prior gaintable(s)
spwmap = []     # Spectral window mapping for each gaintable (see help)
```

This is controlled by the `gaintable` parameter, which takes a string or list of strings giving one or more calibration tables to pre-apply. For example,

```python

gaintable = ['ngc5921.bcal','ngc5921.gcal']
```

specifies two tables, in this case bandpass and gain calibration tables respectively.

The other parameters key off `gaintable`, taking single values or lists, with an entry for each table in `gaintable`. The order is given by that in `gaintable`.

The `gainfield` parameter specifies which fields from the respective `gaintable` to select for apply. This is a list, with each entry a string or list of strings. The default `' '` for an entry means to use all in that table. For example,

```python

gaintable = ['ngc5921.bcal','ngc5921.gcal']
gainfield = ['1331+305', ['1331+305','1445+099']]
```

or using indices

```python

gainfield = ['0', ['0','1']]
```
to specify the field '1331+305' from the table 'ngc5921.bcal' and fields '1331+305' and '1445+099' from the second table 'ngc5921.gcal'. We could also have wildcarded the selection, e.g.

\[
\text{gainfield} = [ '0', '*']
\]

taking all fields from the second table. And of course we could have used the default

\[
\text{gainfield} = [ '0', '' ]
\]
or even

\[
\text{gainfield} = [ '0' ]
\]

which is to take all for the second table in \text{gaintable}. In addition, \text{gainfield} can be specified by

\[
\text{gainfield} = [ '\text{nearest}' ]
\]

which selects the calibrator that is the spatially closest (in sky coordinates) to each of the selected MS fields specified in the \text{field} parameter. This is particularly useful for running \text{applycal} with a number of different sources to be calibrated in a single run.

The \text{interp} parameter chooses the interpolation scheme to be used when pre-applying the solution in the tables. Interpolation in both time and frequency (for channel-dependent calibrations) are supported. The choices are currently 'nearest' and 'linear', and 'nearest', 'linear', cubic, and \text{spline} for frequency-dependent interpolation. Frequency-dependent interpolation is only relevant for channel-dependent calibration tables (like bandpasses) that are undersampled in frequency relative to the data.

- 'nearest' just picks the entry nearest in time or freq to the visibility in question;

- 'linear' interpolation calibrates each datum with calibration phases and amplitudes linearly interpolated from neighboring values. In the case of phase, this mode will assume that phase never jumps more than 180° between neighboring points, and so undersampled cycle-slips will not be corrected for. Solutions will not be \text{extrapolated} arbitrarily in time or frequency for data before the first solution or after the last solution; such data will be calibrated using 'nearest' to avoid unreasonable extrapolations.

- 'cubic' interpolation forms a 3rd-order polynomial that passes through the nearest 4 calibration samples (separately in phase and amplitude

- 'spline' interpolation forms a cubic spline that passes through the nearest 4 calibration samples (separately in phase and amplitude

For each gaintable, specify the interpolation style in quotes, with the frequency-dependent interpolation style specified after a comma, if relevant.

If the uncalibrated phase is changing rapidly, a 'nearest' interpolation is not desirable. Usually, \text{interp='linear'} is the best choice. For example,
CHAPTER 4. SYNTHESIS CALIBRATION

```python
gaintable=['gain','bandpass']
interp = ['nearest', 'linear', 'spline']
```

uses nearest “interpolation” on the first table, and linear (in time) and spline (in freq) on the second.

The `spwmap` parameter sets the spectral window combinations to form for the `gaintable(s)`. This is a list, or a list of lists, of integers giving the `spw` IDs to map. There is one list for each table in `gaintable`, with an entry for each ID in the MS. For example,

```python
spwmap=[0,0,1,1] # apply from spw=0 to 0,1 and 1 to 2,3
```

for an MS with `spw=0,1,2,3`. For multiple `gaintable`, use lists of lists, e.g.

```python
spwmap=[[0,0,1,1], [0,1,0,1]] # 2nd table spw=0 to 0,2 and 1 to 1,3
```

4.4.1.5 Solving: `solint`, `combine`, `preavg`, `refant`, `minblperant`, `minsnr`

The parameters controlling common aspects of the solution are:

```python
solint = 'inf'  # Solution interval: e.g. 'inf', '60s' (see help)
combine = 'scan'  # Data axes which to combine for solve (obs, scan, spw, and/or field)
preavg = -1.0  # Pre-averaging interval (sec) (rarely needed)
refant = ''  # Reference antenna name(s)
minblperant = 4  # Minimum baselines _per antenna_ required for solve
minsnr = 3.0  # Reject solutions below this SNR
```

The time and frequency (if relevant) solution interval is given by `solint`. Optionally a frequency interval for each solution can be added after a comma, e.g. `solint='60s,300Hz'`. Time units are in seconds unless specified differently. Frequency units can be either channels or Hz and only make sense for bandpass of frequency dependent polarization calibration. The special values 'inf' and -1 specify an “infinite” solution interval encompassing the entire dataset, while 'int' or zero specify a solution every integration. You can use time quanta in the string, e.g. `solint='1min'` and `solint='60s'` both specify solution intervals of one minute. Note that 'm' is a unit of distance (meters); 'min' must be used to specify minutes. The `solint` parameter interacts with `combine` to determine whether the solutions cross scan or field boundaries.

The parameter controlling the scope of the solution is `combine`. For the default `combine='''`, solutions will break at `obsId`, `scan`, `field`, and `spw` boundaries. Specification of any of these in `combine` will extend the solutions over the boundaries (up to the `solint`). For example, `combine='spw'` will combine spectral windows together for solving, while `combine='scan'` will cross scans, and `combine='obs,scan'` will use data across different observation IDs and scans (usually, `obsIds` consist of many scans, so it is not meaningful to combine `obsIds` without also combining scans). Thus, to do scan-based solutions (single solution for each scan), set

```python
solint = 'inf'
combine = ''
```
while

```python
    solint = 'inf'
    combine = 'scan'
```

will make a single solution for the entire dataset (for a given field and spw).

```python
    solint = 'inf,30ch'
```

will calculate a bandpass solution for each scan, averaging over 30 channels.

You can specify multiple choices for combination:

```python
    combine = 'scan,spw'
```

for example.

The reference antenna is specified by the `refant` parameter. A list of antennas can be provided to this parameter and if the first antenna is not present in the data, the next antenna in the list will be used, etc. It is useful to “lock” the solutions with time, effectively rotating (after solving) the phase of the gain solutions for all antennas such that the reference antenna’s phase is constant at zero. If the selected antenna drops out, another antenna will be selected for ongoing consistency in time (at its “current” value) until the refant returns, usually at a new value (not zero), which will be kept fixed thenceforth. You can also run without a reference antenna, but in this case the solutions will formally float with time; in practice, the first antenna will be approximately constant near zero phase. It is usually prudent to select an antenna in the center of the array that is known to be particularly stable, as any gain jumps or wanders in the `refant` will be transferred to the other antenna solutions. Also, it is best to choose a reference antenna that never drops out.

Setting a `preavg` time (only needed in `polcal`) will let you average data over periods shorter than the solution interval first before solving on longer timescales.

The minimum signal-to-noise ratio allowed for an acceptable solution is specified in the `minsnr` parameter. Default is `minsnr=3`. The `minblperant` parameter sets the minimum number of baselines to other antennas that must be preset for a each antenna to be included in a solution. This enables control of the constraints that a solution will require for each antenna.

### 4.4.1.6 Action: append and solnorm

The following parameters control some things that happen after solutions are obtained:

```python
solnorm = False # Normalize solution amplitudes post-solve.
append = False # Append solutions to (existing) table. False will overwrite.
```

The `solnorm` parameter toggles on the option to normalize the solution after the solutions are obtained. The exact effect of this depends upon the type of solution. Not all tasks use this parameter.
CHAPTER 4. SYNTHESIS CALIBRATION

One should be aware when using `solnorm` that if this is done in the last stage of a chain of calibration, then the part of the calibration that is “normalized” away will be lost. It is best to use this in early stages (for example in a first bandpass calibration) so that later stages (such as final gain calibration) can absorb the lost normalization scaling. It is not strictly necessary to use `solnorm=True` at all, but is sometimes helpful if you want to have a normalized bandpass for example.

The `append` parameter, if set to `True`, will append the solutions from this run to existing solutions in `caltable`. Of course, this only matters if the table already exists. If `append=False` and `caltable` exists, it will overwrite.

4.4.2 Spectral Bandpass Calibration (bandpass)

For channelized data, it is usually desirable to solve for the gain variations in frequency as well as in time. Variation in frequency arises as a result of non-uniform filter passbands or other frequency-dependent effects in signal transmission. It is usually the case that these frequency-dependent effects vary on timescales much longer than the time-dependent effects handled by the gain types ‘G’ and ‘T’. Thus, it makes sense to solve for them as a separate term: ‘B’, using the `bandpass` task.

The inputs to `bandpass` are:

```python
# bandpass :: Calculates a bandpass calibration solution
vis = '' # Name of input visibility file
caltab = '' # Name of output gain calibration table
field = '' # Select field using field id(s) or field name(s)
spw = '' # Select spectral window/channels
intent = '' # Select observing intent
selectdata = False # Other data selection parameters
solint = 'inf' # Solution interval
combine = 'scan' # Data axes which to combine for solve (scan, spw, # and/or field)
refant = '' # Reference antenna name(s)
minblperant = 4 # Minimum baselines _per antenna_ required for solve
minsnr = 3.0 # Reject solutions below this SNR (only applies for # bandtype = B)
solnorm = False # Normalize average solution amplitudes to 1.0
bandtype = 'B' # Type of bandpass solution (B or BPOLY)
fillgaps = 0 # Fill flagged solution channels by interpolation
append = False # Append solutions to the (existing) table
gaintab = ['] # Gain calibration table(s) to apply on the fly
gainfield = ['] # Select a subset of calibrators from gaintable(s)
interp = ['] # Interpolation mode (in time) to use for each gaintable
spwmap = [] # Spectral windows combinations to form for # gaintables(s)
gaincurve = False # Apply internal VLA antenna gain curve correction
opacity = [] # Opacity correction to apply (nepers), per spw
parang = False # Apply parallactic angle correction
```
Many of these parameters are in common with the other calibration tasks and are described above in §4.4.1.

The `bandtype` parameter selects the type of solution used for the bandpass. The choices are 'B' and 'BPOLY'. The former solves for a complex gain in each channel in the selected part of the MS. See §4.4.2.2 for more on 'B'. The latter uses a polynomial as a function of channel to fit the bandpass, and expands further to reveal a number of sub-parameters See §4.4.2.3 for more on 'BPOLY'.

It is usually best to solve for the bandpass in channel data before solving for the gain as a function of time. However, if the gains of the bandpass calibrator observations are fluctuating over the timerange of those observations, then it can be helpful to first solve for the gains of that source with `gaincal`, and input these to `bandpass` via `gaintable`. See more below on this strategy.

We now describe the issue of bandpass normalization, followed by a description of the options `bandtype='B'` and `bandtype='BPOLY'`.

### 4.4.2.1 Bandpass Normalization

The `solnorm` parameter (§4.1.6) deserves more explanation in the context of the bandpass. Most users are used to seeing a normalized bandpass, where the mean amplitude is unity and fiducial phase is zero. The toggle `solnorm=True` allows this. However, the parts of the bandpass solution normalized away will be still left in the data, and thus you should not use `solnorm=True` if the `bandpass` calibration is the end of your calibration sequence (e.g. you have already done all the gain calibration you want to). Note that setting `solnorm=True` will NOT rescale any previous calibration tables that the user may have supplied in `gaintable`.

You can safely use `solnorm=True` if you do the bandpass first (perhaps after a throw-away initial gain calibration) as we suggest above in §4.2, as later gain calibration stages will deal with this remaining calibration term. This does have the benefit of isolating the overall (channel independent) gains to the following `gaincal` stage. It is also recommended for the case where you have multiple scans on possibly different bandpass calibrators. It may also be preferred when applying the bandpass before doing `gaincal` and then `fluxscale` (§4.4.4), as significant variation of bandpass among antennas could otherwise enter the gain solution and make (probably subtle) adjustments to the flux scale.

We finally note that `solnorm=False` at the bandpass step in the calibration chain will still in the end produce the correct results. It only means that there will be a part of what we usually think of the gain calibration inside the bandpass solution, particularly if `bandpass` is run as the first step.

### 4.4.2.2 B solutions

Calibration type 'B' differs from 'G' only in that it is determined for each channel in each spectral window. It is possible to solve for it as a function of time, but it is most efficient to keep the 'B'
solving timescale as long as possible, and use 'G' or 'T' for frequency-independent rapid time-scale variations.

The 'B' solutions are limited by the signal-to-noise ratio available per channel, which may be quite small. It is therefore important that the data be coherent over the time-range of the 'B' solutions. As a result, 'B' solutions are almost always preceded by an initial 'G' or 'T' solve using gaincal (§4.4.3). In turn, if the 'B' solution improves the frequency domain coherence significantly, a 'G' or 'T' solution following it will be better than the original.

For example, to solve for a 'B' bandpass using a single short scan on the calibrator, then

```python
default('bandpass')
vis = 'n5921.ms'
caltab = 'n5921.bcal'
gaintab = '' # No gain tables yet
gainfield = ''
interp = ''
field = '0' # Calibrator 1331+305 = 3C286 (FIELD_ID 0)
spw = '' # all channels
selectdata = False # No other selection
gaincurve = False # No gaincurve at L-band
opacity = 0.0 # No troposphere
bandtype = 'B' # standard time-binned B (rather than BPOLY)
solint = 'inf' # set solution interval arbitrarily long
refant = '15' # ref antenna 15 (=VLA:N2) (ID 14)
bandpass()
```

On the other hand, we might have a number of scans on the bandpass calibrator spread over time, but we want a single bandpass solution. In this case, we could solve for and then pre-apply an initial gain calibration, and let the bandpass solution cross scans:

```python
gaintab = 'n5921.init.gcal' # Our previously determined G table
gainfield = '0'
interp = 'linear' # Do linear interpolation
solint = 'inf' # One interval over dataset
combine = 'scan' # Solution crosses scans
```

Note that we obtained a bandpass solution for all channels in the MS. If explicit channel selection is desired, for example some channels are useless and can be avoided entirely (e.g. edge channels or those dominated by Gibbs ringing), then `spw` can be set to select only these channels, e.g.

```python
spw = '0:4~59' # channels 4-59 of spw 0
```

This is not so critical for 'B' solutions as for 'BPOLY', as each channel is solved for independently, and poor solutions at edges can be ignored.

If you have multiple time solutions, then these will be applied using whatever time interpolation scheme is specified in later tasks.
The `combine` parameter (§4.4.1.5) can be used to combine data across spectral windows, scans, and fields.

### 4.4.2.3 BPOLY solutions

For some observations, it may be the case that the SNR per channel is insufficient to obtain a usable per-channel 'B' solution. In this case it is desirable to solve instead for a best-fit functional form for each antenna using the `bandtype='BPOLY'` solver. The 'BPOLY' solver naturally enough fits (Chebychev) polynomials to the amplitude and phase of the calibrator visibilities as a function of frequency. Unlike ordinary 'B', a single common 'BPOLY' solution will be determined for all spectral windows specified (or implicit) in the selection. As such, it is usually most meaningful to select individual spectral windows for 'BPOLY' solves, unless groups of adjacent spectral windows are known *a priori* to share a single continuous bandpass response over their combined frequency range (e.g., PdBI data).

The 'BPOLY' solver requires a number of unique sub-parameters:

```plaintext
bandtype = 'BPOLY' # Type of bandpass solution (B or BPOLY)
degamp = 3 # Polynomial degree for BPOLY amplitude solution
dephease = 3 # Polynomial degree for BPOLY phase solution
visnorm = False # Normalize data prior to BPOLY solution
maskcenter = 0 # Number of channels in BPOLY to avoid in center of band
maskedge = 0 # Percent of channels in BPOLY to avoid at each band edge
```

The `degamp` and `dephase` parameters indicate the polynomial degree desired for the amplitude and phase solutions. The `maskcenter` parameter is used to indicate the number of channels in the center of the band to avoid passing to the solution (e.g., to avoid Gibbs ringing in central channels for PdBI data). The `maskedge` drops beginning and end channels. The `visnorm` parameter turns on normalization before the solution is obtained (rather than after for `solnorm`).

The `combine` parameter (§4.4.1.5) can be used to combine data across spectral windows, scans, and fields.

Note that `bandpass` will allow you to use multiple `fields`, and can determine a single solution for all specified fields using `combine='field'`. If you want to use more than one field in the solution it is prudent to use an initial `gaincal` using proper flux densities for all sources (not just 1Jy) and use this table as an input to bandpass because in general the phase towards two (widely separated) sources will not be sufficiently similar to combine them, and you want the same amplitude scale. If you do not include amplitude in the initial `gaincal`, you probably want to set `visnorm=True` also to take out the amplitude normalization change. Note also in the case of multiple `fields`, that the 'BPOLY' solution will be labeled with the field ID of the first `field` used in the 'BPOLY' solution, so if for example you point `plotcal` at the name or ID of one of the other fields used in the solution, `plotcal` does not plot.

For example, to solve for a 'BPOLY' (5th order in amplitude, 7th order in phase), using data from field 2, with G corrections pre-applied:
4.4.3 Complex Gain Calibration (gaincal)

The fundamental calibration to be done on your interferometer data is to calibrate the antenna-based gains as a function of time. Some of these calibrations are known beforehand (“a priori”) and others must be determined from observations of calibrators, or from observations of the target itself (“self-calibration”).

It is best to have determined a (constant or slowly-varying) “bandpass” from the frequency channels by solving for the bandpass (see above). Thus, the `bandpass` calibration table would be input to `gaincal` via the `gaintable` parameter (see below).

The `gaincal` task has the following inputs:

```
gaincal :: Determine temporal gains from calibrator observations
vis = '' # Name of input visibility file
caltagle = '' # Name of output gain calibration table
field = '' # Select field using field id(s) or field name(s)
spw = '' # Select spectral window/channels
intent = '' # Select observing intent
selectdata = False # Other data selection parameters
solint = 'inf' # Solution interval: egs. 'inf', '60s' (see help)
combine = 'scan' # Data axes which to combine for solve (scan, spw, # and/or field)
preavg = -1.0 # Pre-averaging interval (sec) (rarely needed)
refant = '' # Reference antenna name(s)
minblperant = 4 # Minimum baselines _per antenna_ required for solve
minsnr = 3.0 # Reject solutions below this SNR
solnorm = False # Normalize average solution amplitudes to 1.0 (G, T # only)
gaintype = 'G' # Type of gain solution (G,T,GSPLINE,K,KCROSS)
smodel = [] # Point source Stokes parameters for source model.
calmode = 'ap' # Type of solution: ('ap', 'p', 'a')
append = False # Append solutions to the (existing) table
gaintable = [] # Gain calibration table(s) to apply on the fly
gainfield = [] # Select a subset of calibrators from gaintable(s)
interp = [] # Temporal interpolation for each gaintable (=linear)
spwmap = [] # Spectral windows combinations to form for # gaintables(s)
gaincurve = False # Apply internal VLA antenna gain curve correction
```
CHAPTER 4. SYNTHESIS CALIBRATION

opacity = [] # Opacity correction to apply (nepers), per spw
parang = False # Apply parallactic angle correction on the fly
async = False # If true the taskname must be started using gaincal(...)

Data selection is done through the standard field, spw, intent, and selectdata expandable subparameters (see § 2.3). The bulk of the other parameters are the standard solver parameters. See § 4.4.1 above for a description of these.

The gaintype parameter selects the type of gain solution to compute. The choices are 'T', 'G', and 'GSPLINE'. The 'G' and 'T' options solve for independent complex gains in each solution interval (classic AIPS style), with 'T' enforcing a single polarization-independent gain for each co-polar correlation (e.g. RR and LL, or XX and YY), and 'G' having independent gains for these. See § 4.4.3.1 for a more detailed description of 'G' solutions, and § 4.4.3.2 for more on 'T'. The 'GSPLINE' fits cubic splines to the gain as a function of time. See § 4.4.3.3 for more on this option.

4.4.3.1 Polarization-dependent Gain (G)

Systematic time-dependent complex gain errors are almost always the dominant calibration effect, and a solution for them is almost always necessary before proceeding with any other calibration. Traditionally, this calibration type has been a catch-all for a variety of similar effects, including: the relative amplitude and phase gain for each antenna, phase and amplitude drifts in the electronics of each antenna, amplitude response as a function of elevation (gain curve), and tropospheric amplitude and phase effects. In CASA, it is possible to handle many of these effects separately, as available information and circumstances warrant, but it is still possible to solve for the net effect using calibration type G.

Generally speaking, type G can represent any per-spectral window multiplicative polarization- and time-dependent complex gain effect downstream of the polarizers. (Polarization- and time-independent effects upstream of the polarizers may also be treated implicitly with G.) Multi-channel data (per spectral window) will be averaged in frequency before solving (use calibration type B to solve for frequency-dependent effects within each spectral window).

To solve for G on, say, fields 1 & 2, on a 90s timescale, and do so relative to gaincurve corrections:

gaincal('data.ms',
caltab='cal.G', # Write solutions to disk file 'cal.G'
field='0,1', # Restrict field selection
solint=90.0, # Solve for phase and amp on a 90s timescale
gaincurve=True # Note: gaincurve=False by default
refant='3') #

plotcal('cal.G','amp') # Inspect solutions

These G solution will be referenced to antenna 4. Choose a well-behaved antenna that is located near the center of the array and is ever-present for the reference antenna. For non-polarization datasets, reference antennas need not be specified although you can if you want. If no reference
antenna is specified, an effective phase reference that is an average over the data will be calculated and used. For data that requires polarization calibration, you must choose a reference antenna that has a constant phase difference between the right and left polarizations (e.g. no phase jumps or drifts). If no reference antenna (or a poor one) is specified, the phase reference may have jumps in the R–L phase, and the resulting polarization angle response will vary during the observation, thus corrupting the polarization imaging.

To apply this solution to the calibrators (fields 0,1) and the target source (field 2):

```python
applycal('data.ms',
    field='0,1,2', # Restrict field selection (cals + src)
    opacity=0.0, # Don't apply opacity correction
    gaintable='cal.G') # Apply G solutions and correct data
```

```
plotxy('data.ms',xaxis='channel',datacolum='data',subplot=211)
plotxy('data.ms',xaxis='channel',datacolum='corrected',subplot=212)
```

The calibrated data is written to the CORRECTED_DATA column, with calwt=True by default. This parameter can also be a list of Boolean values for which each entry then controls the calculation of weights based on each individual input calibration table.

**Alert:** Current (as of June 2010) VLA data has no weights to the data. To avoid trouble, calwt=False should be set for those data sets. Older VLA data should still be calibrated with calwt=True.

### 4.4.3.2 Polarization-independent Gain (T)

At high frequencies, it is often the case that the most rapid time-dependent gain errors are introduced by the troposphere, and are polarization-independent. It is therefore unnecessary to solve for separate time-dependent solutions for both polarizations, as is the case for 'G'. Calibration type 'T' is available to calibrate such tropospheric effects, differing from 'G' only in that a single common solution for both polarizations is determined. In cases where only one polarization is observed, type 'T' is adequate to describe the time-dependent complex multiplicative gain calibration.

In the following example, we assume we have a 'G' solution obtained on a longish timescale (longer than a few minutes, say), and we want a residual 'T' solution to track the polarization-independent variations on a very short timescale:

```python
gaincal('data.ms',
    caltable='cal.T', # Specify output table name
    gaintype='T', # Solve for T
    field='0,1', # Restrict data selection to calibrators
    solint=3.0, # Obtain solutions on a 3s timescale
    gaintable='cal120.G') # Pre-apply prior G solution
```

For dual-polarization observations, it will always be necessary to obtain a 'G' solution to account for differences and drifts between the polarizations (which traverse different electronics), but solutions
for rapidly varying polarization-independent effects such as those introduced by the troposphere
will be optimized by using 'T'. Note that 'T' can be used in this way for self-calibration purposes,
too.

4.4.3.3 GSPLINE solutions

At high radio frequencies, where tropospheric phase fluctuates rapidly, it is often the case that
there is insufficient signal-to-noise ratio to obtain robust 'G' or 'T' solutions on timescales short
enough to track the variation. In this case it is desirable to solve for a best-fit functional form for
each antenna using the 'GSPLINE' solver. This fits a time-series of cubic B-splines to the phase
and/or amplitude of the calibrator visibilities.

The combine parameter (§4.4.1.5) can be used to combine data across spectral windows, scans, and
fields. Note that if you want to use combine='field', then all fields used to obtain a 'GSPLINE'
amplitude solution must have models with accurate relative flux densities. Use of incorrect relative
flux densities will introduce spurious variations in the 'GSPLINE' amplitude solution.

The 'GSPLINE' solver requires a number of unique additional parameters, compared to ordinary
'G' and 'T' solving. The sub-parameters are:

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Value</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>gaintype</td>
<td>'GSPLINE'</td>
<td>Type of solution (G, T, or GSPLINE)</td>
</tr>
<tr>
<td>splinetime</td>
<td>3600.0</td>
<td>Spline (smooth) timescale (sec), default=1 hours</td>
</tr>
<tr>
<td>npointaver</td>
<td>3</td>
<td>Points to average for phase wrap (okay)</td>
</tr>
<tr>
<td>phasewrap</td>
<td>180</td>
<td>Wrap phase when greater than this (okay)</td>
</tr>
</tbody>
</table>

The duration of each spline segment is controlled by splinetime. The actual splinetime will be
adjusted such that an integral number of equal-length spline segments will fit within the overall
range of data.

Phase splines require that cycle ambiguities be resolved prior to the fit; this operation is controlled
by npointaver and phasewrap. The npointaver parameter controls how many contiguous points
in the time-series are used to predict the cycle ambiguity of the next point in the time-series, and
phasewrap sets the threshold phase jump (in degrees) that would indicate a cycle slip. Large values
of npointaver improve the SNR of the cycle estimate, but tend to frustrate ambiguity detection if
the phase rates are large. The phasewrap parameter may be adjusted to influence when cycles are
detected. Generally speaking, large values (> 180°) are useful when SNR is high and phase rates
are low. Smaller values for phasewrap can force cycle slip detection when low SNR conspires to
obscure the jump, but the algorithm becomes significantly less robust. More robust algorithms for
phase-tracking are under development (including fringe-fitting).

For example, to solve for 'GSPLINE' phase and amplitudes, with splines of duration 600 seconds,

```python
gaincal('data.ms',
      caltable='cal.spline.ap',
      gaintype='GSPLINE'       # Solve for GSPLINE
      calmode='ap'             # Solve for amp & phase
      field='0,1',             # Restrict data selection to calibrators
      splinetime=600.)        # Set spline timescale to 10min
```
ALERT: The 'GSPLINE' solutions can not yet be used in fluxscale. You should do at least some 'G' amplitude solutions to establish the flux scale, then do 'GSPLINE' in phase before or after to fix up the short timescale variations. Note that the “phase tracking” algorithm in 'GSPLINE' needs some improvement.

4.4.3.4 Antenna Delays — 'K' solutions

gaintype='K' solves for simple antenna-based single-band delays via Fourier transforms of the spectra on baselines to the reference antenna. This is not a global fringe fit but will be useful for deriving delays from data of reasonable snr. A subsequent bandpass is recommended to describe higher-order channel-dependent variation in the phase (and amplitude).

4.4.3.5 Cross-Hand Delays — 'KROSS' solutions

gaintype='KROSS' solves for a global cross-hand delay. Use parang=T and apply prior gain and bandpass solutions.

4.4.4 Establishing the Flux Density Scale (fluxscale)

The 'G' or 'T' solutions obtained from calibrators for which the flux density was unknown and assumed to be 1 Jansky are correct in a time- and antenna- relative sense, but are mis-scaled by a factor equal to the inverse of the square root of the true flux density. This scaling can be corrected by enforcing the constraint that mean gain amplitudes determined from calibrators of unknown flux density should be the same as determined from those with known flux densities. The fluxscale task exists for this purpose.

The inputs for fluxscale are:

```plaintext
# fluxscale :: Bootstrap the flux density scale from standard calibrators
vis      = ''   # Name of input visibility file (MS)
caltable = ''   # Name of input calibration table
fluxtable = ''   # Name of output, flux-scaled calibration table
reference = [''] # Reference field name(s) (transfer flux scale FROM)
transfer = [''] # Transfer field name(s) (transfer flux scale TO), '' -> all
listfile = ''   # Name of listfile that contains the fit information. Default is (no file).
append   = False # Append solutions?
refspwmap = [-1] # Scale across spectral window boundaries. See help fluxscale
incremental = False # incremental caltable
async    = False # If true the taskname must be started using fluxscale(...)```

The inputs for fluxscale are:
Before running `fluxscale`, one must have first run `setjy` for the reference sources and run a gaincal that includes reference and transfer fields. After running `fluxscale` the output fluxtable caltable will have been scaled such that the correct scaling will be applied to the transfer sources.

For example, given a 'G' table, e.g. 'cal.G', containing solutions for a flux density calibrator (in this case '3C286') and for one or more gain calibrator sources with unknown flux densities (in this example '0234+285' and '0323+022'):

```python
fluxscale(vis='data.ms',
caltab='cal.G',
fluxtable='cal.Gflx', # Write scaled solutions to cal.Gflx
reference='3C286', # 3C286 = flux calibrator
transfer='0234+285, 0323+022') # Select calibrators to scale
```

The output table, 'cal.Gflx', contains either the scaling factors alone (incremental=T) to be used alongside with the input gain table 'cal.G', or a scaled version of the gain table (incremental=F), that replaces it for the execution of applycal.

Note that the assertion that the gain solutions are independent of the calibrator includes the assumption that the gain amplitudes are strictly not systematically time-dependent in any way. While synthesis antennas are designed as much as possible to achieve this goal, in practice, a number of effects conspire to frustrate it. When relevant, it is advisable to pre-apply `gaincurve` and `opacity` corrections when solving for the 'G' solutions that will be flux-scaled (see §4.3 and §4.4.1.3). When the 'G' solutions are essentially constant for each calibrator separately, the fluxscale operation is likely to be robust.

`fluxscale` will report the fluxes of each spw for each source. In addition, it will attempt a fit across the spws of each source and report a spectral index and curvature ($S \propto (\nu/\nu_0)^{\alpha+\beta\log(\nu/\nu_0)}$). This information can be subsequently used to build up a model for the spectral slope of a calibrator with the `setjy` task if required.

The `fluxscale` task can be executed on either 'G' or 'T' solutions, but it should only be used on one of these types if solutions exist for both and one was solved relative to the other (use fluxscale only on the first of the two).

**ALERT:** The 'GSPLINE' option is not yet supported in `fluxscale` (see §4.4.3.3).

If the `reference` and `transfer` fields were observed in different spectral windows, the `refspwmap` parameter may be used to achieve the scaling calculation across spectral window boundaries.

The `refspwmap` parameter functions similarly to the standard `spwmap` parameter (§4.4.1.4), and takes a list of indices indicating the spectral window mapping for the reference fields, such that `refspwmap[i]=j` means that reference field amplitudes from spectral window `j` will be used for spectral window `i`.

**Note:** You should be careful when you have a dataset with spectral windows with different bandwidths, and you have observed the calibrators differently in the different `spw`. The flux-scaling will probably be different in windows with different bandwidths.

For example,
CHAPTER 4. SYNTHESIS CALIBRATION

219

fluxscale(vis='data.ms',
caltab='cal.G',
fluxtable='cal.Gflx',
reference='3C286',
transfer='0234+258,0323+022' # Select input table,
refspwmap=[0,0,0]) # Write scaled solutions to cal.Gflx
# 3C286 = flux calibrator
# Select calibrators to scale
# Use spw 0 scaling for spwids 1 & 2

will use spw=0 to scale the others, while in

fluxscale(vis='data.ms',
caltab='cal.G',
fluxtable='cal.Gflx',
reference='3C286',
transfer='0234+285,0323+022',
refspwmap=[0,0,1,1]) # Select calibrators to scale,
# select spwids for scaling,

the reference amplitudes from spectral window 0 will be used for spectral windows 0 and 1 and
timeference amplitudes from spectral window 2 will be used for spectral windows 2 and 3.

4.4.4.1 Using Resolved Calibrators

If the flux density calibrator is resolved, the assumption that it is a point source will cause solutions
on outlying antennas to be biased in amplitude. In turn, the fluxscale step will be biased on
these antennas as well. In general, it is best to use model for the calibrator, but if such a model is
not available, it is important to limit the solution on the flux density calibrator to only the subset
of antennas that have baselines short enough that the point-source assumption is valid. This can
be done by using antenna and uvrange selection when solving for the flux density calibrator. For
example, if antennas 1 through 8 are the antennas among which the baselines are short enough
that the point-source assumption is valid, and we want to be sure to limit the solutions to the use
of baselines shorter than 15000 wavelengths, then we can assemble properly scaled solutions for the
other calibrator as follows (note: specifying both an antenna and a uvrange constraint prevents
inclusion of antennas with only a small number of baselines within the specified uvrange from being
included in the solution; such antennas will have poorly constrained solutions):

As an example, we first solve for gain solutions for the flux density calibrator (3C286 observed in
field 0) using a subset of antennas

gaincal(vis='data.ms',
caltab='cal.G',
field='0',
selectdata=True,
antenna='0~7',
uvrange='0~15klambda',
solint=90) # write solutions to table called cal.G

Now solve for other calibrator (0234+285 in field 1) using all antennas (implicitly) and append
these solutions to the same table
gaincal(vis='data.ms',
caltable='cal.G', # write solutions to cal.G
field='1',
solint=90,
append=T) # Set up to write to the same table

Finally, run fluxscale to adjust scaling

fluxscale(vis='data.ms',
caltable='cal.G', # Input table with unscaled cal solutions
fluxtable='cal.Gflx', # Write scaled solutions to cal.Gflx
reference='3C286', # Use 3c286 as ref with limited uvrange
transfer='0234+285') # Transfer scaling to 0234+285

The fluxscale calculation will be performed using only the antennas common to both fields, but the result will be applied to all antennas on the transfer field. Note that one can nominally get by only with the \texttt{uvrange} selection, but you may find that you get strange effects from some antennas only having visibilities to a subset of the baselines and thus causing problems in the solving.

4.4.5 Instrumental Polarization Calibration (D,X)

Full support for instrumental polarization calibration for the circular feed basis (e.g., VLA) is provided in CASA. Support for the linear feed basis (e.g., ALMA) is now practical (as of v4.0) and is also described below. The linear feed basis treatment will be expanded and streamlined for the v4.1 release.

The inputs to \texttt{polcal} are:

\begin{verbatim}
# polcal :: Determine instrumental polarization calibrations
vis = '' # Name of input visibility file
caltable = '' # Name of output gain calibration table
field = '' # Select field using field id(s) or field name(s)
spw = '' # Select spectral window/channels
intent = '' # Select observing intent
selectdata = False # Other data selection parameters
solint = 'inf' # Solution interval
combine = 'scan' # Data axes which to combine for solve (scan, spw, # and/or field)
preavg = -1.0 # Pre-averaging interval (sec)
refant = '' # Reference antenna name(s)
mhythperant = 4 # Minimum baselines _per antenna_ required for solve
minsnr = 3.0 # Reject solutions below this SNR
poltype = 'D+QU' # Type of instrumental polarization solution (see help)
smodel = [] # Point source Stokes parameters for source model.
append = False # Append solutions to the (existing) table
gaintable = [''] # Gain calibration table(s) to apply
gainfield = [''] # Select a subset of calibrators from gaintable(s)
interp = [''] # Interpolation mode (in time) to use for each gaintable
\end{verbatim}
The polcal task uses many of the standard calibration parameters as described above in §4.4.1.

The key parameter controlling polcal is poltype. The choices are:

'D' — Solve for instrumental polarization (leakage D-terms), using the transform of an IQU model; requires no parallactic angle coverage, but if the source polarization is non-zero, the gain calibration must have the correct R-L phase registration. (Note: this is unlikely, so just use 'D+X' to let the position angle registration float.) This will produce a calibration table of type D.

'D+X' — Solve for instrumental polarization D-terms and the polarization position angle correction, using the transform of an IQU model; this mode requires at least 2 distinct parallactic angles to separate the net instrumental polarization and the PA. This will produce a calibration table of type 'D'. ALERT: no table of type 'X' will be produced, so you must follow this by a run of polcal with polmode='X' (see below).

'D+QU' — Solve for instrumental polarization and source Q + iU; requires at least 3 distinct parallactic angles to separate the net instrumental polarization from the source Q and U. Effectively sets the polarization PA to the value if the R-L phase difference were 0°. This will produce a calibration table of type 'D'.

'X' — Solve only for the position angle correction; best to use this after getting the D-terms from one of the above modes. Requires the observation of a calibrator with known Q + iU (or at least known U/Q). This will produce a calibration table of type 'X'.

'Dflls' — A specialized mode for instrumental polarization solving for the linear feed basis. This will probably be consolidated with other options in a future release.

There are channelized solution modes for the above options. For example, substitute 'Df' for 'D' in the 'D*' modes described above to get a channelized D-term solution.

ALERT: polcal will obtain a separate D-term solution for each field supplied to it. This limitation will be relaxed in the future, enabling more sensitive solutions.

4.4.5.1 Heuristics and Strategies for Polarization Calibration

ALERT: This section concentrates on polarization calibration for the circular feed basis. It will be generalized to include the linear feed basis for the v4.1 release. See §4.4.5.4 for the currently supported processing steps for the linear feed basis.

Fundamentally, with good ordinary gain (and bandpass, if relevant) calibration already in hand, good polarization calibration must deliver both the instrumental polarization and position angle
calibration. An unpolarized source can deliver only the first of these, but does not require parallactic angle coverage. A polarized source can only deliver the position angle calibration also if its polarization is known a priori. Sources that are polarized, but with unknown polarization, must always be observed with sufficient parallactic angle coverage, where "sufficient" is determined by SNR and the details of the solving mode.

These principles are stated assuming the instrumental polarization solution is solved using the "linear approximation" where cross-terms in more than a single product of the instrumental or source polarizations are ignored in the Measurement Equation (see § 4.4.5.2). A more general non-linearized solution, with sufficient SNR, may enable some relaxation of the requirements indicated here, and modes supporting such an approach are currently under development.

For instrumental polarization calibration, there are 3 types of calibrator choice:

*CASA Polarization Calibration Modes*

<table>
<thead>
<tr>
<th>Cal Polarization</th>
<th>Parallactic Angles</th>
<th>model</th>
<th>polmode</th>
<th>Result</th>
</tr>
</thead>
<tbody>
<tr>
<td>unpolarized</td>
<td>any</td>
<td>set $Q = U = 0$</td>
<td>'D' or 'Df'</td>
<td>D-terms only</td>
</tr>
<tr>
<td>known non-zero</td>
<td>2+ scans</td>
<td>set $Q, U$</td>
<td>'D+X' or 'Df+X'</td>
<td>D-terms and PA</td>
</tr>
<tr>
<td>unknown</td>
<td>2+ scans</td>
<td>ignored</td>
<td>'D+QU' or 'Df+QU'</td>
<td>D-terms and source</td>
</tr>
</tbody>
</table>

Note that the parallactic angle ranges spanned by the scans in the modes that require this should be large enough to give good separation between the components of the solution. In practice, 60° is a good target.

Each of these solutions should be followed with a 'X' solution on a source with known polarization position angle (and correct $Q + iU$ in the model). **ALERT:** polmode='D+X' will soon be enhanced to deliver this automatically.

The polcal task will solve for the 'D' or 'X' terms using the model visibilities that are in the model attached to the MS. Calibration of the parallel hands must have already been carried out using gaincal and/or bandpass in order to align the phases over time and frequency. This calibration must be supplied through the gaintable parameters, but any cal-tables to be used in polcal must agree (e.g. have been derived from) the data in the DATA column and the FT of the model. Thus, for example, one would not use the cal-table produced by fluxscale as the rescaled amplitudes would no longer agree with the contents of the model.

Be careful when using resolved calibrators for polarization calibration. A particular problem is if the structure in $Q$ and $U$ is offset from that in $I$. Use of a point model, or a resolved model for $I$ but point models for $Q$ and $U$, can lead to errors in the 'X' calibration. Use of a uvrange will help here. The use of a full-Stokes model with the correct polarization is the only way to ensure a correct calibration if these offsets are large.

### 4.4.5.2 A Note on channelized polarization calibration

When your data has more than one channel per spectral window, it is important to note that the calibrator polarization estimate currently assumes the source polarization signal is coherent
across each spectral window. In this case, it is important to be sure there is no large cross-hand delay still present in your data. Unless the online system has accounted for cross-hand delays (typically intended, but not always achieved), the gain and bandpass calibration will only correct for parallel-hand delay residuals since the two polarizations are referenced independently. Good gain and bandpass calibration will typically leave a single cross-hand delay (and phase) residual from the reference antenna. Plots of cross-hand phases as a function of frequency for a strongly polarized source (i.e., that dominates the instrumental polarization) will show the cross-hand delay as a phase slope with frequency. This slope will be the same magnitude on all baselines, but with different sign in the two cross-hand correlations. This cross-hand delay can be estimated using the \texttt{gaintype=’KCROSS’} mode of \texttt{gaincal} (in this case, using the strongly polarized source 3C286):

```python
default('gaincal')
vis = 'polcal_20080224.cband.all.ms'
caltable = 'polcal.xdelcal'
field = '3C286'
spw = '',
solint = 'inf'
combine = 'scan'
refant = 'VA15'
smodel = [1.0,0.11,0.0,0.0]
gaintype = 'KCROSS'
gaintable = ['polcal.gcal','polcal.bcal']
gaincal()
```

Note that \texttt{smodel} is used to specify that 3C286 is polarized; it is not important to specify this polarization stokes parameters correctly, as only the delay will be solved for (not any absolute position angle or amplitude scaling). The resulting solution should be carried forward and applied along with the gain (.gcal) and bandpass (.bcal) solutions in subsequent polarization calibration steps.

4.4.5.3 A Polarization Calibration Example - Circular Feed Basis (e.g., VLA $\nu > 1$ GHz)

In the following example, we do a standard ‘D+QU’ solution on the bright source BLLac (2202+422) which has been tracked through a range in parallactic angle:

```python
default('polcal')
vis = 'polcal_20080224.cband.all.ms'
caltable = 'polcal.pcal'
field = '2202+422'
spw = '',
solint = 'inf'
combine = 'scan'
preavg = 300.0
refant = 'VA15'
minsnr = 3
poltype = 'D+QU'
```
CHAPTER 4. SYNTHESIS CALIBRATION

```python
gaintable = ['polcal.gcal','polcal.bcal','polcal.xdelcal']
gainfield = ['']
polcal()
```

This assumes `setjy` and `gaincal` have already been run. Note that the original gain-calibration table is used in `gaintable` so that what is in the model is in agreement with what is in the `gaintable`, rather than using the table resulting from `fluxscale`.

Now, we need to set the R-L phase using a scan on 3C48 (0137+331):

```python
default('polcal')
vis = 'polcal_20080224.cband.all.ms'
caltab = 'polcal.pcal'
field = '0137+331'
refant = 'VA15'
minsnr = 3
poltype = 'X'
smodel = [1.0,-0.0348,-0.0217,0.0] # the fractional Stokes for 3C48
gaintable = ['polcal.gcal','polcal.bcal','polcal.xdelcal','polcal.pcal']
polcal()
```

Note that the fractional polarization of 3C48 has been properly specified in `smodel` here.

If, on the other hand, we had a scan on an unpolarized bright source, for example 3C84 (0319+415), we could use this to calibrate the leakages:

```python
default('polcal')
vis = 'polcal_20080224.cband.all.ms'
caltab = 'polcal.pcal'
field = '0319+415'
refant = 'VA15'
poltype = 'D'
gaintable = ['polcal.gcal','polcal.bcal','polcal.xdelcal']
polcal()
```

We would then do the 'X' calibration as before (but using this D-table in `gaintable`).

4.4.5.4 A Polarization Calibration Example - Linear Feed Basis (e.g., ALMA, VLA $\nu < 1$ GHz)

CASA v4.0.0 introduces supports for instrumental polarization calibration for the linear feed basis at a level that is now practical for the general user. Some details remain to be implemented with full flexibility, and much of what follows will be streamlined for the v4.1 release.

Calibrating the instrumental polarization for the linear feed basis is somewhat more complicated than the circular feed basis because the polarization effects (source and instrument) appear in all four correlations at first or zeroth order (whereas for circular feeds, the polarization information only enters the parallel hand correlations at second order). As a result, e.g., the time-dependent
CHAPTER 4. SYNTHESIS CALIBRATION

gain calibration will be distorted by any non-zero source polarization, and some degree of iteration will be required to isolate the gain calibration if the source polarization is not initially known. These complications can actually be used to advantage in solving for the instrumental calibration; in can be shown, for example, that a significantly linearly polarized calibrator enables a better instrumental polarization solution than an unpolarized calibrator.

In the following example, we show the processing steps for calibrating the instrumental polarization using a strongly (> 5%) polarized point-source calibrator (which is also the time-dependent gain calibrator) that has been observed over a range of parallactic angle (a single scan is not sufficient). We assume that we have calibrated the gain, bandpass, and cross-hand delay as described above, and that the gain calibration (polcal.gcal) was obtained assuming the calibrator was unpolarized.

First, we import some utility functions from the CASA recipes area:

```python
from recipes.linfeedpolhelpers import *
```

Since the gain calibrator was assumed unpolarized, the time-dependent gain solutions contain information about the source polarization. This can be seen by plotting the amp vs. time for this table using poln='/. The antenna-based polarization amplitude ratios will reveal the sinusoidal (in parallactic angle) of the source polarization. Run a utility method (qufromgain()) to extract the apparent source polarization estimates for each spw:

```python
qu=qufromgain('polcal.gcal')
```

The source polarization reported for all spws should be reasonably consistent. This estimate is not as good as can be obtained from the cross-hands (see below) since it relies on the gain amplitude polarization ratio being stable which may not be precisely true. However, this estimate will be useful in resolving an ambiguity that occurs in the cross-hand estimates.

Next we estimate both the XY-phase offset and source polarization from the cross-hands. The XY-phase offset is a spectral phase-only bandpass relating the X and Y systems of the reference antenna. The cross-hand delay solved for above represents a systematic component (linear phase in frequency). If the XY-phase is solved for in a channel-dependent manner (as below), it is strictly not necessary to have solved for the cross-hand delay above, but it does not hurt (at it allows reasonably coherent channel averages for data examination). The source polarization occurs in the cross-hands as a sinusoidal function of parallactic angle that is common to both cross-hands on all baselines (for a point-source). If the XY-phase bandpass is uniformly zero, then the source linear polarization function will occur entirely in the real part of the cross-hand visibilities. Non-zero XY-phase has the effect of rotating the source linear polarization signature partially into the imaginary part, where circular (and instrumental) polarization occur (cf the circular feed basis where the cross-hand phase merely rotates the position angle of linear polarization). The following solve averages all baselines together and first solves for a channelized XY-phase (the slope of the source polarization function in the complex plane), then corrects the slope and solves for a channel-averaged source polarization. This calibration is obtained using gaintype='XYf+QU' in gaincal:
CHAPTER 4. SYNTHESIS CALIBRATION

```
default('gaincal')
vis = 'polcal_linfeed.ms'
caltab = 'polcal.xy0amb'  # possibly with 180deg ambiguity
field = '1'  # the calibrator
solint = 'inf'
combine = 'scan'
preavg = 200.0  # minimal parang change
smode = [1,0,1,0]  # non-zero U assumed
gaintype = 'XYf+QU'
gaintab = ['polcal.gcal','polcal.bcal','polcal.xdelcal']
gaincal()
```

Note that we imply non-zero Stokes U in `smode`; this is to enforce the assumption of non-zero source polarization signature in the cross-hands in the ratio of data and model. This solve will report the center-channel XY-phase and apparent Q,U for each spw. The Q,U results should be recognizable in comparison to that reported by `qufromgain()` above. However, since the XY-phase has a 180 degree ambiguity (you can rotate the source polarization signature to lie entirely in the visibility real part by rotating clockwise or counter-clockwise), some or all spw QU estimates may have the wrong sign. We correct this using the `xyamb()` utility method, using the `qu` obtained from `qufromgain()` above (which is not ambiguous):

```
S=xyamb(xy='polcal.xy0amb',qu=qu,xyout='polcal.xy0')
```

The python variable `S` now contains the mean source model (Stokes I = 1; fractional Q,U; V=0) that can be used in a revision of the gain calibration and instrumental polarization calibration.

Next we revise the gain calibration using the full polarization source model:

```
default('gaincal')
vis = 'polcal_linfeed.ms'
caltab = 'polcal.gcal1'
field = '1'
solint = 'int'  # or whatever was used previously
smode = S  # obtained from xyamb
gaintype = 'G'
gaintab = ['polcal.bcal']
parang = T  # so source poln properly rotated
gaincal()
```

Note that `parang=T` so that the supplied source linear polarization is properly rotated in the parallel-hand visibility model. This new gain solution can be plotted with `poln='/'` as above to show that the source polarization is no longer distorting it. Also, if `qufromgain` is run on this new gain table, the reported source polarization should be statistically indistinguishable from zero.

Finally, we can now solve for the instrumental polarization:
Note that no reference antenna is used since this solve will produce an absolute instrumental polarization solution that is registered to the assumed source polarization ($S$) and prior calibrations. Applying a refant (referring all instrumental polarization terms to a reference antenna’s X feed, which would then be assumed perfect) would, in fact, discard valid information about the imperfections in the reference antenna’s X feed. (Had we used an unpolarized calibrator, we would not have a valid xy-phase solution, nor would we have had access to the absolute instrumental polarization solution demonstrated here.)

A few points:

- Since the gain, bandpass, and XY-phase calibrations were obtained prior to the instrumental polarization solution and maybe distorted by it, it is generally desirable to resolve for them using the instrumental polarization solution. In effect, this means iterating the sequence of calibration steps using all of the best of the available information at each stage, including the source polarization (and parang=T). This is a generalization of traditional self-calibration. For the CASA v4.1 release, we expect to provide utility methods for iteration.

- If the source linear polarization fraction and position angle is known a priori, the processing steps outlined above can be amended to use that source polarization assertion in the gain and instrumental calibration solves. The qufromgain() method is not needed (but can be used to verify assumptions), the gaincal(...,gaintype='XYf+QU',...) should not be altered (parallactic angle coverage is still required!), and the xyamb() run should use the a priori polarization for qu. If there is likely to be a large systematic offset in the mean feed position angle, iteration of the gain, bandpass, and instrumental polarization terms is required to properly isolate the calibration effects.

- Note that the above process does not explicitly include a position angle calibration. In effect, the estimated source polarization sets the mean feed position angle as the reference position angle, and this is usually within a degree or so of optimal. If your mean X feed position angle is not $\sim 0$ degrees, and your MS does not account for the offset in its FEED subtable, be careful in your interpretation of the final position angle. Currently, the circular feed-specific position angle calibration modes of polcal (poltype='X' or 'Xf') will not properly handle the linear feed basis; this will be fixed in the CASA v4.1 release.
CHAPTER 4. SYNTHESIS CALIBRATION

A full processing example for linear feed basis polarimetry is under development and will be distributed with an upcoming CASA release.

4.4.6 Baseline-based Calibration (blcal)

You can use the blcal task to solve for baseline-dependent (non-closing) errors. **WARNING:** this is in general a very dangerous thing to do, since baseline-dependent errors once introduced are difficult to remove. You must be sure you have an excellent model for the source (better than the magnitude of the baseline-dependent errors).

The inputs are:

```plaintext
# blcal :: Calculate a baseline-based calibration solution (gain or bandpass)
vis = '' # Name of input visibility file
caltab = '' # Name of output gain calibration table
field = '' # Select field using field id(s) or field name(s)
spw = '' # Select spectral window/channels
intent = '' # Select observing intent
selectdata = False # Other data selection parameters
solint = 'inf' # Solution interval
combine = 'scan' # Data axes which to combine for solve (scan, spw, # and/or field)
freqdep = False # Solve for frequency dependent solutions
calmode = 'ap' # Type of solution ('ap', 'p', 'a')
solnorm = False # Normalize average solution amplitudes to 1.0
gaintable = [''] # Gain calibration table(s) to apply on the fly
gainfield = [''] # Select a subset of calibrators from gaintable(s)
interp = [''] # Interpolation mode (in time) to use for each gaintable
spwmap = [] # Spectral windows combinations to form for # gainvalues(s)
gaincurve = False # Apply internal VLA antenna gain curve correction-opacity = [] # Opacity correction to apply (nepers), per spw
parang = False # Apply parallactic angle correction
async = False # If true the taskname must be started using blcal(...)```

The `freqdep` parameter controls whether blcal solves for “gain” (`freqdep=False`) or “bandpass” (`freqdep=True`) style non-closing calibration.

Other parameters are the same as in other calibration tasks. These common calibration parameters are described in §4.4.1.

4.5 Plotting and Manipulating Calibration Tables

At some point, the user should examine (plotting or listing) the calibration solutions. Calibration tables can also be manipulated in various ways, such as by interpolating between times (and sources), smoothing of solutions, and accumulating various separate calibrations into a single table.
CHAPTER 4. SYNTHESIS CALIBRATION

4.5.1 Plotting Calibration Solutions (plotcal)

The plotcal task is available for examining solutions of all of the basic solvable types (G, T, B, D, M, MF, K). The inputs are:

```
# plotcal :: An all-purpose plotter for calibration results:

caltab   = '' # Name of input calibration table
xaxis    = '' # Value to plot along x axis (time,chan,amp,phase,real,imag,snr)
yaxis    = '' # Value to plot along y axis (amp,phase,real,imag,snr)
poln     = '' # Polarization to plot (RL,R,L,XY,X,Y,/)  
field    = '' # Field names or index: '='all, '3C286,P1321*', '0~3'
antenna  = '' # Antenna selection. E.g., antenna='3~5'
spw      = '' # Spectral window: '='all, '0,1' means spw 0 and 1

timerange = '' # Time selection ''=all
subplot = 111 # Panel number on display screen (xy
overplot = False # Overplot solutions on existing display

clearpanel = 'Auto' # Specify if old plots are cleared or not
iteration = '' # Iterate on antenna, time, spw, field

clearplot = [] # plot axes ranges: [xmin,xmax,ymin,ymax]
showflags = False # If true, show flags

clearplots = '.' # pylab plot symbol

clearplotcolor = 'blue' # initial plotting color

clearmarkersize = 5.0 # size of plot symbols

clearfontsize = 10.0 # size of label font
showgui = True # Show plot on gui

clearfigfile = '' # ''= no plot hardcopy, otherwise supply name
```

**ALERT:** Currently, plotcal needs to know the MS from which caltable was derived to get indexing information. It does this using the name stored inside the table, which does not include the full path, but assumes the MS is in the cwd. Thus if you are using a MS in a directory other than the current one, it will not find it. You need to change directories using cd in IPython (or os.chdir() inside a script) to the MS location.

The controls for the plotcal window are the same as for plotxy (see § 3.3.2.1).

The xaxis and yaxis plot options available are:

- `'amp'` — amplitude,
- `'phase'` — phase,
- `'real'` — the real part,
- `'imag'` — the imaginary part,
- `'snr'` — the signal-to-noise ratio,

of the calibration solutions that are in the caltable. The xaxis choices also include `'time'` and `'channel'` which will be used as the sensible defaults (if xaxis='') for gain and bandpass solutions respectively.
The `poln` parameter determines what polarization or combination of polarization is being plotted. The `poln='RL'` plots both R and L polarizations on the same plot. The respective XY options do equivalent things. The `poln='/'` option plots amplitude ratios or phase differences between whatever polarizations are in the MS (R and L. or X and Y).

The `field`, `spw`, and `antenna` selection parameters are available to obtain plots of subsets of solutions. The syntax for selection is given in §2.3.

The `subplot` parameter is particularly helpful in making multi-panel plots. The format is `subplot=yxn` where `yxn` is an integer with digit `y` representing the number of plots in the y-axis, digit `x` the number of panels along the x-axis, and digit `n` giving the location of the plot in the panel array (where `n = 1, ... , xy`, in order upper left to right, then down). See §3.3.2.8 for more details on this option.

The `iteration` parameter allows you to select an identifier to iterate over when producing multi-panel plots. The choices for `iteration` are: `antenna`, `time`, `spw`, `field`. For example, if per-antenna solution plots are desired, use `iteration='antenna'`. You can then use `subplot` to specify the number of plots to appear on each page. In this case, set the `n` to 1 for `subplot=yxn`. Use the `Next` button on the plotcal window to advance to the next set of plots. Note that if there is more than one timestamp in a `B` table, the user will be queried to interactively advance the plot to each timestamp, or if `multiplot=True`, the antennas plots will be cycled through for each timestamp in turn. Note that `iteration` can take more than one iteration choice (as a single string containing a comma-separated list of the options). **ALERT:** the iteration order is fixed (independent of the order specified in the `iteration` string), for example:

```
iteration = 'antenna, time, field'
iteration = 'time, antenna, field'
```

will both iterate over each field (fastest) then time (next) and antenna (slowest). The order is:

```
iteration = 'antenna, time, field, spw'
```

from the slowest (outer loop) to fastest (inner loop).

The `markersize` and `fontsize` parameters are especially helpful in making the dot and label sizes appropriate for the plot being made. The screen shots in this section used this feature to make the plots more readable in the cookbook. Adjusting the `fontsize` can be tricky on multi-panel plots, as the labels can run together if too large. You can also help yourself by manually resizing the Plotter window to get better aspect ratios on the plots. **ALERT:** Unfortunately, `plotcal` has many of the same problems that `plotxy` does, as they use similar code underneath. An overhaul is underway, so stay tuned.

### 4.5.1.1 Examples for `plotcal`

For example, to plot amplitude or phase as a function of time for `G` solutions (after rescaling by `fluxscale` can look like
default('plotcal')
fontsize = 14.0      # Make labels larger
markersize = 10.0   # Make dots bigger

caltab = 'ngc5921. testcase. fluxscale'
yaxis = 'amp'
subplot = 211
plotcal()

yaxis = 'phase'
subplot = 212
plotcal()

The results are shown in Figure 4.4. This makes use of the subplot option to make multi-panel displays.

Figure 4.4: Display of the amplitude (upper) and phase (lower) gain solutions for all antennas and polarizations in the ngc5921 post-fluxscale table.
Similarly, to plot amplitude or phase as a function of channel for 'B' solutions for NGC5921:

```python
default('plotcal')
fontsize = 14.0  # Make labels larger
markersize = 10.0  # Make dots bigger

caltable = 'ngc5921.usecase.bcal'
antenna = '1'
yaxis = 'amp'
subplot = 311
plotcal()

yaxis = 'phase'
subplot = 312
plotcal()

yaxis = 'snr'
subplot = 313
plotcal()
```

The results are shown in Figure 4.5. This stacks three panels with amplitude, phase, and signal-to-noise ratio. We have picked `antenna='1'` to show.

For example, to show 6 plots per page of 'B' amplitudes on a $3 \times 2$ grid:

```python
default('plotcal')
fontsize = 12.0  # Make labels just large enough
markersize = 10.0  # Make dots bigger

caltable = 'ngc5921.usecase.bcal'
yaxis = 'amp'
subplot = 231
iteration = 'antenna'

plotcal()
```

See Figure 4.6 for this example. This uses the `iteration` parameter.

### 4.5.2 Listing calibration solutions with (listcal)

The `listcal` task will list the solutions in a specified calibration table.

The inputs are:

```python
# listcal :: List data set summary in the logger:

vis = ''  # Name of input visibility file (MS)
caltable = ''  # Input calibration table to list
field = ''  # Select data based on field name or index
```
Figure 4.5: Display of the amplitude (upper), phase (middle), and signal-to-noise ratio (lower) of the bandpass 'B' solutions for antenna='0' and both polarizations for ngc5921. Note the falloff of the SNR at the band edges in the lower panel.

antenna = '' # Select data based on antenna name or index
spw = '' # Spectral window, channel to list
listfile = '' # Disk file to write, else to terminal
pagerows = 50 # Rows listed per page
async = False

An example listing is:

Listing CalTable: jupiter6cm.usecase.split.ms.smoothcal2 (G Jones)
---------------------------------------------------------------

SpwId = 0, channel = 0.
Time Field Ant : Amp Phase Amp Phase
------------------ -------- -------- -------------- --------------
Figure 4.6: Display of the amplitude of the *bandpass* 'B' solutions. Iteration over antennas was turned on using *iteration='antenna'*.

The first page is shown. The user would use the **Next** button to advance to the next set of antennas.

1999/04/16/14:10:43.5 'JUPITER'

<p>| | | | |</p>
<table>
<thead>
<tr>
<th></th>
<th></th>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>1'</td>
<td>1.016</td>
<td>-11.5</td>
<td>1.016</td>
</tr>
<tr>
<td>2'</td>
<td>1.013</td>
<td>-5.3</td>
<td>0.993</td>
</tr>
<tr>
<td>3'</td>
<td>0.993</td>
<td>-0.8</td>
<td>0.990</td>
</tr>
<tr>
<td>4'</td>
<td>0.997</td>
<td>-10.7</td>
<td>0.999</td>
</tr>
<tr>
<td>5'</td>
<td>0.985</td>
<td>-2.7</td>
<td>0.988</td>
</tr>
<tr>
<td>6'</td>
<td>1.005</td>
<td>-8.4</td>
<td>1.009</td>
</tr>
<tr>
<td>7'</td>
<td>0.894</td>
<td>-8.7</td>
<td>0.897</td>
</tr>
<tr>
<td>8'</td>
<td>1.001</td>
<td>-0.1</td>
<td>0.992</td>
</tr>
<tr>
<td>9'</td>
<td>0.989</td>
<td>-12.4</td>
<td>0.992</td>
</tr>
<tr>
<td>10'</td>
<td>1.000F</td>
<td>-4.2F</td>
<td>1.000F</td>
</tr>
<tr>
<td>11'</td>
<td>0.896</td>
<td>-0.0</td>
<td>0.890</td>
</tr>
<tr>
<td>12'</td>
<td>0.996</td>
<td>-10.6</td>
<td>0.996</td>
</tr>
<tr>
<td>13'</td>
<td>1.009</td>
<td>-8.4</td>
<td>1.011</td>
</tr>
<tr>
<td>14'</td>
<td>0.993</td>
<td>-17.6</td>
<td>0.994</td>
</tr>
</tbody>
</table>
### 4.5.3 Calibration table statistics (calstat)

The `calstat` task will print the statistics of solutions in a specified calibration table.

The inputs are:

```python
# calstat :: Displays statistical information on a calibration table
caltab = '' # Name of input calibration table
axis = 'amp' # Which values to use
datacolumn = 'gain' # Which data column to use
useflags = True # Take flagging into account? (not implemented)
async = False # If true the taskname must be started using calstat(...)
```

For example:

CASA <3>: calstat('ngc5921.demo.gcal', axis='amp', datacolumn='gain')

```
{'GAIN': {  'max': 1.6031942367553711,
           'mean': 1.4448433067117419,
           'medabsdevmed': 0.0086394548416137695,
           'median': 1.5732669830322266,
           'min': 0.99916577339172363,
           'npts': 280.0,
           'quartile': 0.020265340805053711,
           'rms': 1.4650156497955322,
           'stddev': 0.24271160321065546,
           'sum': 404.55612587928772,
           'sumsq': 600.95579999685287,
           'var': 0.058908922333086665}}
```

CASA <4>: calstat('ngc5921.demo.gcal', axis='phase', datacolumn='gain')

```
Out[4]:
```
The statistics can be captured as return variables from the task:

```python
CASA <7>: mystat = calstat('ngc5921.demo.gcal',axis='amp',datacolumn='gain')
CASA <8>: print 'Gain Amp = ',mystat['GAIN']['mean'],'+/-',mystat['GAIN']['stddev']
Gain Amp = 1.44484330671 +/- 0.242711603211
```

**ALERT:** This task is still under development and currently offers no selection (e.g. by antenna) for the statistics.

### 4.5.4 Calibration Smoothing (smoothcal)

The `smoothcal` task will smooth calibration solutions (most usefully $G$ or $T$) over a longer time interval to reduce noise and outliers. The inputs are:

```python
# smoothcal :: Smooth calibration solution(s) derived from one or more sources:
vis = ''   # Name of input visibility file
tablein = '' # Input calibration table
caltab = '' # Output calibration table
field = ''  # Field name list
smoothtype = 'median' # Smoothing filter to use
smoothtime = 60.0 # Smoothing time (sec)
async = False # if True run in the background, prompt is freed
```

Note that if no `caltab` is specified as output, `smoothcal` will overwrite the input `tablein` calibration table.

The smoothing will use the `smoothtime` and `smoothtype` parameters to determine the new data points which will replace the previous points on the same time sampling grid as for the `tablein` solutions. The currently supported `smoothtype` options:

- `'mean'` — use the mean of the points within the window defined by `smoothtime` (a “boxcar” average),
• *median* — use the median of the points within the window defined by `smoothtime` (most useful when many points lie in the interval).

Note that `smoothtime` defines the width of the time window that is used for the smoothing.

**ALERT:** Note that `smoothcal` currently smooths by `field` and `spw`, and thus you cannot smooth solutions from different sources or bands together into one solution.

![G table: n4826_16apr.gcal](image1.png)

![G table: n4826_16apr.smoothcal](image2.png)

Figure 4.7: The *amp* of gain solutions for NGC4826 before (top) and after (bottom) smoothing with a 7200 sec `smoothtime` and `smoothtype='mean'`. Note that the first solution is in a different `spw` and on a different source, and is not smoothed together with the subsequent solutions.

An example using the `smoothcal` task to smooth an existing table:

```python
smoothcal('n4826_16apr.ms',
          tablein='n4826_16apr.gcal',
          caltable='n4826_16apr.smoothcal',
          smoothtime=7200.,
```
smoothtype='mean')

# Plot up before and after tables
plotcal('n4826_16apr.gcal','','amp',antenna='1',subplot=211)
plotcal('n4826_16apr.smoothcal','','amp',antenna='1',subplot=212)

This example uses 2 hours (7200 sec) for the smoothing time and smoothtype='mean'. The plotcal results are shown in Figure 4.7.

4.5.5 Calibration Interpolation and Accumulation (accum)

**ALERT:** The accum task is generally no longer recommended for most calibration scenarios. Please write to the NRAO CASA helpdesk if you need support using accum.

The **accum** task is used to interpolate calibration solutions onto a different time grid, and to *accumulate* incremental calibrations into a *cumulative* calibration table. The manual accumulation of calibration is rarely required and can usually be achieved implicitly simply by running **applycal** with all the calibration tables given as a list in the **gaintable** parameter (and using **gainfiled**, **spwmap**, and **interp** appropriately. However, sometimes it is desirable to see the interpolated calibration prior to application, and this section describes how this can be done.

Its inputs are:

```
# accum :: Accumulate incremental calibration solutions
vis = '' # Name of input visibility file
tablein = '' # Input (cumulative) calibration table; use '' on first run
accumtime = 1.0 # Timescale on which to create cumulative table
incrtable = '' # Input incremental calibration table to add
caltab = '' # Output (cumulative) calibration table
field = '' # List of field names to process from tablein.
calfield = '' # List of field names to use from incrtable.
interp = 'linear' # Interpolation mode to use for resampling incrtable solutions
spwmap = [-1] # Spectral window combinations to apply
```

The mapping implied here is

```
tablein + incrtable => caltable
```

(mathematically the cal solutions are multiplied as complex numbers as per the Measurement Equation). The **tablein** is optional (see below). You must specify an **incrtable** and a **caltab**.

The **tablein** parameter is used to specify the existing cumulative calibration table to which an incremental table is to be applied. Initially, no such table exists, and if **tablein=''** then accumulate will generate one from scratch (on-the-fly), using the timescale (in seconds) specified by the sub-parameter **accumtime**. These nominal solutions will be unit-amplitude, zero-phase calibration, ready to be adjusted by accumulation according to the settings of other parameters. When
**CHAPTER 4. SYNTHESIS CALIBRATION**

accumtime is negative (the default), the table name specified in tablein must exist and will be used. If tablein is specified, then the entries in that table will be used.

The incrtable parameter is used to specify the incremental table that should be applied to tablein. The calibration type of incrtable sets the type assumed in the operation, so tablein (if specified) must be of the same type. If it is not, accum will exit with an error message. (Certain combinations of types and subtypes will be supported by accum in the future.)

The caltable parameter is used to specify the name of the output table to write. If un-specified (''), then tablein will be overwritten. Use this feature with care, since an error here will require building up the cumulative table from the most recent distinct version (if any).

The field parameter specifies those field names in tablein to which the incremental solution should be applied. The solutions for other fields will be passed to caltable unaltered. If the cumulative table was created from scratch in this run of accumulate, then the solutions for these other fields will be unit-amplitude, zero-phase, as described above.

The calfield parameter is used to specify the fields to select from incrtable to use when applying to tablein. Together, use of field and calfield permit completely flexible combinations of calibration accumulation with respect to fields. Multiple runs of accum can be used to generate a single table with many combinations. In future, a 'self' mode will be enabled that will simplify the accumulation of field-specific solutions.

The spwmap parameter gives the mapping of the spectral windows in the incrtable onto those in tablein and caltable. The syntax is described in § 4.4.1.4.

The interp parameter controls the method used for interpolation. The options are (currently): 'nearest' and 'linear' for time-dependent interpolation, and 'nearest', 'linear', cubic, and spline for (optional) frequency-dependent interpolation. These are described in § 4.4.1.4. For most purposes, the 'linear' option should suffice.

We now describe the two uses of accum.

### 4.5.5.1 Interpolation using (accum)

**ALERT:** The accum task is generally no longer recommended for most calibration scenarios. Please write to the NRAO CASA helpdesk if you need support using accum.

Calibration solutions (most notably G or T) can be interpolated onto the timestamps of the science target observations using accum.

The following example uses accum to interpolate an existing table onto a new time grid:

```plaintext
accum(vis='n4826_16apr.ms',
     tablein='',
     accumtime=20.0,
     incrtable='n4826_16apr.gcal',
     caltable='n4826_16apr.20s.gcal',
     interp='linear',
     spwmap=[0,1,1,1,1])
```
CHAPTER 4. SYNTHESIS CALIBRATION

See Figure 4.8 for the plotcal results. The data used in this example is BIMA data (single polarization YY) where the calibrators were observed in single continuum spectral windows (\texttt{spw=’0,1’}) and the target NGC4826 was observed in 64-channel line windows (\texttt{spw=’2,3,4,5’}). Thus, it is necessary to use \texttt{spwmap=[0,1,1,1,1,1]} to map the bandpass calibrator in \texttt{spw=’0’} onto itself, and the phase calibrator in \texttt{spw=’1’} onto the target source in \texttt{spw=’2,3,4,5’}.

Figure 4.8: The ‘phase’ of gain solutions for NGC4826 before (top) and after (bottom) ‘linear’ interpolation onto a 20 sec \texttt{accumtime} grid. The first scan was 3C273 in \texttt{spw=’0’} while the calibrator scans on 1331+305 were in \texttt{spw=’1’}. The use of \texttt{spwmap} was necessary to transfer the interpolation correctly onto the NGC4826 scans.
4.5.5.2 Incremental Calibration using \texttt{(accum)}

It is occasionally desirable to solve for and apply calibration incrementally. This is the case when a calibration table of a certain type already exists (from a previous solve), a solution of the same type and incremental relative to the first is required, and it is not possible or convenient to recover the cumulative solution by a single solve.

Much of the time, it is, in fact, possible to recover the cumulative solution. This is because the equation describing the solution for the incremental solution (using the original solution), and that describing the solution for their product are fundamentally the same equation—the cumulative solution, if unique, must always be the same no matter what initial solution is. One circumstance where an incremental solution is necessary is the case of phase-only self-calibration relative to a full amplitude and phase calibration already obtained (from a different field).

For example, a phase-only 'G' self-calibration on a target source may be desired to tweak the full amplitude and phase 'G' calibration already obtained from a calibrator. The initial calibration (from the calibrator) contains amplitude information, and so must be carried forward, yet the phase-only solution itself cannot (by definition) recover this information, as a full amplitude and phase self-calibration would. In this case, the initial solution must be applied while solving for the phase-only solution, then the two solutions combined to form a cumulative calibration embodying the net effect of both. In terms of the Measurement Equation, the net calibration is the product of the initial and incremental solutions.

Cumulative calibration tables also provide a means of generating carefully interpolated calibration, on variable user-defined timescales, that can be examined prior to application to the data with \texttt{applycal}. The solutions for different fields and/or spectral windows can be interpolated in different ways, with all solutions stored in the same table.

The only difference between incremental and cumulative calibration tables is that incremental tables are generated directly from the calibration solving tasks (\texttt{gaincal}, \texttt{bandpass}, etc), and cumulative tables are generated from other cumulative and incremental tables via \texttt{accum}. In all other respects (internal format, application to data with \texttt{applycal}, plotting with \texttt{plotcal}, etc.), they are the same, and therefore interchangeable. Thus, accumulate and cumulative calibration tables need only be used when circumstances require it.

The \texttt{accum} task represents a generalization on the classic AIPS \texttt{CLCAL} (see sidebox) model of cumulative calibration in that its application is not limited to accumulation of 'G' solutions. In principle, any basic calibration type can be accumulated (onto itself), as long as the result of the accumulation (matrix product) is of the same type. This is true of all the basic types, except 'D'. Accumulation is currently supported for 'B', 'G', and 'T', and, in future, 'F' (ionospheric Faraday rotation), delay-rate, and perhaps others. Accumulation of certain specialized types (e.g., 'GSPLINE', 'TOPAC', etc.) onto the basic types will be supported in the near future. The treatment of various calibration from ancillary data (e.g., system temperatures, weather data, WVR, etc.), as they become available, will also make use of accumulate to achieve the net calibration.

\begin{center}
\begin{tabular}{|l|}
\hline
\textbf{Other Packages:} \\
The analog of \texttt{accum} in classic AIPS is the use of \texttt{CLCAL} to combine a series of (incremental) \texttt{SN} calibration tables to form successive (cumulative) \texttt{CL} calibration tables. AIPS \texttt{SN/CL} tables are the analog of 'G' tables in CASA. \\
\hline
\end{tabular}
\end{center}
CHAPTER 4. SYNTHESIS CALIBRATION

Note that accumulation only makes sense if treatment of a uniquely incremental solution is required (as described above), or if a careful interpolation or sampling of a solution is desired. In all other cases, re-solving for the type in question will suffice to form the net calibration of that type. For example, the product of an existing 'G' solution and an amplitude and phase 'G' self-cal (solved with the existing solution applied), is equivalent to full amplitude and phase 'G' self-cal (with no prior solution applied), as long as the timescale of this solution is at least as short as that of the existing solution.

One obvious application is to calibrate the amplitudes and phases on different timescales during self-calibration. Here is an example:

```plaintext
# Add clean model
ft(vis='jupiter6cm.usecase.split.ms',
    model='jupiter6cm.usecase.clean1.model')

# Phase only self-cal on 10s timescales
gaincal(vis='jupiter6cm.usecase.split.ms',
    caltable='jupiter6cm.usecase.phasecal1',
    gaintype='G',
    calmode='p',
    refant='6',
    solint=10.0,
    minsnr=1.0)

# Plot up solution phase and SNR
plotcal('jupiter6cm.usecase.phasecal1','','phase',antenna='1',subplot=211)
plotcal('jupiter6cm.usecase.phasecal1','','snr',antenna='1',subplot=212)

# Amplitude and phase self-cal on scans
gaincal(vis='jupiter6cm.usecase.split.ms',
    caltable='jupiter6cm.usecase.scancal1',
    gaintable='jupiter6cm.usecase.phasecal1',
    gaintype='G',
    calmode='ap',
    refant='6',
    solint='inf',
    minsnr=1.0)

# Plot up solution amp and SNR
plotcal('jupiter6cm.usecase.scancal1','','amp',antenna='1',subplot=211)
plotcal('jupiter6cm.usecase.scancal1','','snr',antenna='1',subplot=212)

# Now accumulate these - they will be on the 10s grid
accum(vis='jupiter6cm.usecase.split.ms',
    tablein='jupiter6cm.usecase.phasecal1',
    incrtable='jupiter6cm.usecase.scancal1',
    caltable='jupiter6cm.usecase.selfcal1',
    interp='linear')

# Plot this up
plotcal('jupiter6cm.usecase.selfcal1','','amp',antenna='1',subplot=211)
```
plotcal('jupiter6cm.usecase.selfcal1',' ','phase','antenna='1',subplot=212)

The final plot is shown in Figure 4.9

Figure 4.9: The final ‘amp’ (top) and ‘phase’ (bottom) of the self-calibration gain solutions for Jupiter. An initial phase calibration on 10s solint was followed by an incremental gain solution on each scan. These were accumulated into the cumulative solution shown here.

**ALERT:** Only interpolation is offered in **accum**, no smoothing (as in **smoothcal**).

### 4.6 Application of Calibration to the Data

After the calibration solutions are computed and written to one or more calibration tables, one then needs to apply them to the data.
4.6.1 Application of Calibration (applycal)

After all relevant calibration types have been determined, they must be applied to the target source(s) before splitting off to a new MS or before imaging. This is currently done by explicitly taking the data in the DATA column in the MAIN table of the MS, applying the relevant calibration tables, and creating the CORRECTED_DATA scratch column. The original DATA column is untouched.

The applycal task does this. The inputs are:

```python
# applycal :: Apply calibrations solutions(s) to data
vis = '' # Name of input visibility file
field = '' # Select field using field id(s) or field name(s)
spw = '' # Select spectral window/channels
intent = '' # Select observing intent
selectdata = True # Other data selection parameters
timerange = '' # Select data based on time range
uvrange = '' # Select data within uvrange (default units # meters)
antenna = '' # Select data based on antenna/baseline
scan = '' # Scan number range
observation = '' # Select by observation ID(s)
msselect = '' # Optional complex data selection (ignore for # now)
gaintable = [''] # Gain calibration table(s) to apply on the fly
gainfield = [''] # Select a subset of calibrators from # gaintable(s)
interp = [''] # Interp type in time[,freq], per gaintable. # default=linear,linear
spwmap = [] # Spectral windows combinations to form for # gaintables(s)
gaincurve = False # Apply internal VLA antenna gain curve # correction
opacity = [] # Opacity correction to apply (nepers), per spw
parang = False # Apply parallactic angle correction
calwt = True # Calibrate data weights from all relevant # calibrations
applymode = '' # Calibration mode:
# ""="calflag","trial","flagonly", or "calonly"
flagbackup = True # Automatically back up the state of flags before # the run?
async = False # If true the taskname must be started using # applycal(...)
```

As in other tasks, setting selectdata=True will open up the other selection sub-parameters (see §2.3). In addition, you can also select data based on the scan intents that were set during the observations (find them through listobs). Many of the other parameters are the common calibration parameters that are described in §4.4.1.
The single non-standard parameter is the **calwt** option to toggle the ability to scale the visibility weights by the inverse of the products of the scale factors applied to the amplitude of the antenna gains (for the pair of antennas of a given visibility). This should in **almost all cases** be set to its default (`True`). The weights should reflect the inverse noise variance of the visibility, and errors in amplitude are usually also in the weights.

**Alert:** Current (as of June 2010) VLA data has no weights to the data. To avoid trouble, `calwt=False` should be set for those data sets. Older VLA data should still be calibrated with `calwt=True`.

For **applycal**, the list of final cumulative tables is given in **gaintable**. In this case you will have run **accum** if you have done incremental calibration for any of the types, such as `’G’`. You can also feed **gaintable** the full sets and rely on use of **gainfield**, **interp** and **spwmap** to do the correct interpolation and transfer. In particular, for frequency interpolation, the interpolation methods ending in `’PD’`, **nearestPD** and **linearPD** also scale the phase by the frequency ratio between the measured and interpolated values. It is often more convenient to go through accumulation of each type with **accum** as described above (see § 4.5.5.2), as this makes it easier to keep track of the sequence of incremental calibration as it is solved and applied. You can also do any required smoothing of tables using **smoothcal** (§ 4.5.4), as this is not yet available in **accum** or **applycal**.

**applycal** has different **applymodes**: `’calflag’` will apply all flags from a calibration table to the data and apply the calibration itself to the remaining visibilities. `’trial’` will only report on the calibration table flags but not manipulate the data, `’flagonly’` applies the flags but not the calibration itself, and `’calonly’` will apply the calibration and but not the solution table flags. Data that would `’calflag’` would flag are thus passed through uncalibrated. This option can be useful when **applycal** is executed in consecutive steps, one calibration table at a time. Portions of the data that were not calibrated in the first run can then be calibrated in a second run with a different calibration table. This option should be used with care such that no uncalibrated data remains in the final data product.

**applycal** will flag all data that have no calibration solution. Flags will distribute into all of your scratch columns, ie. it will affect your uncalibrated visibilities, too. To be able to restore the flags to the state before **applycal** is starting its duty, the task will make a backup of your current flags by default (`flagbackup=True`). Restore them with **flagmanager**, if you are not happy with the **applycal** results.

If you are not doing polarization calibration or imaging, then you can set `parang=False` to make the calculations faster. If you are applying polarization calibration, or wish to make polarization images, then set `parang=True` so that the parallactic angle rotation is applied to the appropriate correlations. Currently, you must do this in **applycal** as this cannot be done on-the-fly in **clean** or **mosaic**. See § 4.4.1.3 for more on `parang`.

For example, to apply the final bandpass and flux-scaled gain calibration tables solutions to the NGC5921 data:

```python
default(‘applycal’)

vis=’ngc5921.usecase.ms’
```
# We want to correct the calibrators using themselves
# and transfer from 1445+099 to itself and the target N5921

# Start with the fluxscale/gain and bandpass tables
gaintable=['ngc5921.usecase.fluxscale','ngc5921.usecase.bcal']

# pick the 1445+099 (field 1) out of the gain table for transfer
# use all of the bandpass table
gainfield = ['1','*']

# interpolation using linear for gain, nearest for bandpass
interp = ['linear','nearest']

# only one spw, do not need mapping
spwmap = []

# all channels, no other selection
spw = ''
selectdata = False

# no prior calibration
gaincurve = False
 opacity = 0.0

# select the fields for 1445+099 and N5921 (fields 1 and 2)
field = '1,2'
applycal()

# Now for completeness apply 1331+305 (field 0) to itself

field = '0'
gainfield = ['0','*']
applycal()

# The CORRECTED_DATA column now contains the calibrated visibilities

In another example, we apply the final cumulative self-calibration of the Jupiter continuum data obtained in the example of §4.5.5.2:

applycal(vis='jupiter6cm.usecase.split.ms',
         gaintable='jupiter6cm.usecase.selfcal1',
         selectdata=False)

Again, it is important to remember the relative nature of each calibration term. A term solved for in the presence of others is, in effect, residual to the others, and so must be used in combination with them (or new versions of them) in subsequent processing. At the same time, it is important to avoid isolating the same calibration effects in more than one term, e.g., by solving for both 'G' and 'T' separately (without applying the other), and then using them together.
It is always a good idea to examine the corrected data after calibration (using `plotxy` to compare the raw (`data`) and corrected (`corrected`) visibilities), as we describe next.

### 4.6.2 Examine the Calibrated Data

Once the source data is calibrated using `applycal`, you should examine the $uv$ data and flag anything that looks bad. If you find source data that has not been flanked by calibration scans, delete it (it will not be calibrated).

For example, to look at the calibrated Jupiter data in the last example given in the previous section:

```python
plotxy('jupiter6cm.usecase.split.ms','uvdist','amp','corrected',
       selectdata=True,correlation='RR LL',fontsize = 14.0)
```

will show the `CORRECTED_DATA` column. See Figure 4.10.

See § 3.3 for a description of how to display and edit data using `plotms` or `plotxy`, and § 7.5 for use of the `viewer` to visualize and edit a Measurement Set.

### 4.6.3 Resetting the Calibration Models (delmod and clearcal)

Whenever calibration tasks are run, the models associated with the MS will be overwritten. Sometimes, however, one would like to completely remove the model and the task `delmod` can perform this functionality:

```python
# delmod :: Deletes model representations in the MS
vis     = ''   # Name of input visibility file (MS)
otf     = True  # Delete the on-the-fly model data keywords
scr     = False # Delete the MODEL_DATA scr col (if it exists)
async   = False # If true the taskname must be started using
                # delmod(...)              
```

To do so, the parameter `otf` should be set to `True`. `delmod` can also be used if for any reason a `MODEL` column was created and should be removed to avoid confusion between the on-the-fly model and the `MODEL` column (the `MODEL_DATA` column was required in CASA 3.3 and earlier). This can be achieved with `scr=T`.

`delmod` replaces the functionality of the older `clearcal` task. If one still decides to use the `MODEL_DATA` columns, however, `clearcal` is still useful and will reset both the `MODEL_DATA` and `CORRECTED_DATA` columns to unity:

CASA <11>: inp clearcal
---------> inp(clearcal)

```python
# clearcal :: Re-initializes the calibration for a visibility data set
vis     = ''   # Name of input visibility file (MS)
field   = ''   # Select field using field id(s) or field name(s)
spw     = ''   # Select spectral window/channel.
intent  = ''   # Select observing intent
```

CASA <11>: inp clearcal
---------> inp(clearcal)

```python
# clearcal  :: Re-initializes the calibration for a visibility data set
vis     = ''   # Name of input visibility file (MS)
field   = ''   # Select field using field id(s) or field name(s)
spw     = ''   # Select spectral window/channel.
intent  = ''   # Select observing intent
```
with `field`, `spw`, and `intent` being data selection parameters. With the introduction of the on-the-fly calculation of the MODEL visibilities, and the fact that `applycal` overwrites any previously existing `CORRECTED_DATA` column, `clearcal` is not required anymore unless `usescratch=True` is chosen in calibration tasks, and it is also not recommended to use `clearcal` to create the scratch columns at the beginning of data calibration; all benefits from the on-the-fly model would be made obsolete.

### 4.7 Other Calibration and UV-Plane Analysis Options

#### 4.7.1 Splitting out Calibrated uv data (`split`)  

The `split` task will apply calibration and output a new sub-MS containing a specified list of sources (usually a single source). The inputs are:
# split :: Create a visibility subset from an existing visibility set:
vis = '' # Name of input measurement set
outputvis = '' # Name of output measurement set
datacolumn = 'corrected' # Which data column(s) to split out
field = '' # Select field using field id(s) or field name(s)
spw = '' # Select spectral window/channels
width = 1 # Number of channels to average to form one output channel
antenna = '' # Select data based on antenna/baseline
timebin = '0s' # Value for timeaveraging
timerange = '' # Select data based on time range
scan = '' # Select data based on scan numbers
array = '' # Select (sub)array by array ID number(s)
urrange = '' # Select data based on uv distance range
async = False # If true the taskname must be started using split(...)

Usually you will run split with datacolumn='corrected' as previous operations (e.g. applycal) will have placed the calibrated data in the CORRECTED_DATA column of the MS. This will produce a new MS with this corrected data in its DATA column. The modes available in datacolumn are:

- 'data', 'model', 'corrected', # produce MS with single DATA column
- 'data,model', 'data,corrected', 'model,corrected', # pairs of columns
- 'all' # all columns 'data,model,corrected'

We recommend sticking to the simple single-column modes (e.g. 'data' or 'corrected') or 'all' if all columns are in the MS. Further processing may get confused by mismatched pairs of columns.

For example, to split out 46 channels (5-50) from spw 1 of our NGC5921 calibrated dataset:

split(vis='ngc5921.usecase.ms',
      outputvis='ngc5921.split.ms',
      field='2', # Output NGC5921 data (field 2)
      spw='0:5~50', # Select 46 chans from spw 0
datacolumn='corrected') # Take the calibrated data column

4.7.1.1 Averaging in split

Time and channel averaging are now available using the timebin and width parameters.

The timebin parameter gives the averaging interval. It takes a quantity, e.g.

    timebin = '30s'

When time averaging, the ignorables subparameter can be used to specify that the bins should not be split by changes in SCAN_NUMBER, (sub)ARRAY_ID, and/or STATE_ID.

The width parameter defines the number of channels to average to form a given output channel. This can be specified globally for all spw, e.g.

    width = 5
or specified per `spw`, e.g.

```
width = [2,3]
```

to average 2 channels of 1st spectral window selected and 3 in the second one.

**ALERT:** When averaging channels split will produce negative channel widths (as reported by `listobs`) if frequency goes down with increasing channel number, whether or not the input channel widths are negative. The bandwidths and channel resolutions will still be positive.

### 4.7.2 Recalculation of uvw values (fixvis)

Sometimes the u,v,w coordinates of a measurement set are not recorded correctly by the correlator. In those cases, it may be necessary to recalculate them based on the antenna positions. `fixvis` will perform this task.

```
# fixvis :: Recalculates (u, v, w) and/or changes Phase Center
vis = '' # Name of the input visibility set.
outputvis = '' # Name of the output visibility set. (Can be the same
 # as vis.)
field = '' # Fields to operate on. = all.
refcode = '' # reference frame to convert UVW coordinates to
reuse = True # base UVW calculation on the old values?
phasedcenter = '' # use this direction as phase center
async = False # If true the taskname must be started using fixvis(...) 
```

A useful feature of `fixvis` is that it can also change the phase center of a measurement set. This can be done with absolute coordinates or using offsets. An example is:

```
fixvis(vis='Moon.ms',outputvis='Moon-fixed.ms',field='Moon', phasedir='J2000 9h25m00s 05d12m00s')
```

that will recalculate the u,v,w coordinates relative to the new phase center for the field 'Moon'.

### 4.7.3 Hanning smoothing of uv data (hanningsmooth)

For strong spectral line sources (like RFI sources), the Gibbs phenomenon may cause ringing across the frequency channels of an observation. This is called the Gibbs phenomenon and a proven remedy is the Hanning smoothing algorithm. Hanning smoothing is a running mean across the spectral axis with a triangle as a smoothing kernel. The central channel is weighted by 0.5 and the two adjacent channels by 0.25 to preserve the flux. Hanning smoothing significantly reduces Gibbs ringing but there’s no gain without a penalty and here it is the loss of a factor of two in spectral resolution.

In CASA, the `hanningsmooth` task will apply Hanning smoothing to a spectral line uv data measurement set. The inputs are:
# hanningsmooth :: Hanning smooth frequency channel data to remove Gibbs ringing

```
vis = '' # Name of input visibility file (MS)
datacolumn = 'all' # the name of the MS column into which
                 # to write the smoothed data
outputvis = '' # name of the output visibility file
              # (MS)
async = False # If true the taskname must be started
              # using hanningsmooth(...)
```

`hanningsmooth` will operate on the input measurement set if no `outputvis` file name is provided. This option will keep the disk usage of large datasets under control. But one should be aware that the data is overwritten. If `outputvis` is provided, the task will copy the input MS to a new file with that name and operate there. The `datacolumn` parameter determines which of the data columns is to be Hanning smoothed: `all`, `corrected` or `data`. `all` refers to both, the `CORRECTED_DATA` and the `DATA` column. If `corrected` is specified but does not exist in the MS, `hanningsmooth` will create this column for your convenience.

**ALERT:** We intend to make the kernel size a user supplied parameter. In the longer term we intend to offer other varieties of spectral smoothing as well.

### 4.7.4 Model subtraction from uv data (uvsub)

The `uvsub` task will subtract the Fourier transform of the associated model of the MS (added to the MS with the tasks `ft` or `setjy`) from that in the `CORRECTED_DATA` column in the input MS and store the result in that same `CORRECTED_DATA` column.

The reverse operation is achieved by specifying `reverse = True`: in that case `uvsub` will add the value of the Fourier transform of the associated model to that in the `CORRECTED_DATA` column in the input MS and store the result in that same `CORRECTED_DATA` column.

The inputs are:

```
# uvsub :: Subtract/add model from/to the corrected visibility data.
vis = '' # Name of input visibility file (MS)
reverse = False # reverse the operation (add rather than subtract)
async = False
```

For example:

```
uvsub('ngc5921.split.ms')
```

**ALERT:** Currently, `uvsub` operates on the `CORRECTED_DATA` column in the MS `vis`. Eventually we will provide the option to write out a new MS.
4.7.5 UV-Plane Continuum Subtraction (uvcontsub)

At this point, consider whether you are likely to need continuum subtraction. If there is significant continuum emission present in what is intended as a spectral line observation, continuum subtraction may be desirable. You can estimate and subtract continuum emission in the \textit{uv}-plane prior to imaging or wait and subtract an estimate of it in the image-plane. Note that neither method is ideal, and the choice depends primarily upon the distribution and strength of the continuum emission. Subtraction in the \textit{uv}-plane is desirable if continuum emission dominates the source, since deconvolution of the line emission will be more robust if it not subject to the deconvolution errors of the brighter continuum. There is also a performance benefit since the continuum is nearly the same in each channel of the observation, and it is desirable to avoid repeating its deconvolution in each channel. However, doing the continuum estimation in the \textit{uv}-plane has the serious drawback that interpolating visibilities between channels is only a good approximation for emission from near the phase center. Thus, \texttt{uvcontsub} will do an increasingly poor job for emission distributed further from the phase center. If the continuum emission is relatively weak, it is usually adequate to subtract it in the image plane; this is described in the Image Analysis section of this cookbook. Here, we describe how to do continuum subtraction in the \textit{uv}-plane.

The \textit{uv}-plane continuum subtraction is performed by the \texttt{uvcontsub} task. First, determine which channels in your data cube do not have line emission, perhaps by forming a preliminary image as described in the next chapter. This image will also help you decide whether or not you need to come back and do \textit{uv}-plane continuum subtraction at all.

The inputs to \texttt{uvcontsub} are:

\begin{verbatim}
# uvcontsub :: Continuum fitting and subtraction in the uv plane
vis = ''  # Name of input MS. Output goes to vis + ".contsub"
# (will be overwritten if already exists)
field = ''  # Select field(s) using id(s) or name(s)
fitspw = ''  # Spectral window:channel selection for fitting the continuum
combine = ''  # Data axes to combine for the continuum estimation
# (none, or spw and/or scan)
solint = 'int'  # Continuum fit timescale (int recommended!)
fitorder = 0  # Polynomial order for the fits
spw = ''  # Spectral window selection for output
want_cont = False  # Create vis + ".cont" to hold the continuum estimate.
async = False  # If true the taskname must be started using
# uvcontsub(...)  
\end{verbatim}

For each baseline, and over the timescale specified in \texttt{solint}, \texttt{uvcontsub} will provide a polynomial fit to the real and imaginary parts of the (continuum-only) channels specified in \texttt{fitspw} (using the standard \texttt{spw} selection syntax), and then subtract this model from all channels specified in \texttt{spw}, or from all channels in spectral windows of \texttt{fitspw} if \texttt{spw='}'. By setting the subparameter \texttt{excludechannels=True}, the channel selection in \texttt{fitspw} will be inverted. In that case one can select the line channels themselves and/or corrupted channels that are not used in the continuum fit to the data. \texttt{fitspw} can also take frequency ranges, e.g.
where '*' indicates to go across all spws.

Typically, low orders for the polynomial work best, like $0^{\text{th}}$ (a constant), or $1^{\text{st}}$ order (a linear fit). Use higher orders with caution and check your results carefully.

Usually, one should set $\text{solint}=\text{'int'}$ which does no averaging and fits each integration. However, if the continuum emission comes from a small region around the phase center and $\text{fitorder} = 0$, then you can set solint larger (as long as it is shorter than the timescale for changes in the visibility function of the continuum). If your scans are short enough you can also use scan averaging with $\text{combine}=\text{'scan'}$ and $\text{solint}=\text{'inf'}$. Be warned, setting solint too large will introduce “time smearing” in the estimated continuum and thus not properly subtract emission not at the phase center. Increasing solint speeds up the calculation but it does not improve the overall result quality of $\text{uvcontsub}$ - although the continuum estimates of each baseline may be noisy (just like each visibility in a continuum MS may be noisy), it is better to use the ensemble of individual fits than to average the ensemble before fitting. Note that $\text{plotms}$ can do time and baseline averaging on the fly to help you examine noisy data.

So, the recommended procedure is as follows:

- Finish calibration as described in the previous chapter.
- Use the invert or clean task on the split result to form an exploratory image that is useful for determining the line-free channels.
- Use $\text{uvcontsub}$ with as low fit orders as possible to estimate and subtract the continuum from $\text{vis}$, and write the continuum-subtracted dataset to $\text{vis + '.contsub'}$.
- Use $\text{clean}$ with $\text{vis + '.contsub'}$ to make an image cube of the line emission.
- If a continuum image is desired, clean the line-free channels of the original MS with $\text{mode='mfs'}$ and $\text{spw=fitspw}$. Note that using the line free channels directly is preferred over the imaging the 'continuum' model fitted by $\text{uvcontsub}$. The fitting procedure will also fit noise and artifacts which produce a nice line cube when subtracted, but the model may not represent the true underlying continuum.

For example, we perform $\text{uv}$-plane continuum subtraction on our NGC5921 dataset:

```
# Want to use channels 4-6 and 50-59 for continuum
$\text{uvcontsub(vis='ngc5921.usecase.ms,}$
$\text{field='NS5921',}$
$\text{spw='',}$ # all spw (only 0 in this data)
$\text{fitspw='0:4~7;50~59'}$ # channels 4-6 and 50-59
$\text{solint='int',}$ # leave it at the default
$\text{fitorder=0)}$ # mean only

# You will see it made a new MS:
# ngc5921.usecase.ms.contsub"
4.7.6 Spectral regridding of the MS (cvel)

Although not strictly a calibration operation, spectral regridding of a MS is available to aid in calibration operations (e.g. continuum subtraction) and preparation for imaging. For this purpose, the cvel task has been developed.

The inputs are:

```plaintext
# cvel :: regrid an MS to a new spectral window / channel structure or frame
vis = '' # Name of input measurement set
outputvis = '' # Name of output measurement set
passall = False # Pass through (write to output MS) non-selected data with no change
field = '' # Select field using field id(s) or field name(s)
spw = '' # Select spectral window/channels
selectdata = False # Other data selection parameters
mode = 'velocity' # Regridding mode
nchan = -1 # Number of channels in output spw (-1=all)
start = 0 # Velocity of first image channel: e.g '0.0km/s'
width = 1 # image channel width in velocity units: e.g '-1.0km/s'
interpolation = 'linear' # Spectral interpolation method
phasecenter = '' # Image phase center: position or field index
restfreq = '' # rest frequency (see help)
outframe = '' # Output frame (''=keep input frame)
veltype = 'radio' # velocity definition
hanning = False # If true, Hanning smooth data before regridding to remove Gibbs ringing.
async = False # If true the taskname must be started using cvel(...)
```

The key parameters for the operation of cvel are the regridding mode, the output reference outframe and veltype, and the standard selection parameters (in particular spw and field).

The syntax for mode options ('channel','velocity','frequency','channel_b') has been made compatible with the respective modes of clean ($\S$ 5.2.5). The combination of selected spw and mode will determine the output channels and spw(s):

```plaintext
spw = 0,1; mode = channel
# will produce a single spw containing all channels in spw 0 and 1
spw=0:5^2; mode = channel
# will produce a single spw made with channels (5,7,9,...,25,27)
spw = 0; mode = channel; nchan=3; start=5; width=4
# will produce an spw with 3 output channels
# new channel 1 contains data from channels (5+6+7+8)
# new channel 2 contains data from channels (9+10+11+12)
# new channel 3 contains data from channels (13+14+15+16)
spw = 0:63^2; mode=channel; nchan=21; start = 0; width = 1
# will produce an spw with 21 channels
# new channel 1 contains data from channel 0
```
The simplest use of `cvel` is to shift a single spectral window into an output frame without regridding. This is done with `mode='channel'`. For example:

```python
cvel(vis='test_w3oh_nohann.ms',
     outputvis = 'test_w3oh_nohann_chanbary.ms',
     mode='channel',nchan=-1,start=0,width=1,
     interpolation='linear',
     phasecenter='',
     spw='',
     restfreq='1665.4018MHz',
     outframe='BARY')
```

does this for an observation of the OH line.

There is also a special `mode='channel_b'` that does not force a linear output frequency grid, e.g. for irregularly spaced/overlapping spectral windows), but is nominally faster. This is not equivalent to a `clean` output gridding mode, although `clean` will work on this spectral lattice.

Mode `channel` is intended to not interpolate between channels. It will perform binning if needed. For most scientific applications we recommend using the `mode='velocity'` and `mode='frequency'` options, as it is easiest to determine what the resulting channelization will be. For example:

```python
cvel(vis='test_w3oh_nohann.ms',
     outputvis = 'test_w3oh_nohann_cvellsrk.ms',
     mode='velocity',nchan=45,start='-35.0km/s',width='-0.55km/s',
     interpolation='linear',
     phasecenter='',
     spw='',
     restfreq='1665.4018MHz',
     outframe='LSRK')
cvel(vis='test_w3oh_nohann.ms',
     outputvis = 'test_w3oh_nohann_cvelbary.ms',
     mode='velocity',nchan=45,start='-35.0km/s',width='-0.55km/s',
     interpolation='linear',
     phasecenter='',
     spw='',
     restfreq='1665.4018MHz',
     outframe='BARY')
```

will transform a MS into the LSRK and BARYcenter frames respectively.
The sign of the width parameter determines whether the channels run along increasing or decreasing values of frequency or velocity (i.e., if the cube is reversed or not).

The intent of cvel regridding is to transform channel labels and the visibilities to a spectral reference frame which is appropriate for the science analysis, e.g., from TOPO to LSRK, e.g., to correct for Doppler shifts throughout the time of the observation. Naturally, this will change the shape of the spectral features to some extent. According to the Nyquist theorem you should oversample a spectrum with twice the numbers of channels to retain the shape. Based on some tests, however, we recommend to observe with at least 3-4 times the number of channels for each significant spectral feature (like 3-4 channels per linewidth). This will minimize regridding artifacts in cvel.

If cvel has already established the grid that is desired for the imaging, clean should be run with the default channel mode (> width=1) or with exactly the same frequency/velocity parameters as was used in cvel. This will avoid additional regridding in clean. Hanning smoothing is optionally offered in cvel, but tests have shown that already the regridding process itself, if it involved a transformation from TOPO to a non-terrestrial reference frame, implies some smoothing (due to channel interpolation) such that Hanning smoothing may not be necessary.

The interpolation method fftshift calculates the transformed visibilities by applying a FFT, then a phase ramp, and then an inverse FFT. Note that if you want to use this interpolation method, your frequency grid needs to be equidistant, i.e., it only works in mode velocity with veltype=radio, in mode frequency, and in mode channel (in the latter only if the input grid is itself equidistant in frequency). Note also that, as opposed to all other interpolation methods, this method will apply a constant (frequency-independent) shift in frequency which is not fully correct in the case of large fractional bandwidth of the given spectral window.

4.7.7 UV-Plane Model Fitting (uvmodelfit)

It is often desirable to fit simple analytic source component models directly to visibility data. Such fitting has its origins in early interferometry, especially VLBI, where arrays consisted of only a few antennas and the calibration and deconvolution problems were poorly constrained. These methods overcame the calibration uncertainties by fitting the models to calibration-independent closure quantities and the deconvolution problem by drastically limiting the number of free parameters required to describe the visibilities. Today, even with larger and better calibrated arrays, it is still desirable to use visibility model fitting in order to extract geometric properties such as the positions and sizes of discrete components in radio sources. Fits for physically meaningful component shapes such as disks, rings, and optically thin spheres, though idealized, enable connecting source geometry directly to the physics of the emission regions.

Visibility model fitting is carried out by the uvmodelfit task. The inputs are:

```
# uvmodelfit :: Fit a single component source model to the uv data:

vis = '' # Name of input visibility file
field = '' # field name or index
spw = '' # spectral window
selectdata = False # Activate data selection details
```
niter = 5  # Number of fitting iterations to execute
comptype = 'P'  # Component type (P=pt source,G=ell. gauss,D=ell. disk)
sourcepar = [1, 0, 0]  # Starting guess (flux,xoff,yoff,bmajaxrat,bpa)
varypar = []  # Which parameters can vary in fit
outfile = ''  # Optional output component list table
async = False  # if True run in the background, prompt is freed

**ALERT:** This task currently only fits a single component.

The user specifies the number of non-linear solution iterations (niter), the component type (comptype), an initial guess for the component parameters (sourcepar), and optionally, a vector of Booleans selecting which component parameters should be allowed to vary (varypar), and a filename in which to store a CASA componentlist for use in other applications (file). Allowed comptypes are currently point 'P' or Gaussian 'G'.

The function returns a vector containing the resulting parameter list. This vector can be edited at the command line, and specified as input (sourcepar) for another round of fitting.

The sourcepar parameter is currently the only way to specify the starting parameters for the fit. For points, there are three parameters: I (total flux density), and relative direction (RA, Dec) offsets (in arcsec) from the observation’s phase center. For Gaussians, there are three additional parameters: the Gaussian’s semi-major axis width (arcsec), the aspect ratio, and position angle (degrees). It should be understood that the quality of the result is very sensitive to the starting parameters provided by the user. If this first guess is not sufficiently close to the global $\chi^2$ minimum, the algorithm will happily converge to an incorrect local minimum. In fact, the $\chi^2$ surface, as a function of the component’s relative direction parameters, has a shape very much like the inverse of the absolute value of the dirty image of the field. Any peak in this image (positive or negative) corresponds to a local $\chi^2$ minimum that could conceivably capture the fit. It is the user’s responsibility to ensure that the correct minimum does the capturing.

Currently, uvmodelfit relies on the likelihood that the source is very near the phase center (within a beamwidth) and/or the user’s savvy in specifying the starting parameters. This fairly serious constraint will soon be relieved somewhat by enabling a rudimentary form of uv-plane weighting to increase the likelihood that the starting guess is on a slope in the correct $\chi^2$ valley.

Improvements in the works for visibility model fitting include:

- User-specifiable uv-plane weighting
- Additional component shapes, including elliptical disks, rings, and optically thin spheroids.
- Optional calibration pre-application
- Multiple components. The handling of more than one component depends mostly on efficient means of managing the list itself (not easy in command line options), which are currently under development.
- Combined component and calibration fitting.
CHAPTER 4. SYNTHESIS CALIBRATION

Example (see Figure 4.11):

```
# Note: It's best to channel average the data if many channels
# before running a modelfit
#
split('ngc5921.ms','1445+099_avg.ms',
datacolumn='corrected',field='1445*',width='63')

# Initial guess is that it's close to the phase center
# and has a flux of 2.0 (a priori we know it's 2.47)
uvmodelfit('1445+099_avg.ms', # use averaged data
  niter=5, # Do 5 iterations
  comptype='P', # P=Point source, G=Gaussian, D=Disk
  sourcepar=[2.0,.1,.1], # Source parameters for a point source
  outfile='gcal.cl') # Output component list file

# Output looks like:
There are 19656 - 3 = 19653 degrees of freedom.
iter=0: reduced chi2=0.0418509: I=2, dir=[0.1, 0.1] arcsec
iter=1: reduced chi2=0.003382: I=2.48562, dir=[-0.020069, -0.0268826] arcsec
iter=2: reduced chi2=0.00338012: I=2.48614, dir=[0.00323428, -0.00232235] arcsec
iter=3: reduced chi2=0.00338012: I=2.48614, dir=[0.00325324, -0.00228963] arcsec
iter=4: reduced chi2=0.00338012: I=2.48614, dir=[0.00325324, -0.00228963] arcsec
iter=5: reduced chi2=0.00338012: I=2.48614, dir=[0.00325324, -0.00228963] arcsec
If data weights are arbitrarily scaled, the following formal errors
  will be underestimated by at least a factor sqrt(reduced chi2). If
  the fit is systematically poor, the errors are much worse.
I = 2.48614 +/- 0.0176859
x = 0.00325324 +/- 0.163019 arcsec
y = -0.00228963 +/- 0.174458 arcsec
Writing componentlist to file: /home/sandrock/smyers/Testing/Patch2/N5921/gcal.cl

# Fourier transform the component list to a model of the MS
ft('1445+099_avg.ms', complist='gcal.cl')

# Plot data versus uv distance
plotxy('1445+099_avg.ms', xaxis='uvdist', datacolumn='corrected')

# Specify green circles for model data (overplotted)
plotxy('1445+099_avg.ms', xaxis='uvdist', datacolumn='model',
  overplot=True, plotsymbol='go')

4.7.8 Reweighing visibilities based on their scatter (statwgt)

Alert: statwgt is still an experimental task. Please check the results carefully and report any
problems to the NRAO CASA helpdesk.
Figure 4.11: Use of plotxy to display corrected data (red and blue points) and uv model fit data (green circles).

In most cases, the data that comes from the telescopes have the correct absolute or relative weights associated (absolute weights will be supplied once the VLA switched power application becomes standard; for ALMA the Tsys application is already in place). However, there are data sets where one would like to adjust the weights based on the scatter of the visibilities (typically as a function of time, antenna, and/or baseline). This calculation is performed by the task `statwt` that updates the WEIGHT and SIGMA columns of the measurement set. `statwt` inputs are:

```plaintext
# statwt :: Reweight visibilities according to their scatter
vis = ''            # Name of measurement set
drms = False        # Use rms instead of stddev?
byantenna = False   # Estimate the noise per antenna -not
                    # implemented (vs. per baseline)
fitspw = ''         # The signal-free spectral window:channels
                    # to estimate the scatter from
fitcorr = ''        # The signal-free correlation(s) to estimate
                    # the scatter from (not implemented)
```
combine = '' # Let estimates span changes in spw, corr, # scan and/or state

# Bin length for estimates (not implemented)
timebin = '0s'

# Minimum number of unflagged visibilities for estimating the scatter
minsamp = 2

# Select field using ID(s) or name(s)
field = ''

# Select spectral window/channels
spw = ''

# Select data based on antenna/baseline
antenna = ''

time = '' # Select data by time range

# Select data by scan numbers
scan = ''

# Select data by scan intents
intent = ''

# Select (sub)array(s) by array ID number
array = ''

# Select correlations to reweight
correlation = ''

# Select by observation ID(s)
observation = ''

datacolumn = 'corrected' # Which data column to calculate the scatter from

async = False # If true the taskname must be started using statwt(...)

statwt should only be run after all calibration steps have been performed. The parameter dorms switches from a scatter standard deviation to a root mean square scatter estimator. datacolumn specifies the column on which the task operates and the usual data selection parameters apply. Channels with strong RFI or a spectral line should be avoided for the calculation and good channel range should be specified via fitspw. In its current implementation, statwgt uses data samples of an integration time interval but eventually wider sample intervals can be specified by the timebin parameter. Those samples are contained within a scan, spw, and polarization product but using the combine can relax this restriction. minsamp sets the minimum number of unflagged visibilities used for the calculation.

4.7.9 Change the signs of visibility phases (conjugatevis)

conjugatevis is an easy task to flip the signs of the phases of visibilities, thus creating the complex conjugate numbers. The inputs are like:

# conjugatevis :: Change the sign of the phases in all visibility columns.
vis = '' # Name of input visibility file.
spwlist = '' # Spectral window selection
outputvis = '' # Name of output visibility file
overwrite = False # Overwrite the outputvis if it exists.
async = False # If true the taskname must be started using conjugatevis(...)

The task works on all scratch columns.

4.8 Examples of Calibration

The data reduction tutorials on casaguides.nrao.edu provide walkthroughs for high and low frequency, spectral line and polarization calibration techniques.
Chapter 5

Synthesis Imaging

This chapter describes how to make and deconvolve images starting from calibrated interferometric data, possibly supplemented with single-dish data or an image made from single-dish data. This data must be available in CASA (see §2 on importing data). See §4 for information on calibrating synthesis data. In the following sections, the user will learn how to make various types of images from synthesis data, reconstruct images of the sky using the available deconvolution techniques, include single-dish information in the imaging process, and to prepare to use the results of imaging for improvement of the calibration process (“self-calibration”).

5.1 Imaging Tasks Overview

The current imaging and deconvolution tasks are:

- **clean** — calculate a deconvolved image with a selected clean algorithm, including mosaicing, or make a dirty image (§5.3),
- **feather** — combine a single dish and synthesis image in the Fourier plane (§5.5),
- **deconvolve** — image-plane only deconvolution based on the dirty image and beam, using one of several algorithms (§5.8),
- **pclean** — an experimental task for **clean** to work in a parallelized way for multi-node and core computing systems (§5.10)

There are also tasks that help you set up the imaging or interface imaging with calibration:

- **boxit** - create “cleanbox” deconvolution regions automatically from an image (§5.6.1),
• ft - add a source model to the MS (§ 5.7).

The full “tool kit” that allows expert-level imaging must still be used if you do not find enough functionality within the tasks above.

Information on other useful tasks and parameter setting can be found in:

• listobs — list what’s in a MS (§ 2.2.6),
• split— Write out new MS containing calibrated data from a subset of the original MS (§ section: cal.split),
• cvel — regrid a spectral MS onto a new frequency channel system (§ 4.7.6),
• data selection — general data selection syntax (§ 2.3),
• viewer — image display including region statistics and image cube slice and profile capabilities (§ 7).

5.2 Common Imaging Task Parameters

We now describe some parameters are are common to the imaging tasks. These should behave the same way in any imaging task that they are found in. These are in alphabetical order.

**Inside the Toolkit:**

The im.setimage method is used to set many of the common image parameters. The im.advise method gives helpful advice for setting up for imaging.

**ALERT:** clean tries to use up to four cores on the computer that it is running on. If this is not desired, the environment variable OMP_NUM_THREAD can be set to a lower value.

5.2.1 Parameter cell

The cell parameter defines the pixel size in the x and y axes for the output image. If given as floats or integers, this is the cell size in arc seconds, e.g.

```
cell=[0.5, 0.5]
```

make 0.5″ pixels. You can also give the cell size in quantities, e.g.

```
cell=['1arcmin', '1arcmin']
```

If a single value is given, then square pixels of that size are assumed.
5.2.2 Parameter field

The **field** parameter selects the field indexes or names to be used in imaging. Unless you are making a mosaic, this is usually a single index or name:

```python
field = '0'  # First field (index 0)
field = '1331+305'  # 3c286
field = '*'  # all fields in dataset
```

The syntax for **field** selection is given in §2.3.2.

5.2.3 Parameter imagename

The value of the **imagename** parameter is used as the root name of the output image. Depending on the particular task and the options chosen, one or more images with names built from that root will be created. For example, the **clean** task run with `imagename='ngc5921` a series of output images will be created with the names `ngc5921.clean`, `ngc5921.residual`, `ngc5921.model`, etc.

If an image with that name already exists, it will in general be overwritten. Beware using names of existing images however. If the **clean** is run using an **imagename** where `<imagename>.residual` and `<imagename>.model` already exist then **clean** will continue starting from these (effectively restarting from the end of the previous **clean**). Thus, if multiple runs of **clean** are run consecutively with the same **imagename**, then the cleaning is incremental (as in the **difmap** package).

The output image may also have a different beam per plane. For datasets with very large fractional bandwidth, **clean** will use a different PSF for each channel when the PSF changes by more than half a pixel as a function of frequency. To smooth to a common resolution, use the parameter **restoringbeam** within **clean** (§5.3.11) or the task **imsmooth** after **cleaning**. Data analysis tasks such as **immoments** in CASA support changing beams per plane.

5.2.4 Parameter imsize

The image size in numbers of pixels on the x and y axes is set by **imsize**. For example,

```python
imsize = [640, 640]
```

makes a square image 640 pixels on a side. If a single value is given, then a square image of that dimension is made. The underlying algorithms work best for certain image sizes. If you pick a size where that algorithm will be particularly slow, the logger will send a warning message, suggesting the nearest optimal values. In general, the best performance is obtained with image sizes that are even and factorizable to 2,3,5,7 only. An easy rule of thumb would be $2^n \times 10$ where $n$ is an integer number, like 160, 320, 640, 1280, 2560, etc.
5.2.5 Parameter mode

The **mode** parameter defines how the frequency channels in the synthesis MS are mapped onto the image. The allowed values are: **mfs, channel, velocity, frequency**. The **mode** parameter is expandable, with some options uncovering a number of sub-parameters, depending upon its value.

5.2.5.1 Mode mfs

```plaintext
mode = 'mfs'  # Spectral gridding type (mfs, channel,
# velocity, frequency)
nterms = 1  # Number of terms used to model the sky
# frequency dependence (Note: nterms>1
# is under development)
reffreq = '' # Reference frequency for MFS (relevant
# only if nterms > 1),'' defaults to
# central data-frequency
```

The default **mode='mfs'** emulates multi-frequency synthesis in that each visibility-channel datum \( k \) with baseline vector \( B_k \) at wavelength \( \lambda_k \) is gridded into the uv-plane at \( u_k = B_k / \lambda_k \). The result is one or more images (depending on **nterms**), regardless of how many channels are in the input dataset. The first image plane is at the frequency given by the midpoint between the highest and lowest frequency channels in the input spw(s). Currently, there is no way to choose the center frequency of the output image plane independently.

WideBand imaging (**mfs** with **nterms > 1**) is now available in CASA. This algorithm models the wide-band sky brightness as a linear combination of Gaussian-like functions whose amplitudes follow a Taylor-polynomial in frequency. The output images are a set of Taylor-coefficient images, from which spectral index and curvature maps are derived. The **reffreq** parameter sets the reference frequency \( \nu_0 \) about which the Taylor expansion is done. The Taylor expansion is a polynomial in frequency:

\[
I_{\nu}^{\text{sky}} = \sum_t I_t^{\text{sky}} \left( \frac{\nu - \nu_0}{\nu_0} \right)^t
\]  

(5.1)

\( I_t^{\text{sky}} \) an image of the \( t \)th coefficient of the Taylor-polynomial expansion.

When Eq. (5.1) is applied on a source with a spectral index

\[
I_{\nu}^{\text{sky}} = I_{\nu_0}^{\text{sky}} \left( \frac{\nu}{\nu_0} \right)^{\alpha + \beta \log(\nu/\nu_0)}
\]  

(5.2)

The Taylor terms \( I_t^{\text{sky}} \) can be used to constrain the sky brightness, \( \alpha \), and \( \beta \) through

\[
I_{\nu_0}^{\text{sky}} = I_0^{\text{sky}}
\]  

(5.3)
CHAPTER 5. SYNTHESIS IMAGING

\[ \alpha = \frac{I_{\text{sky},1}}{I_{\text{sky},0}} = \frac{I_{\text{sky}}^{\nu_1}}{I_{\text{sky}}^{\nu_0}} \]  \hspace{1cm} (5.4)

\[ \beta = \frac{I_{\text{sky},2}}{I_{\text{sky},0}} - \frac{\alpha(\alpha - 1)}{2} = \frac{I_{\text{sky}}^{\nu_2}}{I_{\text{sky}}^{\nu_0}} - \frac{\alpha(\alpha - 1)}{2} \]  \hspace{1cm} (5.5)


Alert: The MS-MFS (multiscale-multifrequency) algorithm in the current release is new and is still being developed/tested/debugged. Its basic operation has been tested on wide-band JVLA data for Stokes I imaging.

Explanation of the Parameters:

nterms: The number of terms in the Taylor polynomial used to model the frequency structure. nterms > 1 triggers MS-MFS. nterms = 1 triggers standard point-source clean or multi-scale-clean. Note: The choice of nterms follows the same rules used while fitting a polynomial to a 1D set of noisy data points. To prevent overfitting, the order of the polynomial needs to depend on the available signal-to-noise in the data. A very rough rule-of-thumb is as follows: For high SNR data (single channel SNR > 100), and fields dominated by point-sources with spectral indices around \(-1.0\) across a 2:1 bandwidth, choose nterms = 3 or 4. For lower SNR data (5 < SNR < 100), flatter spectra, or when there is significant extended emission, nterms = 2 is a much safer option. For very low SNR data (SNR < 5), choose nterms = 1).

reffreq: The reference frequency used to compute Taylor functions \([(\text{freq} - \text{reffreq})/(\text{reffreq})]^i\). If left blank (reffreq ="), it defaults to the middle frequency of the selected data. Note: For the current release, the use of reffreq=" is recommended.

multiscale: The MS-MFS algorithm always uses scale sizes set via the multiscale parameter. For point-source deconvolution, set multiscale=[0] (also the default). Note: Unlike standard msclean (multiscale = [0,6,10,....] with nterms=1), with higher nterms the largest specified scale size must lie within the sampled range of the interferometer. If not, there can be an ambiguity in the spectral reconstruction at very large spatial scales.

gridmode: Wideband W-Projection is supported, and can be triggered via gridmode='widefield'.

modelimage: Supply a list of Taylor-coefficient images, to start the deconvolution from. If only one image is specified, it will be used as the model for the ‘tt0’ image.

Output images: [xxx.image.tt0, xxx.image.tt1,... ] : Images of Taylor coefficients that describe the frequency-structure. The "tt0" image is the total-intensity image at the reference frequency, and is equivalent to "xxx.image" obtained via standard imaging.

[xxx.image.alpha, xxx.image.beta] : Spectral index and spectral curvature at the reference-frequency. These are computed from tt0, tt1, tt2 only for regions of the image where there is sufficient signal-to-noise to compute them. These regions are chosen via a threshold on the intensity image (tt0) computed as MAX( userthreshold*5 , peakresidual/10 ) ). This threshold is reported in the logger. Elsewhere, the values are currently set to zero.
[xxx.image.alpha.error] contains the errors of the spectral index solutions.

The following is a list of differences between MS-MFS (\texttt{nterms} > 1) and standard imaging, in the current CASA release.

1. Iterations always proceed as cs-clean major/minor cycles, and uses the full psf during minor cycle iterations. There are currently no user-controls on the \texttt{cyclespeedup}, and the flux-limit per major cycle is chosen as 10\% of the peak residual. In future releases, this will be made more adaptive/controllable.

2. Currently, the following options are not supported for \texttt{nterms} > 1: \texttt{psfmode}, \texttt{pbcorr}, \texttt{minpb}, \texttt{imagermode}='mosaic', \texttt{gridmode}='aprojection', \texttt{cyclespeedup}, and allowed are one of Stokes I, Q, U, V, RR, LL, XX, YY at a time. More options and combinations are currently under development and testing. Under 'Using CASA' → 'Other Documentation' → 'Imaging Algorithms in CASA' you can find the latest implementations.

5.2.5.2 **Mode channel**

\textbf{ALERT:} Note that \texttt{mode='channel'} is intended as a shortcut to produce a cube based on the input MS channelization. It will be in the frame of the input MS. We recommend that users instead use the 'velocity' and 'frequency' modes which will produce cubes in other frames with more control of the cube spacing. These modes have defaults that will work from the MS spacing, reproducing the action of \texttt{mode='channel'}.

If \texttt{mode='channel'} is chosen, then an image cube will be created. This is an expandable parameter, with dependent parameters:

\begin{verbatim}
mode = 'channel'  # Spectral image definition(mfs, channel, velocity,frequency)
nchan = -1  # Number of channels (planes) in output image
start = 0  # first input channel to use
width = 1  # Number of input channels to average
interpolation = 'nearest'  # Spectral interpolation(nearest, linear, cubic)
\end{verbatim}

The default \texttt{nchan=-1} will automatically produce a cube with the number of channels needed to span the (regridded) spectral windows of the MS. If multiple MSs are used, the spectral frames of these need to be identical, e.g. LSRK\footnote{\textbf{ALERT:} This often results in extra blank channels at the beginning and end of the image cube, so it is usually more precise to specify \texttt{nchan} and \texttt{start} to get what you want. For best results, we also recommend 'nearest' interpolation for the \texttt{mode=channel}.}

The channelization of the resulting image is determined by the channelization in the MS of \texttt{vis} of the first \texttt{spw} specified (the “reference \texttt{spw}”). The actual channels to be gridded and used in the clean are selected via the \texttt{spw} parameter as usual. The resulting image cube will have \texttt{nchan}
CHAPTER 5. SYNTHESIS IMAGING 267

channels spaced evenly in frequency. The first output channel will be located at the frequency of channel start in the (first) reference spw (independent of what channels are selected using spw). If width > 1, then input MS channels with centers within a frequency range given by \((width + 1)/2\) times the reference spw spacing will be gridded together (as in mode = 'mfs' above) into the channels of the output image cube. The output channel spacing is thus given by width channels in the reference spw of the MS.

The interpolation sub-parameter (§5.2.5.5) sets how channels are gridded into the image cube planes. For 'nearest', the channels in spw beyond the first are mapped into the nearest output image channel within half a channel (if any). Otherwise, the chosen interpolation scheme will be used. Image channels that lie outside the MS frequency range or have no data mapped to them will be blank in the output image, but will be in the cube.

Example:

```python
mode = 'channel'
nchan = 46
start = 5
width = 1
```

which will produce a 46-channel cube starting with channel 5 of the MS with the same channel width as the MS. Note: the start channel is in reference to the channels in the MS, not the subset selected by spw.

5.2.5.3 Mode frequency

For mode='frequency', an output image cube is created with nchan channels spaced evenly in frequency.

```python
mode = 'frequency' # Spectral image definition(mfs, channel, velocity,frequency)
nchan = -1 # Number of channels (planes) in output image
start = '' # Frequency of first image channel: e.g. '1.4GHz'(''=default)
width = '' # Image channel frequency width: e.g '1.0kHz'(''=default)
interpolation = 'linear' # Spectral interpolation(nearest, linear, cubic)
outframe = '' # velocity frame of output image
```

The frequency of the first output channel is given by start and spacing by width. Output channels have width also given by width. The sign of width determines whether the output channels ascend or descend in frequency. Data from the input MS with centers that lie within one-half an input channel overlap of the frequency range of ±width/2 centered on the output channels are gridded together.

The defaults are designed to safely choose output cube channels to span the input MS(s). The default nchan=-1 will choose the number of channels needed to span the frequencies of the channels in the MS. The defaults start=''' and width=''' will use the channel frequency and width of the first channel of the first specified spectral window selected in spw. ALERT: As in “channel” mode, this is currently the first channel of the first spw, not the first channel selected from that spw.
The interpolation sub-parameter (§5.2.5.5) sets how channels are gridded into the image cube planes.

Using the NGC5921 dataset as an example:

```python
mode = 'frequency'
nchan = 21
start = '1412.830MHz'
width = '50kHz'
outframe = 'LSRK'
```

would produce a 21-channel output cube with 50 kHz wide channels rather than the default channelization of the MS (24.4 kHz).

### 5.2.5.4 Mode velocity

If `mode='velocity'` is chosen, then an output image cube with `nchan` channels will be created, with channels spaced evenly in velocity. Parameters are:

```python
mode = 'velocity' # Spectral image definition(mfs, channel, velocity,frequency)
nchan = -1 # Number of channels (planes) in output image
start = '' # Velocity of first image channel: e.g '0.0km/s'(''=default)
width = '' # Image channel velocity width: e.g '-1.0km/s'(''=default)
interpolation = 'linear' # Spectral interpolation(nearest, linear, cubic)
outframe = '' # velocity reference frame of output image; '' =input
veltype = 'radio' # velocity definition
```

Note that velocities are calculated with respect to the rest frequency in the MS or specified through the `restfreq` parameter (§5.2.7).

The velocity of the first output channel is given by `start` and spacing by `width`. Averaging is as in `mode='frequency'`. The interpolation sub-parameter (§5.2.5.5) sets how channels are gridded into the image cube planes.

The defaults are designed to safely choose output cube channels to span the input MS(s). The default `nchan=-1` will choose the number of channels needed to span the velocities of the channels in the MS. The defaults `start=''` and `width=''` will use the channel velocity and width of the first channel of the first specified spectral window selected in `spw`. **ALERT:** As in “channel” mode, this is currently the first channel of the first `spw`, not the first channel selected from that `spw`.

Again, using the NGC5921 dataset as an example:

```python
mode = 'velocity'
nchan = 21
start = '1383.0km/s'
width = '10km/s'
outframe = 'LSRK'
```

Note that in this case the velocity axis runs forward, as opposed to the default channelization for 'channel’ or 'frequency'.
5.2.5.5 Sub-parameter interpolation

The interpolation sub-parameter controls how spectral channels in the MS are gridded into the output image cube. This is available in all modes except ‘mfs’. The options are: ‘nearest’, ‘linear’, ‘cubic’.

For ‘nearest’, the channels in spw beyond the first are mapped into the nearest output image channel within half a channel (if any).

For ‘linear’, the channels are gridded into the planes using weights given by a linear function of the frequency of the MS channel versus the plane. Each input channel will be mapped to 1 or 2 output planes. For most users, this is the best choice.

For ‘cubic’, the channels are gridded using a cubic interpolation function.

‘Linear’ and ‘cubic’ interpolation methods require that there are two datapoints that sandwich your new, regridded bin. This can introduce edge effects like in the first or last channel or adjacent to flagged channels where data is only available on one side of the spectrum. interpolation='nearest' will avoid such edge effects but may not work so well for data with spws that overlap. For mode='velocity' or 'frequency', 'linear' interpolation usually works best and for mode='channel' the ‘nearest’ interpolation method is superior. But this could be different for your dataset and you should carefully check your results.

5.2.6 Parameter phasecenter

The phasecenter parameter indicates which of the field IDs should be used to define the phase center of the mosaic image, or what that phase center is in RA and Dec. The default action is to use the first one given in the field list.

For example:

```
phasecenter='5' # field 5 in multi-src ms
phasecenter='J2000 19h30m00 -40d00m00' # specify position
```

Note that the format for angles prefers to use hm for RA/time units and dm for Dec/Angle units as separators. The colon :: separator is interpreted as RA/time even if its used for the Dec, so be careful not to copy/paste from other sources.

5.2.7 Parameter restfreq

The value of the restfreq parameter, if set, will over-ride the rest frequency in the header of the first input MS to define the velocity frame of the output image.

**ALERT:** The restfreq parameter takes the options of transitions and frequencies as in the corresponding plotxy parameter (§3.3.2.12), but the frame information is controlled under the mode parameter (§5.2.5).

For example:
restfreq='115.2712GHz',

will set the rest frequency to that of the CO 1-0 line.

**ALERT:** Setting `restfreq` explicitly here in `clean` is good practice, and may be necessary if your MS has been concatenated from different files for different spectral windows (§2.2.11).

### 5.2.8 Parameter `spw`

The `spw` parameter selects the spectral windows that will be used to form the image, and possibly a subset of channels within these windows.

The `spw` parameter is a string with an integer, list of integers, or a range, e.g.

```
spw = '1'  # select spw 1
spw = '0,1,2,3'  # select spw 0,1,2,3
spw = '0~3'  # same thing using ranges
```

You can select channels in the same string with a : separator, for example

```
spw = '1:10~30'  # select channels 10-30 of spw 1
spw = '0:55,3:5;6;7'  # chans 5-55 of spw 0 and 5,6,7 of spw 3
```

This uses the standard syntax for `spw` selection is given in §2.3.3. See that section for more options.

Note that the order in which multiple `spws` are given is important for `mode = 'channel'`, as this defines the origin for the channelization of the resulting image.

### 5.2.9 Parameter `stokes`

The `stokes` parameter specifies the Stokes parameters for the resulting images. Note that forming Stokes Q and U images requires the presence of cross-hand polarizations (e.g. RL and LR for circularly polarized systems such as the VLA) in the data. Stokes V requires both parallel hands (RR and LL) for circularly polarized systems or the cross-hands (XY and YX) for linearly polarized systems such as ALMA and ATCA.

This parameter is specified as a string of up to four letters and can indicate stokes parameters themselves, Right/Left hand polarization products, or linear polarization products (X/Y). For example,

```
stokes = 'I'  # Intensity only
stokes = 'IQU'  # Intensity and linear polarization
stokes = 'IV'  # Intensity and circular polarization
stokes = 'IQUV'  # All Stokes imaging
stokes = 'RR'  # Right hand polarization only
stokes = 'XXXXY'  # Both linear polarizations
```
CHAPTER 5. SYNTHESIS IMAGING

are common choices (see the inline help of clean for a full range of possible options). The output image will have planes (along the “polarization axis”) corresponding to the chosen Stokes parameters.

If as input to deconvolution tasks such as clean, the stokes parameter includes polarization planes other than I, then choosing psfmode='hogbom' (§ 5.3.1.2) or psfmode='clarkstokes' (§ 5.3.1.3) will clean (search for components) each plane sequentially, while psfmode='clark' (§ 5.3.1.1) will deconvolve jointly.

Alert: As of Release 3.2, clean expects that all input polarizations are present. E.g. if you have RR and LL dual polarization data and you flagged parts of RR but not LL, clean will ignore both polarizations in slice. It is possible to split out a polarization product with split and image separately. But you will not be able to combine these part-flagged data in the uv-domain. We will remove that restriction in a future CASA release.

5.2.10 Parameter uvtaper

This controls the radial weighting of visibilities in the uv-plane (see § 5.2.11 below) through the multiplication of the visibilities by the Fourier transform of an elliptical Gaussian. This is itself a Gaussian, and thus the visibilities are “tapered” with weights decreasing as a function of uv-radius.

The uvtaper parameter expands the menu upon setting uvtaper=True to reveal the following sub-parameters:

```
uvtaper = True  # Apply additional uv tapering of visibilities.
   outertaper = []  # uv-taper on outer baselines in uv-plane
   innertaper = []  # uv-taper in center of uv-plane (not implemented)
```

The sub-parameters specify the size and optionally shape and orientation of this Gaussian in the uv-plane or optionally the sky plane. The outertaper refers to a Gaussian centered on the origin of the uv-plane.

Some examples:

```
   outertaper=[]             # no outer taper applied
   outertaper=['5klambda']  # circular uv taper FWHM=5 kilo-lambda
   outertaper=['5klambda','3klambda','45.0deg'] # elliptical Gaussian
   outertaper=['10arcsec']  # on-sky FWHM 10"
   outertaper=['300.0']     # 300m in aperture plane
```

Note that if no units are given on the taper, then the default units are assumed to be meters in aperture plane.

ALERT: The innertaper option is not yet implemented.

5.2.11 Parameter weighting
CHAPTER 5. SYNTHESIS IMAGING

In order to image your data, we must have a map from the visibilities to the image. Part of that map, which is effectively a convolution, is the weights by which each visibility is multiplied before gridding. The first factor in the weighting is the “noise” in that visibility, represented by the data weights in the MS (which is calibrated along with the visibility data). The weighting function can also depend upon the uv locus of that visibility (e.g. a “taper” to change resolution). This is actually controlled by the \texttt{uvtaper} parameter (see \S\ 5.2.10). The weighting matrix also includes the convolution kernel that distributes that visibility onto the uv-plane during gridding before Fourier transforming to make the image of the sky. This depends upon the density of visibilities in the uv-plane (e.g. “natural”, “uniform”, “robust” weighting).

The user has control over all of these.

**ALERT:** You can find a weighting description in the online User Reference Manual at:

\url{http://casa.nrao.edu/docs/casaref/imager.weight.html}

The \texttt{weighting} parameter expands the menu to include various sub-parameters depending upon the mode chosen:

5.2.11.1 \textit{natural} weighting

For \texttt{weighting='natural'}, visibilities are weighted only by the data weights, which are calculated during filling and calibration and should be equal to the inverse noise variance on that visibility. Imaging weight \( w_i \) of sample \( i \) is given by

\[
  w_i = \omega_i = \frac{1}{\sigma_i^2}
\]

where the data weight \( \omega_i \) is determined from \( \sigma_i \) is the rms noise on visibility \( i \). When data is gridded into the same uv-cell for imaging, the weights are summed, and thus a higher uv density results in higher imaging weights. No sub-parameters are linked to this mode choice. It is the default imaging weight mode, and it should produce “optimum” image with with the lowest noise (highest signal-to-noise ratio). Note that this generally produces images with the poorest angular resolution, since the density of visibilities falls radially in the uv-plane

5.2.11.2 \textit{uniform} weighting

For \texttt{weighting = 'uniform'}, the data weights are calculated as in \textit{natural} weighting. The data is then gridded to a number of cells in the uv-plane, and after all data is gridded the uv-cells are re-weighted to have “uniform” imaging weights. This pumps up the influence on the image of data with low weights (they are multiplied up to be the same as for the highest weighted data), which sharpens resolution and reduces the sidelobe level in the field-of-view, but increases the rms image noise. No sub-parameters are linked to this mode choice.
For uniform weighting, we first grid the inverse variance $\omega_i$ for all selected data onto a grid with uv cell-size given by $2/FOV$ where $FOV$ is the specified field of view (defaults to the image field of view). This forms the gridded weights $W_k$. The weight of the $i$-th sample is then:

$$w_i = \frac{\omega_i}{W_k}.$$  (5.7)

5.2.11.3 'superuniform' weighting

The weighting = 'superuniform' mode is similar to the 'uniform' weighting mode but there is now an additional npixels sub-parameter that specifies a change to the number of cells on a side (with respect to uniform weighting) to define a uv-plane patch for the weighting renormalization. If npixels=0 you get uniform weighting.

5.2.11.4 'radial' weighting

The weighting = 'radial' mode is a seldom-used option that increases the weight by the radius in the uv-plane, ie.

$$w_i = \omega_i \cdot \sqrt{u_i^2 + v_i^2}.$$  (5.8)

Technically, I would call that an inverse uv-taper since it depends on uv-coordinates and not on the data per-se. Its effect is to reduce the rms sidelobes for an east-west synthesis array. This option has limited utility.

5.2.11.5 'briggs' weighting

The weighting = 'briggs' mode is an implementation of the flexible weighting scheme developed by Dan Briggs in his PhD thesis. See:

http://www.aoc.nrao.edu/dissertations/dbriggs/

This choice brings up the sub-parameters:

- weighting = 'briggs'  # Weighting to apply to visibilities
- robust = 0.0  # Briggs robustness parameter
- npixels = 0  # number of pixels to determine uv-cell size 0=> field of view

The actual weighting scheme used is:

$$w_i = \frac{\omega_i}{1 + W_k f^2}$$  (5.9)

where $W_k$ is defined as in uniform and superuniform weighting, and

$$f^2 = \frac{(5 \times 10^{-R})^2}{\sum_k W_k^2} \sum_i \omega_i$$  (5.10)
and $R$ is the robust parameter.

The key parameter is the robust parameter, which sets $R$ in the Briggs equations. The scaling of $R$ is such that $R = 0$ gives a good trade-off between resolution and sensitivity. The robust $R$ takes value between $-2.0$ (close to uniform weighting) to $2.0$ (close to natural).

Superuniform weighting can be combined with Briggs weighting using the npixels sub-parameter. This works as in 'superuniform' weighting (§ 5.2.11.3).

### 5.2.11.6 'briggsabs' weighting

For weighting='briggsabs', a slightly different Briggs weighting is used, with

$$ w_i = \frac{\omega_i}{W_k R^2 + 2\sigma_R^2} $$

(5.11)

where $R$ is the robust parameter and $\sigma_R$ is the noise parameter.

This choice brings up the sub-parameters:

```python
weighting = 'briggsabs' # Weighting to apply to visibilities
robust = 0.0 # Briggs robustness parameter
noise = '0.0Jy' # noise parameter for briggs weighting when rmode='abs'
npixels = 0 # number of pixels to determine uv-cell size 0=> field of view
```

Otherwise, this works as weighting='briggs' above (§ 5.2.11.5).

### 5.2.12 Parameter vis

The value of the vis parameter is either the name of a single MS, or a list of strings containing the names of multiple MSs, that should be processed to produce the image. The MS referred to by the first name in the list (if more than one) is used to determine properties of the image such as channelization and rest frequency.

For example,

```python
vis = 'ngc5921.ms'
```

set a single input MS, while

```python
vis = ['ngc5921_day1.ms', 'ngc5921_day2.ms', 'ngc5921_day3.ms']
```

points to three separate measurement sets that will be gridded together to form the image. This means that you do not have to concatenate datasets, for example from different configurations, before imaging.

For the multiple MS case, all selection commands like field, spw, etc. are lists that refer to the list of input MSs, like
spw=["1:2~9","0:10~22","<2"]
field=['0','ngc5921','12']

will use the first entry of each selection criterion and apply it to the first dataset (spw='1:2~9'
and field='0' to 'ngc5921_day1.ms'), the second selection criterion to the second dataset etc.

5.2.13 Primary beams in imaging

The CASA imaging task and tools use primary beams based on models for each observatory’s
antenna types. In addition to different antenna diameters, different functions may be used.

The voltage patterns are based on the following antenna primary beams, based on the TELESCOPE_NAME
keyword in the OBSERVATION table:

VLA — Airy disk fitted to measurement. Note that a R/L beam squint is also included with feed
dependent angle;

ALMA — Airy disk for 12m dish with a blockage of 1m;

ATA — Airy disk for 6m dish;

ATCA — polynomial fitted to measurement of main lobe;

BIMA, HATCREEK — Gaussian with halfwidth of λ/2D;

CARMA — Airy patterns for the BIMA or OVRO dish sizes as appropriate;

GBT — polynomial fitted to measurement of main lobe;

GMRT — VLA Airy disk scaled to 45.0m;

IRAMPDB — Airy disk for dish of 15m with a blockage of 1m;

NRAO12M — VLA beam scaled to 12m;

OVRO — VLA Airy disk scaled to 10.4m;

SMA — Spheroidal function fit to FWHM;

WSRT — polynomial fitted to measurement of main lobe;

If the telescope name is unknown, or is CARMA or ALMA, then the DISH_DIAMETER in the ANTENNA
table is used with a scaled VLA pattern.

Note that for the purposes of mosaicing in clean, the primary beams that are Airy or spheroidal
are best-behaved (see §5.3.15).
5.3 Deconvolution using CLEAN (clean)

To create an image and then deconvolve it with the CLEAN algorithm, use the clean task. This task will work for single-field data, or for multi-field mosaics (§5.3.15), in both narrow and wide-field imaging modes.

**ALERT:** For large fractional bandwidths the psf in clean may vary considerably with frequency in data cubes. To accommodate this fact we have introduced a per-plane psf (dirty beam) when the change is larger than half the size of a pixel. Analysis tasks in CASA can deal with such beam variation. If a single beam size is requested, imsmooth can be invoked on the clean products to smooth to a common, uniform beam for all channels.

**Toolkit Note:** MEM is not included in clean, but is available in the toolkit.

clean will use the CORRECTED_DATA column from your measurement set if it exists. If that column is not available, it will use DATA. The clean task utilizes many of the common imaging parameters. These are described above in §5.2. There are also a number of parameters specific to clean. These are listed and described below.

The default inputs to clean are:

```plaintext
# clean :: Deconvolve an image with selected algorithm
vis = ''  # name of input visibility file
imagename = ['']  # Pre-name of output images
outlierfile = ['']  # Text file with image names, sizes, centers
field = ['']  # Field Name
spw = ['']  # Spectral windows:channels; '' is all
selectdata = False  # Other data selection parameters
mode = 'mfs'  # Type of selection (mfs, channel, velocity,frequency)
nterms = 1  # Number of taylor terms to use for modeling the sky frequency dependence
reffreq = ['']  # Reference frequency for MFS (relevant only if nterms > 1)
gridmode = ['']  # The kind gridding kernel to be used for FFT-based transforms
niter = 500  # Maximum number of iterations
gain = 0.1  # Loop gain for cleaning
threshold = '0.0mJy'  # Flux level to stop cleaning. Must include units
psfmode = 'clark'  # method of PSF calculation to use during minor cycles
imagermode = ['']  # Use csclean or mosaic. If '', use psfmode
multiscale = []  # deconvolution scales (pixels); [] = default standard clean
interactive = False  # use interactive clean (with GUI viewer)
mask = []  # cleanbox(es), mask image(s), and/or region(s) used in cleaning
imsize = [256, 256]  # x and y image size in pixels, symmetric for single value
cell = ['1.0arcsec', '1.0arcsec']  # x and y cell size. default unit arcsec
phasescenter = ['']  # Image phase center: position or field index
restfreq = ['']  # rest frequency to assign to image (see help)
stokes = 'I'  # Stokes params to image (eg I,IV, QU, IQUV)
weighting = 'natural'  # Weighting of uv (natural, uniform, briggs, ...)
uvtaper = False  # Apply additional uv tapering of visibilities.
modelimage = ['']  # Name of model image(s) to initialize cleaning
restoringbeam = ['']  # Output Gaussian restoring beam for CLEAN image
```
**CHAPTER 5. SYNTHESIS IMAGING**

```
pbcor = False  # Output primary beam-corrected image
minpb = 0.1    # Minimum PB level to use
usescratch = False  # True if to save model visibilities in MODEL_DATA column
async = False  # If true the taskname must be started using clean(...)

The clean task will produce a number of output images based on the root name given in imagename. These include:

- `<imagename>.clean.image` # the restored image
- `<imagename>.clean.flux` # the effective response (e.g. for pbcor)
- `<imagename>.clean.flux.pbcoverage` # the PB coverage (ftmachine='mosaic’ only)
- `<imagename>.clean.model` # the model image
- `<imagename>.clean.residual` # the residual image
- `<imagename>.clean.psf` # the synthesized (dirty) beam

The mode, psfmode, imagermode, and weighting parameters open up other sub-parameters. These are detailed in the common imaging task parameters section (§5.2). The gridmode parameter (§5.3.13) is available to select more advanced imaging options such as widefield imaging and beam squint correction.

A typical setup for clean on the NGC5921 dataset, after setting parameter values, might look like:

```
vis = 'ngc5921.usecase.ms.contsub'  # Name of input visibility file
imagename = 'ngc5921.usecase.clean'  # Pre-name of output images
field = '0'  # Field Name
spw = ''  # Spectral windows:channels: '' is all
selectdata = False  # Other data selection parameters
mode = 'channel'  # Type of selection (mfs, channel, velocity, frequency)
nchan = 46  # Number of channels (planes) in output image
start = 5  # first input channel to use
width = 1  # Number of input channels to average
interpolation = 'linear'  # Spectral interpolation (nearest, linear, cubic)
gridmode = ''  # The kind gridding kernel to be used for FFT-based transforms
niter = 6000  # Maximum number of iterations
gain = 0.1  # Loop gain for cleaning
threshold = 8.0  # Flux level to stop cleaning. Must include units
psfmode = 'clark'  # method of PSF calculation to use during minor cycles
imagermode = ''  # Use cs-clean or mosaic, or image-plane only if ''
multiscale = []  # set deconvolution scales (pixels)
interactive = False  # use interactive clean (with GUI viewer)
mask = [108, 108, 148, 148]  # cleanbox(es), mask image(s), and/or region(s)
imsize = [256, 256]  # x and y image size in pixels
cell = [15.0, 15.0]  # x and y cell size. default unit arcsec
phasecenter = ''  # Image phase center: position or field index
restfreq = ''  # rest frequency to assign to image (see help)
stokes = 'I'  # Stokes params to image (eg I,IV, QU, IQUV)
weighting = 'briggs'  # Weighting to apply to visibilities
robust = 0.5  # Briggs robustness parameter
npixels = 0  # uv-cell size in pixels 0=> field of view
```
An example of the `clean` task to create a continuum image from many channels is given below:

```python
clean(vis='ggtau.1mm.split.ms', # Use data in ggtau.1mm.split.ms
    imagename='ggtau.1mm', # Name output images 'ggtau.1mm.*' on disk
    psfmode='clark', # Use the Clark CLEAN algorithm
    imagermode='', # Do not mosaic or use csclean
    mask='', # Do not use clean box or mask
    niter=500, gain=0.1, # Iterate 500 times using gain of 0.1
    mode='mfs', # multi-frequency synthesis (combine channels)
    spw='0~2:2~57', # Combine channels from 3 spectral windows
    field='0', #
    stokes='I', # Image stokes I polarization
    weighting='briggs', # Use Briggs robust weighting
    rmode='norm', robust=0.5, # with robustness parameter of 0.5
    cell=[0.1,0.1], # Using 0.1 arcsec pixels
    imsize=[256,256]) # Set image size = 256x256 pixels
```

This example will clean the entire inner quarter of the primary beam. However, if you want to limit the region over which you allow the algorithm to find clean components then you can make a deconvolution region (or mask). To use a deconvolution region, box, or mask, set the `mask` parameter (§5.3.6).

For example, you can set up a simple 'cleanbox' region. To do this, make a first cut at the image and clean the inner quarter. Then use the `viewer` to look at the image and get an idea of where the emission is located. You can use the `viewer adjustment` panel to view the image in pixel coordinates and read out the pixel locations of your cursor.

Then, you can use those pixel read-outs you just go to define a clean box region with the CASA region format described in Chapter D. For example, say you have a continuum source near the center of your image between the pixel coordinates [80,80] and [120,120], you may use the rectangular region:

```
mask='box[[80pix,80pix],[120pix,120pix]]'
```

For more complicated and multiple clean regions, it will be best to use the `viewer` to create them interactively or to create a region file (Chapter D) and use that file as an input like:

```
mask='myregions.txt'
```

The following are the `clean` specific parameters and their allowed values, followed by a description of carrying out interactive cleaning.
5.3.1 Parameter psfmode

The psfmode parameter chooses the “algorithm” that will be used to calculate the synthesized beam for use during the minor cycles in the image plane. The value types are strings. Allowed choices are 'clark' (default) and 'hogbom'.

5.3.1.1 The clark algorithm

In the 'clark' algorithm, the cleaning is split into minor and major cycles. In the minor cycles only the brightest points are cleaned, using a subset of the point spread function. In the major cycle, the points thus found are subtracted correctly by using an FFT-based convolution. This algorithm is reasonably fast. Also, for polarization imaging, Clark searches for the peak in $I^2 + Q^2 + U^2 + V^2$.

5.3.1.2 The hogbom algorithm

The hogbom algorithm is the “Classic” image-plane CLEAN, where model pixels are found iteratively by searching for the peak. Each point is subtracted from the full residual image using the shifted and scaled point spread function. In general, this is not a good choice for most imaging problems (clark or csclean are preferred) as it does not calculate the residuals accurately. But in some cases, with poor uv-coverage and/or a PSF with bad sidelobes, the Hogbom algorithm will do better as it uses a smaller beam patch. For polarization cleaning, Hogbom searches for clean peak in $I$, $Q$, $U$, and $V$ independently.

5.3.1.3 The clarkstokes algorithm

In the 'clarkstokes' algorithm, the Clark psf (§5.3.1.1) is used, but for polarization imaging the Stokes planes are cleaned sequentially for components instead of jointly as in 'clark'. This means that this is the same as 'clark' for Stokes I imaging only. This option can also be combined with imagermode='csclean' (§5.3.4).

5.3.2 The multiscale parameter

To activate multi-scale mode, specify a non-blank list of scales in the multiscale parameter. A good rule of thumb for starters is [0, 2xbeam, 5xbeam], and maybe adding larger scales up to the maximum scale the interferometer can image. E.g. for a 2 arcsecond beam

$$\text{multiscale} = [0,6,10,30] \quad \# \text{Four scales including point sources}$$

These are given in numbers of pixels, and specify FWHM of the Gaussians used to compute the filtered images.

Setting the multiscale parameter to a non-empty list opens up the sub-parameter:

Inside the Toolkit:

The im.setscales method sets the multi-scale Gaussian widths. In addition to choosing a list of sizes in pixels, you can just pick a number of scales and get a geometric series of sizes.
multiscale = [0, 6, 10, 30] # set deconvolution scales (pixels)

negcomponent = -1 # Stop cleaning if the largest scale finds this number of neg components

smallscalebias = 0.6 # a bias to give more weight toward smaller scales

The `negcomponent` sub-parameter is here to set the point at which the clean terminates because of negative components. For `negcomponent > 0`, component search will cease when this number of negative components are found at the largest scale. If `negcomponent = -1` then component search will continue even if the largest component is negative.

Increasing `smallscalebias` gives more weight to small scales. A value of 1.0 weighs the largest scale to zero and a value < 0.2 weighs all scales nearly equally. The default of 0.6 is usually a good number as it corresponds to a weighting that approximates the normalization of each component by its area. Depending on the image, however, it may be necessary to tweak the `smallscalebias` for a better convergence of the algorithm. Note that currently, this parameter is ignored by the MS-MFS algorithm. It will be available in a future release.

Multi-scale cleaning is also not as sensitive to the loop gain as regular cleaning algorithms. A loop gain of 0.3 may still work fine and will considerably speed up the processing time. Increasing the `cyclefactor` by a few (e.g. 5) may provide better stability in the solution, in particular when the data exhibit a severely non-Gaussian dirty beam.

The CASA multi-scale algorithm uses “Multi-scale CLEAN” to deconvolve using delta-functions and circular Gaussians as the basis functions for the model, instead of just delta-functions or pixels as in the other clean algorithms. This algorithm is still in the experimental stage, mostly because we are working on better algorithms for setting the scales for the Gaussians. The sizes of the Gaussians are set using the `scales` sub-parameter.

We are working on defining a better algorithm for scale setting. In the toolkit, there is an `nscale` argument which sets scales

$$\theta_i = \theta_{bmin} 10^{(i-N/2)/2}$$  \hspace{1cm} (5.12)

where $N = \text{nscales}$ and $\theta_{bmin}$ is the fitted FWHM of the minor axis of the CLEAN beam.

### 5.3.3 Parameter gain

The `gain` parameter sets the fraction of the flux density in the residual image that is removed and placed into the clean model at each minor cycle iteration. The default value is `gain = 0.1` and is suitable for a wide-range of imaging problems. Setting it to a smaller gain per cycle, such as `gain = 0.05`, can sometimes help when cleaning images with lots of diffuse emission. Larger values, up to `gain=1`, are probably too aggressive and are not recommended.

### 5.3.4 Parameter imagermode

This choose the mode of operation of `clean`, either as single-field deconvolution using image-plane major and minor cycles only (`imagermode='i'`), single-field deconvolution using Cotton-Schwab
(CS) residual visibilities for major cycles (imagermode='csclean'), or multi-field mosaics using CS major cycles (imagermode='mosaic').

The default imagermode='csclean' choice specifies the Cotton-Schwab algorithm. This opens up the sub-parameters

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Value</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>magermode</td>
<td>'csclean'</td>
<td># Options: 'csclean' or 'mosaic', '', uses psfmode</td>
</tr>
<tr>
<td>cyclefactor</td>
<td>1.5</td>
<td># Controls how often major cycles are done. (e.g. 5 for frequently)</td>
</tr>
<tr>
<td>cyclespeedup</td>
<td>-1</td>
<td># Cycle threshold doubles in this number of iterations</td>
</tr>
</tbody>
</table>

These options are explained below. In the CS mode, cleaning is split into minor and major cycles. For each field, a minor cycle is performed using the PSF algorithm specified in psfmode (§ 5.3.1). At major-cycle breakpoints, the points thus found are subtracted from the original visibilities. A fast variant does a convolution using a FFT. This will be faster for large numbers of visibilities. If you want to be extra careful, double the image size from that used for the Clark clean and set a mask to clean only the inner quarter or less (this is not done by default). This is probably the best choice for high-fidelity deconvolution of images without lots of large-scale structure.

Note that when using the Cotton-Schwab algorithm with a threshold (§ 5.3.12), there may be strange behavior when you hit the threshold with a major cycle. In particular, it may be above threshold again at the start of the next major cycle. This is particularly noticeable when cleaning a cube, where different channels will hit the threshold at different times.

In the empty mode (imagermode=''), the major and minor clean cycles work off of the gridded FFT dirty image, with residuals updated using the PSF calculation algorithm set by the psfmode
parameter (§ 5.3.1). This method is not recommended for high dynamic range or high fidelity imaging applications, but can be significantly faster than CS clean (the default). Note that for this option only, if mask='', (no mask or box set) then it will clean the inner quarter of the image by default.

**ALERT:** You will see a warning message in the logger, similar to this:

```
Zero Pixels selected with a Flux limit of 0.000551377 and a maximum Residual of 0.00751239
```

whenever it find 0 pixels above the threshold. This is normal, and not a problem, if you’ve specified a non-zero threshold. On the other hand, if you get this warning with the threshold set to the default of '0Jy', then you should look carefully at your inputs or your data, since this usually means that the masking is bad.

The option `imagermode='mosaic'` is for multi-field mosaics. This choice opens up the sub-parameters

```
imagermode       = 'mosaic'  # Use csclean or mosaic. If '', use psfmode
mosweight        = False     # Individually weight the fields of the mosaic
ftmachine        = 'mosaic'  # Gridding method for the image
scaletype        = 'SAULT'   # Controls scaling of pixels in the image plane.
cyclefactor      = 1.5       # change depth in between of csclean cycle
cyclespeedup     = -1        # Cycle threshold doubles in this number of iteration
```

These options are explained below.

### 5.3.4.1 Sub-parameter cyclefactor

This sub-parameter is activated for `imagermode='csclean'` and `mosaic`.

The `cyclefactor` parameter allows the user to change the threshold at which the deconvolution cycle will stop and then degrid and subtract the model from the visibilities to form the residual. This is with respect to the breaks between minor and major cycles that the `clean` part would normally force. Larger values force a major cycle more often.

This parameter in effect controls the threshold used by CLEAN to test whether a major cycle break and reconciliation occurs:

\[
\text{cycle threshold} = \text{cyclefactor} \times \text{max sidelobe} \times \text{max residual}
\]

If mosaic or csclean diverges on your data, try a larger `cyclefactor`. A larger value typically increases the robustness of your deconvolution. The price, however, will be a slower algorithm. On
the other hand, if you find that the cleaning is slow due to taking too many major cycle breaks, then reduce cyclefactor.

Note that currently the cycle_threshold will saturate at a maximum value of 0.80 even when you set cyclefactor to a very high value or you have very high PSF sidelobes. This means that with a gain = 0.1 you will get 3 minor cycles per major cycle when hitting the limit.

Some rules of thumb:

If you have data taken with a small number of antennas, for example from ALMA in the commissioning and early-science phase, then you will have high sidelobes in the PSF. In this case, you will have to reduce cyclefactor considerably, likely into the range 0.25 to 0.5, if you want efficient cleaning of simple source structures (e.g. point sources). You can use the viewer to look at your PSF image and see what the maximum sidelobe level is and judge accordingly.

However, if your uv-coverage results in a poor PSF and you have complex source structure, then you should reconcile often (a cyclefactor of 4 or 5). For reasonable PSFs, use cyclefactor in the range 1.5 to 2.0. For good PSFs, or for faster cleaning at the expense of some fidelity, we recommend trying a lower value, e.g. cyclefactor = 0.25, which at least in some of our mosaicing tests led to a speedup of around a factor of two with little change in residuals.

5.3.4.2 Sub-parameter cyclespeedup

This sub-parameter is activated for imagermode='csclean' and 'mosaic'.

The cyclespeedup parameter allows the user to let clean to raise the threshold at which a major cycle is forced if it is not converging to that threshold. To do this, set cyclespeedup to an integer number of iterations at which if the threshold is not reached, the threshold will be doubled. See cyclefactor above for more details. By default this is turned off (cyclespeedup = -1). In our tests, a value like cyclespeedup = 50 has been used successfully.

5.3.4.3 Sub-parameter ftmachine

This sub-parameter is activated for imagermode='mosaic'. Note: The actual “ftmachine” used may be overridden by choices made to other parameters, such as gridmode.

The ftmachine parameter controls the gridding method and kernel to be used to make the image. A string value type is expected. Choices are: 'ft', 'sd', 'both', or 'mosaic' (the default).

The 'ft' option uses the standard gridding kernel (as used in clean).

The 'sd' option forces gridding as in single-dish data.

For combining single-dish and interferometer MS in the imaging, the 'both' option will allow clean to choose the 'ft' or 'sd' machines as appropriate for the data.
The ‘mosaic’ option (the default) uses the Fourier transform of the primary beam (the aperture cross-correlation function in the uv-plane) as the gridding kernel. This allows the data from the multiple fields to be gridded down to a single uv-plane, with a significant speed-up in performance in most (non-memory limited) cases. The effect of this extra convolution is an additional multiplication (apodization) by the primary beam in the image plane. This can be corrected for, but does result in an image with optimal signal to noise ratio across it.

The primary beams used in CASA are described in §5.2.13.

**ALERT:** Note that making a non-square image (e.g. using unequal values in imsize) for ftmachine='mosaic' will grid the data into a uv-plane with correspondingly non-square cells. This has not been extensively tested, and may result in undesired image artifacts. We recommend that the user make square mosaic images when possible, but in principle non-square images should work.

### 5.3.4.4 Sub-parameter mosweight

If mosweight=False (default) then the data will be weighted for optimal signal to noise ratio across the mosaic image. This should be used for most cases.

If mosweight=True then individual mosaic field relative weights will be readjusted on a per visibility basis (much like uniform gridding weights). This may give better performance in cases where one or a few fields in the mosaic have drastically different weights and/or integration time, and it is desired that the noise be more “uniform” across the mosaic image. Use this with care, we have not explored its use fully.

### 5.3.4.5 Sub-parameter scaletype

The scaletype parameter controls weighting of pixels in the image plane. This sub-parameter is activated for imagermode='mosaic'.

The default scaletype='PBCOR' scales the image to have the correct flux scale across it (out to the beam level cutoff minpb). This means that the noise level will vary across the image, being increased by the inverse of the weighted primary beam responses that are used to rescale the fluxes. This option should be used with care, particularly if your data has very different exposure times (and hence intrinsic noise levels) between the mosaic fields.

If scaletype='SAULT' then the image will be scaled so as to have constant noise across it. This means that the point source response function varies across the image attenuated by the weighted primary beam(s). However, this response is output in the .flux image and can be later used to correct this.
Note that this scaling as a function of position in the image occurs after the weighting of mosaic fields specified by `mosweight` and implied by the gridding weights (`ftmachine` and weighting).

### 5.3.4.6 The threshold revisited

For mosaics, the specification of the threshold is not straightforward, as it is in the single field case. This is because the different fields can be observed to different depths, and get different weights in the mosaic. We now provide internal rescaling (based on `scaletype`) so `clean` does its component search on a properly weighted and scaled version of the sky.

For `ftmachine='ft'`, the minor cycles of the deconvolution are performed on an image that has been weighted to have constant noise, as in ’SAULT’ weighting (see § 5.3.4.5). This is equivalent to making a dirty mosaic by coadding dirty images made from the individual pointings with a sum of the mosaic contributions to a given pixel weighted by so as to give constant noise across the image. This means that the flux scale can vary across the mosaic depending on the effective noise (higher weighted regions have lower noise, and thus will have higher “fluxes” in the ’SAULT’ map). Effectively, the flux scale that threshold applies to is that at the center of the highest-weighted mosaic field, with higher-noise regions down-scaled accordingly. Compared to the true sky, this image has a factor of the PB, plus a scaling map (returned in the `.flux` image). You will preferentially find components in the low-noise regions near mosaic centers.

When `ftmachine='mosaic'` and `scaletype='SAULT'`, the deconvolution is also performed on a “constant noise image”, as detailed above for ’ft’.

**ALERT:** The intrinsic image made using `ftmachine='mosaic'` is equivalent to a dirty mosaic that is formed by coadding dirty images made from the individual fields after apodizing each by the PB function. Thus compared to the true sky, this has a factor of the PB$^2$ in it. You would thus preferentially find components in the centers of the mosaic fields (even more so than in the ’ft’ mosaics). We now rescale this image internally at major-cycle (and interactive) boundaries based on `scaletype`, and do not have a way to clean on the raw unscaled dirty image (as was done in previous released versions).

### 5.3.5 Parameter `interactive`

If `interactive=True` is set, then an interactive window will appear at various “cycle” stages while you clean, so you can set and change mask regions. These breakpoints are controlled by the `npercycle` sub-parameter which sets the number of iterations of clean before stopping.

```python
interactive = True  # use interactive clean (with GUI viewer)
npercycle = 100    # Number of iterations before interactive prompt
```

Note that `npercycle` is currently the only way to control the breakpoints in interactive clean.

For spectral cube imaging, it is often easier to deal with each channel in turn, rather than cleaning all channels in each cycle. We therefore provide the `chaniter=True` option under ’mode’, where it will clean a channel fully before moving to the next one. You will set masks for each channel.

See the example of interactive cleaning in § 5.3.14.
CHAPTER 5. SYNTHESIS IMAGING

5.3.6 Parameter mask

The mask parameter takes a list of elements, each of which can be a list of coordinates specifying a box, or a string pointing to the name of a cleanbox file, mask image, or region file. These are used by CLEAN to define a region to search for components.

Note that for imagermode='' (§ 5.3.4) the default with mask='' is to restrict clean to the inner quarter of the image.

5.3.6.1 Setting clean boxes

mask can be a list of CASA regions. For example,

```
mask = 'box[[80pix, 80pix],[120pix,120pix]],circle[[150pix,150pix],10pix]'
```

defines a box and a circle. They will be applied to all channels. To define different regions for different channel ranges, it will be best to use interactive mode in clean, the viewer (note that the viewer still created old format regions - they are still supported in CASA 3.3) or to create a CASA region file that contain the different regions. Chapter D describes the syntax of CASA regions. They can be specified by;

```
mask = 'regionfile.rgn, regionfile2.rgn'
```

5.3.6.2 Using clean mask images

You can give the mask parameter a string containing the name of a mask image to be used for CLEAN to search for components. You can use interactive=True to create such a mask for your image (§ 5.3.5).

5.3.7 Parameter minpb

The minpb parameter sets the level down to which the primary beam (or more correctly the voltage patterns in the array) can go and have a given pixel included in the image. This is important as it defines where the edge of the visible image or mosaic is. The default is 0.1 or equivalent to the 10% response level. If there is a lot of emission near the edge, then set this lower if you want to be able to clean it out.

NOTE: The minpb parameter is the level in the “primary beam” (PB) at which the cut is made. If you are using ftmachine='mosaic' (§ 5.3.4.3), this will show up in the .flux.pbcoverage image (new in version 2.4.0). See the discussion of threshold (§ 5.3.4.6) for related issues.
5.3.8 Parameter modelimage

The modelimage parameter specifies the name(s) of one or more input starting image(s) to use to calculate the first residual before cleaning. These are used in addition to any image with a name defaulting from the imagename root (e.g. on a restart). The output model will contain this model plus clean components found during deconvolution.

If the units of the image are Jy/pixel, then this is treated as a model image.

If the units of the image are Jy/beam or Jy per solid angle, then this is treated as a “single-dish” image and rescaled by the resolution (in the ‘beam’ image header keyword). Inclusion of the SD image here is superior to feathering it in later. See §5.5 for more information on feathering.

5.3.9 Parameter niter

The niter parameter sets the maximum total number of minor-cycle CLEAN iterations to be performed during this run of clean. If restarting from a previous state, it will carry on from where it was. Note that the threshold parameter can cause the CLEAN to be terminated before the requested number of iterations is reached.

5.3.10 Parameter pbcor

The pbcor parameter controls whether the final .image is scaled to correct for the Primary Beam of the array or not.

If pbcor=False (the default), then no such scaling is done and the image is in whatever “raw” scaling used by the imagermode algorithm underneath. For single-field cleaning with imagermode='csclean', this is the standard constant-noise image. If imagermode='mosaic', then this is the 'SAULT' scaled image (regardless of what scaletype is set to).

If pbcor=True, the at the end of deconvolution and imaging the “raw” image is rescaled by dividing by the noise and PB correction image. This is what is output by clean as the .flux image.

Note that regardless of what you set pbcor to, you can recover the other option using immath (§6.6) to either multiply or divide by the .flux image.

5.3.11 Parameter restoringbeam

The restoringbeam parameter allows the user to set a specific Gaussian restoring beam to make the final restored .image from the final .model and residuals.

If restoringbeam='' (the default), then the restoring beam is calculated by fitting to the PSF (e.g. the .psf image). For a mosaic, this is at the center of the field closest to the phasecenter.

The restoring beam can also be used to establish a single beam for large fractional bandwidths. If the PSF changes more that half a pixel across all channels in a cube, the PSF itself will be stored in
the form of a cube, changing size from channel to channel. A specified restoring beam will output all planes at the same resolution and thus collapse to a single PSF (note that this can also be done in hindsight using imsmooth).

To specify a restoring beam, provide \texttt{restoringbeam} a list of \texttt{[bmaj, bmin, bpa]} which are the parameters of an elliptical Gaussian. The default units are in arc-seconds for \texttt{bmaj, bmin} components and degrees for the \texttt{bpa} component.

For example,

\begin{verbatim}
restoringbeam=\['10arcsec'\]  # circular Gaussian FWHM 10"
restoringbeam=\['10.0','5.0','45.0deg'\] # 10"x5" at PA=45 degrees
\end{verbatim}

5.3.12 Parameter threshold

The \texttt{threshold} parameter instructs \texttt{clean} to terminate when the maximum absolute residual reaches this level or below. Note that it may not reach this residual level due to the value of the \texttt{niter} parameter which may cause it to terminate early.

If \texttt{threshold} is given a floating-point number, then this is the threshold in milli-Jansky.

You can also supply a flux density \textit{quanta} to \texttt{threshold}, e.g.

\begin{verbatim}
threshold = '8.0mJy'
threshold = '0.008Jy'
\end{verbatim}

(these do the same thing).

5.3.13 Parameter gridmode

The \texttt{gridmode} parameter is now provided to access more advanced deconvolution capabilities. The default \texttt{gridmode=''} is recommended for most cases.

The \texttt{gridmode='widefield'} option allows imaging in the wide-field regime where the W-term is not negligible. The CASA implementation allows both standard uv-plane faceting as well as the W-Projection algorithm\footnote{Cornwell et al. IEEE JSTSP (2008).} or a combination of the two. Its sub-parameters are:

\begin{verbatim}
gridmode       = 'widefield'   # Gridding kernel for FFT-based transforms, default=''
    wprojplanes = 1          # Number of w-projection planes for convolution
    facets      = 1          # Number of facets along each axis (main image only)
\end{verbatim}

The \texttt{wprojplanes} parameter sets the number of pre-computed w-planes used for the W-Projection algorithm (\texttt{wprojplanes=1} disables w-projection). The \texttt{facets} parameter sets the number of facets used. W-Projection, if used, is done for each facet. See §5.3.18 below for more on wide-field imaging.
gridmode='aprojection': A-Projection is an algorithm to account for the effects of the antenna primary beam (PB) during imaging. The time-dependent effects of the PB are projected-out during the imaging phase and the PB is included in the prediction phase of the iterative image deconvolution (see Bhatnagar, Cornwell, Golap & Uson 2008, A&A, 487, 419) for more details. Please also refer to this publication in your papers if this algorithm is used for imaging. The narrow-band A-Projection can be used by setting the gridmode='aprojection' in the clean task. This opens up the following new parameters:

gridmode = 'aprojection' # Gridding kernel for FFT-based transforms, default=None

cfcache = 'cfcache.dir' # Convolution function cache directory

rotpainc = 5.0 # Parallactic angle increment (degrees) for OTF A-term rotation

painc = 360.0 # Parallactic angle increment (degrees) for computing A-term

cfcache is used to cache functions required in the A-Projection algorithm. The PB is rotated on-the-fly when a change of greater than rotpainc is detected. Alternatively, PB is re-computed if the P.A. changes by greater than painc.

Note that this code is still in the development and testing stage and should be used on shared-risk basis. Note also that the cost of imaging will be higher when using A-Projection. Therefore make a careful evaluation of whether you need to invoke it.

5.3.14 Interactive Cleaning — Example

If interactive=True is set, then an interactive window will appear at various “cycle” stages while you clean, so you can set and change mask regions. These breakpoints are controlled by the npercycle sub-parameter which sets the number of iterations of clean before stopping.

The window controls are fairly self-explanatory. It is basically a form of the viewer. A close-up of the controls are shown in Figure 5.1 and an example can be found in Figures 5.2-5.4. You assign one of the drawing functions (rectangle or polygon, default is rectangle) to the right-mouse button (usually), then use it to mark out regions on the image. Zoom in if necessary (standard with the left-mouse button assignment). Double-click inside the marked region to add it to the mask. If you want to reduce the mask, click the Erase radio button (rather than Add), then mark and select as normal. When finished setting or changing your mask, click the green clockwise arrow “Continue Cleaning” Next Action button. If you want to finish your clean with no more changes to the mask, hit the blue right arrow “Apply mask edits and proceed with non-interactive clean” button. If you want to terminate the clean, click the red X “Stop deconvolving now” button.

While stopped in an interactive step, you can change a number of control parameters in the boxes provided at the left of the menu bar. The main use of this is to control how many iterations before the next breakpoint (initially set to npercycle), how many cycles before completion (initially equal to niter/npercycle), and to change the threshold for ending cleaning. Typically, the user would start with a relatively small number of iterations (50 or 100) to clean the bright emission in tight mask regions, and then increase this as you get deeper and the masking covers more of the emission region. For extended sources, you may end up needing to clean a large number of components (10000 or more) and thus it is useful to set niter to a large number to begin with.
Figure 5.2: Screen-shots of the interactive clean window during deconvolution of the VLA 6m Jupiter dataset. We start from the calibrated data, but before any self-calibration. In the initial stage (left), the window pops up and you can see it dominated by a bright source in the center. Next (right), we zoom in and draw a box around this emission. We have also at this stage dismissed the tape deck and Position Tracking parts of the display (§7.2) as they are not used here. We have also changed the iterations to 30 for this boxed clean. We will now hit the Next Action Continue Cleaning button (the green clockwise arrow) to start cleaning.

— you can always terminate the clean interactively when you think it is done. Note that if you change iterations you may also want to change cycles or your clean may terminate before you expect it to.

For strangely shaped emission regions, you may find using the polygon region marking tool (the second from the right in the button assignment toolbar) the most useful.

The sequence of cleaning starting with the “raw” externally calibrated data is shown in Figures 5.2 – 5.4.

The final result of all this cleaning for Jupiter is shown in Figure 5.5. The viewer (§7) was used to overplot the polarized intensity contours and linear polarization vectors calculated using immath (§6.6) on the total intensity. See the following chapters on how to make the most of your imaging results.
FIGURE 5.3: We continue in our interactive cleaning of Jupiter from where Figure 5.2 left off. In the first (left) panel, we have cleaned 30 iterations in the region previously marked, and are zoomed in again ready to extend the mask to pick up the newly revealed emission. Next (right), we have used the Polygon tool to redraw the mask around the emission, and are ready to Continue Cleaning for another 100 iterations.

For spectral cube images you can use the tapedeck to move through the channels. You also use the panel with radio buttons for choosing whether the mask you draw applies to the Displayed Plane or to All Channels. See Figure 5.6 for an example. Note that currently the Displayed Plane option is set by default. This toggle is unimportant for single-channel images or mode='mfs'.

Advanced Tip: Note that while in interactive clean, you are using the viewer. Thus, you have the ability to open and register other images in order to help you set up the clean mask. For example, if you have a previously cleaned image of a complex source or mosaic that you wish to use to guide the placement of boxes or polygons, just use the Open button or menu item to bring in that image, which will be visible and registered on top of your dirty residual image that you are cleaning on. You can then draw masks as usual, which will be stored in the mask layer as before. Note you can blink between the new and dirty image, change the colormap and/or contrast, and carry out other standard viewer operations. See §7 for more on the use of the viewer.

ALERT: Currently, interactive spectral line cleaning is done globally over the cube, with halts for interaction after searching all channels for the requested npercycle total iterations. It is more
CHAPTER 5. SYNTHESIS IMAGING

Figure 5.4: We continue in our interactive cleaning of Jupiter from where Figure 5.3 left off. In the first (left) panel, it has cleaned deeper, and we come back and zoom in to see that our current mask is good and we should clean further. We change `npercycle` to 500 (from 100) in the box at upper right of the window. In the final panel (right), we see the results after this clean. The residuals are such that we should terminate the `clean` using the red X button and use our model for self-calibration.

Convenient for the user to treat the channels in order, cleaning each in turn before moving on. This will be implemented in an upcoming update.

5.3.15 Mosaic imaging

The `clean` task contains the capability to image multiple pointing centers together into a single “mosaic” image. This ability is controlled by setting `imagermode='mosaic'` (§ 5.3.4).

The key parameter that controls how `clean` produces the mosaic is the `ftmachine` sub-parameter (§ 5.3.4.3). For `ftmachine='ft'`, `clean` will perform a weighted combination of the images produced by transforming each mosaic pointing separately. This can be slow, as the individual sub-images must be recombined in the image plane. **NOTE:** this option is preferred for data taken with sub-optimal mosaic sampling (e.g. fields too far apart, on a sparse irregular pattern, etc.).
Figure 5.5: After clean and self-calibration using the intensity image, we arrive at the final polarization image of Jupiter. Shown in the viewer superimposed on the intensity raster is the linear polarization intensity (green contours) and linear polarization B-vectors (vectors). The color of the contours and the sampling and rotation by 90 degrees of the vectors was set in the Display Options panel. A LEL expression was used in the Load Data panel to mask the vectors on the polarized intensity.

The primary beams used in CASA are described in §5.2.13.

If ftmachine='mosaic', then the data are gridded onto a single uv-plane which is then transformed to produce the single output image. This is accomplished by using a gridding kernel that approximates the transform of the primary beam pattern. Note that for this mode the <imagemame>.flux image includes this convolution kernel in its effective weighted response pattern (needed to “primary-beam correct” the output image). For this mode only, an additional image <imagemame>.flux.pbcoverage is produced that is the primary-beam coverage only used to compute the minpb cutoff (§5.3.7).

**ALERT:** In order to avoid aliasing artifacts for ftmachine='mosaic' in the mosaic image, due to the discrete sampling of the mosaic pattern on the sky, you should make an image in which the
desired unmasked part of the image (above minpb) lies within the inner quarter. In other words, make an image twice as big as necessary to encompass the mosaic.

It is also important to choose an appropriate phasecenter for your output mosaic image (§ section:im.pars.phasecenter). The phase center should not be at the edge of an image with pointings around it. In that case, FFT aliasing may creep into the image.

Figure 5.6: Screen-shot of the interactive clean window during deconvolution of the NGC5921 spectral line dataset. Note where we have selected the mask to apply to the Displayed Plane rather than All Channels. We have just used the Polygon tool to draw a mask region around the emission in this channel, which will apply to this channel only.
An example of a simple mosaic clean call is shown below:

```python
clean(vis='n4826_tboth.ms',
    imagename='tmosaic',
    mode='channel',
    nchan=30, start=46, # Make the output cube 30 chan
    width=4, # start with 46 of spw 0, avg by 4 chans
    spw='0~2',
    field='0~6',
    cell=[1.,1.],
    imsize=[256,256],
    stokes='I',
    psfmode='clark',
    niter=500,
    imagermode='mosaic',
    scaletype='SAULT',
    cyclefactor=0.1)
```

## 5.3.16 Heterogeneous imaging

The clean task and underlying tools can handle cases where there are multiple dish sizes, and thus voltage patterns and primary beams, in the array. This is effected by using the dish sizes stored in the ANTEenna sub-table of the MS. Depending on how the data was written and imported into CASA, the user may have to manually edit this table to insert the correct dish sizes (e.g. using `browsetable` or the `tb` table tool).

## 5.3.17 Polarization imaging

The clean task handles full and partial Stokes polarization imaging through the setting of the stokes parameter (§ 5.2.9). The subsequent deconvolution of the polarization planes of the image and the search for clean components is controlled by the psfmode parameter (§ 5.3.1). If the stokes parameter includes polarization planes other than I, then choosing `psfmode='hogbom'` (§ 5.3.1.2) or `psfmode='clarkstokes'` (§ 5.3.1.3) will clean (search for components) each plane sequentially, while `psfmode='clark'` (§ 5.3.1.1) will deconvolve jointly.

The interactive clean example given above (§ 5.3.14) shows a case of polarization imaging.

## 5.3.18 Wide-field imaging and deconvolution in clean

When imaging sufficiently large angular regions, the sky can no longer be treated as a two-dimensional plane and the use of the standard clean task will produce distortions around sources that become increasingly severe with increasing distance from the phase center. In this case, one must use a “wide-field” imaging algorithm such as w-projection or faceting.

When is wide-field imaging needed? The number of required facets $N$ depends on the the maximum baseline $B_{\text{max}}$, the dish diameter $D$ and the wavelength $\lambda$ as:
Table 5.1: Combinations of observing band (wavelength,) and antenna array configurations that require w-projection.

\[
N = \frac{B_{\text{max}} \lambda}{D^2}
\]  

and w-projection is required when \( N > 1 \). (For details, see “Synthesis Imaging in Radio Astronomy II”, ed. Taylor, G., Carilli, C., Perley, R. 1999). With 25 m diameter JVLA dishes (which implies that imaging is requested out to the primary beam FWHM), w-projection is required for array configurations as listed in Table 5.1.

The relevant inputs for clean for wide-field imaging are:

- `gridmode = 'widefield'` # The kind gridding kernel to be used for FFT-based transforms
- `wprojplanes = 1` # Number of w-projection planes for convolution
- `facets = 1` # Number of facets along each axis (main image only)

Most of the clean parameters behave as described previously.

Wide-field imaging can be carried out using two major modes: First, the w-projection mode as chosen with ftmachine deals with the w-term (the phase associated with the sky/array curvature) internally. Secondly, the image can be broken into many facets, each small enough so that the w-term is not significant. These two basic methods can be combined, as discussed below in §5.3.18.4.

**5.3.18.1 Outlier fields**

When using wide-field imaging, the position and image size of any independent images must be specified. Those positions will be used to add additional cleaning components to strong sources that may reside in that area and influence the central image.

There are a two options to specify the outlier fields:

**Direct listing of fields** The outlier field directions are provided via their centers (phasecenter parameter), and their sizes as a second entry in the imsize parameter, e.g. 128 pixels in the example below. clean will derive two additional images and their names are to be provided in the imagename field that will then be a list of the main field name plus the outlier field names:
vis = 'wfield.ms'  # name of input visibility file
imagename=['n5921','outlier1','outlier2']  # Pre-name of output images
outlierfile = ''  # Text file with image names, sizes, centers
mask = [['image_setup.rgn'],[],['

imagename='n5921'
outlierfile = 'outliers.txt'
imsize=[1024,1024]
phasescenter = ''

outliers.txt provides all outlier fields with a syntax that is similar to the direct input, but separated by field. Below is an example for an outlierfile:

#content of outliers.txt
#
#outlier field1
imagename='outlier1'
imsize=[512,512]
phasescenter = 'J2000 13h30m52.15 43d23m08.0'
mask='box[[245pix,245pix],[265pix,265pix]]'
#
#outlier field2
imagename='outlier2'
imsize=[512,512]
phasescenter = 'J2000 13h24m08.16 43d09m48.0'

The syntax rules for the outlier files are:

- each field must begin with imagename followed by
- imsize and phasescenter must be given
- optionally a mask can be provided. The mask parameter follows the CASA region file convention (Chapter D) or can be a mask file or LEL string.

The older AIPS-style convention (and box definition) that was used in CASA 3.2 and earlier is still supported in CASA 3.3 but will be deprecated for CASA 3.4 and higher.
CHAPTER 5. SYNTHESIS IMAGING

5.3.18.2 Setting up w-projection

The w-projection mode is controlled using \texttt{wprojplanes} sub-parameter, e.g.

```plaintext
gridmode = 'widefield'  # The kind gridding kernel to be used for FFT-based transforms
wprojplanes = 64       # Number of w-projection planes for convolution
facets = 1             # Number of facets along each axis (main image only)
```

will construct 64 w-projection planes.

A reasonable value for \texttt{wprojplanes} is equal to $n_w = B_{max}(\text{ink}\lambda) \times \text{imagewidth(inarcmin}^2)/600$, with a minimum value of $n_w = 16$. The w-projection algorithm is much faster than using faceting, but it does consume a lot of memory. On most 32-bit machines with 1 or 2 Mbytes of memory, images larger than about $4000 \times 4000$ cannot be made.

5.3.18.3 Setting up faceting

Faceting will break the image into many small parts. This is invoked using \texttt{facets}:

```plaintext
gridmode = 'widefield'  # The kind gridding kernel to be used for FFT-based transforms
wprojplanes = 1        # Number of w-projection planes for convolution
facets = 7             # Number of facets along each axis (main image only)
```

In this example the image is broken into 49 $(7 \times 7)$ facets.

A reasonable value of facets is such that the image width of each facet does not need the w-term correction. The computation method with pure faceting is slow, so that w-projection is recommended.

5.3.18.4 Combination of w-projection and faceting

You can also use a combination of w-projection and faceting:

```plaintext
gridmode = 'widefield'  # The kind gridding kernel to be used for FFT-based transforms
wprojplanes = 32       # Number of w-projection planes for convolution
facets = 3             # Number of facets along each axis (main image only)
```

This hybrid method allows for a smaller number of \texttt{wprojplanes} in order to try to conserve memory if the image size approached the memory limit of the computer. However, there is a large penalty in execution time.
5.4 Primary Beam Correction ($impbcor$, $widebandpbcor$)

The primary beam correction can be applied during the imaging with $clean$. It is also possible to correct after imaging using the task $impbcor$ for 'regular' data sets, or $widebandpbcor$ for those that used the Taylor-term expansion function in $clean (nterms > 1)$. $pbcor$ has the following inputs:

```python
# impbcor :: Construct a primary beam corrected image from an image and a primary beam pattern.
# imagename = '' # Name of the input image
# pbimage = '' # Name of the primary beam image which must exist or array of values for the pb response. Default ""
# outfile = '' # Output image name. If empty, no image is written. Default ""
# box = '' # One or more boxes to use for fit region(s). Default is to use the entire directional plane.
# region = '' # The region to correct. Default is entire image. If both box and region are specified, box is used and region is not.
# chans = '' # The frequency planes to correct. Default is all frequencies.
# stokes = 'I' # The correlations to correct. Default is all.
# mask = [] # Boolean LEL expression or mask region. Default is none.
# mode = 'velocity' # Divide or multiply the image by the primary beam image. Minimal match supported. Default "divide"
# cutoff = -1.0 # PB cutoff. If mode is "d", all values less than this will be masked. If "m", all values greater will be masked. Less than 0, no cutoff. Default no cutoff
# wantreturn = False # Return an image tool referencing the corrected image?
# async = False # If true the taskname must be started using impbcor(...)
```

The main inputs are the input image and the image of a primary beam in the $pbimage$ parameter. The $mode$ parameter will typically be 'divide' but it is also possible to multiply with the beam pattern.

$widebandpbcor$ is an experimental task and its functionality will be incorporated into $clean$ in one of the next versions of CASA. $widebandpbcor$ has the following options

```python
# widebandpbcor :: Wideband PB-correction on the output of the MS-MFS algorithm
# vis = '' # Name of measurement set.
# imagename = '' # Name-prefix of multi-termimages to operate on.
# nterms = 2 # Number of taylor terms to use
# threshold = '' # Intensity above which to re-calculate spectral index
# action = 'pbcor' # PB-correction (pbcor) or only calc spectral-index (calcalpha)
# reffreq = '' # Reference frequency (if specified in clean)
# pbmin = 0.2 # PB threshold below which to not correct
# field = '' # Fields to include in the PB calculation
```
CHAPTER 5. SYNTHESIS IMAGING

```
spwlist = '' # List of N spw ids
chanlist = [] # List of N channel ids
weightlist = [] # List of N weights (relative)
async = False # If true the taskname must be started using widebandpbcor(...)
```

`action='pbcor'` computes Taylor-coefficient images that represent the primary beam spectrum and applies them to the input Taylor coefficient images. The `action='calcalpha'` will recalculate spectral index maps based on the primary beam correction polynomials.

### 5.5 Combined Single Dish and Interferometric Imaging (feather)

The term “feathering” is used in radio imaging to describe how to combine or “feather” two images together by forming a weighted sum of their Fourier transforms in the (gridded) uv-plane. Intermediate size scales are down-weighted to give interferometer resolution while preserving single-dish total flux density.

The feathering technique does the following:

1. The single-dish and interferometer images are Fourier transformed.
2. The beam from the single-dish image is Fourier transformed ($FTSDB(u, v)$), (alternatively, one can specify some smaller portion of the single dish aperture, which corresponds to a wider beam).
3. The Fourier transform of the interferometer image is multiplied by ($1 - FTSDB(u, v)$). This basically down weights the shorter spacing data from the interferometer image.
4. The Fourier transform of the single-dish image is scaled by the volume ratio of the interferometer restoring beam to the single dish beam.
5. The results from 3 and 4 are added and Fourier transformed back to the image plane.

The term feathering derives from the tapering or down-weighting of the data in this technique; the overlapping, shorter spacing data from the deconvolved interferometer image is weighted down compared to the single dish image while the overlapping, longer spacing data from the single-dish are weighted down compared to the interferometer image.

The tapering uses the transform of the low resolution point spread function. This can be specified as an input image or the appropriate telescope beam for the single-dish. The point spread function for a single dish image may also be calculated using `clean`.

Advice: Note that if you are feathering large images, be advised to have the number of pixels along the X and Y axes to be composite numbers and definitely not prime numbers. In general FFTs
work much faster on even and composite numbers. You may use subimage function of the image tool to trim the number of pixels to something desirable.

The inputs for \texttt{feather} are:

\begin{verbatim}
# feather :: Combine two images using their Fourier transforms
imagename = ''    # Name of output feathered image
highres = ''      # Name of high resolution (interferometer) image
lowres = ''       # Name of low resolution (single dish) image
sdfactor = 1.0    # Scale factor to apply to Single Dish image
effdishdiam = -1.0 # New effective SingleDish diameter to use in m
lowpassfiltersd = False # Filter out the high spatial frequencies of the SD image
async = False     # If true the taskname must be started using
\end{verbatim}

The single-dish data cube is specified by the \texttt{lowres} and the interferometric data cube by the \texttt{highres} keyword. The combined, feathered output cube name is given by the \texttt{imagename} parameter. \texttt{sdfactor} can be used to adjust the flux calibration of the images. Since single-dish processing typically involves the fit of a baseline level, it might be the one with the most uncertain calibration and \texttt{sdfactor} will multiply with the single-dish image values for any needed correction.

The weighting functions for the data are usually the Fourier transform of the Single Dish beam FFT(PB\textsubscript{SD}) for the Single dish data, and the inverse, 1-FFT(PB\textsubscript{SD}) for the interferometric data. It is possible, however, to change the weighting functions by pretending that the SD is smaller in size via the \texttt{effdishdiameter} parameter. This tapers the high spatial frequencies of the SD data and adds more weight to the interferometric data. The \texttt{lowpassfiltersd} can take out artifacts at very high spatial frequencies that are often present but non-physical in SD data.

Note that the only inputs are for images and \texttt{feather} will attempt to regrid the images to a common shape, i.e. pixel size, pixel numbers, and spectral channels. \texttt{feather} does not do any deconvolution but combines presumably deconvolved images after the fact. This implies that the short spacings extrapolated by the deconvolution process will be those that are down-weighted the most. The single dish image must have a well-defined beam shape and the correct flux units for a model image (Jy/beam instead of Jy/pixel) so use the tasks \texttt{imhead} and \texttt{immath} first to convert if needed.

Starting with a cleaned synthesis image and a low resolution image from a single dish telescope, the following example shows how they can be feathered:

\begin{verbatim}
feather(imagename='feather.im', # Create an image called feather.im
      highres='synth.im',     # The synthesis image is called synth.im
      lowres='single_dish.im'  # The SD image is called single_dish.im
    )
\end{verbatim}

\subsection{Visual Interface for feather (\texttt{casafeather})}

CASA also provides a visual interface to the \texttt{feather} task. The interface is run \textit{from a command line outside CASA} by typing \texttt{casafeather} in a shell. Fig.\ref{fig:casafeather} shows an example. As a first step, one needs to specify a high and a low resolution image, typically an interferometric and a single
dish map. Note that the single dish map needs to be in units of Jy beam$^{-1}$. An output image is usually specified, too. On the main GUI, press “Feather” to start the feathering process, which includes regridding the low resolution image to the high resolution image.

“casafeather” has the ability to show two major rows of displays (see Fig. 5.7) that can be turned on or off. A good visualization is usually obtained by making both axes logarithmic. This can be specified in the “Customize menu”, the toothed wheel symbol at the top of the panel. The two rows of displays are: 1) “Original Data Slice”: Cuts through the u and v directions of the Fourier transformed input images. A vertical line shows the location of the effective dish diameter(s). 2) “Feathered Data Slice”: The same cuts, but scaled by the “low resolution scale factor” and weighted by the weighting functions (see §5.5). In this display, the weighting functions themselves are shown, too.

At the top of the display effdshdiameter for u and v and sdfactor can be provided in the “Effective Dish Diameter” and “Low Resolution Scale Factor” input boxes.

5.6 Making Deconvolution Masks or Box Regions

For most careful imaging, you will want to restrict the region over which you allow CLEAN components to be found. To do this, you can create a ‘deconvolution region’ or ‘mask’ image using the boxit or the viewer. Note that clean can take simple boxes or box files as direct input to its mask parameter, so these tasks are most useful when direct input to clean (or use of interactive clean) will not suffice.

There are two ways to construct region files or mask images for use in deconvolution. The boxit task will find a set of box regions based upon an input image and control parameters.

5.6.1 Making Deconvolution Regions from an Image (boxit)

The boxit task creates “cleanbox” deconvolution regions automatically from an image. It searches the image to find “islands”: all contiguous sets of pixels above the given threshold. The extreme x- and y-pixels of the island are used to determine the corners of a rectangular box that covers each island. The set of boxes are written out into a single region file with extension .rgn. Boxit works on single-plane images as well as multi-channel images: in the latter case, the thresholding and boxing is done separately in each plane of the image. The output region file from boxit can be used as the mask input parameter for the clean task (§5.3).

The parameter inputs for boxit are:

```python
# boxit :: Box regions in image above given threshold value.
imagename = '' # Name of image to threshold
regionfile = '' # Output region file
threshold = '0.0mJy' # Threshold value. Must include units.
minsize = 2 # Minimum number of pixels for a boxable island
diag = False # Count diagonal connections?
boxstretch = 1 # Increase box sizes by this many pixels beyond thresholded pixels.
```
Figure 5.7: Visual “casafeather” interface to the feather task.

overwrite = False  # Overwrite existing region file?
async = False  # If true the taskname must be started using boxit(...)
ALERT: The boxit task is a prototype under active development and coded in Python. Eventually we will add functionality to deal with the creation of non-rectangular regions and with multi-plane masks, as well as efficiency improvements.

5.7 Insert an Image Model (ft)

The ft task will add a source model (units should be Jy/pixel) or a clean component list to a Measurement Set. This is especially useful if you have a resolved calibrator and you want to start with a model of the source before you derive accurate gain solutions. This is also helpful for self-calibration (see § 5.9 below).

The inputs for ft are:

```python
# ft :: Insert a source model into the MODEL_DATA column of a visibility set:
vis = '' # Name of input visibility file (MS)
field = '' # Field selection
spw = '' # Spw selection
model = '' # Name of input model image(s)
nterms = 1 # Number of terms used to model the sky
# frequency dependence
complist = '' # Name of component list
incremental = False # Add to the existing model visibility?
usescratch = False # If True predicted visibility is stored in
# MODEL_DATA column
async = False # If true the taskname must be started using
# ft(...) 
```

An example on how to do this:

```python
ft(vis='n75.ms', # Start with the visibility dataset n75.ms 
   field='1328', # Select field name '1328+307' (minimum match)
   model='1328.model.image') # Name of the model image you have already
```

This example will add the source model '1328.model.imag' to all entries that match the field name '1328'. If the parameter usescratch is set to 'True', ft will Fourier transform the source model and fill the MODEL_DATA column with the data. This, however, is only needed in special applications and usescratch=F is the default.

Alternatively, one can add a clean component list to be used as a model to the MS. The following procedure is an example:

```python
# for a point source with no spectral index
c1.addcomponent(flux=0.39, fluxunit='Jy',shape='point', dir='J2000 19h33m09s 15d01m20s')

# for a Gaussian with a spectral index
c1.addcomponent(flux=1.25, fluxunit='mJy', polarization='Stokes',
dir='J2000 19h30m00s 15d00m00s', shape='gaussian', majoraxis='10arcsec',
```
minoraxis='6arcsec', positionangle='0deg', freq='1.25GHz',
spectrumtype='spectral index', index=-0.8)
### you can add more components if you wish by calling addcomponent repeatedly with different params

### save it to disk
c1.rename('my_component.cl')
c1.close()

### write the model into into the measurement set ('myms')
ft(vis='myms', complist='my_component.cl')

5.8 Image-plane deconvolution (deconvolve)

If you have only an image (obtained from some telescope) and an image of its point spread function, then you can attempt a simple image-plane deconvolution. Note that for interferometer data, full uv-plane deconvolution using clean or similar algorithm is superior!

The default inputs for deconvolve are:

```python
# deconvolve :: Deconvolving a point spread function from an image

imagename = '' # Name of image to decolvolve
model = '' # Name of output image to which deconvolved components are stored
psf = '' # Name of psf or gaussian parameters if psf is assumed gaussian
alg = 'clark' # Deconvolution algorithm to use
niter = 10 # number of iteration to use in deconvolution process
gain = 0.1 # CLEAN gain parameter
threshold = '0.0Jy' # level below which sources will not be deconvolved
mask = '' # Name of image that has mask to limit region of deconvolution
async = False # if True run in the background, prompt is freed
```

The algorithm (alg) options are: 'clark', 'hogbom', 'multiscale' or 'mem'. The 'multiscale' and 'mem' options will open the usual set of sub-parameters for these methods.

5.9 Self-Calibration

Once you have a model image or set of model components reconstructed from your data using one of the deconvolution techniques described above, you can use it to refine your calibration. This is called self-calibration as it uses the data to determine its own calibration (rather than observations of special calibration sources).

In principle, self-calibration is no different than the calibration process we described earlier (§4). In effect, you alternate between calibration and imaging cycles, refining the calibration and the model as you go. The trick is you have to be careful, as defects in early stages of the calibration can get into the model, and thus prevent the calibration from improving. In practice, it is best to not clean very deeply early on, so that the CLEAN model contains correct components only.
One important thing to keep in mind is that the self-calibration relies upon having the most recent source model inside the MS. This is indeed the case if you follow the imaging (using clean) directly by the self-calibration. If you have done something strange in between and have lost or overwritten source model (for example done some extra cleaning that you do not want to keep), then use the ft task (see § 5.7 above), which adds a source model image or clean component lists to an MS.

Likewise, during self-calibration (once you have a new calibration solution) the imaging part relies upon having the CORRECTED_DATA column contain the self-calibrated data. This is done with the applycal task (§ 4.6.1).

The clearcal command can be used during the self-calibration if you need to clear the CORRECTED_DATA column and revert to the original DATA. If you need to restore the CORRECTED_DATA to any previous stage in the self-calibration, use applycal again with the appropriate calibration tables.

**ALERT:** In later patches we will change the tasks so that users need not worry what is contained in the MS scratch columns and how to fill them. CASA will handle that underneath for you!

For now, we refer the user back to the calibration chapter for a reminder on how to run the calibration tasks.

### 5.10 Parallel Cleaning (pclean)

pclean is an experimental task to allow clean speedup by using more than a single computing node.

The inputs are somewhat different from clean but we will merge the two tasks in the future:

```python
# pclean :: Invert and deconvolve images with parallel engines
vis = '' # Name of input visibility file
imname = '' # Pre-name of output images
ims = [256, 256] # Image size in pixels (nx,ny), symmetric for single value

cell = ['1.0arcsec', '1.0arcsec'] # The image cell size in arcseconds.
phasecenter = '' # Image center: direction or field index
stokes = '' # Stokes params to image (eg I,IV,IQ,IQUV)
mask = '' # mask image
field = '' # Field Name or id
spw = '' # Spectral windows e.g. '0~3', '' is all
ftmachine = 'ft' # Fourier Transform Engine ('ft', 'sd', 'mosaic' or 'wproject')
alg = 'clark' # Deconvolution algorithm ('clark', 'hogbom', 'multiscale')
cyclefactor = 1.5 # Control number of major cycle, threshold of cycle=residualPeak*psfSidelobe*cyclefactor
niter = 500 # Maximum number of iterations
gain = 0.1 # Gain to use in deconvolution
threshold = '0.0Jy' # Flux level to stop cleaning, must include units: '1.0mJy'
weighting = 'natural' # Type of weighting
```
mode = 'extend'  # Clean mode ('continuum', 'cube')
interactive = False  # Interactive clean
overwrite = False  # Overwrite an existing model image
uvtaper = False  # Apply additional uv tapering of visibilities
timerange = ''  # Range of time to select from data
uvrange = ''  # Select data within uvrange
antenna = ''  # Select data based on antenna/baseline
scan = ''  # Scan number range
observation = ''  # Observation ID range
pbcor = False  # Correct for the primary beam post deconvolution
minpb = 0.2  # Fractional of peak of pb coverage where to stop
#the pb correction
clusterdef = ''  # File that contains cluster definition
async = False  # If true the taskname must be started using
#pclean(...)

In pclean, the parameter als controls whether the 'clark', 'hogbom', or 'multiscale' cleaning algorithms are used. 'ft', 'sd', 'mosaic', and 'wproject' are specified via ftmachine, similar to imagermode in clean. Important is the clusterdef parameter. It specifies a file with all computer names, the number of CPU cores and temporary directories that can be used for pclean. It is formatted like:

```
############################
hal9000, 10, /home/ptest
sal9000, 12, /home/ptest
nearstar, 6, /home/ptest
############################
```

It is advisable to leave one or two cores unused by pclean on computers that run the task. This will allow other, sometimes vital, processes to continue.

IMPORTANT: the user have to have passwordless ssh access to all the computers used in a cluster definition file and the working directories has to be crossmounted by all the computers under the same names.

pclean attempts so slice the data in time bins for continuum imaging and in channel bins for spectral imaging and send sub-processes to the individual nodes. Since they all report back to the main terminal while they are executed, the logging may look a bit messy. After the clean processes on the nodes concluded, the data will be put back together to create single image files.

### 5.11 Examples of Imaging

The data reduction tutorials on [casaguides.nrao.edu](https://casaguides.nrao.edu) provide walkthroughs for high and low frequency, spectral line and polarization imaging techniques.
Chapter 6

Image Analysis

Once data has been calibrated (and imaged in the case of synthesis data), the resulting image or image cube must be displayed or analyzed in order to extract quantitative information, such as statistics or moment images. In addition, there need to be facilities for the coordinate conversion of images for direct comparison.

The image analysis tasks are:

- **imhead** — summarize and manipulate the “header” information in a CASA image (§ 6.2)
- **imsubimage** — Create a (sub)image from a region of the image (§ 6.3)
- **imcontsub** — perform continuum subtraction on a spectral-line image cube (§ 6.4)
- **imfit** — image plane Gaussian component fitting (§ 6.5)
- **immath** — perform mathematical operations on or between images (§ 6.6)
- **immoments** — compute the moments of an image cube (§ 6.7)
- **impv** — generate a position-velocity diagram along a slit (§ 6.8)
- **imstat** — calculate statistics on an image or part of an image (§ 6.9)

**Inside the Toolkit:**

Image analysis is handled in the **ia** tool. Many functions exist there, including region statistics and image math. See § 6.21 below for more information.
• imval — extract the data and mask values from a pixel or region of an image (§6.10)
• imtrans — reorder the axes of an image or cube (§6.11)
• incollapse — collapse image along one or more axes by aggregating pixel values along that axis (§6.12)
• imregrid — regrid an image onto the coordinate system of another image (§6.13)
• imreframe — change the frame in which the image reports its spectral values (§6.14)
• imsmooth — smooth images in the spectral and angular directions (§6.15)
• specfit — fit 1-dimensional Gaussians, polynomial, and/or Lorentzians models to an image or image region (§6.16)
• makemask — image mask handling (§6.17)
• slsearch — query a subset of the Splatalogue spectral line catalog (§6.18)
• splattotable — convert a file exported from Splatalogue to a CASA table (§6.19)
• importfits — import a FITS image into a CASA image format table (§6.20.2)
• exportfits — write out an image in FITS format (§6.20.1)

There are other tasks which are useful during image analysis. These include:

• viewer — there are useful region statistics and image cube slice and profile capabilities in the viewer (§7)

We also give some examples of using the CASA Toolkit to aid in image analysis (§6.21).

6.1 Common Image Analysis Task Parameters

We now describe some sets of parameters are are common to the image analysis. These should behave the same way in any of the tasks described in this section that they are found in.
ALERT: As of CASA 4.0.0 we introduced changed clean such that for large fractional bandwidths, if the PSF changes more than half a pixel, a different beam will be used for each image plane. These cubes are supported in all image analysis tasks.

6.1.1 Region Selection (box)

Direction (eg RA, Dec) areal selection in the image analysis tasks is controlled by the box parameter or through the region parameter (§ 6.1.5). Note that one should either specify a region (recommended) or any of box/chans/stokes. Specifying both at the same time is not unique anymore and can lead to unwanted selections. In the future we may remove the box/chans/stokes selection (for CASA 3.3 we keep both selection methods for backward compatibility).

The box parameter selects spatial rectangular areas (this parameter will be removed for CASA 3.4 and higher):

```
box = '' # Select one or more box regions
#
# string containing blcx,blcy,trcx,trcy
#
# A box selection in the directional portion of an image.
# The directional portion of an image are the axes for right
# ascension and declination, for example. Boxes are specified
# by there bottom-left corner (blc) and top-right corner (trc)
# as follows: blcx, blcy, trcx, trcy;
# ONLY pixel values acceptable at this time.
# Default: none (all);
# Example: box='0,0,50,50'
```

To get help on box, see the in-line help

```
help(par.box)
```

6.1.2 Plane Selection (chans, stokes)

The channel, frequency, or velocity plane(s) of the image is chosen using the chans parameter:

```
chans = '' # Select the channel(spectral) range
#
# string containing channel range
#
# immath, imstat, and imcontsub - takes a string listing
# of channel numbers, velocity, and/or frequency
# numbers, much like the spw parameter
# Only channel numbers acceptable at this time.
# Default: none (all);
```
# Example: chans='3~20'
# chans="0,3,4,8"
# chans="3~20,50,51"

chans can also be set in the CASA region format to allow settings ins frequency and velocity, e.g.

```plaintext
chans=("range=[-50km/s,50km/s], restfreq=100GHz, frame=LSRK")
```

this example would even define a new velocity system independent of the one in the image itself. If the rest frequency and velocity fram within the image are being used, the latter two entires are not needed. The parentheses are needed when the call is in a single command.

A frequency selection looks as follows:

```plaintext
chans=('range=[100GHz,100.125GHz]')
```

The polarization plane(s) of the image is chosen with the stokes parameter:

```plaintext
stokes = '' # Stokes params to image (I,IV,IQU,IQUV)
# string containing Stokes selections
# Stokes parameters to image, may or may not be separated
# by commas but best if you use commas.
# Default: none (all); Example: stokes='IQUV';
# Example: stokes='I,Q'
# Options: 'I','Q','U','V',
# 'RR','RL','LR','LL',
# 'XX','YX','XY','YY',...
```

To get help on these parameters, see the in-line help

```plaintext
help(par.chans)
help(par.stokes)
```

Sometimes, as in the immoments task, the channel/plane selection is generalized to work on more than one axis type. In this case, the planes parameter is used. This behaves like chans in syntax.

### 6.1.3 Lattice Expressions (expr)

Lattice expressions are strings that describe operations on a set of input images to form an output image. These strings use the Lattice Expression Language (LEL). LEL syntax is described in detail in AIPS++ Note 223

[http://aips2.nrao.edu/docs/notes/223/223.html](http://aips2.nrao.edu/docs/notes/223/223.html)
CHAPTER 6. IMAGE ANALYSIS

ALERT: This document was written in the context of glish-based AIPS++ and is not yet updated to CASA syntax (see below).

The expr string contains the LEL expression:

```
expr = 'min(image2.im)+(2*max(image1.im))'
```

For examples using LEL expr, see § 6.6.1 below. Note that in immath, shortcut names have been given to the images provided by the user in imagename that can be used in the LEL expression, for the above example:

```
imagename=['image2.im','image1.im']
```

ALERT: LEL expressions use 0-based indices. Also, the functions must be lowercase (in almost all cases we know about).

6.1.4 Masks (mask)

The mask string contains a LEL expression (see § 6.1.3 above). This string can be an on-the-fly (OTF) mask expression or refer to an image pixel mask.

```
mask = 'min(IM0)+(2*max(IM1))'
```

Note that the mask file supplied in the mask parameter must have the same shape, same number of axes and same axes length, as the images supplied in the expr parameter, with one exception. The mask may be missing some of the axes — if this is the case then the mask will be expanded along these axes to become the same shape.

For examples using mask, see § 6.6.2 below.
CHAPTER 6. IMAGE ANALYSIS

6.1.5 Regions (region)

The region parameter points to a CASA region which can be directly specified or listed in a ImageRegion file. An ImageRegion file can be created with the CASA viewer’s region manager (§ 7.4.3). Or directly using the CASA region syntax (Chapter D). Typically ImageRegion files will have the suffix ‘.crtf’ for CASA Region Text Format.

Alert: When both the region parameter and any of box/chans/stokes are specified simultaneously, the task may perform unwanted selections. Only specify one of these (sets of) parameters. We recommend the use of CASA regions and may remove the box/chans/stokes selection in later releases.

For example:

```
region='circle[[18h12m24s, -23d11m00s], 2.3arcsec]'
```

or

```
region='myimage.im.crtf'
```

for to specify a region file.

For the most part, the region parameter in tasks only accepts strings (eg, file names, region shape descriptions) while the region parameter in ia tool methods only accepts python region dictionaries (eg produced using the rg tool).

6.2 Image Header Manipulation (imhead)

To summarize and change keywords and values in the “header” of your image, use the imhead task. Its inputs are:

```
# imhead :: List, get and put image header parameters
imagename = '' # Name of the input image
mode = 'summary' # imhead options: add, del, get, history, list, put, summary
verbose = False # Give a full listing of beams or just a short summary?
# Only used when the image has multiple beams and
# mode="summary".
async = False # If true the taskname must be started using imhead(...)  
```

The mode parameter controls the operation of imhead.

Setting mode='summary’ will print out a summary of the image properties and the header to the logger.
Setting `mode='list'` prints out a list of the header keywords and values to the terminal.

The `mode='get'` allows the user to retrieve the current value for a specified keyword `hdkey`:

```python
mode = 'get' # imhead options: list, summary, get, put
hdkey = '' # The FITS keyword
```

Note that to catch this value, you need to assign it to a Python variable. See §1.4.3 for more on return values.

The `mode='put'` allows the user to replace the current value for a given keyword `hditem` with that specified in `hdvalue`. There are two sub-parameters that are opened by this option:

```python
mode = 'put' # imhead options: list, summary, get, put
hdkey = '' # The FITS keyword
hdvalue = '' # Value of hdkey
hdtype = '' # Data type of the header keyword.
hdcomment = '' # Comment associated with the header keyword
```

**WARNING:** Be careful when using `mode='put'`. This task does no checking on whether the values you specify (e.g. for the axes types) are valid, and you can render your image invalid. Make sure you know what you are doing when using this option!

### 6.2.1 Examples for `imhead`

Here is an example – we can print the summary to the logger:

```python
CASA <51>: imhead('ngc5921.demo.cleanimg.image',mode='summary')
```

prints in the logger:

```text
##### Begin Task: imhead #####
Image name : ngc5921.demo.cleanimg.image
Object name : N5921_2
Image type : PagedImage
Image quantity : Intensity
Pixel mask(s) : None
Region(s) : None
Image units : Jy/beam
Restoring Beam : 52.3782 arcsec, 45.7319 arcsec, -165.572 deg
Direction reference : J2000
Spectral reference : LSRK
Velocity type : RADION
Rest frequency : 1.42041e+09 Hz
Pointing center : 15:22:00.000000 +05.04.00.000000
Telescope : VLA
```
### End Task: imhead

If the beam size per plane differs, the beam information will be displayed for the channel with the smallest beam, the one with the largest beam, and the channel closest to the median beam size. E.g.,

**Restoring Beams**

<table>
<thead>
<tr>
<th>Pol</th>
<th>Type</th>
<th>Chan</th>
<th>Freq</th>
<th>Vel</th>
</tr>
</thead>
<tbody>
<tr>
<td>I</td>
<td>Max</td>
<td>0</td>
<td>9.680e+08</td>
<td>0</td>
</tr>
<tr>
<td>I</td>
<td>Min</td>
<td>511</td>
<td>1.990e+09</td>
<td>-316516</td>
</tr>
<tr>
<td>I</td>
<td>Median</td>
<td>255</td>
<td>1.478e+09</td>
<td>-157949</td>
</tr>
</tbody>
</table>

If verbose=T the beam information for every plane will be provided.

If you choose mode='list', you get the summary in the logger and a listing of keywords and values to the terminal:

```
CASA <52>: imhead('ngc5921.demo.cleanimg.image',mode='list')
```

```
Out[52]:
{'beammajor': 52.378242492675781,
 'beamminor': 45.731891632080078,
 'beampa': -165.5721435546875,
 'bunit': 'Jy/beam',
 'cdelt1': '-3.722205221664e-05',
 'cdelt2': '7.272205221664e-05',
 'cdelt3': '1.0',
 'cdelt4': '24414.0625',
 'crpix1': 128.0,
 'crpix2': 128.0,
 'crpix3': 0.0,
 'crpix4': 0.0,
 'crval1': '4.02298392585',
 'crval2': '0.0884300154344',
 'crval3': 'I',
 'crval4': '1412787144.08',
 'ctype1': 'Right Ascension',
 'ctype2': 'Declination',
 'ctype3': 'Stokes',
```
'ctype4': 'Frequency',
'cunit1': 'rad',
'cunit2': 'rad',
'cunit3': '',
'cunit4': 'Hz',
'datamax': 'Not Known',
'datamin': -0.010392956435680389,
'date-obs': '1995/04/13/00:00:00',
'equinox': 'J2000',
'imtype': 'Intensity',
'masks': 'Not Known',
'maxpixpos': array([134, 134, 0, 38], dtype=int32),
'maxpos': '15:21:53.976, +05.05.29.998, I, 1.41371e+09Hz',
'minpixpos': array([117, 0, 0, 21], dtype=int32),
'minpos': '15:22:11.035, +04.31.59.966, I, 1.4133e+09Hz',
'object': 'N5921_2',
'observer': 'TEST',
'projection': 'SIN',
'reffreqtype': 'LSRK',
'restfreq': [1420405752.0],
'telescope': 'VLA'}

Note that this list is a return value and can be captured in a variable:

```python
mylist = imhead('ngc5921.demo.cleanimg.image', mode='list')
```

The values for these keywords can be queried using `mode='get'`. At this point you should capture the return value:

```python
CASA <53>: mybmaj = imhead('ngc5921.demo.cleanimg.image', mode='get', hdkey='beammajor')
```

```python
CASA <54>: mybmaj
Out[54]: {'unit': 'arcsec', 'value': 52.378242492699997}
```

```python
CASA <55>: myobserver = imhead('ngc5921.demo.cleanimg.image', mode='get', hdkey='observer')
```

```python
CASA <56>: print myobserver
{'value': 'TEST', 'unit': ''}
```

You can set the values for these keywords using `mode='put'`. For example:

```python
CASA <57>: imhead('ngc5921.demo.cleanimg.image', mode='put', hdkey='observer', hdvalue='CASA')
Out[57]: 'CASA'
```

```python
CASA <58>: imhead('ngc5921.demo.cleanimg.image', mode='get', hdkey='observer')
Out[58]: {'unit': '', 'value': 'CASA'}
```
6.3 Extracting sub-images (imsubimage)

The task `imsubimage` provides a way to extract a smaller data cube from a bigger one. The inputs are:

```python
# imsubimage :: Create a (sub)image from a region of the image
ingame = '' # Input image name. Default is unset.
outfile = '' # Output image name. Default is unset.
region = '' # Region of interest. Default is whole image.
mask = '' # Mask to use. See help par.mask. Default is none.
dropdeg = False # Drop degenerate axes
overwrite = False # Overwrite (unprompted) pre-existing output file?
verbose = True # Post additional informative messages to the logger
stretch = False # Stretch the mask if necessary and possible?
wantreturn = True # If True, return an image analysis tool associated with the subimage. If False, return nothing.
async = False # If true the taskname must be started using imsubimage(...)
```

The `region` keyword defines the size of the smaller cube and is specified via the CASA region CRTF syntax. E.g.

```plaintext
region='box [100pix , 130pix] , [120pix, 150pix ]'
```

will extract the portion of the image that is between pixel coordinates (100,130) and (120,150). `dropdeg=T` is useful to remove axes in the data cube that are degenerate, i.e. axes with a single plane only. A single Stokes I axis is a common example.

6.4 Continuum Subtraction on an Image Cube (imcontsub)

One method to separate line and continuum emission in an image cube is to specify a number of line-free channels in that cube, make a linear fit to the visibilities in those channels, and subtract the fit from the whole cube. Note that the task `uvcontsub` serves a similar purpose; see §4.7.5 for a synopsis of the pros and cons of either method.

The `imcontsub` task will subtract a polynomial baseline fit to the specified channels from an image cube.

The default inputs are:
Area selection using box and region is detailed in §6.1.1 and §6.1.5 respectively. Image cube plane selection using chans and stokes are described in §6.1.2.

**ALERT:** imcontsub has issues when the image does not contain a spectral or stokes axis. Errors are generated when run on an image missing one or both of these axes. You will need to use the Toolkit (e.g. the ia.adddegaxes method) to add degenerate missing axes to the image.

### 6.4.1 Examples for imcontsub

For example, we first make a clean image without the uv-plane continuum subtraction:

```python
# First, run clearcal to clear the uvcontsub results from the
clearcal('ngc5921.demo.src.split.ms')

# Now clean, keeping all the channels except first and last
default('clean')
vis = 'ngc5921.demo.src.split.ms'
imagename = 'ngc5921.demo.nouvcontsub'
mode = 'channel'
nchan = 61
start = 1
width = 1
imsize = [256,256]
psfmode = 'clark'
imagermode = ''
cell = [15.,15.]
niter = 6000
threshold='8.0mJy'
weighting = 'briggs'
robust = 0.5
interactive=False
clean()

# It will have made the image:
# ----------------------------
You can clearly see continuum sources in the image which were removed previously in the script by the use of `uvcontsub`. Let's see if `imcontsub` can work as well.

Using the viewer, it looks like channels 0 through 4 and 50 through 60 are line-free. Then:

```python
default('imcontsub')
imagename = 'ngc5921.demo.nouvcontsub.image'
linefile = 'ngc5921.demo.nouvcontsub.lineimage'
contfile = 'ngc5921.demo.nouvcontsub.contimage'
fitorder = 1
chans = '0~4,50~60'
stokes = 'I'
imcontsub()
```

This did not do too badly!

### 6.5 Image-plane Component Fitting (imfit)

The inputs are:

```python
# imfit : Fit one or more elliptical Gaussian components on an image region(s)
imagename = '' # Name of the input image
box = '' # Specify one or more box regions for the fit.
region = '' # Region. See help par.region for specs.
chans = '' # Spectral channels on which to perform fit.
stokes = '' # Stokes parameter to fit. If blank, first stokes plane is used.
mask = '' # Mask to use. See help par.mask. Default is none.
includepix = [] # Range of pixel values to include for fitting.
excludepix = [] # Range of pixel values to exclude for fitting.
residual = '' # Name of output residual image.
model = '' # Name of output model image.
estimates = '' # Name of file containing initial estimates of component parameters.
logfile = '' # Name of file to write fit results.
newestimates = '' # File to write fit results which can be used as initial estimates.
complist = '' # Name of output component list table.
dooff = False # Also fit a zero level offset? Default is False
async = False # If true the taskname must be started using imfit(...)
```

This task will return (as a Python dictionary) the results of the fit, but the results can also be written into a component list table or a logfile.

Note that to fit more than a single component, you must provide starting estimates for each component via the `estimates` file. See `"help imfit"` for more details on this.
6.5.1 Examples for imfit

The following are some examples using the B1608+656 Tutorial

```
http://casa.nrao.edu/Doc/Scripts/b1608_demo.py
```

as an example.

```python
# First fit only a single component at a time
# This is OK since the components are well-separated and not blended
# Box around component A
xfit_A_res = imfit('b1608.demo.clean2.image', box='121,121,136,136',
                   newestimates='b1608.demo.clean2.newestimate')

# Now extract the fit part of the return value
xfit_A = xfit_A_res['results']['component0']
```

```python
# Now the other components
xfit_B_res = imfit('b1608.demo.clean2.image', box='108,114,120,126',
                   newestimates='b1608.demo.clean2.newestimate')
```
newestimates='b1608.demo.clean2.newestimate',append=True)
xfit_B = xfit_B_res['results']['component0']

xfit_C_res = imfit('b1608.demo.clean2.image',box='108,84,120,96')
xfit_C = xfit_C_res['results']['component0']

xfit_D_res = imfit('b1608.demo.clean2.image',box='144,98,157,110')
xfit_D = xfit_D_res['results']['component0']

print ""
print "Imfit Results:"
print "--------------"
print "A Flux = %6.4f Bmaj = %6.4f" % (xfit_A['flux']['value'][0],xfit_A['shape']['majoraxis']['value'])
print "B Flux = %6.4f Bmaj = %6.4f" % (xfit_B['flux']['value'][0],xfit_B['shape']['majoraxis']['value'])
print "C Flux = %6.4f Bmaj = %6.4f" % (xfit_C['flux']['value'][0],xfit_C['shape']['majoraxis']['value'])
print "D Flux = %6.4f Bmaj = %6.4f" % (xfit_D['flux']['value'][0],xfit_D['shape']['majoraxis']['value'])
print ""

Now try fitting four components together. For this we will have to provide an estimate file. We will use the clean beam for the estimate of the component sizes:

estfile=open('b1608.demo.clean2.estimate','w')
print >>estfile,'# peak, x, y, bmaj, bmin, bpa'
print >>estfile,'0.017, 128, 129, 0.293arcsec, 0.238arcsec, 21.7deg'
print >>estfile,'0.008, 113, 120, 0.293arcsec, 0.238arcsec, 21.7deg'
print >>estfile,'0.008, 113, 90, 0.293arcsec, 0.238arcsec, 21.7deg'
print >>estfile,'0.002, 151, 104, 0.293arcsec, 0.238arcsec, 21.7deg'
estfile.close()

Then, this can be used in imfit:

xfit_all_res = imfit('b1608.demo.clean2.image',
estimates='b1608.demo.clean2.estimate',
logfile='b1608.demo.clean2.imfitall.log',
newestimates='b1608.demo.clean2.newestimate',
box='121,121,136,136,108,114,120,126,108,84,120,96,144,98,157,110')

# Now extract the fit part of the return values
xfit_allA = xfit_all_res['results']['component0']
xfit_allB = xfit_all_res['results']['component1']
xfit_allC = xfit_all_res['results']['component2']
xfit_allD = xfit_all_res['results']['component3']

These results are almost identical to those from the individual fits. You can see a nicer printout of the fit results in the logfile.

6.6 Mathematical Operations on an Image (immath)

The inputs are:
CHAPTER 6. IMAGE ANALYSIS

# immath :: Perform math operations on images
imagename = '' # a list of input images
mode = 'evalexpr' # mode for math operation (evalexpr, spix, pola, poli)
expr = '' # Mathematical expression using images
varnames = '' # a list of variable names to use with the image files
outfile = 'immath_results.im' # File where the output is saved
mask = '' # Mask to be applied to the images
region = '' # File path which contains an Image Region
box = '' # Select one or more box regions in the input images
chans = '' # Select the channel(spectral) range
stokes = 'I' # Stokes params to image (I,IV,IQU,IQUV)
async = False # If true the taskname must be started using immath(...)

In all cases, outfile must be supplied with the name of the new output file to create.

The mode parameter selects what immath is to do.

The default mode='evalexpr' lets the user specify a mathematical operation to carry out on one or more input images. The sub-parameter expr contains the Lattice Expression Language (LEL) string describing the image operations based on the images in the imagename parameter. See §6.1.3 for more on LEL strings and the expr parameter.

Mask specification is done using the mask parameter. This can optionally contain an on-the-fly mask expression (in LEL) or point to an image with a pixel mask. See §6.1.4 for more on the use of the mask parameter. See also §6.1.3 for more on LEL strings. Sometimes, one would like to use a flat image (e.g. a moment image) mask to be applied to an entire cube. The stretch=True subparameter in mask allows one to expand the mask to all planes of the cube.

Region selection is carried out through the region and box parameters. See §6.1.1 and §6.1.5 for more on area selection.

Image plane selection is controlled by chans and stokes. See §6.1.2 for details on plane selection.

For mode='evalexpr', the standard usage for specifying images to be used in the LEL expression is to provide them as a list in the imagename parameter, and then access there in the LEL expression by the names IM0, IM1, .... For example,

```python
immath(imagename=['image1.im','image2.im'],expr='IM0-IM1',outfile='ImageDiff.im')
```

would subtract the second image given from the first.

For the special modes 'spix', 'pola', 'poli', the required images for the given operation are to be provided in imagename (some times in a particular order). V3.0 ALERT: For mode='pola' you MUST call as a function as in the example below (§6.6.1.2), giving the parameters as arguments, or immath will fail.

Detailed examples are given below.
6.6.1 Examples for immath

In the following, we show a few examples of immath. Note that the image names in the expr are assumed to refer to existing image files in the current working directory.

6.6.1.1 Simple math

Select a single plane (channel 22) of the 3-D cube and subtract it from the original image:

```python
immath(imagename='ngc5921.demo.cleanimg.image',
       expr='IM0', chans='22',
       outfile='ngc5921.demo.chan22.image')
```

Double all values in our image:

```python
immath(imagename=['ngc5921.demo.chan22.image'],
       expr='IM0*2.0',
       outfile='ngc5921.demo.chan22double.image')
```

Square all values in our image:

```python
immath(imagename=['ngc5921.demo.chan22.image'],
       expr='IM0^2',
       outfile='ngc5921.demo.chan22squared.image')
```

Note that the units in the output image are still claimed to be “Jy/beam”, ie. immath will not correctly scale the units in the image for non-linear cases like this. Beware.

You can do other mathematical operations on an image (e.g. trigonometric functions) as well as use scalars results from an image (e.g. max, min, median, mean, variance). You also have access to constants such as $e()$ and $pi()$ (which are doubles internally, while most images are floats). For example: Take the sine of an image:

```python
immath(imagename=['ngc5921.demo.chan22.image', 'ngc5921.demo.chan22squared.image'],
       expr='sin(float(pi()))*IM0/sqrt(max(IM1))',
       outfile='ngc5921.demo.chan22sine.image')
```

Note again that the units are again kept as they were.

Select a single plane (channel 22) of the 3-D cube and subtract it from the original image:

```python
immath(imagename='ngc5921.demo.cleanimg.image',
       expr='IM0', chans='22',
       outfile='ngc5921.demo.chan22.image')
```

```python
immath(imagename=['ngc5921.demo.cleanimg.image', 'ngc5921.demo.chan22.image'],
       expr='IM0-IM1',
       outfile='ngc5921.demo.sub22.image')
```
Note that in this example the 2-D plane gets extended in the third dimension and the 2-D values are applied to each plane in the 3-D cube.

Select and save the inner 1/4 of an image for channels 40, 42, 44 as well as channels 10 and below:

```plaintext
default('immath')
imagename=['ngc5921.demo.cleanimg.image']
expr='IM0'
region='box[[64pix,64pix],[192pix,192pix]]'
chans='<10;40,42,44'
outfile='ngc5921.demo.inner.image'
immath()
```

**ALERT:** Note that if chan selects more than one channel then the output image has a number of channels given by the span from the lowest and highest channel selected in chan. In the example above, it will have 45 channels. The ones not selected will be masked in the output cube. If we had set

```plaintext
chans = '40,42,44'
```

then there would be 5 output channels corresponding to channels 40, 41, 42, 43, 44 of the MS with 41, 43 masked. Also, the chans='<10' selects channels 0–9.

Note that the chans syntax allows the operators '<', '<=', '>', '>=' . For example,

```plaintext
chans = '<17,>79'
chans = '<=16,>=80'
```
do the same thing.

Divide an image by another, with a threshold on one of the images:

```plaintext
immath(imagename=['ngc5921.demo.cleanimg.image','ngc5921.demo.chan22.image'],
expr='IM0/IM1[IM1>0.008]',
outfile='ngc5921.demo.div22.image')
```

### 6.6.1.2 Polarization manipulation

The following are some examples using the 3C129 Tutorial

[http://casa.nrao.edu/Doc/Scripts/3c129_tutorial.py](http://casa.nrao.edu/Doc/Scripts/3c129_tutorial.py)
as an example.

It is helpful to extract the Stokes planes from the cube into individual images:
V3.0 ALERT: For mode='pola' you MUST call as a function as in this example (giving the parameters as arguments) or immath will fail.

Create a fractional linear polarization image:

    default('immath')
    imagename = ['3C129BC.I','3C129BC.Q','3C129BC.U']
    outfile='3C129BC.fractional_linpol'
    expr='sqrt((IM1^2 + IM2^2)/IM0^2)'  
    stokes=''                        
    immath()

Create a polarized intensity image:

    default('immath')
    imagename = ['3C129BC.Q','3C129BC.U','3C129BC.V']
    outfile='3C129BC.pol_intensity'
    expr='sqrt(IM0^2 + IM1^2 + IM2^2)'  
    stokes=''                        
    immath()                         

Toolkit Tricks: The following uses the toolkit §6.21. You can make a complex linear polarization (Q+iU) image using the imagepol tool:

    # See CASA User Reference Manual:
    # http://casa.nrao.edu/docs/casaref/imagepol-Tool.html
    #
    # Make an imagepol tool and open the clean image
    potool = casac.homefinder.find_home_by_name('imagepolHome')
    po = potool.create()
    po.open('3C129BC.clean.image')
    # Use complexlinpol to make a Q+iU image
    po.complexlinpol('3C129BC.cmplxlinpol')
    po.close()
You can now display this in the viewer, in particular overlay this over the intensity raster with the intensity contours. When you load the image, use the LEL:

'3C129BC.cmplxlinpol'[3C129BC.P > 0.0001]

which is entered into the LEL box at the bottom of the Load Data menu (§7.3.1).

### 6.6.2 Using masks in `imath`

The `mask` parameter is used inside `imath` to apply a mask to all the images used in `expr` before calculations are done (if you are curious, it uses the `ia.subimage` tool method to make virtual images that are then input in the LEL to the `ia.imagecalc` method).

For example, lets assume that we have made a single channel image using `clean`

```plaintext
default('clean')
vis = 'ngc5921.demo.src.split.ms.contsub'
imagename = 'ngc5921.demo.chan22.cleanimg'
mode = 'channel'
nchan = 1
start = 22
step = 1
field = '',
spw = '',
imsize = [256,256]
cell = [15.,15.]
psfalg = 'clark'
gain = 0.1
niter = 6000
threshold='8.0mJy'
weighting = 'briggs'
rmode = 'norm'
robust = 0.5
clean()
```

There is now a file 'ngc5921.demo.chan22.cleanimg.mask' that is an image with values 1.0 inside the cleanbox region and 0.0 outside.

We can use this to mask the clean image:

```plaintext
default('imath')
imagename = 'ngc5921.demo.chan22.cleanimg.image'
expr='IM0'
```
Toolbox Tricks: Note that there are also pixel masks that can be contained in each image. These are Boolean masks, and are implicitly used in the calculation for each image in \texttt{expr}. If you want to use the mask in a different image not in \texttt{expr}, try it in \texttt{mask}:

```python
# First make a pixel mask inside \texttt{ngc5921.demo.chan22.cleanimg.mask}
ia.open('ngc5921.demo.chan22.cleanimg.mask')
ia.calcmask('"ngc5921.demo.chan22.cleanimg.mask">0.5')
ia.summary()
ia.close()
# There is now a 'mask0' mask in this image as reported by the summary

# Now apply this pixel mask in \texttt{immath}
default('immath')
imagename='ngc5921.demo.chan22.cleanimg.image'
expr='IM0'
mask='mask(ngc5921.demo.chan22.cleanimg.mask)'
outfile='ngc5921.demo.chan22.cleanimg.imasked1'
immath()
```

Note that nominally the axes of the mask must be congruent to the axes of the images in \texttt{expr}. However, one exception is that the image in \texttt{mask} can have fewer axes (but not axes that exist but are of the wrong lengths). In this case \texttt{immath} will extend the missing axes to cover the range in the images in \texttt{expr}. Thus, you can apply a mask made from a single channel to a whole cube.

```python
# drop degenerate stokes and freq axes from mask image
ia.open('ngc5921.demo.chan22.cleanimg.mask')
im2 = ia.subimage(outfile='ngc5921.demo.chan22.cleanimg.mymask',dropdeg=True)
im2.summary()
im2.close()
# mymask has only RA and Dec axes

# Now apply this mask to the whole cube
default('immath')
imagename='ngc5921.demo.cleanimg.image'
expr='IM0'
mask='"ngc5921.demo.chan22.cleanimg.mymask">0.5'
outfile='ngc5921.demo.cleanimg.imasked'
immath()
```

For more on masks as used in LEL, see

http://aips2.nrao.edu/docs/notes/223/223.html

or in §\[6.1.4]\textsuperscript{1} above.
6.7 Computing the Moments of an Image Cube (immoments)

For spectral line datasets, the output of the imaging process is an image cube, with a frequency or velocity channel axis in addition to the two sky coordinate axes. This can be most easily thought of as a series of image planes stacked along the spectral dimension.

A useful product to compute is to collapse the cube into a moment image by taking a linear combination of the individual planes:

$$M_m(x_i, y_i) = \sum_k w_m(x_i, y_i, v_k) I(x_i, y_i, v_k)$$  \hspace{1cm} (6.1)

for pixel $i$ and channel $k$ in the cube $I$. There are a number of choices to form the $m$ moment, usually approximating some polynomial expansion of the intensity distribution over velocity mean or sum, gradient, dispersion, skew, kurtosis, etc.). There are other possibilities (other than a weighted sum) for calculating the image, such as median filtering, finding minima or maxima along the spectral axis, or absolute mean deviations. And the axis along which to do these calculation need not be the spectral axis (i.e. do moments along Dec for a RA-Velocity image). We will treat all of these as generalized instances of a “moment” map.

The immoments task will compute basic moment images from a cube. The default inputs are:

```python
# immoments :: Compute moments of an image cube:

# Input image name
imagename = ''
# List of moments you would like to compute
moments = [0]
# The moment axis: ra, dec, lat, long, spectral, or stokes
axis = 'spectral'
# Image Region. Use viewer
region = ''
# Select one or more box regions
box = ''
# Select the channel(spectral) range
chans = ''
# Stokes params to image (I,IV,IQU,IQUV)
stokes = ''
# mask used for selecting the area of the image to calculate the moments on
mask = ''
# Range of pixel values to include
includepix = -1
# Range of pixel values to exclude
excludepix = -1
# Output image file name (or root for multiple moments)
outfile = ''
# If true the taskname must be started using immoments(...)
async = False
```

This task will operate on the input file given by `imagename` and produce a new image or set of images based on the name given in `outfile`.

The `moments` parameter chooses which moments are calculated. The choices for the operation mode are:

- `moments=-1` - mean value of the spectrum
- `moments=0` - integrated value of the spectrum
- `moments=1` - intensity weighted coordinate; traditionally used to get ‘velocity fields’
- `moments=2` - intensity weighted dispersion of the coordinate; traditionally used to get ‘velocity dispersion’
- `moments=3` - median of I
moments=4 - median coordinate
moments=5 - standard deviation about the mean of the spectrum
moments=6 - root mean square of the spectrum
moments=7 - absolute mean deviation of the spectrum
moments=8 - maximum value of the spectrum
moments=9 - coordinate of the maximum value of the spectrum
moments=10 - minimum value of the spectrum
moments=11 - coordinate of the minimum value of the spectrum

The meaning of these is described in the CASA Reference Manual:

http://casa.nrao.edu/docs/casaref/image.moments.html

The axis parameter sets the axis along which the moment is “collapsed” or calculated. Choices are: 'ra', 'dec', 'lat', 'long', 'spectral', or 'stokes'. A standard moment-0 or moment-1 image of a spectral cube would use the default choice 'spectral'. One could make a position-velocity map by setting 'ra' or 'dec'.

The includepix and excludepix parameters are used to set ranges for the inclusion and exclusion of pixels based on values. For example, includepix=[0.05, 100.0] will include pixels with values from 50 mJy to 1000 Jy, and excludepix=[100.0, 1000.0] will exclude pixels with values from 100 to 1000 Jy.

If a single moment is chosen, the outfile specifies the exact name of the output image. If multiple moments are chosen, then outfile will be used as the root of the output filenames, which will get different suffixes for each moment.

For image cubes that contain different beam sizes for each plane, immoments will smooth all planes to the largest beam size first, then collapse to the desired moment.

6.7.1 Hints for using (immoments)

In order to make an unbiased moment-0 image, do not put in any thresholding using includepix or excludepix. This is so that the (presumably) zero-mean noise fluctuations in off-line parts of the image cube will cancel out. If you image has large biases, like a pronounced clean bowl due to missing large-scale flux, then your moment-0 image will be biased also. It will be difficult to alleviate this with a threshold, but you can try.

To make a usable moment-1 (or higher) image, on the other hand, it is critical to set a reasonable threshold to exclude noise from being added to the moment maps. Something like a few times the "rms noise level in the usable planes seems to work (put into includepix or excludepix as needed. Also use chans to ignore channels with bad data.

6.7.2 Examples using (immoments)

Below is an example for immoments:
default('immoments')
imagename = 'ngc5921.demo.cleanimg'
# Do first and second spectral moments
axis = 'spectral'
chans = '',
moments = [0,1]
# Need to mask out noisy pixels, currently done
# using hard global limits
excludepix = [-100,0.009]
outfile = 'ngc5921.demo.moments'

immoments()

# It will have made the images:
# --------------------------------------
# ngc5921.demo.moments.integrated
# ngc5921.demo.moments.weighted_coord

Other examples of NGC2403 (a moment zero image of a VLA line dataset) and NGC4826 (a moment one image of a BIMA CO line dataset) are shown in Figure 6.1.

![NGC2403 VLA moment zero image](image1)

![NGC4826 BIMA moment one image](image2)

Figure 6.1: NGC2403 VLA moment zero (left) and NGC4826 BIMA moment one (right) images as shown in the viewer.

**ALERT:** We are working on improving the thresholding of planes beyond the global cutoffs in includepix and excludepix.
6.8 Generating Position-Velocity Diagrams (impv)

CASA can generate position-velocity (pV) diagrams via the task `impv` or directly in the viewer (see §7.4.9). The viewer application calls the task:

```python
# impv :: Construct a position-velocity image by choosing two points in the direction plane.

imagename = ''  # Name of the input image
outfile = ''  # Output image name. If empty, no image is written.
start = []  # The starting pixel in the direction plane (array of two values).
end = []  # The ending pixel in the direction plane (array of two values).
width = 1  # Width in pixels for averaging pixels perpendicular to the slice. Must be an odd integer >= 1 (1 means only use the pixels along the slice).
unit = 'arcsec'  # Unit for the offset axis in the resulting image. Must be a unit of angular measure.
chans = ''  # Channels to use. See "help par.chans" for examples. Channels must be contiguous. Default is to use all channels.
region = ''  # Region selection. Default is entire image. No selection is permitted in the direction plane. See help par.region.

stokes = ''  # Stokes planes to use. Planes must be contiguous. Default is to use all stokes.
mask = ''  # Mask to use. See help par.mask. Default is none.
async = False  # If true the taskname must be started using impv(...)```

PV diagrams are generated by placing a “slicing” a datacube through the RA/DEC planes. The “slit” can have a width defined by `halfwidth` and the averaged values across the slit are then stored in a new image with position and velocity as the two axes. The slit position is specified by a start and end pixel in the RA/DEC plane of the data cube. An angular `unit` can be set to define what is stored in the resulting pV image.

6.9 Computing image statistics (imstat)

The `imstat` task will calculate statistics on a region of an image, and return the results as a return value in a Python dictionary.

The inputs are:
# imstat :: Displays statistical information from an image or image region

```
imagename = '' # Name of the input image
axes = -1 # List of axes to evaluate statistics over. Default is all axes.
region = '' # Image Region or name. Use Viewer
box = '' # Select one or more box regions
chans = '' # Select the channel(spectral) range. See "help par.chans" for examples.
stokes = '' # Stokes params to image (I,IV,IQU,IQUV). Default "" => include all
listit = True # Print stats and bounding box to logger?
verbose = True # Print additional messages to logger?
mask = '' # Mask to use. See help par.mask. Default is none.
logfile = '' # Name of file to write fit results.
async = False # If true the taskname must be started using imstat(...)```

Area selection using region and mask is detailed in §6.1.5 and (§5.3.6) respectively.

Plane selection is controlled by chans and stokes. See §6.1.2 for details on plane selection.

The parameter axes will select the dimensions that the statistics is calculated over. Typical data cubes have axes like: RA axis 0, DEC axis 1, Velocity axis 2. So, e.g. axes=[0,1] would be the most common setting to calculate statistics per spectral channel.

A typical output of imstat on a cube with axes=[0,1] looks like:

---

```
No region specified. Using full positional plane.
Using all spectral channels.
Using polarizations ALL
Determining stats for image IRC10216_HC3N.cube_r0.5.image
Set region from supplied region record
Regions ---
-- bottom-left corner (pixel) [blc]: [0, 0, 0, 0]
-- top-right corner (pixel) [trc]: [299, 299, 0, 63]
-- bottom-left corner (world) [blcf]: 09:48:01.492, +13.15.40.658, I, 3.63994e+10Hz
-- top-right corner (world) [trcf]: 09:47:53.299, +13.17.40.258, I, 3.63915e+10Hz
No region specified. Using full positional plane.
Using all spectral channels.
Using polarizations ALL
Selected bounding box :
[0, 0, 0, 0] to [299, 299, 0, 63] (09:48:01.492, +13.15.40.658, I, 3.63994e+10Hz to 09:47:53.299, +13.17.40.258, I, 3.63915e+10Hz)
# Frequency Frequency(Plane) Npts Sum Mean Rms Std dev
3.6393552e+10 0 9.000000e+04 0.000000e+00 0.000000e+00 0.000000e+00 0.000000e+00
3.6399230e+10 1 9.000000e+04 0.000000e+00 0.000000e+00 0.000000e+00 0.000000e+00
3.6399152e+10 2 9.000000e+04 0.000000e+00 0.000000e+00 0.000000e+00 0.000000e+00
3.6399898e+10 3 9.000000e+04 0.000000e+00 0.000000e+00 0.000000e+00 0.000000e+00
3.6398855e+10 4 9.000000e+04 0.000000e+00 0.000000e+00 0.000000e+00 0.000000e+00
3.6398730e+10 5 9.000000e+04 6.069948e-01 6.744386e-06 1.534640e-03 1.534634e-03
```
where the header information provides the specifications of the data that were selected followed by the table with the frequency values of the lanes, the plane numbers, Npts the number of pixels per plane, and the Sum, Median, RMS, Standard deviations, Minimum, and Maximum of the pixel values for each plane. Similar output is provided when the data is averaged over different axes. The logger output can also be written into a log file for further processing elsewhere (logfile parameter).

6.9.1 Using the task return value

The contents of the return value of `imstat` are in a Python dictionary of key-value sets. For example,

```python
xstat = imstat()
```

will assign this to the Python variable `xstat`. The keys for `xstat` are then:

```python
KEYS
blc
blcf
trc
trcf
flux
npts
max
min
maxpos
maxposf
minpos
minposf
sum
sumsq
mean
sigma
rms
median
medabsdevmed
quartile
```

- `blc` - absolute PIXEL coordinate of the bottom left corner of the bounding box surrounding the selected region
- `blcf` - Same as blc, but uses WORLD coordinates instead of pixels
- `trc` - the absolute PIXEL coordinate of the top right corner of the bounding box surrounding the selected region
- `trcf` - Same as trc, but uses WORLD coordinates instead of pixels
- `flux` - the integrated flux density if the beam is defined and the if brightness units are $Jy/beam$
- `npts` - the number of unmasked points used
- `max` - the maximum pixel value
- `min` - minimum pixel value
- `maxpos` - absolute PIXEL coordinate of maximum pixel value
- `maxposf` - Same as maxpos, but uses WORLD coordinates instead of pixels
- `minpos` - absolute pixel coordinate of minimum pixel value
- `minposf` - Same as minpos, but uses WORLD coordinates instead of pixels
- `sum` - the sum of the pixel values: $\sum I_i$
- `sumsq` - the sum of the squares of the pixel values: $\sum I_i^2$
- `mean` - the mean of pixel values:
  $$\bar{I} = \frac{\sum I_i}{n}$$
- `sigma` - the standard deviation about the mean:
  $$\sigma^2 = \frac{\sum I_i - \bar{I})^2}{n-1}$$
- `rms` - the root mean square:
  $$\sqrt{\frac{\sum I_i^2}{n}}$$
- `median` - the median pixel value (if robust=T)
- `medabsdevmed` - the median of the absolute deviations from the median (if robust=T)
- `quartile` - the inter-quartile range (if robust=T). Find the points which are 25% largest and 75% largest (the median is
50% largest), find their difference and divide that difference by 2.

For example, an `imstat` call might be

```python
default('imstat')
imagename = 'ngc5921.demo.cleanimg.image'  # The NGC5921 image cube
box = '108,108,148,148'  # 20 pixels around the center
chans = '21'  # channel 21

xstat = imstat()
```

In the terminal window, `imstat` reports:

Statistics on `ngc5921.usecase.clean.image`

Region ---
-- bottom-left corner (pixel) [blc]: [108, 108, 0, 21]
-- top-right corner (pixel) [trc]: [148, 148, 0, 21]
-- bottom-left corner (world) [blcf]: 15:22:20.076, +04.58.59.981, I, 1.41332e+09Hz
-- top-right corner (world) [trcf]: 15:21:39.919, +05.08.59.981, I, 1.41332e+09Hz

Values --
-- flux [flux]:  0.111799236126
-- number of points [npts]: 1681.0
-- maximum value [max]: 0.029451508075
-- minimum value [min]: -0.00612453464419
-- position of max value (pixel) [maxpos]: [124, 131, 0, 21]
-- position of min value (pixel) [minpos]: [142, 110, 0, 21]
-- position of max value (world) [maxposf]: 15:22:04.016, +05.04.44.999, I, 1.41332e+09Hz
-- position of min value (world) [minposf]: 15:21:45.947, +04.59.29.990, I, 1.41332e+09Hz
-- Sum of pixel values [sum]: 1.32267159822
-- Sum of squared pixel values [sumsq]: 0.0284534543692

Statistics ---
-- Mean of the pixel values [mean]: 0.000786836167885
-- Standard deviation of the Mean [sigma]: 0.00403944306904
-- Root mean square [rms]: 0.00411418313161
-- Median of the pixel values [median]: 0.000137259965413
-- Median of the deviations [medabsdevmed]: 0.00152346317191
-- Quartile [quartile]: 0.00305395200849

The return value in `xstat` is

```python
CASA <152>: xstat
Out[152]:
{'blc': array([108, 108, 0, 21]),
 'blcf': '15:22:20.076, +04.58.59.981, I, 1.41332e+09Hz',
```
'flux': array([ 0.11179924]),
'max': array([ 0.02945151]),
'maxpos': array([124, 131, 0, 21]),
'maxposf': '15:22:04.016, +05.04.44.999, I, 1.41332e+09Hz',
'mean': array([ 0.00078684]),
'medabsdevmed': array([ 0.00152346]),
'median': array([ 0.00013726]),
'min': array([-0.00612453]),
'minpos': array([142, 110, 0, 21]),
'minposf': '15:21:45.947, +04.59.29.990, I, 1.41332e+09Hz',
'npts': array([ 1681.]),
'quartile': array([ 0.00305395]),
'rms': array([ 0.00411418]),
'sigma': array([ 0.00403944]),
'sum': array([ 1.3226716]),
'sumsq': array([ 0.02845345]),
'trc': array([148, 148, 0, 21]),
'trcf': '15:21:39.919, +05.08.59.981, I, 1.41332e+09Hz'}

**Alert:** The return dictionary currently includes NumPy array values, which have to be accessed by an array index to get the array value. To access these dictionary elements, use the standard Python dictionary syntax, e.g.

```
xstat[<key string>][<array index>]
```

For example, to extract the standard deviation as a number

```
mystddev = xstat['sigma'][0]
print 'Sigma = ' + str(xstat['sigma'][0])
```

### 6.9.2 Examples for imstat

The following are some examples using the B1608+656 Tutorial


as an example.

To extract statistics for the final image:

```
xstat = imstat('b1608.demo.clean2.image')
# Printing out some of these
print 'Max   = ' + str(xstat['max'][0])
print 'Sigma = ' + str(xstat['sigma'][0])
# results:
# Max    = 0.016796965152
# Sigma  = 0.0003631979385
```
In a box around the brightest component:

```python
xstat_A = imstat('b1608.demo.clean2.image', box='124,125,132,133')
# Printing out some of these
print 'Comp A Max Flux = '+str(xstat_A['max'][0])
print 'Comp A Max X,Y = ('+str(xstat_A['maxpos'][0])+','+str(xstat_A['maxpos'][1])+')'
# results:
# Comp A Max Flux = 0.016796965152
# Comp A Max X,Y = (128,129)
```

### 6.10 Extracting data from an image (imval)

The `imval` task will extract the values of the data and mask from a specified region of an image and place in the task return value as a Python dictionary.

The inputs are:

```python
# imval :: Get the data value(s) and/or mask value in an image.
imagename = '' # Name of the input image
region = '' # Image Region. Use viewer
box = '' # Select one or more box regions
chans = '' # Select the channel(spectral) range
stokes = '' # Stokes params to image (I,IV,IQU,IQUV)
async = False
```

Area selection using `box` and `region` is detailed in §6.1.1 and §6.1.5 respectively. By default, `box=''` will extract the image information at the reference pixel on the direction axes.

Plane selection is controlled by `chans` and `stokes`. See §6.1.2 for details on plane selection. By default, `chans=''` and `stokes=''` will extract the image information in all channels and Stokes planes.

For instance,

```python
xval = imval('myimage', box='144,144', stokes='I' )
```

will extract the Stokes I value or spectrum at pixel 144,144, while

```python
xval = imval('myimage', box='134,134.154,154', stokes='I' )
```

will extract a 21 by 21 pixel region.

Extractions are returned in NumPy arrays in the return value dictionary, plus some extra elements describing the axes and selection:
CHAPTER 6. IMAGE ANALYSIS

CASA <2>: xval = imval('ngc5921.demo.moments.integrated')

CASA <3>: xval

Out[3]:
{'axes': [[0, 'Right Ascension'],
          [1, 'Declination'],
          [3, 'Frequency'],
          [2, 'Stokes']],
   'blc': [128, 128, 0, 0],
   'data': array([ 0.89667124]),
   'mask': array([ True], dtype=bool),
   'trc': [128, 128, 0, 0],
   'unit': 'Jy/beam.km/s'}

extracts the reference pixel value in this 1-plane image. Note that the 'data' and 'mask' elements are NumPy arrays, not Python lists.

To extract a spectrum from a cube:

CASA <8>: xval = imval('ngc5921.demo.clean.image',box='125,125')

CASA <9>: xval

Out[9]:
{'axes': [[0, 'Right Ascension'],
          [1, 'Declination'],
          [3, 'Frequency'],
          [2, 'Stokes']],
   'blc': [125, 125, 0, 0],
   'data': array([ 8.45717848e-04, 1.93370355e-03, 1.53750915e-03,
                  2.88399984e-03, 2.3863447e-03, 2.89159478e-04,
                  3.16268904e-03, 9.3398636e-03, 1.88773088e-02,
                  3.01138610e-02, 3.14478502e-02, 4.03211266e-02,
                  3.82498614e-02, 3.06552909e-02, 2.8073401e-02,
                  1.72479432e-02, 1.2084273e-02, 6.13593217e-03,
                  9.04005766e-03, 1.71429547e-03, 5.22095338e-03,
                  2.49114982e-03, 5.30831999e-04, 4.80734324e-03,
                  1.9265869e-05, 1.29435991e-03, 3.75700940e-04,
                  2.34788167e-03, 2.76204497e-03, 1.78467855e-03,
                  9.74952069e-04, 2.24676146e-03, 1.82263291e-04,
                  1.98463408e-06, 2.02975096e-03, 9.6532148e-04,
                  1.68218743e-03, 2.92119570e-03, 1.29359076e-03,
                  -5.11484570e-04, 1.54162932e-03, 4.68662125e-04,
                  -8.50282842e-04, -7.91683051e-05, 2.96954203e-04,
                  -1.30131458e-03]),
   'mask': array([ True, True, True, True, True, True, True, True,
                  True, True, True, True, True, True, True, True,
                  True, True, True, True, True, True, True, True,
                  True, True, True, True, True, True, True, True,
                  True, True, True, True, True, True, True, True],
                dtype=bool),
   'trc': [125, 125, 0, 45],
   'unit': 'Jy/beam'}
To extract a region from the plane of a cube:

CASA <13>: xval = imval('ngc5921.demo.clean.image',box='126,128,130,129',chans='23')

CASA <14>: xval

Out[14]:

{'axes': [[0, 'Right Ascension'],
          [1, 'Declination'],
          [3, 'Frequency'],
          [2, 'Stokes']],
 'blc': [126, 128, 0, 23],
 'data': array([[ 0.00938627, 0.01487772],
                [ 0.00955847, 0.01688832],
                [ 0.00696965, 0.01501907],
                [ 0.00460964, 0.01220793],
                [ 0.00358087, 0.00990202]]),
 'mask': array([[ True, True],
                [ True, True],
                [ True, True],
                [ True, True],
                [ True, True]], dtype=bool),
 'trc': [130, 129, 0, 23],
 'unit': 'Jy/beam'}

CASA <15>: print xval['data'][0][1]

0.0148777160794

In this example, a rectangular box was extracted, and you can see the order in the array and how to address specific elements.

### 6.11 Reordering the Axes of an Image Cube (imtrans)

Sometimes data cubes can be in axis orders that are not adequate for processing. The CASA task `imtrans` can change the ordering of the axis:

```python
# imtrans :: Reorder image axes
# Name of the input image
imagename = ''
# Name of output CASA image.
outfile = ''
# New zero-based axes order.
order = ''
# Return an image tool referencing the transposed image
wantreturn = True
# If true the taskname must be started using imtrans(...)
async = False
```

The `order` parameter is the most important input here. It is a string of numbers that shows how axes 0, 1, 2, 3, ... are mapped onto the new cube (note that the first axis has the label 0, as typical in python). E.g. `order='1032'` will reorder the input axis 0 to be axis 1 in the output, input axis 1 to be...
output axis 0, input axis 2 to output axis 3 (the last axis) and input axis 3 to output axis 2. Alternatively, axes can be specified by their names. E.g., to reorder an image with right ascension, declination, and frequency and reverse the first two, \texttt{order=['declination', 'right ascension', 'frequency']} will work. The axes names can be found typing (\texttt{ia.coordsys().names()}). Minimum match is supported, so that \texttt{order=['d', 'f', 'r']} will produce the same results.

Axes can simultaneously be transposed and reversed. To reverse an axis, precede it by a "-". For example, \texttt{order='10-32'} will reverse the direction of the first and third axis of the input image (the zeroth and second axes in the output image).

Example:

Swap the stokes and spectral axes in an RA-Dec-Stokes-Frequency image

\begin{verbatim}
imagename = "myim.im"
outfile = "outim.im"
order = "0132"
imtrans()

or

outfile = "myim_2.im"
order = 132
imtrans()

or

outfile = "myim_3.im"
order = ["r", "d", "f", "s"]
imtrans()

or

outfile = "myim_4.im"
order = ["rig", "declin", "frequ", "stok"]
imtrans()
\end{verbatim}

If the outfile parameter is empty, only a temporary image is created; no output image is written to disk. The temporary image can be captured in the returned value (assuming \texttt{wantreturn} is true).

### 6.12 Collapsing an Image Along an Axis (\texttt{imcollapse})

\texttt{imcollapse} allows to apply an aggregation function along one or more axes of an image. Functions supported are 'max', 'mean', 'median', 'min', 'rms', 'stdev', 'sum', 'variance' (minimum match supported). The relevant axes will then collapse to a single value or plane (i.e. they will result in a degenerate axis). The functions are specified in the \texttt{function} parameter of the \texttt{imcollapse} inputs:
# imcollapse :: Collapse image along one axis, aggregating pixel values along that axis.

```python
# Name of the input image
imagename = ''

# Function used to compute aggregation of pixel values.
function = ''

# Zero-based axis number(s) or minimal match strings to collapse.
axes = [0]

# Name of output CASA image.
outfile = ''

# Optional direction plane box ("blcx, blcy, trcx, trcy").
box = ''

# Name of optional region file to use.
region = ''

# Optional zero-based contiguous frequency channel specification.
chans = ''

# Optional contiguous stokes planes specification.
stokes = ''

# Optional mask to use.
mask = ''

# Should an image analysis tool referencing the collapsed image be returned?
wantreturn = True

# If true the taskname must be started
async = False
```

wantreturn=True returns an image analysis tool containing the newly created collapsed image.

Example:

myimage.im is a 512x512x128x4 (ra,dec,freq,stokes; i.e. in the 0-based system, frequency is labeled as axis 2) image and we want to collapse a subimage of it along its spectral axis avoiding the 8 edge channels at each end of the band, computing the mean value of the pixels (resulting image is 256x256x1x4 in size):

```bash
imcollapse(imagename="myimage.im", outfile="collapse_spec_mean.im",
function="mean", axis=2, box="127,127,383,383", chans="8~119")
```

Note that imcollapse will not smooth to a common beam for all planes if they differ. If this is desired, run imsmooth before imcollapse.

### 6.13 Regridding an Image (imregrid)

It is occasionally necessary to regrid an image onto a new coordinate system. The imregrid task will regrid one image onto the coordinate system of another, creating an output image. In this task, the user need only specify the names of the input, template, and output images.

Inside the Toolkit:

More complex coordinate system and image regridding operation can be carried out in the toolkit. The coordsys (cs) tool and the ia.regrid method are the relevant components.
CHAPTER 6. IMAGE ANALYSIS

If the user needs to do more complex operations, such as regridding an image onto an arbitrary (but known) coordinate system, changing from Equatorial to Galactic coordinates, or precessing Equinoxes, the CASA toolkit can be used (see sidebox). Some of these facilities will eventually be provided in task form.

The default inputs are:

```python
# imregrid :: regrid an image onto a template image
imagename = ''   # Name of the source image
template = 'get'  # A dictionary, refcode, or name of an image that
                 # provides the output shape and coordinate system
output = ''      # Name for the regridded image
asvelocity = True # Regrid spectral axis in velocity space rather than
                  # frequency space?
axes = [-1]      # The pixel axes to regrid. -1 => all.
async = False    # If true the task name must be started using

The output image will have the data in imagename regridded onto the coordinate system provided by the template parameter. template is used universally for a range of ways to define the grid of the output image:

- **a template image**: specify an image name here and the input will be regridded to the same 3-dimensional coordinate system as the one in template. Values are filled in as blanks if they do not exist in the input. Note that the input and template images must have the same coordinate structure to begin with (like 3 or 4 axes, with the same ordering)

- **a coordinate system (reference code)**: to convert from one coordinate frame to another one, e.g. from B1950 to J2000, the template parameter can be used to specify the output coordinate system. These following recognized keywords are supported: 'J2000', 'B1950', 'B1950\_VLA', 'GALACTIC', 'HADEC', 'AZEL', 'AZELSW', 'AZELNE', 'ECLIPTIC', 'MECLIPTIC', 'TECLIPTIC', 'SUPERGAL'

- 'get': This option returns a python dictionary in the {'csys': csys_record, 'shap': shape} format

- **a python dictionary**: In turn, such a dictionary can be used as a template to define the final grid

6.14 Regridding an Image (imreframe)

imreframe can be used to change the velocity system of an image. It is not applying a regridding as a change from radio to optical conventions would require, but it will change the labels of the velocity axes.
CHAPTER 6. IMAGE ANALYSIS

# imreframe :: Change the frame in which the image reports its spectral values
imagename = '' # Name of the input image
output = '' # Name of the output image; '' => modify input image
outframe = 'lsrk' # Spectral frame in which the frequency or velocity values will be reported by default
restfreq = '' # restfrequency to use for velocity values (e.g "1.420GHz" for the HI line)
async = False # If true the taskname must be started using outframe

outframe defines the velocity frame (LSRK, BARY, etc, see §C.2) of the output image and a rest frequency should be specified to relabel the spectral axis in new velocity units.

6.15 Image Convolution(imsmooth)

A data cube can be smoothed across spatial dimensions with imsmooth. The inputs are:

# imsmooth :: Smooth an image or portion of an image
imagename = '' # Name of the input image
kernel = 'gauss' # Type of kernel to use: gaussian or boxcar.
major = '2.5arcsec' # Major axis for the kernels, default direction is along y-axis.
minor = '2.0arcsec' # Minor axis in gaussian and boxcar kernels
pa = '0deg' # Position angle for gaussian kernel
targetres = False # If gaussian kernel, specified parameters are to be resolution of output image (True) or parameters of gaussian to convolve with input image (False).

region = '' # Image Region or name. Use viewer
box = '' # Select one or more box regions
chans = '' # Select the spectral channel range
stokes = '' # Stokes parameters to image
# (I,IV,IQU,IQUV)
mask = '' # Mask used for selecting the area of the image
outfile = '' # Output, smoothed, image file name
async = False # If true the taskname must be started

where the cube/image imasename will be convolved with a kernel defined in the kernel keyword. Available kernels are 'gauss' and 'boxcar'. Both of these kernels need the major and minor axes sizes as input, the Gaussian kernel smoothing also requires a position angle. By default, the kernel size defines the kernel itself, i.e. the data will be smoothed with this kernel. If the targetres
parameter for Gaussian kernels is set to 'True', major and minor axes will be those from the output resolution, and the kernel will be adjusted for each plane to arrive at the final resolution.

Examples:

1) smoothing with a gaussian kernel 20" by 10"

```python
imsmooth( imagename='my.image', kernel='gauss', major='10arcsec', minor='10arcsec')
```

2) Smoothing using pixel coordinates and a boxcar kernel.

```python
imsmooth( imagename='new.image', major='20pix', minor='10pix', kernel='boxcar')
```

### 6.16 Spectral Line fitting with specfit

`specfit` is a powerful task to perform spectral line fits in data cubes. Three types of fitting functions are currently supported, polynomials, Gaussians, and Lorentians. `specfit` can fit these functions in two ways: over data that were averaged across a region (`multifit=False`) or on a pixel by pixel basis (`multifit=True`).

```python
# specfit :: Fit 1-dimensional gaussians and/or polynomial models to an image or image region
imagename = '' # Name of the input image
box = '' # Rectangular box in direction coordinate blc, trc. Default: entire image ('').
region = '' # Region of interest. See help par.region # for possible specifications. Default: Do not use a region.
chans = '' # Channels to use. Channels must be contiguous. Default: all channels ('').
stokes = '' # Stokes planes to use. Planes must be contiguous. Default: all stokes ('').
axis = -1 # The profile axis. Default: use the spectral axis if one exists, axis 0 otherwise (<0).
mask = '' # Mask to use. See help par.mask. Default is none.
poly = -1 # Order of polynomial element. Default: do not fit a polynomial (<0).
estimates = '' # Name of file containing initial estimates. Default: No initial estimates ('').
ngauss = 1 # Number of Gaussian elements. Default: 1.
pampest = '' # Initial estimate of PCF profile (gaussian or lorentzian) amplitudes.
pcenterest = '' # Initial estimate PCF profile centers, in pixels.
pfwhmest = '' # Initial estimate PCF profile FWHMs, in pixels.
```
CHAPTER 6. IMAGE ANALYSIS

pfix = '' # PCF profile parameters to fix during fit.
pfunc = '' # PCF singlet functions to fit. "gaussian"
# or "lorentzian" (minimal match
# supported). Unspecified means all
# gaussians.

minpts = 0 # Minimum number of unmasked points
# necessary to attempt fit.
multifit = True # If true, fit a profile along the desired
# axis at each pixel in the specified
# region. If false, average the non-fit
# axis pixels and do a single fit to that
# average profile. Default False.

amp = '' # Name of amplitude solution image. Default:
# do not write the image ("").
amperr = '' # Name of amplitude solution error image.
center = '' # Name of center solution image. Default: do
# not write the image ("").
centererr = '' # Name of center solution error image.

fwhm = '' # Name of fwhm solution image. Default: do
# not write the image ("").
fwhmerr = '' # Name of fwhm solution error image.

integral = '' # Prefix of ame of integral solution image.
# Name of image will have gaussian
# component number appended. Default: do
# not write the image ("").
integralerr = '' # Prefix of name of integral error solution
# image. Name of image will have gaussian
# component number appended. Default: do
# not write the image ("").

model = '' # Name of model image. Default: do not write
# the model image ("").
residual = '' # Name of residual image. Default: do not
# write the residual image ("").
wantreturn = True # Should a record summarizing the results be
# returned?
logresults = True # Output results to logger?
gmncomps = 0 # Number of components in each gaussian
# multiplet to fit
gmampcon = '' # The amplitude ratio constraints for non-
# reference components to reference
# component in gaussian multiplets.
gmcentercon = '' # The center offset constraints (in pixels)
# for non-reference components to reference
# component in gaussian multiplets.
gmfwhmcon = '' # The FWHM ratio constraints for non-
### 6.16.1 Polynomial Fits

Polynomials can be fit by specifying the polynomial order in `poly`. Negative orders will not fit any polynomials.

### 6.16.2 Lorentzian and Gaussian Fits

Gaussian and Lorentzian fits are very similar, they both require amplitude, center, and FWHM to be fully specified. All of the following discussion is thus valid for both functions. The parameter `pfunc` controls whether Gaussian or Lorentzian functions are to be used. Default is all Gaussians. `pfunc=['L', 'G', 'G', 'L']` would use Lorentzian, Gaussian, Gaussian, and Lorentzian components in the order they appear in the estimates file (see below).

#### 6.16.2.1 One or more single Gaussian/Lorentzian

For Gaussian and Lorentzian fits, the task will allow multiple components and `specfit` will try to find the best solution. The parameter space, however, is usually not uniform and to avoid local minima in the goodness-of-fit space, one can provide initial start values for the fits. This can
be done either through the parameters pampest, pcenterest, and pfwhmest for the amplitudes, center, and FWHM estimates in image coordinates. pfix can take parameters that specify fixed fit values. Any combination of the characters 'p' (peak), 'c' (center), and 'f' (fwhm) are permitted, e.g. "fc" will hold the fwhm and the center constant during the fit. Fixed parameters will have no errors associated with them in the solution. Alternatively, a file with initial values can be supplied via the estimates parameter (one Gaussian/Lorentzian parameter set per line). The file has the following format:

[peak intensity], [center], [fwhm], [optional fixed parameter string]

The first three values are required and must be numerical values. The peak intensity must be expressed in map units, while the center and fwhm must be specified in pixels. The fourth value is optional and if present, represents the parameter(s) that should be held constant during the fit (see above).

An example estimates file is:

```
# estimates file indicating that two gaussians should be fit
# first gaussian estimate, peak=40, center at pixel number 10.5,
# fwhm = 5.8 pixels, all parameters allowed to vary during
# fit
40, 10.5, 5.8
# second gaussian, peak = 4, center at pixel number 90.2,
# fwhm = 7.2 pixels, hold fwhm constant
4, 90.2, 7.2, f
# end file
```

and the output of a typical execution, e.g.

```
specfit(imagename='IRC10216_HC3N.cube_r0.5.image', region='specfit.crtf', multifit=F, estimates='', ngauss=2)

('specfit.crtf' is a CASA regions file, see Section[D])
```

will be

```
Fit :
  RA :  09:47:57.49
  Dec :  13.16.46.46
  Stokes : I
  Pixel : [146.002, 164.499, 0.000, *]
  Attempted : YES
  Converged : YES
  Iterations : 28
Results for component 0:
  Type : GAUSSIAN
  Peak : 5.76 +/- 0.45 mJy/beam
```
CHAPTER 6. IMAGE ANALYSIS

Center : -15.96 +/- 0.32 km/s
        40.78 +/- 0.31 pixel
FWHM  : 7.70 +/- 0.77 km/s
        7.48 +/- 0.74 pixel
Integral : 47.2 +/- 6.0 mJy/beam.km/s

Results for component 1:
Type  : GAUSSIAN
Peak  : 4.37 +/- 0.33 mJy/beam
Center : -33.51 +/- 0.58 km/s
        23.73 +/- 0.57 pixel
FWHM  : 15.1 +/- 1.5 km/s
        14.7 +/- 1.5 pixel
Integral : 70.2 +/- 8.8 mJy/beam.km/s

If wantreturn=True (the default value), the task returns a python dictionary (here captured in a variable with the inventive name of 'fitresults'):

fitresults=specfit(imagename='IRC10216_HC3N.cube_r0.5.image', region='specfit.rgn', multifit=F, estimates='', ngauss=2)

The values can then be used by other python code for further processing.

6.16.2.2 Gaussian Multiplets

It is possible to fit a number of Gaussians together, as multiplets with restrictions. All restrictions are relative to a reference Gaussian (the zero’th component of each multiplet). gncomps specifies the number of Gaussians for each multiplets, and, in fact, a number of these multiplets can be fit simultaneously. gncomps=[2,4,3], e.g. fits a 2-component Gaussian, a 4-component Gaussian, and a 3-component Gaussian all at once. The initial parameter estimates can be specified with the gmampest, gcenterest, and gmfwhmest parameters and the estimates are simply listed in the sequence of gncomps. E.g. if gncomps=[2,4,3] is specified with multiplet G0 consisting of 2 Gaussians a, b, multiplet G1 of 4 Gaussians c, d, e, f, and multiplet G2 of three Gaussians g, h, i, the parameter list in gm*est would be like gm*est=[a,b,c,d,e,f,g,h,i].

Restrictions can be specified via the gmampcon parameter for the amplitude ratio (non-reference to reference), gcentercon for the offset in pixels (to a reference), and gmfwhmcon for the FWHM ratio (non-reference to reference). A value of 0 will not constrain anything. The reference is always the zero’th component in each multiplet, in our example, Gaussians a, c, and g. They cannot be constrained. So gmcomps=[2, 4, 3], gmampcon= [ 0 , 0.2, 0 , 0.1, 4.5, 0 ], gcentercon=[24.2, 45.6, 92.7, 0 , -22.8, -33.5], and gmfwhmcon="" would constrain Gaussians b relative to a with a 24.2 pixel offset, Gaussian d to c with a amplitude ratio of 0.2 and a 45.6 pixel offset, Gaussian e to c with a offset of 92.7 pixels, etc. Restrictions will overrule any estimates.

The parameters goodamprange, goodcenterrange, and goodfwhmrange can be used to limit the range of amplitude, center, and fwhm solutions for all Gaussians.
6.16.3 Pixel-by-pixel fits

As mentioned above, specfit can also fit spectral cubes on a pixel by pixel basis. In this case, one can choose to write none, any or all of the solution and error images for Gaussian/Lorentzian fits via the parameters \texttt{amp}, \texttt{amperr}, \texttt{center}, \texttt{centererr}, \texttt{fwhm}, and \texttt{fwhmerr}. The files written contain all the components along a “component number” axis. They can be inspected by using the “hidden axes” slider in the \texttt{viewer} (\textcircled{7.4.1}). Writing analogous images for polynomial coefficients is not yet supported although polynomial fits when \texttt{multifit=True} is supported. Best fit coefficients are written to the logger. Pixels for which fits were not attempted or did not converge will be masked as bad.

6.17 Image Mask Handling \texttt{makemask}

\texttt{makemask} facilitates the handling of image masks in CASA. There are two basic mask formats: 1) one or more Boolean masks stored internally in the image file, and 2) images with zero and non-zero image values. \texttt{makemask} looks like:

```
# makemask :: Makes and manipulates image masks
mode = 'list' # Mask method # (copy,expand,merge,delete,setdefaultmask)
            # (copy,expand,merge,delete,setdefaultmask)
inpimage = '' # Name of input image.
async = False # If true the taskname must be started using
              # makemask(...)
```

To distinguish between Boolean internal masks and zero/non-zero images, \texttt{makemask} uses the syntax \texttt{galaxy.image:mask0} for Boolean masks within an image, in this example the Boolean mask \texttt{mask0} within the image \texttt{galaxy.image}. Without the colon separator, the image itself is assumed to be treated like a zero/non-zero mask.

- \texttt{mode='list'} lists all the internal Boolean masks that are present in an image. The default masks can be set with mode \texttt{setdefaultmask} and they can be deleted with the mode \texttt{delete}. The default mask is used when an image is displayed in the \texttt{viewer} and is used in all analysis tasks.

- \texttt{mode='copy'} lets a user to copy a Boolean mask from one image to another image, or to write out the Boolean mask as a zero/non-zero image. The latter format is very useful when different masks are combined or manipulated. All the image analysis tools, in particular \texttt{immath} are applicable for such zero/non-zero masks as they act like normal images. \texttt{makemask} will always attempt to regrid the input mask to the output image.

- \texttt{mode='expand'} furthermore expands a mask in the spectral domain. It regrids first then stretches the edge channels. E.g. a one plane continuum image would be stretched to all planes of a data cube.

- \texttt{mode='merge'} merges CASA region files (CRTF files) with a mask that is already present. E.g. one can use the \texttt{viewer} to create a region file, then use this mode in \texttt{makemask} to convert the regions into an image mask, either an internal Boolean mask or an image with zero/non-zero values.
6.18 Search for Spectral Line Rest Frequencies (slsearch)

The `slsearch` task allows the spectral line enthusiast to find their favorite spectral lines in subset of the Splatalogue spectral line catalog (http://www.splatalogue.net) which is distributed with CASA. In addition, one can export custom catalogs from Splatalogue and import them to CASA using the task `splattotable` (Sect. 6.19) or tool method `sl.splattotable()`. One can even import catalogs with lines not in Splatalogue using the same file format.

The inputs to `slsearch` are as follows:

```python
# slsearch :: Search a spectral line table.
tablename = '' # Input spectral line table name to search. If not specified, use the default table in the system.
outfile = '' # Results table name. Blank means do not write the table to disk.
freqrange = [84, 90] # Frequency range in GHz.
species = [''] # Species to search for.
reconly = False # List only NRAO recommended frequencies.
chemnames = [''] # Chemical names to search for.
qns = [''] # Resolved quantum numbers to search for.
rrlinclude = True # Include RRLs in the result set?
rrlonly = False # Include only RRLs in the result set?
intensity = -1 # CDMS/JPL intensity range. -1 -> do not use an intensity range.
smu2 = -1 # S*mu*mu range in Debye**2. -1 -> do not use an S*mu*mu range.
loga = -1 # log(A) (Einstein coefficient) range. -1 -> do not use a loga range.
eu = -1 # Upper energy state range in Kelvin. -1 -> do not use an eu range.
el = -1 # Lower energy state range in Kelvin. -1 -> do not use an el range.
verbose = True # List result set to logger (and optionally logfile)?
logfile = '' # List result set to this logfile (only used if verbose=True).
append = True # If true, append to logfile if it already exists, if false overwrite logfile it it exists. Only used if verbose=True and logfile not blank.
wantreturn = True # If true, return the spectralline tool associated with the result set.
async = False # If true the taskname must be started
```
The table is provided in the `tablename` parameter but if it is blank (the default), the catalog which is included with CASA will be used. Searches can be made in a parameter space with large dimensionality:

- **freqrange** Frequency range in GHz.
- **species** Species to search for.
- **reconly** List only NRAO recommended frequencies.
- **chemnames** Chemical names to search for.
- **qns** Resolved quantum numbers to search for.
- **intensity** CDMS/JPL intensity range.
- **smu2** $S\mu^2$ range in Debye$^2$.
- **loga** log(A) (Einstein coefficient) range.
- **el** Lower energy state range in Kelvin.
- **eu** Upper energy state range in Kelvin.
- **rrlinclude** Include RRLs in the result set?
- **rrlonly** Include only RRLs in the result set?

Notation is as found in the Splatalogue catalog.

Example:
Search for all lines of the species HOCN and HOCO+ in the 200-300GHz range:

```python
slsearch(outfile="myresults.tbl", freqrange=[200,300], species=['HOCN', 'HOCO+'])
```

The task can also return a python dictionary if assigned a variable like:

```python
myLines = slsearch(outfile="myresults.tbl", freqrange=[200,300], species=['HOCN', 'HOCO+'])
```

### 6.19 Convert Exported Splatalogue Catalogs to CASA Tables (**splattotable**)

In some cases the internal spectral line catalog may not contain the lines in which one is interested. In that case, one can export a catalog from Splatalogue [http://www.splatalogue.net](http://www.splatalogue.net) or even create their own "by hand" (be careful to get the format exactly right though!). CASA’s task **splattotable** can then be used to create a CASA table that contains these lines and can be searched:
CHAPTER 6. IMAGE ANALYSIS

6.20 Image Import/Export to FITS

These tasks will allow you to write your CASA image to a FITS file that other packages can read, and to import existing FITS files into CASA as an image.

6.20.1 FITS Image Export (exportfits)

To export your images to fits format use the exportfits task. The inputs are:

   # exportfits :: Convert a CASA image to a FITS file
   imagename = '' # Name of input CASA image
   fitsimage = '' # Name of output image FITS file
   velocity = False # Use velocity (rather than frequency) as spectral axis
   optical = False # Use the optical (rather than radio) velocity convention
   bitpix = -32 # Bits per pixel
   minpix = 0 # Minimum pixel value
   maxpix = 0 # Maximum pixel value
   overwrite = False # Overwrite pre-existing imagename
   dropstokes = False # Drop the Stokes axis?
   stokeslast = True # Put Stokes axis last in header?
   async = False # If true the taskname must be started using exportfits(...)

The dropstokes or stokeslast parameter may be needed to make the FITS image compatible with an external application.

For example,

   exportfits('ngc5921.demo.cleanimg.image','ngc5921.demo.cleanimg.image.fits')
6.20.2 FITS Image Import (importfits)

You can also use the importfits task to import a FITS image into CASA image table format. Note, the CASA viewer can read fits images so you don’t need to do this if you just want to look at the image. The inputs for importfits are:

```
# importfits :: Convert an image FITS file into a CASA image:

fitsimage = ''  # Name of input image FITS file
imagename = ''  # Name of output CASA image
whichrep = 0    # Which coordinate representation (if multiple)
whichhdu = 0    # Which image (if multiple)
zeroblanks = True # If blanked fill with zeros (not NaNs)
overwrite = False # Overwrite pre-existing imagename
async = False   # if True run in the background, prompt is freed
```

For example, we can read the above image back in

```
importfits('ngc5921.demo.cleanimg.image.fits','ngc5921.demo.cleanimage')
```

6.21 Using the CASA Toolkit for Image Analysis

Although this cookbook is aimed at general users employing the tasks, we include here a more detailed description of doing image analysis in the CASA toolkit. This is because there are currently only a few tasks geared towards image analysis, as well as due to the breadth of possible manipulations that the toolkit allows that more sophisticated users will appreciate.

To see a list of the ia methods available, use the CASA help command:

```
CASA <1>: help ia
--------> help(ia)
Help on image object:
```

```
class image(_builtin_.object)
 | image object
 | |
 | Methods defined here:
 |
 | __init__(...)  
 | x.__init__(...) initializes x; see x.__class__.__doc__ for signature  
 |
 | __str__(...)  
 | x.__str__() <==> str(x)
```

**Inside the Toolkit:**
The image analysis tool (ia) is the workhorse here. It appears in the User Reference Manual as the image tool. Other relevant tools for analysis and manipulation include measures (me), quanta (qa) and coordsys (cs).
CHAPTER 6. IMAGE ANALYSIS

```
<p>| adddegaxes(...) |
| Add degenerate axes of the specified type to the image' : |
| outfile |
| direction = false |
| spectral = false |
| stokes |
| linear = false |
| tabular = false |</p>
<table>
<thead>
<tr>
<th>overwrite = false</th>
</tr>
</thead>
<tbody>
<tr>
<td>addnoise(...)</td>
</tr>
</tbody>
</table>

...

<p>| unlock(...) |</p>
<table>
<thead>
<tr>
<th>Release any lock on the image'</th>
</tr>
</thead>
<tbody>
<tr>
<td>Data and other attributes defined here:</td>
</tr>
<tr>
<td><strong>new</strong> = &lt;built-in method <strong>new</strong> of type object at 0x55d0f20&gt;</td>
</tr>
<tr>
<td>T.<strong>new</strong>(S, ...) -&gt; a new object with type S, a subtype of T</td>
</tr>
</tbody>
</table>

or for a compact listing use <TAB> completion on ia., e.g.

CASA <5>: ia.
Display all 105 possibilities? (y or n)
```
| ia.__class__ | ia.deconvolvecomponentlist | ia.ispersistent | ia.reorder |
| ia.__delattr__ | ia.deconvolvefrombeam | ia.lock | ia.replacemaskedpixels |
| ia.__doc__ | ia.done | ia.makearray | ia.restoringbeam |
| ia.__getattribute__ | ia.echo | ia.makecomplex | ia.rotate |
| ia.__hash__ | ia.findsources | ia.maketestimage | ia.sepconvolve |
| ia.__init__ | ia.fft | ia.maskhandler | ia.set |
| ia.__new__ | ia.fitallprofiles | ia.maxfit | ia.setboxregion |
| ia.__reduce__ | ia.fitcomponents | ia.miscinfo | ia.setbrightnessunit |
| ia.__reduce_ex__ | ia.fitpolynomial | ia.modify | ia.setcoordsys |
| ia.__repr__ | ia.fitprofile | ia.moments | ia.sethistory |
| ia.__str__ | ia.fromarray | ia.name | ia.setmiscinfo |
| ia.adddegaxes | ia.fromascii | ia.newimage | ia.setrestoringbeam |
| ia.addnoise | ia.fromfits | ia.newimagefromarray | ia.shape |
| ia.boundingbox | ia.fromimage | ia.newimagefromfile | ia.statistics |
| ia.brightnessunit | ia.fromrecord | ia.newimagefromfits | ia.subimage |
| ia.calc | ia.getchunk | ia.newimagefromshapetime | ia.summary |
| ia.calcmask | ia.getregion | ia.open | ia.toASCII |
| ia.close | ia.getslice | ia.outputvariant | ia.topixel |
```
A common use of the ia tool is to do region statistics on an image. The imhead task has mode='stats' to do this quickly over the entire image cube. The tool can do this on specific planes or sub-regions. Here is an example on how to use the ia tool to get on-source and off-source statistics:

```python
# The variable clnimage points to the clean image name
ia.open(clnimage)
on_statistics=ia.statistics()
thistest_immax=on_statistics['max'][0]
oldtest_immax = 1.07732224464
print ' Clean image ON-SRC max should be ',oldtest_immax
print ' Found : Max in image = ',thistest_immax
diff_immax = abs((oldtest_immax-thistest_immax)/oldtest_immax)
print ' Difference (fractional) = ',diff_immax

print ''
# Now do stats in the lower right corner of the image
box = ia.setboxregion([0.75,0.00],[1.00,0.25],frac=true)
off_statistics=ia.statistics(region=box)
thistest_imrms=off_statistics['rms'][0]
oldtest_imrms = 0.0010449
print ' Clean image OFF-SRC rms should be ',oldtest_imrms
print ' Found : rms in image = ',thistest_imrms
diff_imrms = abs((oldtest_imrms-thistest_imrms)/oldtest_imrms)
print ' Difference (fractional) = ',diff_imrms

print ''
print ' Final Clean image Dynamic Range = ',thistest_immax/thistest_imrms
print ''
print ' =============== '

ia.close()
```

Note: If you don’t close the file with, e.g., ia.close() the file will stay in a 'locked' state. Other processes won’t be able to access the file until the file is properly closed.
6.22 Examples of CASA Image Analysis

The data reduction tutorials on casaguides.nrao.edu provide walkthroughs for high and low frequency, spectral line and polarization analysis techniques.
Chapter 7

Visualization With The CASA Viewer

This chapter describes using the CASA Viewer to display data. The Viewer can be started as a stand alone executable or by the viewer task inside a CASA shell. It can display both images and Measurement Sets. We are in the process of splitting the task-level access to the Viewer into two tasks: imview for images and msview for measurement sets. These tasks offer improved scriptability, giving command line access to many of the viewer features.

7.1 Starting the Viewer

![Figure 7.1: The Viewer Display Panel (left) and the Data Display Options (right) panel for a regular image or data cube.](image)

Within the casapy environment, the viewer task can be used to start the CASA Viewer, displaying an image or MS. The inputs are:
CHAPTER 7. VISUALIZATION WITH THE CASA VIEWER

# viewer :: View an image or visibility data set.

infile = ''  # (Optional) Name of file to visualize.
displaytype = 'raster'  # (Optional) Type of visual rendering
# (raster, contour, vector or marker).
# lel if an lel expression is given
# for infile (advanced).

Examples of starting the CASA Viewer:

   CASA <1>: viewer()

   CASA <2>: viewer('ngc5921.demo.ms')

   CASA <3>: viewer('ngc5921.demo.cleaning.image')

   CASA <4>: viewer('ngc5921.demo.cleaning.image', 'contour')

   CASA <5>: viewer('"ngc5921.demo.cleaning.image"^2', 'lel')

The first command creates an empty Viewer Display Panel (§7.2) and a Load Data window (§7.3.1). The second starts the CASA Viewer and loads a Measurement Set. The third example starts the Viewer and opens an image data cube (see Figure 7.1).

Examples four and five make use of the second parameter (displaytype). Example four displays the image as a contour map rather than the default raster map. Example five uses 'Lattice (Image) Expression Language' to display the square of the image data.

Note that the Viewer can open FITS files, CASA image files, Measurement Sets, and saved viewer states. The Viewer determines the type of file being opened automatically.

For additional scripting options when opening the Viewer, see the discussion of the imview and msview tasks at the end of this Chapter (§7.7 and 7.8).

7.1.1 Running the CASA Viewer outside casapy

If you have CASA installed, then the CASA Viewer is available as a stand-alone application called casaviewer. From the operating system prompt, the following commands work the same as the casapy task commands given in the previous Section:

   casaviewer &
   casaviewer ms_filename &
   casaviewer image_filename &
   casaviewer image_filename contour &
   casaviewer '"image_filename"^2' lel &
7.2 The Viewer Display Panel

The CASA Viewer consists of a number of graphical user interface (GUI) windows. The main Viewer Display Panel (§ 7.2) is used for both image and Measurement Set viewing. It is shown in the left panels of Figures 7.1 and 7.2 and appears the same whether an image or Measurement Set is being displayed.

Figure 7.2: The Viewer Display Panel (left) and Data Display Options (right) panels with a Measurement Set open.

At the top of the Viewer Display Panel are drop down menus:

- **Data**
  - **Open** — open the Data Manager window (§ 7.3).
- **Register** — select and de-select which of the loaded data file(s) should be displayed. The menu expands to the right showing all loaded data sets. Unchecking an image will cause it not to be displayed, but does not close it.

- **Close** — close (unload) the selected data file. The menu expands to the right showing all loaded data.

- **Adjust Data Display** — open the Data Display Options ('Adjust') window (§7.4.1).

- **Save as...** — save/export data to a file

- **Print** — print the displayed image

- **Save Panel State** — to a 'restore' file (xml format)

- **Restore Panel State** — from a restore file

- **Preferences** — manually edit the viewer configuration

- **Close Panel** — close this Viewer Display Panel. If this is the last display panel open, this will exit the Viewer.

- **Quit Viewer** — close all display panels and exit

• **Display Panel**

  - **New Panel** — create a new, empty Viewer Display Panel

  - **Panel Options** — open the Viewer Canvas Manager window to edit margins, the number of panels, and the background (§7.4.1.5).

  - **Save Panel State** — save the current state of the viewer as a file that can later be reloaded.

  - **Restore Panel State** — restore the viewer to a state previously saved as a file.

  - **Print** — print displayed image

  - **Close Panel** — close this Viewer Display Panel. If this is the last display panel open, this will exit the Viewer.

• **Tools**

  - **Spectral Profile** — Open the Spectral Profile Browser window to look at intensity as a function of frequency for part of an image (§7.4.4.2)

  - **Collapse Image** — Open the Collapse/Moments window, which allows you to create new images from a data cube by integrating along the spectral axis (§7.4.6)

  - **Histogram** — Open the Histogram inspection window, which allows you to graphically examine the distribution of pixel values in a data cube (§7.4.7)

  - **Fit** — Open the two-d fitting window, which can be used to fit Gaussians to two dimensional intensity distributions (§7.4.8)

  - **Interactive Clean** — Open a window to look at ongoing interactive clean processes.

• **View**

  - **Main Toolbar** — show/hide the top row of icons (Figure 7.3, §7.2.1).
- **Mouse Toolbar** — show/hide the second row of mouse-button action selection icons (Figure 7.4 §7.2.2).

- **Animator** — show/hide tape deck control panel attachment to the main Viewer Display Panel (§7.2.3).

- **Position Tracking** — show/hide the position tracking attachment to the main Viewer Display Panel (§7.2.3).

- **Regions** — show/hide the region manager attachment to the main Viewer Display Panel (§7.2.3).

### 7.2.1 The Main Toolbar

![Main Toolbar](image)

Figure 7.3: The display panel’s **Main Toolbar** appears directly below the menus and contains 'shortcut' buttons for most of the frequently-used menu items.

Below the drop down menus is the **Main Toolbar** (Figure 7.3). This top row of icons offers fast access to these menu items:

- **folder** (*Data: Open* shortcut) — open the Data Manager window (§7.3)

- **wrench** (*Data: Adjust* shortcut) — open the Data Display Options ('Adjust') window (§7.4.1)

- **panels** (*Data: Register* shortcut) — select and de-select which of the loaded data file(s) should be displayed. The menu expands to the right showing all loaded data sets. Unchecking an image will cause it not to be displayed, but does not close it.

- **delete** (*Data: Close* shortcut) — close (unload) the selected data file. The menu expands to the right showing all loaded data.

- **save data** (*Data: Save as*) — save the current data to a file.

- **new panel** (*Display Panel: New Panel*) — create a new, empty Viewer Display Panel

- **panel wrench** (*Display Panel: Panel Options*) — open the Viewer Canvas Manager window to edit margins, the number of panels, and the background (§7.4.1.5).

- **save panel** (*Display Panel: Save Panel State*) — save panel state to a 'restore' file

- **restore panel** (*Display Panel: Restore Panel State*) — restore panel state from a restore file

- **spectral profile** (*Tools: Spectral Profile*) — open the Spectral Profile Browser window to look at intensity as a function of frequency for part of an image (§7.4.4.2)
• collapse/moments (Tools: Collapse Image) — Open the Collapse/Moments window, which allows you to create new images from a data cube by integrating along the spectral axis (§7.4.6).

• histogram (Tools: Histogram) — Open the Histogram inspection window, which allows you to graphically examine the distribution of pixel values in a data cube (§7.4.7).

• fitting (Tools: Fit) – Open the two-d fitting window, which can be used to fit Gaussians to two dimensional intensity distributions (§7.4.8).

• print (Display Panel: Print) — print the current display

• magnifier box — zoom out all the way

• magnifier plus — zoom in (by a factor of 2)

• magnifier minus — zoom out (by a factor of 2)

### 7.2.2 The Mouse Toolbar

Figure 7.4: The ’Mouse Tool’ Bar allows you to assign how mouse buttons behave in the image display area. Initially, zooming, color adjustment, and rectangular regions are assigned to the left, middle and right mouse buttons. Click on a tool with a mouse button to assign that tool to that mouse button.

Below the Main Toolbar are eleven Mouse Tool buttons (Figure [7.4]). These allow you to assign what behavior the three mouse buttons have when clicked in the display area. Clicking a mouse tool icon will [re-]assign the mouse button that was clicked to that tool. Black and white squares beneath the icons show which mouse button is currently assigned to which tool.

The mouse tools available from the toolbar are:

( _Note that the ’escape’ key can be used to cancel any mouse tool operation that was begun but not completed, and to erase a region, point, or other tool showing in the display area._)

• **Zooming (magnifying glass icon):** To zoom into a selected area, press the Zoom tool’s mouse button (the left button by default) on one corner of the desired rectangle and drag to the desired opposite corner. Once the button is released, the zoom rectangle can still be moved or resized by dragging. To complete the zoom, double-click inside the selected rectangle. If you instead double-clicking outside the rectangle, you will zoom out.

• **Panning (hand icon):** Press the tool’s mouse button on a point you wish to move, drag it to the position where you want it moved, and release. _Note: The arrow keys, Page Up, Page Down, Home and End keys can also be used to pan through your data any time you are zoomed in._ (Click on the main display area first, to be sure the keyboard is ’focused’ there).
• **Stretch-shift colormap fiddling (crossed arrows):** This is usually the handiest color adjustment; it is assigned to the middle mouse button by default. Note that you can also adjust the color table quantitatively inside the Data Display Options window (§7.4.1).

• **Brightness-contrast colormap fiddling (light/dark sun):** Another tool to adjust the color stretch.

• **Positioning (plus):** This tool can place a point marker on the display to select a position. It is used to flag Measurement Set data or to select an image position for spectral profiles. Click on the desired position with the tool’s mouse button to place the point; once placed you can drag it to other locations. You can also place multiple points on the display (e.g. for different spectral profile positions) – remove them by hovering over and hitting ESC. Double-click is not needed for this tool. See §7.4.3.2 for more detail.

• **Rectangle, Ellipse and Polygon region drawing:** The rectangle region tool is assigned to the right mouse button by default. As with the zoom tool, a rectangle region is generated by dragging with the assigned mouse button; the selection is confirmed by double-clicking within the rectangle. An ellipse regions is created by dragging with the assigned mouse button. In addition to the elliptical region, also its surrounding rectangle is shown on the display. The selection is confirmed by double-clicking within the ellipse. Polygon regions are created by clicking the assigned mouse button at the desired vertices, clicking the final location twice to finish. Once created, a polygon can be moved by dragging from inside, or reshaped by dragging the handles at the vertices. See §7.4.3.2 for the uses of this tool.

• **Polyline drawing:** A polyline can be created by selecting this tool. It is manipulated similarly to the polygon region tool: create segments by clicking at the desired positions and then double-click to finish the line. [Uses for this tool are still to be implemented].

• **Distance tool:** After selecting the distance tool by assigning any mouse button to it, distances on the image can conveniently be measured by dragging the mouse with the assigned button pressed. The tool measures the distances along the world coordinate axes and along the hypotenuse. If the units in both axes are [deg], the distances are displayed in [arcsec].

• **Position-Velocity Diagram:** Use this mouse tool to drag out a position axis that can be used to generate a position velocity diagram in a new viewer panel from the region manager dock.

### 7.2.3 The Display Area

The main **Display Area** lies below the toolbars. This area shows the image or Measurement Set currently loaded. Clicking the mouse inside the display area allows region or position selection according to the settings in the mouse toolbar.

The Display Area may have up to three attached panels: the **Animator** panel, the **Position Tracking** panel, and the **Regions** panel. These may be displayed or hidden from the ”View” dropdown menu in the main Viewer Display Panel. If one of these is missing from your viewer,
check that it is checked "on" in that menu. The panels can also be turned off by clicked the "X" in the top right corner, in which case you will need to use the View menu to get them back.

By default, the three panels appear attached to the main Viewer Display Panel on the right side of the image. They may be dragged to new positions. Each of the three panels can be attached to the left, top, right, or bottom of the main Viewer Display Panel or they can be entirely undocked and left as free-floating panels.

NOTE: Depending on your window manager, windows without focus, including detached panels and tools like the Spectral Profile Browser may sometimes display odd behavior. As a general rule, giving the window focus by clicking on it will correct the issue. If you seem to "lose" a detached panel (like an Animator Panel), then click in the main window to get it back.

NOTE: With all three panels turned on (and especially with several images loaded), the main display panel can sometimes shrink to very small sizes as the panels grow. Try detaching the panels to get the main display panel back to a useful size.

A restart of the viewer will display all docks in the state of a previous viewer session, given that it was closed normally. In addition, the viewer docking can be changed under “Preferences” In the toolbar (Mac OS under the “CASA Viewer” tab on the toolbar, Linux: “Data”). Fig. 7.5 shows an example. Each item can be changed and the input box will only allow accepted input formats. A complete restart is required to apply the changes.

![Figure 7.5: "Preferences" dialog to manually change the docking and size of the viewer panel.](image_url)
Figure 7.6: The animator panel, which allows one to scroll along the $z$ axis of a data cube (using the Channels tape deck) or cycle among open Images. The panel can be undocked from the main display panel.

7.2.3.1 The Animator Panel

The Animator Panel allows you to scroll through the channels of a data cube and to rotate among loaded images. The main features of the panel are the two “tape decks,” one labeled ”Channels” and one Labeled ”Images” (note that you will only see the Images tape deck when multiple images are loaded.

The Channels tape deck scrolls between planes of an individual image. By default, the channel tape deck scrolls among frequency planes when R.A. and Declination are the displayed axes (in this case, frequency is the "$z$ axis"). From outside to inside, the buttons cause the display to jump all the way to the beginning/end of the $z$ axis, cause the viewer to step one plane forward or backward along the $z$ axis, or start a movie. The limits on the $z$ axis can be set manually using the windows at the end of the scroll bar. The scroll bar can also be dragged or the user can jump the display to a manually entered plane by entering the plane into the text box.

When you have multiple images loaded, the Images tape deck cycles through which is image is being displayed. In the movie mode, it allows you continuously blick between images. Functionally, the image tape deck works similarly to the channels tape deck, with the ability to step, jump, or continuously scroll through images.

NOTE: The check boxes next to the channel and images tabs enable or disable those panels. This doesn’t have much effect when the display has only a single panel, but with multiple panels (i.e., several maps at once in the main window) it changes the nature of the display. If the ”Images” box is is checked then interleaved maps from different cubes are display. Otherwise a series of maps from a single cube are shown.

7.2.3.2 The Position Tracking Panel

The Position Tracking panel (below the images in Fig 7.1) shows the intensity, position (e.g., RA and Dec), Stokes, frequency (or velocity), and pixel location for the point currently under the cursor. A separate box appears for each registered image or Measurement Set and you can see the tracking information for each. Tracking can be ’frozen’ (and unfrozen again) by hitting the space bar when the viewer’s focus is on the main display area (to be sure that this is case first click on the main display area).
CHAPTER 7. VISUALIZATION WITH THE CASA VIEWER

Figure 7.7: The position tracking panel, which gives information about the open data cube at the current location of the cursor. Freeze the position tracking panel using the SPACE bar.

7.2.3.3 The Region Manager Panel

The Region Manager panel becomes active when regions are created. It has a large amount of functionality, from display region statistics and histograms to creating position-velocity cuts. We discuss these in §7.4.3. Like the Animator and Position Tracking panel, the Region Manager Panel can be moved relative to the main viewer display panel or entirely undocked.

7.2.4 Saving and Restoring the Display Panel State

You can save the display panel’s current state — meaning the panel settings and the data on display — or load a saved panel state from disk. To save the display panel state, select Save Panel State from the Display Panel drop-down menu or click the ”Save Display Panel State to File” icon on the main toolbar (an arrow pointing from a picture to a page, see Figure 7.3). It is advisable but not required to retain the file’s '.rstr' ("Restore") extension.

You can restore the display panel to the saved state by loading the saved state from the Data Manager Panel, by selecting Restore Panel State from the Display Panel drop down menu, or by clicking the ”Restore Display Panel State” icon (just to the right of the ”Save Display Panel State” icon).

It is possible to restore panel states viewing Measurement Sets or image and panel states that have multiple layers, such as contour plots over raster images. You can also save LEL displays. You can also the save or restore the panel state with no data loaded, which is a convenient way to restore preferred initial settings such as overall panel size.

Data Locations: The viewer is fairly forgiving regarding data location when restore a saved panel state. It will find files located:

- in the original location recorded in the restore file
- in the current working directory (where you started the viewer)
- in the restore file’s directory
- in the original location relative to the restore file
CHAPTER 7. VISUALIZATION WITH THE CASA VIEWER

This means that you can generally restore a saved panel state if you move that file together with data files. The exception to this rule is that the process is less forgiving if you save the display of an LEL expression. In this case the files must be in the locations specified in the original LEL expression. If a data file is not found, restore will attempt to proceed but results may not be ideal.

Manually Editing Saved Display Panel States: The saved "Restore" files are in ascii (xml) format, and manual edits are possible. However, these files are long and complex. Use caution, and back up restore files before editing. If you make a mistake, the viewer may not even recognize the file as a restore file. It is easier and safer to make changes on the display panel and then save the display panel state again.

7.3 The Data Manager Panel — Saving and Loading Data

Figure 7.8: The load tab of the Data Manager panel. This appears if you open the viewer without any infile specified, if you use select Open from the Data drop down menu, or click the Open (Folder) icon. You can access the save image or save region tabs from this view or by selecting Save as... from the Data drop down menu. The load tab shows all files in the current directory that can be loaded into the viewer — images, MS, CASA region files, and Display Panel State files.

The Data Manager Panel is used to interactively save and load images, Measurement Sets, Display Panel States, and regions. An example of the loading tab in this panel is shown in Figure 7.8. This panel appears automatically if you open the viewer without specifying an input file or it can be accessed through the Data:Open menu or Open icon of the Viewer Display Panel.
7.3.1 Loading Data

The load tab of the Data Manager Panel allows you to interactively choose images or Measurement Sets to load into the viewer. The load tab automatically shows you the available images, Measurement Sets, and Display Panel States in the current directory that can be opened by the viewer. When you highlight an image in this view, the tab shows a brief summary of the image: pixel shape, extent of the image on the sky and in frequency/velocity, and restoring beam (if available).

Selecting a file will bring up information about that file in the panel on the right of the Data Manager Panel provide options for how to display the data. Images can be displayed as:

1. raster image
2. contour map
3. vector map
4. marker map

These options are each discussed in §7.4.

LEL: Instead of only loading an image from disk, you may ask the viewer to evaluate a 'Lattice Expression Language' (LEL) expression (§6.1.3). This can be entered in the box provided after you click the "LEL" box. The images used in the LEL expression should have the same coordinates and extents.

Measurement Sets: A Measurement Set can only be displayed as a raster. For measurement sets, the load tab offers options for data selection. This will reduce loading and processing times for visibility flagging.

Regridding Images on Load: Optionally, you may regrid the velocity axis of an image on load to match the current coordinates grid in the Display Panel. In this case, the viewer will interpolate (using the selected interpolation scheme) the cube on disk to share the same velocity gridding as the loaded coordinates. This can be used, e.g., to overlay contour maps of different spectral lines or to make synchronized movies of multiple cubes. Note that the regridding depends on the rest frequency in the image, which is used to calculate the velocities used in regridding.

7.3.2 Registered vs. Open Datasets

When you load data as described above, it is first opened, and then registered on all existing Display Panels.

An open dataset has been prepared in memory from disk. All open datasets will have a tab in the Data Display Options window, whether currently registered or not.

When a data set is registered to a Display Panel its coordinates are aligned to the other displays in the panel and it is ready for drawing. If multiple Display Panels are open then a data set may
be registered on one Display Panel and not on another. Only those data sets registered on a particular Display Panel show up in its Position Tracking panel.

Why Register More Than One Image? It is useful to have more than one image registered on a panel if you are displaying a contour image over a raster image (§7.4.2.1), to 'blink' between images (see Animator in §7.2), or to compare images using the position tracking panel.

Unregistering Images: A data set can be registered or unregistered using the Register item in the Data drop down menu or the Register icon (third from left). Click the name of the image to toggle its registration state in that Display Panel. Failing to unregister or close data sets that are no longer in use (or not compatible with other data in the Display Panel) may cause problems with the viewer.

Closing vs. Unregistering: You can close a data set that is no longer needed using the Close option in the Data drop-down menu or the ”Close” icon (fourth from left).

If you close a dataset, you must reload it from disk (or recreate it if it’s an LEL expression, regridded image, moment or something similar) to see it again. If you unregister a dataset, it will draw immediately if you re-register it, with its options as you have previously set them. In general, close unneeded datasets but unregister those that you intend to use again.

7.3.3 Saving Data or Regions

Figure 7.9: The Save Data panel that appears when selecting the 'Save as...' (Figure 7.3).

The viewer can create new images by carrying out velocity regridding, evaluating an LEL expression, or collapsing a data cube. You can save these images to disk using the Data Manager Panel. Select Save as under the Data drop-down menu or click the Save as (disk) icon to bring up the Data Manager Panel set to the save tabs. This tab is shown in Figure 7.9.
CHAPTER 7. VISUALIZATION WITH THE CASA VIEWER

From the Save Image tab of the Data Manager Panel, you can export images from the viewer to either a CASA image or FITS file on disk. Select the desired file name and click "save." The Data Manager also allows you to save your current regions to a file, either in the CASA or ds9 format. The left part lists all images that can be exported to disk. To save an image to a file, the user can either enter the new filename in the box labeled 'output name:' followed by the save-button (alternatively the 'Enter'-key), or choose a file name from the right hand side.

7.4 Viewing Images

There are several options for viewing an image. These are seen at the right of the Load Data - Viewer panel described in §7.3.1 and shown in Figure 7.1 after selecting an image. They are:

- **raster image** — a greyscale or color image,
- **contour map** — contours of intensity as a line plot,
- **vector map** — vectors (as in polarization) as a line plot,
- **marker map** — a line plot with symbols to mark positions.

The raster image is the default image display, and is what you get if you invoke the Viewer with an image file and no other options. In this case, you will need to use the Open menu to bring up the Load Data panel to choose a different display.

7.4.1 Viewing a Raster Map

A raster map of an image shows pixel intensities in a two-dimensional cross-section of gridded data with colors selected a colormap according to a scaling that can be specified by the user.

Starting the casaviewer with an image as a raster map will look something like the example in Figure 7.1.

Once loaded, the data display can be adjusted by the user through the Data Display Options panel, which appears when you choose the Data:Adjust menu or use the wrench icon from the Main Toolbar.

The Data Display Options window is shown in the right panel of Figure 7.1. It consists of a tab for each image or MS loaded, under which are a cascading series of expandable categories. For an image, these are:

- **display axes**
- **hidden axes**
- **basic settings**
• position tracking
• axis labels
• axis label properties
• beam ellipse
• color wedge

The basic settings category is expanded by default. To expand a category to show its options, click on it with the left mouse button.

7.4.1.1 Data Display Options — display and hidden axes

In this category the physical axes (i.e. Right Ascension, Declination, Velocity, Stokes) to be displayed can be selected and assigned to the x, y, and z axes of the display. The z axis will be the axis scrolled across by the channel bar in the Animator Panel.

If your image has a fourth axis (typically Stokes), then one of the axes will need to be hidden and not used in viewing. Which axis is hidden can be controlled by a slider within the hidden axes drop-down.

7.4.1.2 Data Display Options — basic settings

This roll-up is open by default showing some commonly-used parameters that alter the way the image is displayed. The most frequently used of these change how the intensity value of a pixel maps to a color on the screen. An example of this part of the panel is shown in Figure 7.10.

The options available are:

• basic settings: aspect ratio
  This option controls the horizontal-vertical size ratio of data pixels on screen. fixed world (the default) means that the aspect ratio of the pixels is set according to the coordinate system of the image (i.e., true to the projected sky). fixed lattice means that data pixels will always be square on the screen. Selecting flexible allows the map to stretch independently in each direction to fill as much of the display area as possible.

• basic settings: pixel treatment
  This option controls the precise alignment of the edge of the current 'zoom window' with the data lattice. edge (the default) means that whole data pixels are always drawn, even on the edges of the display. For most purposes, edge is recommended. center means that data pixels on the edge of the display are drawn only from their centers inwards. (Note that a data pixel’s center is considered its 'definitive' position, and corresponds to a whole number in 'data pixel' or 'lattice' coordinates).
Figure 7.10: The basic settings category of the Data Display Options panel and the interactive tool for setting the mapping from intensity to color.

• basic settings: resampling mode
  This setting controls how the data are resampled to the resolution of the screen. nearest (the default) means that screen pixels are colored according to the intensity of the nearest data point, so that each data pixel is shown in a single color. bilinear applies a bilinear interpolation between data pixels to produce smoother looking images when data pixels are large on the screen. bicubic applies an even higher-order (and somewhat slower) interpolation.

• basic settings: data range
  You can use the entry box provided to set the minimum and maximum data values mapped to the available range of colors as a list \([\text{min}, \text{max}]\). For very high dynamic range images, you will probably want to enter a \(\text{max} \leq \text{data maximum}\) in order to see detail in lower brightness-level pixels.

NOTE: By default you edit the scaling of a single image at once and can click between the tabs at the top of the Data Display Options window to manipulate different windows. By checking the Global Color Settings box at the bottom of this window, you will manipulate the scaling for all images at once. This can be very useful, for example, when attempting detailed comparison multiple reductions of the same data.

• basic settings: scaling power cycles
  This option allows logarithmic scaling of data values to colormap cells, which can be very helpful in the case of very high dynamic range.
  The color for a data value is determined as follows:

  1. The value is clipped to lie within the data range \([\text{min}, \text{max}]\) specified above.
2. This clipped value is mapped to a new value depending on the selected scaling power cycles in the following way:

- If the scaling power cycles is set to 0 (the default), the program considers a linear range from $[\text{min, max}]$ and scales this directly onto the set of available colors.

- For negative scaling values, the data value (after clipping on $[\text{min, max}]$) is scaled linearly to lie between 0 and $10^p$ (where $p$ is the value chosen) and then program takes the logarithm of this values, yielding a value in the range 1 to $p$. That value is scaled linearly to the set of available colors. Thus the data is treated as if it had $p$ decades of range, with an equal number of colors assigned to each decade.

- For positive scaling values, the data value (after clipping on $[\text{min, max}]$) is scaled linearly to lie between 0 and $p$ (where $p$ is the value chosen) and 10 is raised to this power, yielding a value in the range 1 to $10^p$. That value is scaled linearly to the set of available colors.

3. The color corresponding to a number in final range is determined by the selected colormap and its ‘fiddling’ (shift/slope) and brightness/contrast settings (see Mouse Tool-bar, above). Adding a color wedge to your image can help clarify the effect of the various color controls.

See Figure 7.11 for sample curves.

![Figure 7.11: Example curves for scaling power cycles.](image_url)

In practice, you will often manipulate the data range bringing the max down in high dynamic range images, raising the minimum to the near the noise level when using non-zero scaling cycles. It is also common to use negative power cycles when considering high dynamic range images — this lets you bring out the faint features around the bright peaks.

- basic settings: colormap
You can select from a variety of colormaps here. Hot Metal, Rainbow and Greyscale colormaps are the ones most commonly used.

### 7.4.1.3 Graphical Specification of the Intensity Scale

A histogram icon next to the data range in the Data Display opens the Image Color Mapping window, which allows visualization and graphical manipulation of the mapping of intensity to color. The window at the left shows a histogram of the data with a gray range showing the data range. You can use this window to select the data range graphically (with the mouse), manually (by typing into the empty windows), or as a percentile of the data. On the right, you can select the scaling power cycles and see a visualization of the transfer function mapping intensity (x-axis) to color (y-axis).

The functionality here follows the other histogram tools, with the Display tab used to change the histogram plotting parameters. It will often be useful to use a logarithmic scaling of the y-axis and filled histograms when manipulating the color table.

### 7.4.1.4 Data Display Options — other settings

Many of the other settings on the Data Options panel for raster images are self-explanatory such as those which affect beam ellipse drawing (only available if your image provides beam data), or the form of the axis labeling and position tracking information. You can also give your image a color wedge, a key to the current mapping from data values to colors.

### 7.4.1.5 Viewer Canvas Manager — Panels, Margins, and Backgrounds

The display area can also be manipulated from the Viewer Canvas Manager window. Use the wrench icon with a 'P' (or the 'Display Panel' menu) to show this window, which allows you to manipulate the infrastructure of the main display panel. You can set:

- Margins - specify the spacing for the left, right, top, and bottom margins
- Number of panels - specify the number of panels in x and y and the spacing between those panels.
- Background Color - white or black (more choices to come)

Figure 7.12 illustrates a multi-panel display along with the Viewer Canvas Manager settings which created it.
CHAPTER 7. VISUALIZATION WITH THE CASA VIEWER

7.4.2 Viewing a Contour Map

Viewing a contour image is similar to viewing a raster map. A contour map shows lines of equal data value for the selected plane of gridded data (Figure 7.13). Contour maps are particularly useful for overlaying on raster images so that two different measurements of the same part of the sky can be shown simultaneously (§7.4.2.1).

Several basic settings options control the contour levels used:

- The contours themselves are specified by a list in the box Relative Contour Levels. These are defined relative to the two other parameters:
  - The Base Contour Level sets the zero level for the relative contour list corresponds to in units of intensity in the image.
  - The Unit Contour Level sets what 1 in the relative contour list corresponds to in units of intensity in the image.

Additionally, you have the option to manipulate the thickness and color of the image and to have either positive or negative contours appear dashed.
CHAPTER 7. VISUALIZATION WITH THE CASA VIEWER

Figure 7.13: The **Viewer Display Panel** (left) and **Data Display Options** panel (right) after choosing **contour map** from the **Load Data** panel. The image shown is for channel 11 of the NGC5921 cube, selected using the **Animator** tape deck, and zoomed in using the tool bar icon. Note the different options in the open **basic settings** category of the **Data Display Options** panel (as compared to **raster image** in Figure 7.1).

For example, the following settings:

- **Relative Contour Levels** = [0.2, 0.4, 0.6, 0.8]
- **Base Contour Level** = 0.0
- **Unit Contour Level** = <image max>

would map the maximum of the image to 1 in the relative contour levels and the base contour level to zero. So the contours will show 20%, 40%, 60%, and 80% of the peak.

Another approach is to set the unit contour to 1, so that the contours are given in intensity units (usually Jy/beam). So this setup:

- **Relative Contour Levels** = [0.010, 0.020, 0.040, 0.080, 0.160, 0.320]
- **Base Contour Level** = 0.0
- **Unit Contour Level** = 1.0

would create contours starting at 10 mJy/beam and doubling every contour.

Another useful approach is to set contours in units of the rms noise level of the image, which can be worked out from a signal free region. Then a setup like this:
Relative Contour Levels = [-3, 3, 5, 10, 15, 20]
Base Contour Level = 0.0
Unit Contour Level = <image rms>

Would indicate significance in the image. The first two contours show emission at ± 3-sigma and so on.

You can get the image rms using the `imstat` task (§ 6.9) or using the Viewer statistics tool on a region of the image (§ 7.4.3.3).

Not all images are of intensity, for example a moment-1 image (§ 6.7) has units of velocity. In this case, absolute contours (like the last two examples) will work fine, but by default the Viewer will set fractional contours but referred to the min and max of the image:

Relative Contour Levels = [0.2, 0.4, 0.6, 0.8]
Base Contour Level = <image min>
Unit Contour Level = <image max>

Here we have contours spaced evenly from min to max, and this is what you get by default if you load a non-intensity image (like the moment-1 image). See Figure 7.14 for an example of this.

### 7.4.2.1 Overlay Contours on a Raster Map

Contours of either a second data set or the same data set can be used for comparison or to enhance visualization of the data. The Data Options Panel will have multiple tabs (switch between them at the top of the window) that allow you to adjust each overlay individually.

**NOTE:** axis labeling is controlled by the first-registered image overlay that has labeling turned on (whether raster or contour), so make label adjustments within that tab.

To add a Contour overlay, open the Load Data panel (Use the Data menu or click on the folder icon), select the data set and click on contour map. See Figure 7.14 for an example using NGC5921.

### 7.4.3 Regions and the Region Manager

CASA regions are following the CASA ‘crtf’ standard as described in § D. CASA regions can be used in all applications, including clean and image analysis tasks (§ 6).

**NOTE:** A leading ‘ann’ (short for annotation) to a region definition indicates that it is for visual overlay purposes only.

**NOTE:** Whereas the region format is supported by all the data processing tasks, some aspects of the viewer implementation are still limited to rectangles, ellipses, and some markers. Full support for all region types is progressing with each CASA release.

Once one or more regions are created, the Region Manager Panel becomes active (see Figure 7.15). Like the Position Tracking and Animator Panels, this can be docked or detached from the main viewer display. It contains several tabs that can be used to adjust, analyze, and save or load regions.
CHAPTER 7. VISUALIZATION WITH THE CASA VIEWER

Figure 7.14: The Viewer Display Panel (left) and Data Display Options panel (right) after overlaying a Contour Map of velocity on a Raster Image of intensity. The image shown is for the moments of the NGC5921 cube, zoomed in using the tool bar icon. The tab for the contour plot is open in the Data Display Options panel.

Figure 7.15: The Region Manager Panel, which becomes active once at least one region is created. Cycle through available regions using the slider bar at the bottom and use the various tabs to adjust, analyze, load, and save regions.
NOTE: Moving the mouse into a region will bring it into focus for the Spectral Profile or Histogram tools.

### 7.4.3.1 Region Creation, Selection, and Deletion

Within the display area, you can draw regions or select positions using the mouse. Regions can be created with the buttons marked as 'R' in the mouse tool bar (§ 7.2 § 7.4.3.2). The viewer currently supports creation of rectangles, ellipses, polygons, and the point. As usual, a mouse button can be assigned to each button as indicated by the small black square in each button (marking the left, middle, or right mouse button § 7.2 § 7.4.3.2). An example is shown in Fig. 7.16.

Regions can be selected by SHIFT+click, de-selected by pressing SHIFT+click again. The bottom of the Region Manager Panel features a slider to switch between regions in the image. Regions can be removed by hovering over and pressing ESC or by pressing the buttons to the right side of the slider where the first button deletes all regions and the far right button deletes the region that is currently displayed in the panel.

![Figure 7.16: Selecting an image region (done with SHIFT+click). The region can be resized by dragging the handles or deleted by hitting ESCAPE.](image)

Once regions are selected, they will feature little, skeletal squares in the corners of their boundary boxes. Selected regions can be moved by dragging with the mouse button and manually resize by grabbing the corners as handles. If more than one region is selected, all selected regions move together.

The **Rectangle Region** drawing tool currently enables the full functionality of the various Region Manager tabs (see below) as well as:
CHAPTER 7. VISUALIZATION WITH THE CASA VIEWER

- Region statistics reporting for images via double clicking (also shown in the stats tab of the Region Manager),

- Defining a region to be averaged for the spectral profile tool (accessed via the Tools:Spectral Profile drop down menu or "Open the Spectrum Profiler" icon),

- Flagging of Measurement Sets. Note that the Rectangle Region tool’s mouse button must also be double-clicked to confirm an MS flagging edit.

- Selecting Clean regions interactively (§5.3.5)

The Polygon Region and Ellipse Region drawing have the same uses, except that polygon region flagging of a Measurement Set is not supported.

7.4.3.2 Region Positioning

![Region Manager Screenshot](image)

Figure 7.17: The positioning tab in the Region Manager. Use it to manually adjust the location, width, and display style of the selected region.

With at least one region drawn, the region manager becomes active. Using the Properties tab, one can manually adjust the position, annotation, and display style of the region. The frames boxes set which planes of the image cube the region persists through (regions can have a depth associated with them and will only appear in the frames listed in this range). One can manually adjust the width and height and the center of the box in the chosen units. The 'selection' check box is an alternative way to the SHIFT+click to select a region. The 'annotation' checkbox will place the 'ann' string in front of the region ascii output – annotation regions are not be used for processing in, e.g. data analysis tasks. In the line and text tabs, one can set the style with which the region is displayed, the associated text, and the position and style of that text.
CHAPTER 7. VISUALIZATION WITH THE CASA VIEWER

NOTE: Updating the position of a region will update the spectral profile shown if the Spectral Profile tool is open and the histogram if the Histogram tool is open. The views are linked. Dragging a region or adjusting it manually with the Position tab is a good way to explore an image.

7.4.3.3 Region Statistics

One of the most useful features of defining a region is the ability to extract statistics characterizing the intensity distribution inside the region. You can see these in the Statistics tab of the Region Manager Panel (see Figure 7.18). This displays statistics for the current region in the current plane of the current image. When more than a single region is drawn, you can select them one by one and the region panel will update the statistics to reflect the currently selected region. All values are updated on the fly when the region is dragged across the image.

A similar functionality can be achieved by double clicking inside of a region. This will send statistics information for this region in all registered images to the terminal, looking something like this:

```
(image) image
  Stokes  Velocity  Frame  Doppler  Frequency
  I   -2.99447e+11km/s  LSRK  RADIO  3.63499e+10
  BrightnessUnit  BeamArea  Npts  Sum  Flux
  Jy/beam  36.2521  27547  1.087686e-01  3.000336e-03
  Mean  Rms  Std dev  Minimum  Maximum
  3.948473e-06  3.723835e-04  3.723693e-04  -1.045624e-03  9.968892e-03
```

This is an easy way to copy and paste the statistical data to a program outside of CASA for further use.
Taking the RMS of the signal-free portion of an image or cube is a good way to estimate the noise. Contrasting this number with the maximum of the image gives an estimate of the dynamic range of the image. The FluxDensity measurement gives a way to use the viewer to do very basic photometry.

### 7.4.3.4 Saving and Loading Regions

![Image of the save/load tab in the Region Manager](Image)

**Figure 7.19:** The save/load tab in the Region Manager.

The **File** tab in the Region Manager allows one to save or load selected regions, either individually or en masse. You can choose between CASA and ds9 region format. The default is a CASA region file (saved with a *.crtf suffix, see §D). The DS9 format does not offer the full flexibility and cannot capture stokes and spectral axes. DS9 regions will only be usable as annotations in the viewer, they cannot be used for data processing in other CASA tasks. When saving regions, one can choose to save only the current region, all regions that were selected with SHIFT+click, or all regions that are visible on the screen.

**NOTE:** The load functionality for this tab will only become available once at least one region exists. To load a region when no regions exist, use the Data Manager window (§7.3).

### 7.4.3.5 The Region Fit

**NOTE:** This functionality is still under development. Its robustness and functionality will be improved in future version of CASA.

The Viewer can attempt to fit a two dimensional Gaussian to the emission distribution inside the currently selected region. To attempt the fit, go to the **Fit** tab of the Region Manager and click the
gaussfit button in the bottom left of the panel. You can choose whether or not to fit a sky level (e.g., to account for a finite background, either astronomical, sky, or instrumental). After fitting the distribution, the Fit panel shows the results of the fit, the center, major and minor axis, and position angle of the Gaussian fit in pixels (I) and in world coordinates (W, RA and Dec). The detailed results of the fit will also appear in the terminal window, including a flag showing whether the fit converged.

7.4.3.6 The Region Histogram

![Figure 7.20: The histogram tab in the Region Manager. Right click to zoom. Hit SHIFT + Right Click to adjust the details of the histogram display.](image)

The Viewer will automatically derive a histogram of the pixel values inside the selected region. This can be viewed using the Histogram tab of the of the Region Manager Panel. This is a pared down version of the full Histogram Tool. You can manipulate the details of the histogram plot by clicking:

1. Use the Right Click to zoom - either to the full range, a selected percentile, or a range that you have graphically selected by dragging the mouse (may still be under development).

2. Hit SHIFT + Right Click to open the histogram options. This lets you toggle between a logarithmic and linear y-axis, choose between a line, outline, or filled histogram, and adjust the number of bins.

The histogram will update as you change the plane of the cube or shift between region.
7.4.4 The Spectral Profile Tool

The Spectral Profile Tool allows you examine the intensity as a function frequency or velocity. To start a new Spectral Profile window, click the Spectral Profile option from the Tools drop-down menu or click the "Spectral Profile" (red line graph) icon from the Main Toolbar (see Fig. 7.3). A new Spectral Profile window will appear.

NOTE: Make Sure That You Use the Radio Version! This section describes the "Radio" version of the profiler. To be sure that you have the radio version of the tool selected (this may not be the default), click on the preferences icon (the gear fourth from the left) and make sure that the "Optical" option is not checked.

The Spectral Profile Tool consists of a toolbar (7.4.4.1), a main display area (7.4.4.2), and two associated tabs: Spectral-Line Fitting (7.4.4.3) and Line Overlays (7.4.4.4).

Interaction With the Main Display Panel: For the Spectral Profile tool to work, a region or point must be specified in the main Viewer Display window. Use the mouse tools to specify a point, rectangle, ellipse, or polygon region. Alternatively, load a region file. The Spectral Profile tool will show a spectrum extracted from the region most recently highlight by the mouse in the main Viewer Display Panel. The method of extraction can be specified by the user using a drop down menu below the spectrum in the Spectral Profile window; the method of extraction is mean by default.

The Spectral Profile tool can also feed back to the Main Display Panel. By holding CTRL and right...
clicking in the spectrum, you will cause the Main Display Panel to jump to display the frequency channel corresponding to the spectral (x) coordinate of the region clicked in the Spectral Profile tool. Holding CTRL and dragging out a spectral range while holding the right mouse button will queue a movie scrolling through images across that spectral range. You can achieve the same effect with the two-ended-arrow icon towards the right of the toolbar in the Spectral Profile window.

In both tabs, it will be useful to do select regions of frequency or velocity. You can do this with the parallel lines-and-arrow icon (see below) or by holding shift, left clicking, and dragging out the range of interest. A shaded gray region should appear indicating your selection.

**7.4.4.1 Spectral Profile Toolbar**

![Toolbar Image]

Figure 7.22: The toolbar for the Spectral Profile tool allows the user to save the spectrum, print or save the tool as an image, edit preferences (general, tool, legend), pan or zoom around the spectrum, select a range of interest, jump to a channel, or add a label.

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Figure [7.22] shows the toolbar from the top portion of the Spectral Profile window. From left to right, the icons allow the user to:

- (disk) export the current profile to a FITS or ASCII file
- (printer) print the main window to a hard copy
- (writing desk) save the panel as an image (PNG, JPG, PDF, etc.)
- (gear) set plot preferences
- (color wheel) set color preferences for the plot
- (signpost) set legend preferences
- (arrows) pan the spectrum in the indicated direction **NOTE**: The arrow keys also allow one to pan using the keyboard.
- (magnifying glass) zoom to the default zoom, in, and out **NOTE**: the +/- keys allow one to zoom with the keyboard
- (parallel lines+arrows) drag out a range of interest in the spectrum, for use with fitting or line overlays.
- (double-ended arrow) jump to a channel in the main viewer (single click) or define a range over which to play a movie in the viewer (with a drag). **NOTE**: You can also jump to a channel with **CTRL+Right Click** and queue a movie by holding **CTRL** and dragging out a range while holding the right mouse button.
CHAPTER 7. VISUALIZATION WITH THE CASA VIEWER

- notepad and pencil Add or edit a label on the plot. Click this icon to enter a mode where you can drag out a box to create a new annotation box or drag the corners of an existing one to resize it. You can edit the contents, color, and font of an existing annotation by right clicking on it and selecting ”Edit Annotation” in the main Spectral Profile window.

![Preferences options in the Spectral Profile Tool. From the toolbar, one can access dialogs to set overall viewer preferences, colors for plotting, and how the plot legend is displayed.](image)

Figure 7.23: Preferences options in the Spectral Profile Tool. From the toolbar, one can access dialogs to set overall viewer preferences, colors for plotting, and how the plot legend is displayed.

Figure 7.23 shows the setting dialogs accessible from the toolbar. This Preferences dialog opened by the gear icon allows the user to:

- Toggle automatic scaling the x- and y-ranges of the plot.
- Toggle the coordinate grid overlay in the background of the plot.
- Toggle whether registered images other than the current one appear as overlays on the plot.
- Toggle whether these profiles are plotted relative to the main profile (in development).
- Toggle the display of tooltips (in development).
- Toggle the plotting of a top axis.
- Toggle between a histogram and simple line style for the plot.
- Toggle between the radio and optical versions of the Spectral Profile tool Note: We dis- cuss only the radio version here; this mainly impacts the Spectral Line Fitting and Collapse/Moments functionality.
- Toggle the overplotting of a line showing the channel currently being displayed in the main Display Panel.

The Color Curve Preferences dialog opened by the color wheel icon allows the user to:
• Select the color of the line marking the current channel shown in the main Display Panel.
• Select the color used to overlay molecular lines from Splatalogue.
• Select the color to plot the initial Gaussian estimate used in spectral line fitting.
• Select the color used for the zoom rectangle.
• Set a queue of colors used to plot the various data sets registered in the Display Panel.
• Set a queue of colors to plot the set of Gaussian fits.
• Set a queue of colors to plot the synthesized curve.

Two sets of preset colors, "Traditional" or "Alternative", are available and the user can define their own custom color palette.

The legend options opened by the signpost icon allow the user to toggle the plotting of a legend defining the curves shown in the main Spectral Profile window. Using a drop-down dialog, the legend can be placed in the top left corner of the plot, to the right of the plot, or below the plot. Toggling the color bar causes the color of the curve to be indicated either via a short bar or using the color of the text itself. Double click the names of the files or curves to edit the text shown for that curve by hand.

7.4.4.2 Main Spectral Profile Window

![Rectangle Region Profile](image)

Figure 7.24: The main panel for the Spectral Profile tool. Buttons along the bottom row allow the axes to be set. Arrow keys pan and dragging out an area with the mouse zooms. Holding CTRL and right clicking in the spectrum will jump the main Viewer Display panel to display that frequency channel.

The main window shows the spectrum extracted from active region of the image in the main Display Panel. The spectra from the same region in any other registered images are also plotted if overlays are enabled. Menus along the bottom of the image allow the user to select how the spectrum is displayed. From left to right:
• The units for the bottom spectral axis.

• The units for the top spectral axis. **NOTE:** dual axes are enabled only if a single image is registered and the top axis option is enabled. In general, dual axes are not well-defined for mixed data sets. The exception is that open data cubes with matched frequency/spectral axes will allow dual axes.

• The units for the left intensity or flux axis. **Note:** fraction of peak allows easy comparison of data with disparate intensity scales.

• The velocity reference frame used if a velocity axis is chosen for the top or bottom axis.

• The method used to extract spectrum from the region — a mean over all pixels in the region, a median, sum, or a sum converting units to get a flux density over the region (Jy).

• Toggle the calculation and overplotting of error bars calculated from scatter in the data (**rmse** refers to root mean square error).

In addition to these drop-down menus, the main Spectral Profile window allows the user to do the following using keyboard and mouse inputs:

• *jump the main Display Panel window to a specified channel (CTRL+Right click):* hold CTRL and right click in the spectrum. A marker will appear and the main Viewer Display Panel will jump to display that channel.

• *animate the main Display Panel in a movie across a frequency range (CTRL+Right click+drag):* hold CTRL, Right click, and drag. The main Viewer Display panel will respond by showing a movie scrolling across the selected spectral channels.

• *zoom the Spectral Profile (+/-, mouse drag):* Use the +/− keys to zoom in the same way as the toolbar buttons. Alternatively, press and dragging the left mouse button. A yellow box is drawn onto the panel. After releasing the mouse button, the plot will zoom to the selected range.

• *pan the Spectral Profile (arrows):* Use the arrow keys to pan the plot.

• *select a spectral range for analysis:* hold shift, left click, and drag. A gray area will be swept out in the display. This method can be used to select a range for spectral line fitting or collapsing a data cube (in the Collapse/Moments window).

**NOTE:** If the mouse input to the Spectral Profile browser becomes confused hit the **ESC** key several times and it will reset.
CHAPTER 7. VISUALIZATION WITH THE CASA VIEWER

Figure 7.25: The Spectral Line Fitting tab in the Spectral Profile Tool. The user can fit a combination of a polynomial and multiple Gaussian components, specifying the range to be fit (gray region) manually or with a shift+click+drag. Initial estimates for each component may be entered by hand or specified via an initial estimates GUI. The results are output to a dialog and text file with the fit overplotted (here in blue) on the spectrum (with the possibility to save it to disk).

Figure 7.26: The left panel shows the graphical specification of initial estimates for Gaussian fitting. Slider bars specify the center, FWHM, and peak intensity for the initial estimate. The right panel shows the verbose output of the fitting.
7.4.4.3 Spectral-Line Fitting

NOTE: Interactive spectral line fitting is still under development.

The Spectral-Line Fitting tab, shown in Figures 7.25 and 7.26, allows the user to interactively fit a combination of Gaussian and polynomial profiles to the data shown in the Spectral Line Profile tool. The tool includes a number of options, many of which remain under development:

- A drag-down menu at the top of the panel allows the user to pick which data set to fit.
- The spectral range to fit can be specified by either holding shift+left click+dragging out a region in the main spectral profile window or by typing it manually into the box at the top left of the fitting panel.
- Optionally multiple fits can be carried out once, fitting each spectrum in the region in turn. To enable this, check the “MultiFit” box. (Under development.)
- Optionally a polynomial of the specified order may be fit. To do so, check the ”Polynomial” fit check box and then specify the desired order. (Under Development.)
- The results may be saved to a text file. This text file should be specified before the fit is carried out. Click ”Save” and then use the dialog to specify the file name. Note that the fit curve itself becomes a normal spectral profile data set and can be saved to disk using the toolbar (disk icon) after the fit.
- One or more Gaussians can be fit (Results are presently most stable for one Gaussian.). Specify the number of Gaussians and then enter initial estimates for the peak, center, and FWHM in the table below. Any of these values can be fixed for any of the Gaussians being fit. Initial estimates can also be manually specified by clicking Specify Estimates. This brings up an additional GUI window (Figure 7.26), where slides can be used to specify initial estimates for each Gaussian to be fit.
- For plotting purposes, one may wish to oversample the fit (i.e., plot a smooth Gaussian), you can do so by increasing the Fit Samples/Channel to a high number to finely sample the fit when plotting.

NOTE: Currently the tool works well for specifying a single Gaussian. Fitting multiple components can become unstable and polynomial and multiple line-of-sight fitting are still under development. This is an area of active development and future releases will offer improved capabilities.

7.4.4.4 Line Overlays

CASA ships with a local version of the Splatalogue spectral line database (www.splatalogue.net) and this can be used to identify and overplot spectral transitions. This feature, shown in Figure 7.27 allows the user to search Splatalogue over the range of interest.

To overlay spectral lines:
1. Select the **Line Overlays** tab in the Spectral Profiles tab.

2. If you know it, enter the redshift or velocity of your source in the "Doppler Shift" panel. Otherwise, the lines will be overlaid assuming a redshift of 0.

3. Specify a minimum and maximum frequency range to search, either by typing a range or by holding shift and left click and dragging out a range in the spectrum (you will see a gray box appear). If you don’t specify a range, the tool will search over the frequency range of spectrum.

4. Optionally, you may select an astronomical filter from the list (for example, commonly used extragalactic lines or lines often found in hot cores, see Splatalogue for more information). This is usually a good idea because it pare the potentially very large list of candidate lines to a smaller set of reasonable candidates.

5. Click "Search" and the Spectral Profile will search Splatalogue for a list of Spectral lines that that fit that Astronomical Filter in that frequency range for that redshift. A dialog will pop up showing the list of candidate lines.

6. Highlight one or more of these transitions and click "Graph Selected Lines." A set of vertical markers will appear in the main Spectral Profile window at the appropriate (redshifted) frequencies for the line.
We emphasize that this feature remains under active development. Look for improved performance and an expanded feature set in the next release.

**NOTE:** You will want to click "Clear Lines" between searches, especially if you update the redshift.

### 7.4.5 The Brightness Profile Tool

The “line” tool can be used to display 1-dimensional brightness profiles of images. The viewer accepts even more than one line segments such as shown in Fig. 7.28. The “region” dock will then display a preview of the slice in the “Slice Cut” tab and the full “1-D Slice Tool” can be launched from there. This panel allows one to select the interpolation method to connect the pixels, and a number count for the sampled pixels in between markers. “Automatic” will show all pixels. The x-axis of the display can be either the distance or the absolute coordinates of the image, e.g. RA and DEC. All segments are also listed at the bottom with their start and end coordinates, the distance and the position angles of each slice segment. The color tool can be used to give each segment a separate color.

![Figure 7.28: 1-dimensional slice of an image. The 1D slicer tool shows the brightness distribution along line segments.](image)

### 7.4.6 The Collapse/Moments Tool

The CASA Viewer can collapse a data cube into an image, for instance allowing to look at the emission integrated along the $z$ axis or the mean velocity of emission along the line of sight. You can access this functionality via the Collapse/Moments tool (accessed via the Tools menu or the four arrow icons), shown in Figure 7.29.

The tool uses the same format as the Spectral Profile tool and will show the integrated spectrum of whatever region or point is currently selected in the main Display Panel. To create a moment map:
Figure 7.29: The Collapse/Moments tool, accessed from the Main Toolbar or the Tools drop down menu. The mean spectrum from the region in the Main Display Panel appears in the top part of the tool. After selecting a range, a moment to calculate, and optionally data to exclude click collapse to calculate a new image.

1. Select a range over which to integrate either manually using the left part of the window, by adding an interval and typing in the values into the box or by holding **SHIFT + Left Click** and dragging out the range of interest.

2. Pick the set of algorithms that you will use to collapse the image along the $z$ axis. Clicking toggles each moment method, and the collapse will create a new image for each selected moment. For details on the individual collapse method, see the `immoments` task for more details on each moment.

3. The moment may optionally include or exclude pixels within a certain range (for example, you might include only values with signal-to-noise three or greater when calculating the velocity dispersion). You can enter the values to include or exclude manually in the Thresholding window on the right or you can open a histogram tool to specify this range graphically by clicking Specify Graphically (before this can work, you must click "Include" or "Exclude").

4. The results of the collapse be saved to a file, which consists of a string specifying the specific moment tacked onto a root file name that you can specify using Select Root Output File.

5. When you are satisfied with you chosen options, press Collapse.

**NOTE:** Even if you don’t save the results of the collapse to a file, you can still save the map lated using the Save as... entry in the Data pull down menu from the main Viewer Display Panel.

**NOTE:** This area remains under active development and may still exhibit some stability issues in CASA 4.1.
7.4.7 The Histogram Tool

CASA can calculate and visualize a histogram of pixel values inside a region of interest. To examine this histogram, select **Histogram** from the **Tools** drop-down menu or the Histogram icon (looks like a comb). This opens the full histogram tool; more limited versions are accessible from the Region Manager Panel, the graphical color table manipulation tool, and the Collapse/Moments tool.

The resulting Histogram Tool should look something like Figure 7.30. The menus along the top (or the corresponding mouse clicks) allow one to:

- Zoom to the full range, a selected percentile, or a graphical range.
- Change the display of the histogram to show a log axis, display as either a line plot, an outline, or a filled histogram. Change the number of bins in the histogram, or clear the plot (to start over).
- Configure what data are fed into the histogram. You can use this menu to tell the histogram to track the channel currently selected in the main Viewer Display Panel (click the "Track Channel" box) or to integrate across some range of channels (defaulting to the whole image). You can also switch the 2-D footprint used between the whole Image, the Selected Region, and All Regions.

Figure 7.30: The **Histogram** tool, accessed from the Main Toolbar or the **Tools** drop down menu. Details of the display and included pixels can be manipulated via the menus along the top of the window. The right hand panel allows one to attempt to fit a distribution to the histogram.
• Save (via the disk icon) an image of the histogram to a graphical file on disk.

The Histogram Tool also allows you to fit the distribution using either a Gaussian or a Poisson distribution, for example to estimate the noise in the image (a Gaussian will be a good choice to describe the noise in most radio data cubes). You can specify initial estimates or let the program generate initial guesses. The fit is then overplotted on the histogram (colors can be adjusted by clicking the color wheel icon in the toolbar) and details of the fit are printed to the text window below the fit button.

7.4.8 The Two-D Fitting Tool

![Two Dimensional Fitting Interface]

Figure 7.31: The interface to the two dimensional fitting tool (Tools: Fit... or the blue circles icon). The interface allows you to specify and automatically generate (Find Sources) initial estimates, to specify the range of pixel values to be included in the fit, and to specify the output (log file, residual image, and visualization). Click Fit to start the fit.

**NOTE:** This functionality is still under very active development. Not all features are functional at this point.

CASA can fit two dimensional Gaussians to an intensity distribution, and the Two-Dimensional Fitting tool in the Viewer exposes this functionality interactively. This tool, accessed by the blue circles icon or the Tools: Fit... menu item, has an interface like that shown in Figure 7.31. The interface exposes several options:

1. You can select whether to fit only the selected region or the whole image plane and specify
which channel of the cube you want to operate on. **NOTE:** The two dimensional fitter only operates on a single channel at a time.

2. **Initial Estimates:** The box in the top left corner allows the user to specify initial estimates by feeding in a file. The easiest way to make an appropriate file is to edit an existing one. Even easier, you can use the **Find Sources** button to automatically generate a temporary file of initial estimates. **NOTE:** This functionality is still under development. When it is working, you click on **Find Sources**

3. **Pixel Range:** You can choose to only include a certain range of pixel intensity values in the fit. For example, you might choose to only fit Gaussians to pixels above a few times the measured noise level. You can use the **Specify Graphically** button to bring up an interactive histogram of the region (a reduced functionality version of the full Histogram Tool).

4. **Output:** You can choose to save the output of the fit as a file to the specified directory and to subtract the fit from the image and to subtract the fit from the original, creating a **Residual Image** that gets stored as a CASA image and automatically loaded into the viewer. This gives a way to tell how well your fit describes the total emission.

5. **Visualization:** You can toggle whether the fit is displayed on the viewer or not and change the color of the marker.

Click **Fit** to start the fit. If the fit does not converge, try improving your initial estimates and fitting again.

### 7.4.9 Interactive Position-Velocity Diagram Creation

![Interactive Position-Velocity Diagram Creation](image)

Figure 7.32: Interactive creation of position-velocity cuts in the viewer. Use the P/V tool from the Mouse Toolbar to define a cut, then use the pV tool from the Region Manager Panel to adjust the cut (including the width). Click Generate P/V to build the position velocity cut and open it in a new Viewer Display Panel (from which it can be saved to disk).

**NOTE:** This functionality is still under very active development.
As of release 4.1.0, CASA supports the interactive creation of position velocity diagrams from data cubes. The route to create them is illustrated in Figure 7.32:

1. Select the P/V cut tool from the Mouse Toolbar and use it to draw a line across a data cube along the axis you want to visualize.

2. Open the Region Manager Panel and go to the $pV$ tab. Highlight the cut you just drew. You should see the end point coordinates listed, along with information on the length and position angle of the cut. You can set the averaging width (in pixels) in a window at the bottom of the tab.

3. When you are satisfied, hit Generate P/V. This will create a new Main Viewer Display Panel showing the position velocity cut. The axes should be Offset and velocity.

The new image can be saved to disk with the Data:Save as... option.

### 7.5 Viewing Measurement Sets

Visibility data can also be displayed and flagged directly from the viewer. For Measurement Set files the only option for display is 'Raster' (similar to AIPS task tvflg). An example of MS display is shown in Figure 7.2; loading of an MS is shown in Figure 7.33.

**Warning:** Only one MS should be registered at a time on a Display Panel. Only one MS can be shown in any case. You do not have to close other images/MSs, but you should at least 'unregister' them from the Display Panel used for viewing the MS. If you wish to see other images or MSs at the same time, create multiple Display Panel windows.

#### 7.5.1 Data Display Options Panel for Measurement Sets

The Data Display Options panel provides adjustments for MSs similar to those for images, and also includes flagging options. As with images, this window appears when you choose the Data:Adjust menu or use the wrench icon from the Main Toolbar. It is also shown by default when an MS is loaded. The right panel of Figure 7.2 shows a Data Options window. It has a tab for each open MS, containing a set of categories. The options within each category can be either 'rolled up' or expanded by clicking the category label.

For a Measurement Set, the categories are:

- **Advanced**
- **MS and Visibility Selection**
- **Display Axes**
- **Flagging Options**
7.5.1.1 MS Options — Basic Settings

The Basic Settings roll-up is expanded by default. It contains entries similar to those for a raster image (§ 7.4.1.2). Together with the brightness/contrast and colormap adjustment icons on the Mouse Toolbar of the Display Panel, they are especially important for adjusting the color display of your MS.

The available Basic options are:

- Data minimum/maximum
This has the same usage as for raster images. Lowering the data maximum will help brighten weaker data values.

- **Scaling power cycles**
  This has exactly the same usage as for raster images (see §7.4.1.2). Again, lowering this value often helps make weaker data visible. If you want to view several fields with very different amplitudes simultaneously, this is typically one of the best adjustments to make early, together with the Colormap fiddling mouse tool, which is on the middle mouse button by default.

- **Colormap**
  Greyscale or Hot Metal colormaps are generally good choices for MS data.

### 7.5.1.2 MS Options—MS and Visibility Selections

- **Visibility Type**
- **Visibility Component**
- **Moving Average Size**

This roll-up provides choice boxes for Visibility Type (Observed, Corrected, Model, Residual) and Component (Amplitude, Phase, Real, or Imaginary).

Changes to Visibility Type or Component (changing from Phase to Amplitude, for example) require the data to be retrieved again from the disk into memory, which can be a lengthy process. When a large MS is first selected for viewing, the user must trigger this retrieval manually by pressing the **Apply** button (located below all the options), after selecting the data to be viewed (see Field IDs and Spectral Windows, below).

**Tip:** Changing visibility type between 'Observed' and 'Corrected' can also be used to assure that data and flags are reloaded from disk. You should do this if you’re using another flagging tool such as autoflag simultaneously, so that the viewer sees the other tool’s new edits and doesn’t overwrite them with obsolete flags. The **Apply** button alone won’t reload unless something within the viewer itself requires it; in the future, a button will be provided to reload flags from the disk unconditionally.

You can also choose to view the difference from a running mean or the local RMS deviation of either Phase or Amplitude. There is a slider for choosing the nominal number of time slots in the ‘local neighborhood’ for these displays.

(Note: **Insufficient Data** is shown in the tracking area during these displays when there is no other unflagged data in the local neighborhood to compare to the point in question. The moving time windows will not extend across changes in either field ID or scan number boundaries, so you may see this message if your scan numbers change with every time stamp. An option will be added later to ignore scan boundaries).

- **Field IDs**
Figure 7.34: The MS for NGC4826 BIMA observations has been loaded into the viewer. We see the first of the \texttt{spw} in the Display Panel, and have opened up \texttt{MS and Visibility Selections} in the \textbf{Data Display Options} panel. The display panel raster is not full of visibilities because \texttt{spw} 0 is continuum and was only observed for the first few scans. This is a case where the different spectral windows have different numbers of channels also.

- **Spectral Windows**

You can retrieve and edit a selected portion of the MS data by entering the desired Spectral Window and Field ID numbers into these boxes. \textbf{Important:} Especially with large MSs, often the first thing you'll want to do is to select \texttt{spectral windows} which all have the \texttt{same number of channels} and the \texttt{same polarization setup}. It also makes sense to edit only a few fields at a time. Doing this will also greatly reduce data retrieval times and memory requirements.

You can separate the ID numbers with spaces or commas; you do not need to enter enclosing brackets. Changes to either entry box will cause the selected MS data to be reloaded from disk.

If you select, say, spectral windows 7, 8, 23, and 24, the animator, slice position sliders, and axis labeling will show these as 0, 1, 2, and 3 (the 'slice positions' or 'pixel coordinates' of the chosen spectral windows). Looking at the position tracking display is the best way to avoid confusion in such cases. It will show something like: \texttt{Sp Win 23 (s 2)} when you are viewing spectral window 23 (plane 2 of the selected spectral windows).

Changes to MS selections will not be allowed until you have saved (or discarded) any previous edits you have made (see \textbf{Flagging Options -- Save Edits}, below). A warning is printed on the
console (not the logger).

Initially, all fields and spectral windows are selected. To revert to this ‘unselected’ state, choose ‘Original’ under the wrench icons next to the entry boxes.

See Figure 7.34 for an example showing the use of the **MS and Visibility Selections** controls when viewing an MS.

### 7.5.1.3 MS Options — Display Axes

This roll-up is very similar to that for images: it allows the user to choose which axes (from Time, Baseline, Polarization, Channel, and Spectral Window) are on the display and the animator. There are also sliders here for choosing positions on the remaining axes. (It’s useful to note that the data is actually stored internally in memory as an array with these five axes).

![Data Display Options panel](image)

**Figure 7.35:** The MS for NGC4826 from Figure 7.34 now with the **Display Axes** open in the **Data Display Options** panel. By default, **channels** are on the **Animation Axis** and thus in the tapedeck, while **spectral window** and **polarization** are on the **Display Axes** sliders.

For MSs, changing the choice of axis on one control will automatically swap axes, maintaining different axes on each control. Changing axes or slider/animator positions does not normally require pressing **Apply** — the new slice is shown immediately. However, the display may be partially or completely grey in areas if the required data is not currently in memory, either because
CHAPTER 7. VISUALIZATION WITH THE CASA VIEWER

no data has been loaded yet, or because not all the selected data will fit into the allowed memory. Press the **Apply** button in this case to load the data (see § 7.5.1.6 and **Max. Visibility Memory** at the end of § 7.5.1.5).

![Image](image.png)

**Figure 7.36:** The MS for NGC4826, continuing from Figure 7.35. We have now put **spectral window** on the **Animation Axis** and used the tapedeck to step to **spw 2**, where we see the data from the rest of the scans. Now **channels** is on a **Display Axes** slider, which has been dragged to show **Channel 33**.

Within the **Display Axes** rollup you may also select whether to order the baseline axis by antenna1-antenna2 (the default) or by (unprojected) baseline length.

See Figures 7.35, 7.36 showing the use of the **Display Axes** controls to change the axes on the animation and sliders.

### 7.5.1.4 MS Options — Flagging Options

These options allow you to edit (flag or unflag) MS data. The Point Tool and Rectangle Region Mouse Tools (§ 7.4.3.2) are used on the display to select the area to edit. When using the Rectangle Region tool, double-click inside the selected rectangle to confirm the edit.

The options below determine how edits will be applied.

- **Show Flagged Regions**...
You have the option to display flagged regions in the background color (as in TVFLG) or to highlight them with color. In the former case, flagged regions look just like regions of no data. With the (default) color option, flags are shown in shades of blue: darker blue for flags already saved to disk, lighter blue for new flags not yet saved; regions with no data will be shown in black.

- **Flag or Unflag**

  This setting determines whether selected regions will be flagged or unflagged. This does not affect previous edits; it only determines the effect which later edits will have. Both flagging and unflagging edits can be accumulated and then saved in one pass through the MS.

- **Flag/Unflag All...**

  These flagging extent checkboxes allow you to extend your edit over any of the five data axes. For example, to flag all the data in a given time range, you would check all the axes except Time, and then select the desired time range with the Rectangle Region mouse tool. Such edits will extend along the corresponding axes over the entire selected MS (whether loaded into memory or not) and optionally over unselected portions of the MS as well (Use Entire MS, below). Use care in selecting edit extents to assure that you're editing all the data you wish to edit.

- **Flag/Unflag Entire Antenna?**

  This control can be used to extend subsequent edits to all baselines which include the desired antenna[s]. For example, if you set this item to 'Yes' and then click the point tool on a visibility position with baseline 3-19, the edit would extend over baselines 0-3, 1-3, 2-3, 3-3, 3-4, ..., 3-nAntennas-1. Note that the second antenna of the selection (19) is irrelevant here – you can click anywhere within the 'Antenna 3 block', i.e., where the first antenna number is 3, to select all baselines which include antenna 3.

  This item controls the edit extent only along the baseline axis. If you wish to flag all the data for a given antenna, you must still check the boxes to flag all Times, Channels, Polarizations and Spectral Windows. There would be no point, however, in activating both this item and the 'Flag All Baselines' checkbox. You can flag an antenna in a limited range of times, etc., by using the appropriate checkboxes and selecting a rectangular region of visibilities with the mouse.

  **Note:** You do not need to include the entire 'antenna block' in your rectangle (and you may stray into the next antenna if you try). Anywhere within the block will work. To flag higher-numbered antennas, it often helps to zoom in.

- **Undo Last Edit**

- **Undo All Edits**

  The 'Undo' buttons do the expected thing: completely undo the effect of the last edit (or all unsaved edits). Please note, however, that only unsaved edits can be undone here; there is no ability to revert to the flagging state at the start of the session once flags have been saved to disk (unless you have previously saved a 'flag version'. The flag version tool is not available through the viewer directly).
• Use Entire MS When Saving Edits?

"Yes" means that saving the edits will flag/unflag over the entire MS, including fields (and possibly spectral windows) which are not currently selected for viewing. Specifically, data within time range(s) you swept out with the mouse (even for unselected fields) will be edited. In addition, if "Flag/Unflag All..." boxes were checked, such edits will extend throughout the MS. Note that only unselected times (fields) can be edited without checking extent boxes for the edits as well. Unselected spectral windows, e.g., will not be edited unless the edit also has "Flag/Unflag All Spectral Windows" checked.

Warning: Beware of checking "All Spectral Windows" unless you have also checked "All Channels" or turned "Entire MS" off; channel edits appropriate to the selected spectral windows may not be appropriate to unselected ones. Set "Use Entire MS" to "No" if your edits need to apply only to the portion of the MS you have selected for viewing. Edits can often be saved significantly faster this way as well.

Also note that checkboxes apply to individual edits, and must be checked before making the edit with the mouse. "Use Entire MS", on the other hand, applies to all the edits saved at one time, and must be set as desired before pressing "Save Edits".

• Save Edits

MS editing works like a text editor in that you see all of your edits immediately, but nothing is committed to disk until you press 'Save Edits'. Feel free to experiment with all the other controls; nothing but 'Save Edits' will alter your MS on disk. As mentioned previously, however, there is no way to undo your edits once they are saved, except by manually entering the reverse edits (or restoring a previously-saved 'flag version').

Also, you must save (or discard) your edits before changing the MS selections. If edits are pending, the selection change will not be allowed, and a warning will appear on the console. If you close the MS in the viewer, unsaved edits are simply discarded, without prior warning. It’s important, therefore, to remember to save them yourself. You can distinguish unsaved flags (when using the 'Flags In Color' option), because they are in a lighter shade of blue.

The program must make a pass through the MS on disk to save the edits. This can take a little time; progress is shown in the console window.

7.5.1.5 MS Options—Advanced

These settings can help optimize your memory usage, especially for large MSs. A rule of thumb is that they can be increased until response becomes sluggish, when they should be backed down again.

You can run the unix ‘top’ program and hit ‘M’ in it (to sort by memory usage) in order to examine the effects of these settings. Look at the amount of RSS (main memory) and SWAP used by the X server and ‘casaviewer’ processes. If that sounds familiar and easy, then fiddling with these settings is for you. Otherwise, the default settings should provide reasonable performance in most cases.
• **Cache size**

The value of this option specifies the maximum number of different views of the data to save so that they can be redrawn quickly. If you run an animation or scroll around zoomed data, you will notice that the data displays noticeably faster the second time through because of this feature. Often, setting this value to the number of animation frames is ideal. Note, however, that on multi-panel displays, each panel counts as one cached image.

Large images naturally take more room than small ones. The memory used for these images will show up in the X server process. If you need more Visibility Memory (below) for a really large ms, it is usually better to forgo caching a large number of views.

• **Max. Visibility Memory**

This option specifies how many megabytes of memory may be used to store visibility data from the measurement set internally. *Even if you do not adjust this entry, it is useful to look at it to see how many megabytes are required to store your entire (selected) MS in memory.* If the slider setting is above this, the whole selected MS will fit into the memory buffer. Otherwise, some data planes will be ‘grayed out’ (see Apply Button, §7.5.1.6 below), and the selected data will have to be viewed one buffer at a time, which is somewhat less convenient. In most cases, this means you should select fewer fields or spectral windows – see §7.5.1.2.

The 'casaviewer' process contains this buffer memory (it contains the entire viewer, but the memory buffer can take most of the space).

### 7.5.1.6 MS Options — Apply Button

When viewing large MSs the display may be partially or completely grey in areas where the required data is not currently in memory, either because no data has been loaded yet, or because not all the selected data will fit into the allowed memory (see Max. Visibility Memory above). When the cursor is over such an area, the following message shows in the position tracking area:

```
press 'Apply' on Adjust panel to load data
```

Pressing the Apply button (which lies below all the options) will reload the memory buffer so that it includes the slice you are trying to view.

The message **No Data** has a different meaning; in that case, there simply *is* no data in the selected MS at the indicated position.

For large measurement sets, loading visibility data into memory is the most time-consuming step. Progress feedback is provided in the console window. Again, careful selection of the data to be viewed can greatly speed up retrieval.

### 7.6 Printing from the Viewer

You can select **Data:Print** from the drop down menu or click the **Print** icon to bring up the **Viewer Print Manager**. From this panel, you can **Print** the contents of Display Panel to a
Figure 7.37: Printing the display to a hardcopy of a file. From the Viewer Print Manager, located in top right here and accessed by the print icon or from the Data drop down menu, you can use the Save button to save an image or Print directly to a printer. To achieve the best results, it is often helpful to adjust the settings in the Data Display Options and Viewer Canvas Manager, shown at right.

hardcopy or Save them as an image in a format selected from the drop-down menu at the bottom left of the window. Note that the save feature will overwrite the file in question without prompting.

The Viewer Print Manager allows you to adjust the DPI, orientation, and page format (Output Media) for Postscript or PDF files and to scale the image to a desired pixel size for other images.

To achieve the best output it is usually advisable to adjust the settings in the Viewer Print Manager, Data Display Options, and Viewer Canvas Manager. For PDF and Postscript output, turning the DPI up all the way yields the best-looking results. For other images, a white background often makes for better looking images than the default black. It is often necessary to increase the Line Width in the Axis Label Properties (in the Data Display Options panel) to ensure that the labels will be visible when printed. Increasing from the default of 1.4 to a value around 2 often works well.
Figure [7.37] shows an example of printing to a file while adjusting the Data Display Options and Viewer Canvas Manager to improve the appearance of the plot.

### 7.7 Image Viewer (imview)

The `imview` task offers scriptable access to many viewer options. This enables the production of customized plots without invoking the GUI and allows one to open the viewer to a carefully selected state.

`imview` has the following inputs:

```plaintext
# imview :: View an image
raster = {} # (Optional) Raster filename (string)
# or complete raster config
dictionary. The allowed dictionary
# keys are file (string), scaling
# (numeric), range (2 element numeric
# vector), colormap (string), and
# colorwedge (bool).

countour = {} # (Optional) Contour filename (string)
# or complete contour config
dictionary. The allowed dictionary
# keys are file (string), levels
# (numeric vector), unit (float), and
# base (float).

zoom = 1 # (Optional) zoom can specify
# intermental zoom (integer), zoom
# region read from a file (string) or
# dictionary specifying the zoom
# region. The dictionary can have two
# forms. It can be either a simple
# region specified with blc (2 element
# vector) and trc (2 element vector)
# [along with an optional coord key
# ("pixel" or "world"; pixel is the
# default) or a complete region
# rectangle e.g. loaded with
# "rg.fromfiletorecord()". The
# dictionary can also contain a
# channel (integer) field which
# indicates which channel should be
# displayed.

axes = -1 # (Optional) this can either be a
# three element vector (string) where
# each element describes what should
# be found on each of the x, y, and z
# axes or a dictionary containing
# fields "x", "y" and "z" (string).
```
The `raster` and `contour` parameters specify which images to load and how these images should be displayed. These parameters take Python dictionaries as inputs. The fields in these dictionaries specify how the image will be displayed.

An example call to `imview` looks like this:

```python
imview(raster={'file': 'ngc5921.clean.image', 'range': [-0.01, 0.03], 'colormap': 'Hot Metal 2', 'scaling': -1}, contour={'file': 'ngc5921.clean.image'}, axes={'x': 'Declination'}, zoom={'channel': 7, 'blc': [75, 75], 'trc': [175, 175], 'coord': 'pixel'}, out='myout.png')
```

The argument to `raster` is enclosed in the curly braces `{ }`. Within these braces are a number of "key":"value" pairs. Each sets an option in the viewer, with the GUI parameter to set defined by the "key" and the value to set it to defined by "value." In the example above, "file":"ngc5921.clean.image" sets the file name of the raster image, "range": [-0.01,0.03] sets the range of pixel values used for the scaling.

`contour` works similar to 'raster' but can accept multiple dictionaries in order to produce multiple contour overlays on a single image. To specify multiple contour overlays, simply pass multiple dictionaries (comma delimited) in to the contour argument:

```python
contour={'file': 'file1.image', 'levels': [1, 2, 3]}, {'file': 'file2.image', 'levels': [0.006, 0.008, 0.010]}
```
zoom specifies the part of the image to be shown.

axes defines what axes are shown. By default, the viewer will show 'x': 'Right Ascension', 'y': 'Declination' but one may also view position-frequency images.

out defines the filename of the output, with the extension setting the file type.

Currently, the following parameters are supported with additional functionality planned for future releases:

- **raster** -- (string) image file to open
  - (dict) file (string) => image file to open
  - scaling (float) => scaling power cycles
  - range (float*2) => data range
  - colormap (string) => name of colormap
  - colorwedge (bool) => show color wedge?

- **contour** -- (string) file to load as a contour
  - (dict) file (string) => file to load
  - levels (float*N) => relative levels
  - base (numeric) => zero in relative levels
  - unit (numeric) => one in the relative levels

- **zoom** -- (int) integral zoom level
  - (string) region file to load as the zoom region
  - (dict) blc (numeric*2) => bottom left corner
  - trc (numeric*2) => top right corner
  - coord (string) => pixel or world
  - channel (int) => channel to display
  - (dict) <region record> => record loaded
    - e.g. rg.fromfiletorecord()

- **axes** -- (string*3) dimension to display on the x, y, and z axes
  - (dict) x => dimension for x-axes
  - y => dimension for y-axes
  - z => dimension for z-axes

- **out** -- (string) file with a supported extension
  - [jpg, pdf, eps, ps, png, xbm, xpm, ppm]
  - (dict) file (string) => filename
  - format (string) => valid ext (filename ext overrides)
  - scale (numeric) => scale for non-eps, non-ps output
  - dpi (numeric) => dpi for eps or ps output
  - orient (string) => portrait or landscape

Examples are also found in `help imview`.

### 7.8 Measurement Viewer (msview)

The Measurement Viewer `msview` is mostly a clone of the `viewer` at this stage. A difference is that `msview` allows the user to select data before it is loaded into the GUI and displayed. A screenshot is shown in Fig. [7.38](#) and selection parameters are field, spectral window, time range, uv
range, antenna, corr, scan, array, ms selection expression in the usual CASA selection syntax (see Sect. 2.3).

Figure 7.38: Data selection in msview.
Chapter 8

Single Dish Data Processing

For single-dish spectral calibration and analysis, CASA uses the ATNF Spectral Analysis Package (ASAP). ASAP is imported as the `sd` tool at the start-up of CASA.

It forms the basis for a series of tasks (the “SDtasks”) that encapsulates the functionality within the standard CASA task framework. ASAP was developed to support the Australian telescopes such as Mopra, Parkes, and Tidbinbilla, and we have adapted it for use within CASA for GBT (see the note below for limitation of GBT SDFITS handling) and eventually ALMA [Note: Some support for the ALMA is now available]. For R3.4 or later, the ASAP version included in CASA was updated to 4.0 (which is the latest official release of ASAP as of Mar. 2012). In ASAP 4.0, data format was also updated from 3.0 to 4.0. Note that data in version 3.0 format are automatically updated to version 4.0 format and replaced.

For details on ASAP – including the User Guide, Reference Manual, and tutorial – see the ASAP home page at ATNF:


The ASAP tools are prefaced with `sd`. within CASA, e.g., the ASAP tool `scantable` becomes `sd.scantable`. See §8.3 for more information on the tools.

All of the ASAP functionality is available within the CASA installation. Since we extended ASAP, there are certain functionalities that are available only in the CASA version of ASAP. In the following subsections, we outline how to access ASAP from within CASA and the data flow for standard use cases.

If you run into trouble, be sure to check the list of known issues and features of ASAP and the SDtasks presented in §8.5 first.
8.1 Guidelines for Use of ASAP and SDtasks in CASA

8.1.1 Environment Variables

There are a number of environment variables that the ASAP tools (and thus the SDtasks) use to control their operation. They are located in `.asaprc` and are described in the ASAP User Guide. Within CASA, they are contained in the Python dictionary `sd.rcParams` and are accessible through its keys and values. For SDtask users, the most important parameter is `verbose`, which controls the display of detailed messages from the tools. By default,

```
sd.rcParams['verbose'] = True
```

produced by lots of messages. Also, the `scantable.storage` parameter controls whether scantable operations are done in memory or on disk. The default is

```
sd.rcParams['scantable.storage'] = 'memory'
```

which is the best choice if there is enough memory compared with a size of data to be loaded. On the other hand,

```
sd.rcParams['scantable.storage'] = 'disk'
```

forces the task to store datasets on disk, which might be necessary when they are large. See § 8.3.1 for more details on the ASAP environment variables.

**Important Note:**
User must use `sd.rcParams[scantable.storage] = 'disk'` with care when you call any tool level functions since some functions may overwrite original data even if you set `sd.rcParams['insitu'] = False`, which tells the system not to overwrite original data (in contrast, setting `sd.rcParams['insitu']` to True forces to overwrite original data). Relevant methods, which may overwrite original data in the above case, are as follows:

- `sd.average_time`
- `sd.merge`
- four operations (+, -, *, /) of `sd.scantable` instance with scalar or array
- `sd.scantable.add`
- `sd.scantable.clip`
- `sd.scantable.flag`
- `sd.scantable.flag_nans`
- `sd.scantable.flag_row`
- `sd.scantable.scale`
- `sd.scantable.recalc_azel`
- any setter functions of `sd.scantable` class (both `set_xxx` and `_setxxx` functions)

If you only use SDtasks, you don’t need to worry about that since SDtasks are designed to keep original data unchanged.
8.1.2 Assignment

Some ASAP methods and functions require assigning a method to a variable which can then be manipulated. These methods and functions include `sd.scantable` and `sd.selector`, both of which make objects. For example,

\[
s = sd.scantable('OrionS_rawACSmod', average=False)
\]

8.1.3 Lists

For lists of scans or IFs, such as in `scanlist` and `iflist` in the SDtasks, the tasks and functions require a comma-delimited Python list, e.g.,

\[
scanlist = [241, 242, 243, 244, 245, 246]
\]

The python `range` function can be used to generate a list of consecutive numbers, e.g.,

\[
scanlist = range(241,247)
\]

giving the same list as above,

CASA <3>: scanlist=range(241,247)
CASA <4>: print scanlist
[241, 242, 243, 244, 245, 246]

Multiple ranges can be created by summing lists,

CASA <5>: scanlist=range(241,247) + range(251,255)
CASA <6>: print scanlist
[241, 242, 243, 244, 245, 246, 251, 252, 253, 254]

Note that in the future, the `sd` tools and SDtasks will use the same selection language as in the interferometric synthesis part of the CASA.

Spectral regions, such as those for setting masks, are pairs of min and max values for whatever spectral axis unit is currently chosen. These are fed into the tasks and tools as a list of lists, where each list element is a list with the `[min,max]` for that sub-region, e.g.,

\[
masklist=[[1000,3000], [5000,7000]]
\]
8.1.4 Dictionaries

Currently, the SDtasks return the Python dictionary for the results of line fitting (in \texttt{sdfit}) and region statistics (in \texttt{sdstat}). If you invoke these tasks by assigning a variable for the return, you can then access the elements through the keywords, e.g.,

\begin{verbatim}
CASA <10>: line_stat=sdstat()
Current fluxunit = K
No need to convert fluxunits
Using current frequency frame
Using current doppler convention

CASA <11>: line_stat
Out[11]:
{'eqw': 70.861755476162784,
'max': 1.2750182151794434,
'mean': 0.35996028780937195,
'median': 0.23074722290039062,
'min': -0.20840644836425781,
'rms': 0.5309775012969971,
'stddev': 0.39102539420127869,
'sum': 90.350028991699219}
\end{verbatim}

One can then use these values in scripts by accessing this dictionary, e.g.,

\begin{verbatim}
CASA <12>: print "Line max = \%5.3f K" % (line_stat['max'])
Line max = 1.275 K
\end{verbatim}

8.1.5 Line Formatting

The SDtasks trap leading and trailing whitespace on string parameters (such as \texttt{infile}) but ASAP does not, so be careful with setting string parameters. ASAP is case-sensitive, with most parameters being upper-case, such as \texttt{ASAP} for the \texttt{sd.scantable.save} file format. The SDtasks are generally more forgiving. Also, beware Python’s sensitivity to indentation.

8.1.6 Logging

Before R3.0, all messages from ASAP were written to the standard output (\texttt{sys.stdout}) and they disappeared after exiting CASA. After R3.0, the logging system of ASAP is integrated into CASA logging system. Therefore, all outputs from ASAP commands, except for GUI related notifications, are sent to the log file for the current session and they are displayed to the CASA Logger (see §1.5.2).

8.2 Single Dish Analysis Tasks

A set of single dish tasks is available for simplifying basic reduction activities. The list currently includes:
CHAPTER 8. SINGLE DISH DATA PROCESSING

- **sdcal** — select, calibrate, and average SD data
- **sdcal2** — generate sky and tsys caltables for SD data, and apply them
- **sdsMOOTH** — smooth SD spectra
- **sdbaseline** — fit/remove spectral baselines from SD data
- **sdreduce** — **sdcal**, **sdsMOOTH**, and **sdbaseline** combined to perform standard single dish processing all at once
- **sdcoadd** — merge/co-add multiple SD data
- **sdflag** — channel/row flagging of SD spectra
- **sdflagmanager** — enable list, save, restore, delete and rename flag version files
- **sdfit** — line fitting to SD spectra
- **sdgrid** — convolve map data onto regularly spaced grid
- **sdimaging** — create an image from the total power or spectral data
- **sdlist** — print a summary of a SD dataset
- **sdmath** — do simple arithmetic for SD spectra
- **sdplot** — plotting of SD spectra, including overlay of line catalog data
- **sdsave** — save SD data to different format
- **sdscale** — scale SD data
- **sdstat** — compute statistics of regions of SD spectra
- **sdtpimaging** — do a simple calibration and create an image from the total power raster scans
- **sdimprocess** — remove the ‘scanning noise’ from raster scanned image
- **msmoments** — compute moments from spectral data

All of the SDtasks, except those related to imaging (**sdtpimaging**, **sdimaging**, and **sdimprocess**), work from a file on disk rather than from a scantable in memory as the ASAP toolkit does (see §8.3). Inside the tasks we invoke a call to **sd.scantable** to read the data. The scantable objects do not persist within CASA after completion of the tasks and are destroyed to free up memory.

Three tasks **sdcal**, **sdsMOOTH**, and **sdbaseline** are the workhorses for the calibration, selection, averaging, baseline fitting, and smoothing. The output datasets for each task are written to a file on disk. Alternatively, one can use the task **sdreduce** to perform all of the steps in the three tasks described. Its operation is controlled by three main ”mode” parameters: **calmode** (which selects the type of calibration, if any, to be applied), **kernel** (which selects the smoothing), and
blfunc (which selects baseline fitting). There are also parameters controlling the selection such as scanlist, iflist, field, scanaverage, timeaverage, and polaverage. Note that sdreduce can be run with calmode='none' to allow re-selection or writing out of data that is already calibrated. There is a "wiring diagram" of the dataflow and control inputs for sdreduce shown in Figure 8.1.

The SDtasks support the import and export file formats supported by ASAP itself. For import, this includes: ASAP (scantables), MS (CASA Measurement Set), RPFITS, SDFITS (version 1.3) and NRO data format. For export, this includes: ASAP (scantables), MS (CASA Measurement Set), ASCII (text file), SDFITS (a flavor of SD FITS). The sdsave task is available exclusively for exporting with these data selection options. The sdcoadd task is available to merge data in separate data files into one. A brief summary of the data in a file is found in the sdlist task help.

Plotting of spectra is handled in the sdplot task. It also offers some selection, averaging, and smoothing options in case you are working from a dataset that has not been split or averaged. Note that there is some rudimentary plotting capability in many of SDtasks, controlled through the plotlevel parameter, to aid in the assessment of the performance of these tasks.

Scaling of the spectra and Tsys is available in the sdscale. For arithmetic operations of spectra in separate scantables, sdmath has been added.

Calculation of statistics on spectral regions is available in the sdstat task. Results are passed by a Python dictionary return variable. The statistics of spectra can also be calculated via msmoments task. The input of msmoments task must be in CASA Measurement Set format. The task newly creates Measurement Set to store statistics values.

Basic Gaussian line-fitting is handled by the sdfit task. It can deal with the simpler cases, and offers some automation as well as interactive selection of fitting region, but more complicated fitting is best accomplished through the toolkit (sd.fitter).

Basic interactive and non-interactive channel and row flagging are available in the sdflag task. The flags in the input file is updated by default, i.e., outfile=' ' and overwrite=True. Otherwise, a new file is created to store dataset with updated flag information.

Limited total power data analysis functionality is available through the task sdtpimaging. A single dish image data cube can be created using sdimaging, which also handles total power imaging. These tasks directly access the Measurement Set without converting it to scantable format. The sdimprocess is intended to remove the 'scanning noise' from single dish images by either the 'Basket-Weaving' or 'Pressed-out' methods.

The task sdgrid, which convolves map data onto regularly spaced grid, is available. The task can be used as imaging tool although output of this task is not an image but a scantable. Also, it can be regarded as a data averaging tool with various weight.

Although the Measurement Set can store data from multiple antennas even if it consists of only single-dish spectra (auto-correlation data), the scantable cannot distinguish data from multiple antennas. It causes a problem when the user processes the Measurement Set using SDtasks. Therefore, id or name of the antenna that the user want to process must be explicitly specified if the input dataset for SDtasks is Measurement Set. This can be done by antenna parameter. By default (antenna=0), data associate with antenna id 0 is imported. The antenna parameter takes no effect for other input data formats.
Figure 8.1: Wiring diagram for the SDtask \texttt{sdreduce}. The stages of processing within the task are shown, along with the parameters that control them.
8.2.1 SDtask Summaries

The following are the list of parameters and brief descriptions of each of the SDtasks. These descriptions are also contained in help <taskname>.

8.2.1.1 sdcal

Keyword arguments:

infile -- name of input SD dataset
antenna -- antenna name or id (only effective for MS input).
fluxunit -- units for line flux
  options: 'K','Jy',''
  default: '' (keep current fluxunit)
  WARNING: For GBT data, see description below.

  >>> fluxunit expandable parameter
  telescopeparm -- the telescope characteristics
  options: (str) name or (list) list of gain info
  default: '' (none set)
  example: if telescopeparm='', it tries to get the telescope name from the data.
  Full antenna parameters (diameter,ap.eff.) known to ASAP are
  'ATPKSMB', 'ATPKSHOH', 'ATMOPRA', 'DSS-43',
  'CEDUNA','HOBART'. For GBT, it fixes default fluxunit to 'K' first then convert to a new fluxunit.
  telescopeparm=[104.9,0.43] diameter(m), ap.eff.
  telescopeparm=[0.743] gain in Jy/K
  telescopeparm='FIX' to change default fluxunit see description below

specunit -- units for spectral axis
  options: (str) 'channel','km/s','GHz','MHz','kHz','Hz'
  default: '' (=current)
  example: this will be the units for masklist

frame -- frequency frame for spectral axis
  options: (str) 'LSRK','REST','TOPO','LSRD','BARY','
  'GEO','GALACTO', 'LGROUP', 'CMB'
  default: currently set frame in scantable
  WARNING: frame='REST' not yet implemented

doppler -- doppler mode
  options: (str) 'RADIO','OPTICAL','Z','BETA','GAMMA'
  default: currently set doppler in scantable

calmode -- calibration mode
options: 'ps','nod','otf','otfraster',
     'fs','fsotf','quotient','none'
default: 'none'
example: choose mode 'none' if you have
        already calibrated and want to
        try averaging
WARNING: 'fsotf' is not implemented yet

>>> calmode expandable parameter
    fraction -- Edge marking parameter for 'otf' and 'otfraster'.
               specify a number of OFF scans as a fraction of
               total number of data points.
    default: '10%'
    options: '20%' in string style or float value less
             than 1.0 (e.g. 0.15).
    'auto' is available only for 'otfraster'.
    noff -- Edge marking parameter for 'otfraster'.
            It is used to specify a number of OFF scans near
            edge directly. Value of noff comes before setting
            by fraction.
    default: -1 (use fraction)
    options: any positive integer
    width -- Edge marking parameter for 'otf'.
             Pixel width with respect to a median spatial
             separation between neighboring two data in time.
             Default will be fine in most cases.
    default: 0.5
    options: float value
    elongated -- Edge marking parameter for 'otf'.
                Set True only if observed area is elongeted
                in one direction.
    default: False
    markonly -- Set True if you want to save data just after
                edge marking (i.e. uncalibrated data) to see
                how OFF scans are defined.
    default: False
scanlist -- list of scan numbers to process
    default: [] (use all scans)
    example: [21,22,23,24]
    this selection is in addition to field, iflist, and pollist
field -- selection string for selecting scans by name
    default: '' (no name selection)
    example: 'FLS3a*'
    this selection is in addition to scanlist, iflist, and pollist
iflist -- list of IF id numbers to select
    default: [] (use all IFs)
CHAPTER 8. SINGLE DISH DATA PROCESSING

example: [15]
this selection is in addition to scanlist, field, and pollist

pollist -- list of polarization id numbers to select
default: [] (use all polarizations)
example: [1]
this selection is in addition to scanlist, field, and iflist

channelrange -- channel range selection
default: [] (use all channel)
example: [0,5000]
Note that specified values are recognized as 'channel'
regardless of the value of specunit

scanaverage -- average integrations within scans
options: (bool) True,False
default: False

timeaverage -- average times for multiple scan cycles
options: (bool) True,False
default: False
example: if True, this happens after calibration

>>>timeaverage expandable parameter

tweight -- weighting for time average
options: 'none'
  'var' (1/var(spec) weighted)
  'tsys' (1/Tsys**2 weighted)
  'tint' (integration time weighted)
  'tintsys' (Tint/Tsys**2)
  'median' (median averaging)
default: 'none'

averageall -- average multi-resolution spectra
spectra are averaged by referring
their frequency coverage
default: False

polaverage -- average polarizations
options: (bool) True,False
default: False

>>>polaverage expandable parameter

pweight -- weighting for polarization average
options: 'none'
  'var' (1/var(spec) weighted)
  'tsys' (1/Tsys**2 weighted)
default: 'none'
CHAPTER 8. SINGLE DISH DATA PROCESSING

\texttt{tau} -- atmospheric optical depth
\hspace{1cm} default: 0.0 (no correction)
\texttt{verify} -- verify the results of calibration. Only effective if
\hspace{0.7cm} calmode is not 'none'.
\hspace{0.7cm} options: (bool) True,False
\hspace{0.7cm} default: False
\hspace{0.7cm} WARNING: Currently this just asks whether you accept
\hspace{0.7cm} the displayed calibration and if not, continues
\hspace{0.7cm} without doing any calibration.
\texttt{outfile} -- Name of output file
\hspace{1cm} default: '' (<\textit{infile}>_cal)
\texttt{outform} -- format of output file
\hspace{1cm} options: 'ASCII','SDFITS','MS','ASAP'
\hspace{1cm} default: 'ASAP'
\hspace{1cm} example: the ASAP format is easiest for further sd
\hspace{0.7cm} processing; use MS for CASA imaging.
\hspace{0.7cm} If ASCII, then will append some stuff to
\hspace{0.7cm} the outfile name
\texttt{overwrite} -- overwrite the output file if already exists
\hspace{1cm} options: (bool) True,False
\hspace{1cm} default: False
\hspace{1cm} WARNING: if outform='ASCII', this parameter is ignored
\texttt{plotlevel} -- control for plotting of results
\hspace{1cm} options: (int) 0=none, 1=some, 2=more, <0=hardcopy
\hspace{1cm} default: 0 (no plotting)
\hspace{1cm} example: plotlevel<0 as abs(plotlevel), e.g.
\hspace{1cm} -1 => hardcopy of final plot (will be named
\hspace{0.7cm} <\textit{outfile}>_calspec.eps)
\hspace{1cm} WARNING: be careful plotting in fsof mode!

\textbf{DESCRIPTION:}

Task \texttt{sdcal} performs data selection, calibration for single-dish spectra. By setting \texttt{calmode='none'},
one can run \texttt{sdcal} on already calibrated data, for further selection, averaging and atmospheric
optical depth correction. To save the output spectra in a certain range of channels, you set the
range in \texttt{channelrange}.

If you give multiple IFs in \texttt{iflist}, then your scantable will have multiple IFs by default. Averaging
of multi-resolution (multi-IFs) spectra can be achieved by setting a sub-parameter in \texttt{timeaverage},
\texttt{averageall}, to True. It handles multi-IFs by selecting overlaps in frequency coverages and assign-
ing new IFs in the output spectra.

ASAP recognizes the data of the "AT" telescopes, but currently does not know about the GBT or
any other telescope. This task does know about GBT. Telescope name is obtained from the data.
If you wish to change the \texttt{fluxunit} (see below), by leaving the sub-parameter \texttt{telescopeparm}
unset (\texttt{telescopeparm=''}), it will use internal telescope parameters for flux conversion for the
data from AT telescopes and it will use an approximate aperture efficiency conversion for the GBT data. If you give `telescopeparm` a list, then if the list has a single float it is assumed to be the gain in Jy/K, if two or more elements they are assumed to be telescope diameter (m) and aperture efficiency respectively.

Note that `sdcal` assumes that the `fluxunit` is set correctly in the data already. If not, then set `telescopeparm='FIX'` and it will set the default units to `fluxunit` without conversion. **NOTE:** If the data in `infile` is an ms from GBT and the default flux unit is missing, this task automatically fixes the default `fluxunit` to 'K' before the conversion.

Two new `calmode`, `otf` and `otfraster`, are available. If you specify those modes, the task first try to define several scans near edge as OFF scans, then the data are calibrated using those OFF scans. Those modes are designed for OTF observations without explicit OFF scans. If the observing pattern is 'raster', you should use the 'otfraster' mode to calibrate data. Otherwise, the 'otf' mode should be used. For detail about edge marking, see online help of sd.edgemarker module.

**WARNING** for the GBT raw SDFITS format data as input: SDtasks are able to handle GBT raw SDFITS format (version 1.3) data since the data filler is available. However, the functionality is not well tested yet, so that there may be unknown bugs.

**Notes:**

- Direction information is not considered when data is averaged. Use `sdgrid` task if you want to take care of direction information when averaging.
- Calibration of frequency switching data is now fully implemented, including folding.
- Additional calibration algorithms are implemented. These are the 'Chopper-Wheel' calibration and the one adopted in APEX telescope (an advanced version of classical 'Chopper-Wheel' method).

### 8.2.1.2 `sdcal2`

**Keyword arguments:**

- `infile` -- Name of input SD dataset
- `calmode` -- Calibration mode. If you want to generate calibration table or apply existing calibration tables, set `calmode` to simple string. On the other hand, if you want to calibrate data on-the-fly, you have to set `calmode` to a composite `calmode` string separated by comma.
  - options: `ps`, `otf`, `otfraster`, `tsys`, `apply`
  - default: `ps`
  - example: Here is an example for composite `calmode`.
    - `ps,apply` (do sky cal and apply)
    - `ps,tsys,apply` (do sky and Tsys cal and apply)

```
>>> calmode expandable parameter
```

- `fraction` -- Edge marking parameter for 'otf' and
'otfraster'. specify a number of OFF scans as a fraction of
total number of data points.
default: '10%'
options: '20%' in string style or float value less
than 1.0 (e.g. 0.15).
'auto' is available only for 'otfraster'.
noff -- Edge marking parameter for 'otfraster'.
It is used to specify a number of OFF scans near
edge directly. Value of noff comes before setting
by fraction.
default: -1 (use fraction)
options: any positive integer
width -- Edge marking parameter for 'otf'.
Pixel width with respect to a median spatial
separation between neighboring two data in time.
Default will be fine in most cases.
default: 0.5
options: float value
elongated -- Edge marking parameter for 'otf'.
Set True only if observed area is elongated
in one direction.
default: False
tsysiflist -- List of IFNOs for Tsys calibration. It does
no effect if you don't want to do Tsys
calibration.
default: []
applytable -- List of sky/Tsys calibration tables you want to
apply.
default: ''
interp -- Interpolation method in time and frequency axis.
Set comma separated method strings if you want
to use different interpolation in time and
frequency.
options: 'linear', 'cspline', 'nearest',
any numeric string indicating an order
of polynomial.
default: '' (linear in time and frequency)
example: 'linear,cspline' (linear in time, cubic
spline in frequency)
'linear,3' (linear in time, third order
polynomial in frequency)
'nearest' (nearest in time and frequency)
ifmap -- Dictionary defining transfer of Tsys calibration.
Key must be IFNO for Tsys and its value must be
CHAPTER 8. SINGLE DISH DATA PROCESSING

a list of IFNOs for science target.
default: {}
example: {1: [5,6], 3: [7,8]}
Tsys in IFNO1 is transferred to IFNO5, 6
while Tsys in IFNO3 is to IFNO7, 8.

scanlist -- list of scan numbers to process
default: [] (use all scans)
example: [21,22,23,24]
this selection is in addition to field, iflist, and pollist

field -- selection string for selecting scans by name
default: '' (no name selection)
example: 'FLS3a*'
this selection is in addition to scanlist, iflist, and pollist

iflist -- list of IF id numbers to select
default: [] (use all IFs)
example: [15]
this selection is in addition to scanlist, field, and pollist

pollist -- list of polarization id numbers to select
default: [] (use all polarizations)
example: [1]
this selection is in addition to scanlist, field, and iflist

outfile -- Name of output file. If you omit, behavior of the task
depends on calmode. If calmode includes 'apply', then
omitting outfile indicates that infile is overwritten
by the calibrated data. In this case, you have to set
overwrite to True. If calmode doesn’t include 'apply,'
omitting outfile indicates that the task will use default
outfile name based on infile and predefined suffix
('_sky' for sky, '_tsys' for Tsys).

default: '' (<infile>_<suffix> for calibration
while overwrite infile for apply mode)

overwrite -- overwrite the output file if already exists
options: (bool) True,False
default: False

DESCRIPTION:

Task sdcal2 is an implementation of a calibration scheme like as interferometry, i.e., generate
caltables and apply them. Available calibration modes are 'ps', 'otf', 'otfraster', and 'tsys'. Those
modes generates caltables for sky or Tsys calibration. Those caltables can be applied to the data
by using calmode 'apply'. You can calibrate data on-the-fly like sdcal task by setting calmode to a
composite calmode string separated by comma. For example, calmode='ps,apply' means doing sky
calibration and apply it on-the-fly. In this case, caltable is generated as a temporary plain table
and will be deleted at the end.
There are several control parameters for sky/Tsys calibration and application of caltables. See the above parameter description.

8.2.1.3 sdsmooth

Keyword arguments:

infile -- name of input SD dataset
antenna -- antenna name or id (only effective for MS input).
scanaverage -- average integrations within scans
  options: (bool) True,False
  default: False
  example: if True, this happens in read-in
  For GBT, set False!
scanlist -- list of scan numbers to process
  default: [] (use all scans)
  example: [21,22,23,24]
  this selection is in addition to field, iflist, and pollist
field -- selection string for selecting scans by name
  default: '' (no name selection)
  example: 'FLS3a*' 
  this selection is in addition to scanlist, iflist, pollist
iflist -- list of IF id numbers to select
  default: [] (use all IFs)
  example: [15]
  this selection is in addition to scanlist, field, and pollist
pollist -- list of polarization id numbers to select
  default: [] (use all polarizations)
  example: [1]
  this selection is in addition to scanlist, field, and iflist
kernel -- type of spectral smoothing
  options: 'hanning','gaussian','boxcar','regrid'
  default: 'hanning'

>>>kernel expandable parameter

kwidth -- width of spectral smoothing kernel
  options: (int) in channels
  default: 5
  example: 5 or 10 seem to be popular for boxcar
  ignored for hanning (fixed at 5 chans)
  (0 will turn off gaussian or boxcar)
chanwidth -- channel width of regridded spectra
  default: '5' (in channels)
  example: '500MHz', '0.2km/s'
CHAPTER 8. SINGLE DISH DATA PROCESSING

verify -- verify the results of smoothing
  options: (bool) True,False
  default: False
  WARNING: Currently this just asks whether you accept
           the displayed smoothing and if not, continues
           without smoothing.
  Note: verification is not yet available for kernel='regrid'
outfile -- Name of output ASAP format(scantable) file
  default: '' (<infile>_sm)
outform -- format of output file
  options: 'ASCII','SDFITS','MS','ASAP'
  default: 'ASAP'
  example: the ASAP format is easiest for further sd
            processing; use MS for CASA imaging.
            If ASCII, then will append some stuff to
            the outfile name
overwrite -- overwrite the output file if already exists
  options: (bool) True,False
  default: False
  WARNING: if outform='ASCII', this parameter is ignored
plotlevel -- control for plotting of results
  options: (int) 0=none, 1=some, 2=more, <0=hardcopy
  default: 0 (no plotting)
  example: plotlevel<0 as abs(plotlevel), e.g.
           -1 => hardcopy of final plot (will be named
            <outfile>_smspec.eps)

DESCRIPTION:

Task sdsMOOTH performs smoothing of the single-dish spectra. Set plotlevel >= 1 to plot the
spectrum before and after smoothing.

See the sdCAL description for note on GBT raw SDFITS format data.

8.2.1.4 sdbaseline

Keyword arguments:
infile -- name of input SD dataset
antenna -- antenna name or id (only effective for MS input).
fluxunit -- units for line flux
  options: 'K','Jy',''
  default: '' (keep current fluxunit)
  WARNING: For GBT data, see description below.
>>> fluxunit expandable parameter
telescopeparm -- the telescope characteristics
options: (str) name or (list) list of gain info
default: '' (none set)
example: if telescopeparm='', it tries to get the telescope
name from the data.
Full antenna parameters (diameter,ap.eff.) known
to ASAP are
'ATPKSMB', 'ATPKSHOH', 'ATMOPRA', 'DSS-43',
'CEDUNA','HOBART'. For GBT, it fixes default fluxunit
to 'K' first then convert to a new fluxunit.
telescopeparm=[104.9,0.43] diameter(m), ap.eff.
telescopeparm=[0.743] gain in Jy/K
telescopeparm='FIX' to change default fluxunit
see description below

specunit -- units for spectral axis
options: (str) 'channel','km/s','GHz','MHz','kHz','Hz',''
default: '' (=current)
example: this will be the units for masklist

>>> specunit expandable parameters
restfreq -- rest frequency
available type includes float, int, string, list of float,
list of int, list of string, and list of dictionary. the
default unit of restfreq in case of float, int, or string
without unit is Hz. string input can be a value only
(treated as Hz) or a value followed by unit for which 'GHz',
'MHz','kHz',and 'Hz' are available.
a list can be used to set different rest frequencies for
each IF. the length of list input must be nIF. dictionary
input should be a pair of molecule name and frequency with
keys of 'name' and 'value', respectively. values in the
dictionary input follows the same manner as for single
float or string input.
example: 345.796
   '1420MHz'
   [345.8, 347.0, 356.7]
   ['345.8MHz', '347.0MHz', '356.7MHz']
   [{'name':'CO','value':345}]
frame -- frequency frame for spectral axis
options: (str) 'LSRK','REST','TOPO','LSRD','BARY',
'GEO','GALACTO','LGROUP','CMB'
default: currently set frame in scantable
WARNING: frame='REST' not yet implemented
doppler -- doppler mode
options: (str) 'RADIO','OPTICAL','Z','BETA','GAMMA'
default: currently set doppler in scantable
scanlist -- list of scan numbers to process
CHAPTER 8. SINGLE DISH DATA PROCESSING

default: [] (use all scans)
example: [21,22,23,24]
this selection is in addition to field, iflist, and pollist

field -- selection string for selecting scans by name
default: '' (no name selection)
example: 'FLS3a*'
this selection is in addition to scanlist, iflist, and pollist

iflist -- list of IF id numbers to select
default: [] (use all IFs)
example: [15]
this selection is in addition to scanlist, field, and pollist

pollist -- list of polarization id numbers to select
default: [] (use all polarizations)
example: [1]
this selection is in addition to scanlist, field, and iflist

tau -- atmospheric optical depth
default: 0.0 (no correction)

masklist -- list or string of mask regions to INCLUDE in BASELINE fit
a string masklist allows per IF selection of channels.
default: [] (entire spectrum)
example: [[1000,3000],[5000,7000]]
'0:1000~3000;5000~7000, 1:200~350;450~600'
when maskmode is 'auto' or 'interact', this mask
will be applied first before fitting as base mask

maskmode -- mode of setting additional channel masks
options: (str) 'auto','list','interact'
default: 'auto'
example: maskmode='auto' runs linefinder to detect line regions
to be excluded from fitting. this mode requires three
expandable parameters: thresh, avg_limit, and edge.
USE WITH CARE! May need to tweak the expandable parameters.
maskmode='list' uses the given masklist only: no additional
masks applied.
maskmode='interact' allows users to manually modify the
mask regions by dragging mouse on the spectrum plotter GUI.
use LEFT or RIGHT button to add or delete regions,
respectively.

>>> maskmode expandable parameters
thresh -- S/N threshold for linefinder
default: 5
example: a single channel S/N ratio above which the channel is
considered to be a detection

avg_limit -- channel averaging for broad lines
default: 4
example: a number of consecutive channels not greater than
this parameter can be averaged to search for broad lines
edge -- channels to drop at beginning and end of spectrum
default: 0
type: [int]
example: [1000] drops 1000 channels at beginning AND end
[1000,500] drops 1000 from beginning and 500 from end
Note: For bad baselines threshold should be increased,
and avg_limit decreased (or even switched off completely by
setting this parameter to 1) to avoid detecting baseline
undulations instead of real lines.

blfunc -- baseline model function
options: (str) 'poly','chebyshev','cspline','sinusoid'
default: 'poly'
example: blfunc='poly' uses a single polynomial line of
any order which should be given as an expandable
parameter 'order' to fit baseline.
blfunc='chebyshev' uses Chebyshev polynomials.
blfunc='cspline' uses a cubic spline function, a piecewise
polynomial having C2-continuity (i.e., the second
derivative is continuous at the joining points).
blfunc='sinusoid' uses a combination of sinusoidal curves.

>>> blfunc expandable parameters

order -- order of baseline polynomial
options: (int) (<0 turns off baseline fitting)
default: 5
example: typically in range 2-9 (higher values
seem to be needed for GBT)

npiece -- number of the element polynomials of cubic spline curve
options: (int) (<0 turns off baseline fitting)
default: 2

applyfft -- automatically set wave numbers of sinusoidal functions
for fitting by applying some method like FFT.
options: (bool) True, False
default: True

fftmethod -- method to be used when applyfft=True. Now only
'fft' is available and it is the default.

fftthresh -- threshold to select wave numbers to be used for
sinusoidal fitting. both (float) and (str) accepted.
given a float value, the unit is set to sigma.
for string values, allowed formats include:
'xsigma' or 'x' (= x-sigma level. e.g., '3sigma'), or
'topx' (= the x strongest ones, e.g. 'top5').
default is 3.0 (unit: sigma).

addwn -- additional wave number(s) of sinusoids to be used
for fitting.
(list) and (int) are accepted to specify every wave numbers. also (str) can be used in case you need to specify wave numbers in a certain range, e.g., 'a-b' (= a, a+1, a+2, ..., b-1, b), '<a' (= 0,1,...,a-2,a-1), '>=a' (= a, a+1, ... up to the maximum wave number corresponding to the Nyquist frequency for the case of FFT).

default: []
rejwn -- wave number(s) of sinusoid NOT to be used for fitting.
can be set just as addwn but has higher priority:
wave numbers which are specified both in addwn and rejwn will NOT be used.
default: []
clipthresh -- clipping threshold for iterative fitting
default: 3
clipniter -- maximum iteration number
default: 0 (no iteration, i.e., no clipping)
verify -- verify the results of baseline fitting
options: (bool) True,False
default: False
NOTE: Currently available only when blfunc='poly'
WARNING: Currently this just asks whether you accept the displayed fit and if not, continues without doing any baseline fit.
verbose -- output fitting results to logger
default: True
example: If False, the fitting results including coefficients, residual rms, etc., are not output to the CASA logger, while the processing speed gets faster
bloutput -- output fitting results to a text file
default: True
example: If False, the fitting results including coefficients, residual rms, etc., are not output to a text file (<outfile>_blparam.txt), while the processing speed gets faster
blformat -- format of the logger output and text file specified with bloutput
options: '', 'csv'
default:'' (same as in the past, easy to read but huge)
showprogress -- show progress status for large data
default: True
minnrow -- minimum number of input spectra to show progress status
default: 1000
outfile -- Name of output file
default: '' (<infile>_bs)
CHAPTER 8. SINGLE DISH DATA PROCESSING

outform -- format of output file
options: 'ASCII','SDFITS','MS','ASAP'
default: 'ASAP'
example: the ASAP format is easiest for further sd processing; use MS for CASA imaging.
If ASCII, then will append some stuff to the outfile name

overwrite -- overwrite the output file if already exists
options: (bool) True,False
default: False
WARNING: if outform='ASCII', this parameter is ignored

plotlevel -- control for plotting of results
options: (int) 0=none, 1=some, 2=more, <0=hardcopy
default: 0 (no plotting)
example: plotlevel<0 as abs(plotlevel), e.g.
-1 => hardcopy of final plot (will be named <outfile>_bspec.eps)
WARNING: be careful plotting in fsotf mode!

DESCRIPTION:

Task sdbaseline performs baseline fitting/removal for single-dish spectra. The fit parameters, terms and rms of baseline are saved to an ASCII file, <outfile>_blparam.txt.

See the sdcal description for information on fluxunit conversion and the telescopeparm parameter. Also, see the sdcal description for note on GBT raw SDFITS format data.

By setting maskmode='interact', you can set/unset mask regions interactively using mouse buttons. Current mask regions will be shown with yellow shading. Baseline fit parameters and rms of fitted spectra are saved to an ASCII file, <outfile>_blparam.txt, when verbose=True.

The parameter masklist accepts per IF selection of mask regions. See §2.3.3.1 for details. Note, the mask regions should be specified in unit of specunit in this task.

Available functions for baseline subtraction include polynomial, Chebyshev polynomials, cubic spline, and sinusoid. Also, iterative n-σ clipping becomes available with cubic spline and sinusoid.

R4.1 New Features:

- Speed-up: sdbaseline gets 2-10 times faster than in CASA 4.0. The degree of speed-up depends on blfunc, its parameters and the size of spectra (nchan).
- Iterative clipping now available for all of blfunc. You can specify clipthresh and clipniter in case blfunc = 'poly' also.
8.2.1.5  sdreduce

Keyword arguments:
infile -- name of input SD dataset
antenna -- antenna name or id (only effective for MS input).
fluxunit -- units for line flux
   options: 'K','Jy',''
   default: '' (keep current fluxunit)
WARNING: For GBT data, see description below.
>>> fluxunit expandable parameter
telescopeparm -- the telescope characteristics
   options: (str) name or (list) list of gain info
   default: '' (none set)
example: if telescopeparm='', it tries to get the telescope
   name from the data.
   Full antenna parameters (diameter,ap.eff.) known
to ASAP are
   'ATPKSMB', 'ATPKSHOH', 'ATMOPRA', 'DSS-43',
   'CEDUNA','HOBART'. For GBT, it fixes default fluxunit
to 'K' first then convert to a new fluxunit.
telescopeparm=[104.9,0.43] diameter(m), ap.eff.
telescopeparm=[0.743] gain in Jy/K
   telescopeparm='FIX' to change default fluxunit
see description below
specunit -- units for spectral axis
   options: (str) 'channel','km/s','GHz','MHz','kHz','Hz',''
   default: '' (=current)
example: this will be the units for masklist
>>> specunit expandable parameters
restfreq -- rest frequency
   available type includes float, int, string, list of float,
   list of int, list of string, and list of dictionary. the
   default unit of restfreq in case of float, int, or string
   without unit is Hz. string input can be a value only
   (treated as Hz) or a value followed by unit for which 'GHz',
   'MHz','kHz',and 'Hz' are available.
   a list can be used to set different rest frequencies for
   each IF. the length of list input must be nIF. dictionary
   input should be a pair of molecule name and frequency with
   keys of 'name' and 'value', respectively. values in the
   dictionary input follows the same manner as for single
   float or string input.
example: 345.796
   '1420MHz'
   [345.8, 347.0, 356.7]
CHAPTER 8. SINGLE DISH DATA PROCESSING

[['345.8MHz', '347.0MHz', '356.7MHz']
[{'name': 'CO', 'value': 345}]

frame -- frequency frame for spectral axis
options: (str) 'LSRK', 'REST', 'TOPO', 'LSRD', 'BARY', 'GEO', 'GALACTO', 'LGROUP', 'CMB'
default: currently set frame in scantable
WARNING: frame='REST' not yet implemented
doppler -- doppler mode
options: (str) 'RADIO', 'OPTICAL', 'Z', 'BETA', 'GAMMA'
default: currently set doppler in scantable
calmode -- calibration mode
options: 'ps', 'nod', 'fs', 'fsotf', 'quotient', 'none'
default: 'none'
example: choose mode 'none' if you have already calibrated and want to try baselines or averaging
scanlist -- list of scan numbers to process
default: [] (use all scans)
example: [21,22,23,24]
this selection is in addition to field, iflist, and pollist
field -- selection string for selecting scans by name
default: '' (no name selection)
example: 'FLS3a*'
this selection is in addition to scanlist, iflist, and pollist
iflist -- list of IF id numbers to select
default: [] (use all IFs)
example: [15]
this selection is in addition to scanlist, field, and pollist
pollist -- list of polarization id numbers to select
default: [] (use all polarizations)
example: [1]
this selection is in addition to scanlist, field, and iflist
channelrange -- channel range selection
default: [] (use all channel)
example: [0,5000]
Note that specified values are recognized as 'channel' regardless of the value of specunit
average -- averaging on spectral data
options: (bool) True, False
default: False

>>> average expandable parameter
scanaverage -- average integrations within scans
options: (bool) True, False
default: False
example: if True, this happens in read-in
For GBT, set False!

timeaverage -- average times for multiple scan cycles
options: (bool) True, False
default: False
example: if True, this happens after calibration
tweight -- weighting for time average
options: 'none'
  'var' (1/var(spec) weighted)
  'tsys' (1/Tsys**2 weighted)
  'tint' (integration time weighted)
  'tintsys' (Tint/Tsys**2)
  'median' (median averaging)
default: 'none'
averageall -- average multi-resolution spectra
spectra are averaged by referring
their frequency coverage
default: False
polaverage -- average polarizations
options: (bool) True, False
default: False
pweight -- weighting for polarization average
options: 'none'
  'var' (1/var(spec) weighted)
  'tsys' (1/Tsys**2 weighted)

tau -- atmospheric optical depth
default: 0.0 (no correction)
kernell -- type of spectral smoothing
options: 'none', 'hanning', 'gaussian', 'boxcar', 'regrid'
default: 'none' (no smoothing)

>>>kernel expandable parameter
kwidth -- width of spectral smoothing kernel
options: (int) in channels
default: 5
example: 5 or 10 seem to be popular for boxcar
  ignored for hanning (fixed at 5 chans)
  (0 will turn off gaussian or boxcar)
chanwidth -- channel width of regridded spectra
default: '5' (in channels)
example: '500MHz', '0.2km/s'
masklist -- list or string of mask regions to INCLUDE in BASELINE fit
  a string masklist allows per IF selection of channels.
default: [] (entire spectrum)
example: \([[[1000,3000],[5000,7000]]
\)
\('0:1000~3000;5000~7000, 1:200~350;450~600'\)
when maskmode is 'auto' or 'interact', this mask
will be applied first before fitting as base mask

maskmode -- mode of setting additional channel masks for baselining
options: (str) 'auto','list','interact'
default: 'auto'
example: maskmode='auto' runs linefinder to detect line regions
to be excluded from fitting. this mode requires three
expandable parameters: thresh, avg_limit, and edge.
USE WITH CARE! May need to tweak the expandable parameters.
maskmode='list' uses the given masklist only:
o no additional masks applied.
maskmode='interact' allows users to manually modify the
mask regions by dragging mouse on the spectrum plotter GUI.
use LEFT or RIGHT button to add or delete regions, respectively.

>>> maskmode expandable parameters
thresh -- S/N threshold for linefinder
default: 5
tiff example: a single channel S/N ratio above which the channel is
considered to be a detection
avg_limit -- channel averaging for broad lines
default: 4
tiff example: a number of consecutive channels not greater than
this parameter can be averaged to search for broad lines
edge -- channels to drop at beginning and end of spectrum
default: 0
tiff example: [1000] drops 1000 channels at beginning AND end
[1000,5000] drops 1000 from beginning and 500 from end

Note: For bad baselines threshold should be increased,
and avg_limit decreased (or even switched off completely by
setting this parameter to 1) to avoid detecting baseline
undulations instead of real lines.

blfunc -- baseline model function
options: (str) 'none','poly','chebyshev','cspline','sinusoid'
default: 'none' (no baselining)
example: blfunc='poly' uses a single polynomial line of
any order which should be given as an expandable
blfunc='chebyshev' uses Chebyshev polynomials.
pparameter 'order' to fit baseline.
blfunc='cspline' uses a cubic spline function, a piecewise
cubic polynomial having C2-continuity (i.e., the second derivative is continuous at the joining points).
blfunc='sinusoid' uses a combination of sinusoidal curves.

>>> blfunc expandable parameters
order -- order of baseline polynomial
  options: (int) (<0 turns off baseline fitting)
  default: 5
  example: typically in range 2-9 (higher values seem to be needed for GBT)
npiece -- number of the element polynomials of cubic spline curve
  options: (int) (<0 turns off baseline fitting)
  default: 2
applyfft -- automatically set wave numbers of sinusoidal functions for fitting by applying some method like FFT.
  options: (bool) True, False
  default: True
fftmethod -- method to be used when applyfft=True. Now only 'fft' is available and it is the default.
fftthresh -- threshold to select wave numbers to be used for sinusoidal fitting. both (float) and (str) accepted.
given a float value, the unit is set to sigma.
for string values, allowed formats include:
  'xsigma' or 'x' (= x-sigma level. e.g., '3sigma'), or
  'topx' (= the x strongest ones, e.g. 'top5').
  default is 3.0 (unit: sigma).
addwn -- additional wave number(s) of sinusoids to be used for fitting.
  (list) and (int) are accepted to specify every wave numbers. also (str) can be used in case you need to specify wave numbers in a certain range, e.g., 'a-b' (= a, a+1, a+2, ..., b-1, b), '<a' (= 0,1,...,a-2,a-1), '>=a' (= a, a+1, ... up to the maximum wave number corresponding to the Nyquist frequency for the case of FFT).
  default: []
rejwn -- wave number(s) of sinusoid NOT to be used for fitting. can be set just as addwn but has higher priority: wave numbers which are specified both in addwn and rejwn will NOT be used.
  default: []
clipthresh -- clipping threshold for iterative fitting
  default: 3
clipniter -- maximum iteration number
  default: 0 (no iteration, i.e., no clipping)
verifycal -- verify the results of calibration  
options: (bool) True,False  
default: False  
WARNING: Currently verifying parameters just asks whether you accept the displayed calibration/fit and if not, continues without doing any calibration/baseline fit.

verifysm -- verify the results of smoothing  
options: (bool) True,False  
default: False

verifybl -- verify the results of baseline fitting  
options: (bool) True,False  
default: False  
NOTE: Currently available only when blfunc='poly'

verbosebl -- output fitting results to logger  
default: True  
example: If False, the fitting results including coefficients, residual rms, etc., are not output to the CASA logger, while the processing speed gets faster

bloutput -- output fitting results to a text file  
default: True  
example: If False, the fitting results including coefficients, residual rms, etc., are not output to a text file (<outfile>_blparam.txt), while the processing speed gets faster

blformat -- format of the logger output and text file specified with bloutput  
options: '', 'csv'  
default: '' (same as in the past, easy to read but huge)

showprogress -- show progress status for large data  
default: True

minnrow -- minimum number of input spectra to show progress status  
default: 1000

outfile -- Name of output file  
default: '' (<infile>_cal)

outform -- format of output file  
options: 'ASCII','SDFITS','MS','ASAP'  
default: 'ASAP'  
example: the ASAP format is easiest for further sd processing; use MS for CASA imaging. If ASCII, then will append some stuff to the outfile name

overwrite -- overwrite the output file if already exists  
options: (bool) True,False  
default: False  
WARNING: if outform='ASCII', this parameter is ignored
plotlevel -- control for plotting of results
  options: (int) 0=none, 1=some, 2=more, <0=hardcopy
  default: 0 (no plotting)
  example: plotlevel<0 as abs(plotlevel), e.g.
    -1 => hardcopy of final plot (will be named
      <outfile>_calspec.eps)
  WARNING: be careful plotting in fsotf mode!

DESCRIPTION:

Task \texttt{sdreduce} performs data selection, calibration, and/or spectral baseline fitting for single-dish spectra. This task internally calls the tasks \texttt{sdcal}, \texttt{sdsmooth}, and \texttt{sdbaseline}, and it can be used to run all the three steps in one task execution. By setting \texttt{calmode=none} one can run \texttt{sdreduce} on already calibrated data for further selection, averaging and atmospheric optical depth correction. To save the output spectra within a certain range of channels, you set the range in \texttt{channelrange}.

If you give multiple IFs in \texttt{iflist}, then your scantable will have multiple IFs by default. Averaging of multi-resolution (multi-IFs) spectra can be achieved by setting a sub-parameter of \texttt{average}, \texttt{averageall}, to True. It handles multi-IFs by selecting overlaps in frequency coverages and assigning new IFs in the output spectra.

See the \texttt{sdcal} description for information on the \texttt{fluxunit} conversion and the \texttt{telescopeparm} parameter. Also, see the \texttt{sdcal} description for note on GBT raw SDFITS format data.

The \texttt{verifycal}, \texttt{verifysm}, and \texttt{verifybl} parameters correspond to parameter \texttt{verify} in \texttt{sdcal}, \texttt{sdsmooth}, and \texttt{sdbaseline}, respectively.

The parameter \texttt{masklist} accepts per IF selection of mask regions. See §2.3.3.1 for details. Note, the mask regions should be specified in unit of \texttt{specunit} in this task.

\subsection{sdcoadd}

Keyword arguments:

\begin{itemize}
  \item \texttt{infiles} -- list of names of input SD dataset
  \item \texttt{antenna} -- antenna name or id (only effective for MS input).
  \item \texttt{fluxunit} -- units for line flux
    \begin{itemize}
      \item options: 'K','Jy',''
      \item default: '' (keep current fluxunit of the first data in the infiles)
    \end{itemize}
\end{itemize}

>>> fluxunit expandable parameter

\begin{itemize}
  \item \texttt{telescopeparm} -- the telescope characteristics
    \begin{itemize}
      \item options: (str) name or (list) list of gain info
      \item default: '' (none set)
      \item example: if \texttt{telescopeparm=''}, it tries to get the telescope name from the data.
        Full antenna parameters (diameter,ap.eff.) known to ASAP are
'ATPKSMB', 'ATPKSHOH', 'ATMOPRA', 'DSS-43', 'CEDUNA', 'HOBART'. For GBT, it fixes default fluxunit to 'K' first then convert to a new fluxunit. telescopeparm=[104.9,0.43] diameter(m), ap.eff. telescopeparm=[0.743] gain in Jy/K telescopeparm='FIX' to change default fluxunit see description below

specunit -- units for spectral axis
options: (str) 'channel', 'km/s', 'GHz', 'MHz', 'kHz', 'Hz'
default: '' (=current)
example: this will be the units for masklist

frame -- frequency frame for spectral axis
options: (str) 'LSRK', 'REST', 'TOPO', 'LSRD', 'BARY', 'GEO', 'GALACTO', 'LGROUP', 'CMB'
default: currently set frame in scantable
WARNING: frame='REST' not yet implemented

doppler -- doppler mode
options: (str) 'RADIO', 'OPTICAL', 'Z', 'BETA', 'GAMMA'
default: currently set doppler in scantable

scanaverage -- average integrations within scans
options: (bool) True, False
default: False
example: if True, this happens in read-in
For GBT, set False!

timeaverage -- average times for multiple scan cycles
options: (bool) True, False
default: False
example: if True, this happens after calibration

>>>timeaverage expandable parameter
tweight -- weighting for time average
options: 'none'
'var' (1/var(spec) weighted)
'tsys' (1/Tsys**2 weighted)
'tint' (integration time weighted)
'tintsys' (Tint/Tsys**2)
'median' (median averaging)
default: 'none'

polaverage -- average polarizations
options: (bool) True, False
default: False

>>>polaverage expandable parameter
CHAPTER 8. SINGLE DISH DATA PROCESSING

pweight -- weighting for polarization average
options: 'none'
'var' (1/var(spec) weighted)
'tsys' (1/Tsys**2 weighted)
default: 'none'

outfile -- Name of output file
default: '' (scantable)
example:
outform -- format of output file
options: 'ASCII','SDFITS','MS','ASAP'
default: 'ASAP'
example: the ASAP format is easiest for further sd
processing; use MS for CASA imaging.
overwrite -- overwrite the output file if already exists
options: (bool) True,False
default: False
WARNING: if outform='ASCII', this parameter is ignored

DESCRIPTION:

Task `sdcoadd` merges multiple single dish spectral data given by a list of spectral data file names in any of the following formats, ASAP, MS2, and SDFITS. The units of line flux, the units of spectral axis, frame, and doppler are assumed to be those of the first one in the `infiles` if not specified. The `timaverage` and `polaverage` are used to perform time and polarization averaging over scans on the merged scantable to obtained co-added spectra before saving to a file on disk.

See the `sdcal` description for note on GBT raw SDFITS format data.

8.2.1.7 sdflag

Keyword arguments:

infile -- name of input SD dataset
antenna -- antenna name or id (only effective for MS input).
specunit -- units for spectral axis
options: (str) 'channel','km/s','GHz','MHz','kHz','Hz',''
default: '' (=current)
example: this will be the units for maskflag
>>> specunit expandable parameters
restfreq -- rest frequency
available type includes float, int, string, list of float, list of int, list of string, and list of dictionary. the
default unit of restfreq in case of float, int, or string
without unit is Hz. string input can be a value only (treated as Hz) or a value followed by unit for which 'GHz', 'MHz', 'kHz', and 'Hz' are available.
a list can be used to set different rest frequencies for each IF. the length of list input must be nIF. dictionary input should be a pair of molecule name and frequency with keys of 'name' and 'value', respectively. values in the dictionary input follows the same manner as for single float or string input.
example: 345.796
'1420MHz'
[345.8, 347.0, 356.7]
['345.8MHz', '347.0MHz', '356.7MHz']
[{'name': 'CO', 'value': 345}]

frame -- frequency frame for spectral axis
options: (str) 'LSRK', 'REST', 'TOPO', 'LSRD', 'BARY', 'GEO', 'GALACTO', 'LGROUP', 'CMB'
default: currently set frame in scantable
WARNING: frame='REST' not yet implemented
doppler -- doppler mode
options: (str) 'RADIO', 'OPTICAL', 'Z', 'BETA', 'GAMMA'
default: currently set doppler in scantable
scanlist -- list of scan numbers to process
default: [] (use all scans)
example: [21, 22, 23, 24]
this selection is in addition to field and iflist
field -- selection string for selecting scans by name
default: '' (no name selection)
example: 'FLS3a*
this selection is in addition to scanlist, iflist, and pollist
iflist -- list of IF id numbers to select
default: [] (use all IFs)
example: [15]
this selection is in addition to scanlist, field, and pollist
pollist -- list of polarization id numbers to select
default: [] (use all polarizations)
example: [1]
this selection is in addition to scanlist, field, and pollist
maskflag -- list of mask regions to apply flag/unflag
Note, this parameter is ignored if one or more rows are given in flagrow, or clip=True.
default: [] (entire spectrum)
example: [[1000, 3000], [5000, 7000]]
flagrow -- list of row numbers to apply flag/unflag
Note, this parameter is effective only when one or more row
numbers are given explicitly and also clip=False
default: [] (no row selection)
example: [0, 2, 3]

clip -- flag data that are outside a specified range
options: (bool)True,False
default: False

>>> clip expandable parameters
clipminmax -- range of data that will NOT be flagged
default: [] means do not use clip option
example: [0.0,1.5]
clipoutside -- clip OUTSIDE the range ?
options: (bool)True,False
default: True
text: clipoutside=False means flag data WITHIN the range.

flagmode -- flag mode
default: 'flag'
options: 'flag','unflag'

interactive -- determines interactive flagging
options: (bool) True,False
default: False

>>> interactive expandable parameters
showflagged -- show flagged data on plots
default: False

outfile -- Name of output file
default: ''

Note: by default (outfile=''), actual output file name is set as follows:
(1) if overwrite=True (default), infile (input) will be overwritten.
   WARNING: If the formats of input and output files are different,
   this causes complete loss of input file.
(2) if overwrite=False, outfile will be <infile>_f.

outform -- format of output file
options: 'ASCII','SDFITS','MS','ASAP'
default: 'ASAP'

example: the ASAP format is easiest for further sd
   processing; use MS for CASA imaging.
   WARNING: Be sure outform is same as the input file format when you
   overwrite the input file by overwrite=True and outfile='' (default).

overwrite -- overwrite the output file if already exists
options: (bool) True,False
default: True

WARNING: input file is overwritten if overwrite=True and outfile='' (default).
   This causes the complete loss of input file if the formats of
   input and output files are different.

plotlevel -- control for plotting of results
options: (int) 0=none, 1=some, 2=more, <0=hardcopy
default: 0 (no plotting)
example: plotlevel<0 as abs(plotlevel), e.g.
-1 => hardcopy of final plot (will be named <outfile>_flag.eps)
WARNING: be careful plotting in fsotf mode!

DESCRIPTION:
Task sdflag performs both interactive and non-interactive channel/row based flagging on spectra. Currently, the available ways of non-interactive flagging include: (1) channel based flagging by specifying a range of spectral values with clip=True, (2) row based flagging by specifying a list of row numbers to the flagrow parameter, and (3) channel based flagging by specifying regions in channel to the maskflag parameter. These three ways of flagging can not be executed simultaneously. If more than one parameter above are specified, the task looks for them in the above order and operates the first specified way of flagging operation.

Interactive flagging is available when interactive=True. The available ways of interactive flagging include: (1) row based flagging by selecting 'panel' and (2) channel based flagging by selecting 'region's of channels on Flag plotter. Note that the Flag plotter is loaded after carrying out the non-interactive flag operation if any specified. See the following instruction for details of how to select channel regions and spectra on the plotter.

If plotlevel ≥ 1, the task asks you if you really apply the flags before it is actually written to the data with a plot indicating flagged regions. Please note that this task is still experimental.

WARNING for overwrite option:
Be sure outform is the same as data format of input file when you overwrite it. Since CASA 3.1, the default value of the option overwrite has been changed to True, thereby the current dataset (infile) is overwritten unless a different file name is set to outfile. There is a known issue in overwriting infile. If outform differs to the data format of infile, the data is overwritten with the new data format (specified by outform) and the data in the original format will be lost.

See the sdcal description for note on GBT raw SDFITS format data.

Interactive flag operations on the Flag plotter
When sdflag is executed with interactive=True, interactive flag operation is available on a plotter, Flag Plotter, as shown in Figure 8.2. Flag Plotter uses the matplotlib plotting library to display its plots. You can find information on matplotlib at http://matplotlib.sourceforge.net/. Note the plotter is loaded after non-interactive flag operation, if any of maskflag, flagrow, or clip is specified.

The Flag Plotter has two rows of buttons at the bottom to control its operation – in particular, to determine flagging and unflagging behaviors. When no button in the toolbar is depressed, the Flag Plotter is in spectral value mode. Click on a spectrum to select it and drag the mouse to print the spectral value at the channel position of mouse. The value is printed to the bottom right corner of plotter window.
Figure 8.2: The **Flag plotter**. The **bottom set of buttons** are the standard matplotlib toolbar. See the caption of Figure 3.4 for detailed descriptions. The **upper set of buttons in the lower left** are: 1) **region**. Press this to begin marking regions (rather than zooming or panning). 2) **panel**. Press this to begin marking panels to select the whole spectrum. 3,4,5,6) **clear, flag, unflag, statistics**. Click on these to clear, flag, unflag, or calculate statistics of the data within the marked regions and spectra. 7) **notation**. Press this to begin editing notes on the plotter. 8,9) +, −. Click to move to the next or previous page in a series of iterated plots. The page counter on their left shows the current page number. Finally, the **Quit** is on the bottom right.

The buttons on the lower row are the standard matplotlib navigation buttons. See §3.3.2.1 about details of their capabilities.

In a row above it, there are a set of the other buttons (left to right):

- **region** — If depressed lets you mark channel regions in the panels. This is done by left-clicking the mouse twice at start and end channels of a region to mark. The marked regions are indicated with gray boxes. Clicking the button again will un-depress it and go back to the default spectral value mode. You can Mark multiple regions before doing something.

- **panel** — If depressed lets you mark spectra in the panels. This is done by left-clicking the mouse on panels you want to mark the whole spectrum. The marked panels are colored in gray. Clicking the button again will un-depress it and go back to the default spectral value mode. You can Mark multiple spectra before doing something.
• clear — Click this to forget marked regions and spectra.

• flag — Click this to Flag the points in marked regions and spectra.

• unflag — Click this to Unflag any flagged point that would be in marked regions and spectra (even if invisible).

• statistics — Click this to print out statics of marked regions and spectra to the logger.

• notation — If depressed lets you edit texts on the plotter. Clicking the button again will un-depress it and go back to the default spectral value mode. See §8.2.1.14 for details.

• + and − — Step to the next or previous plot in an iteration. The page counter on their left shows the current page number.

• Quit — Click this to close Flag Plotter.

To operate flagging and unflagging interactively, press region button (which will appear to depress), then mark channel regions by left-clicking the mouse at start and end channels of the region (each selection will add an additional region), and/or press panel button (which will appear to depress), then mark spectra by left-clicking on their panels (each selection will add an additional spectrum). You can get rid of all your regions and spectra by clicking clear button. Once regions and spectra are marked, click on one of flag, unflag, and statistics button to take the action.

8.2.1.8 sdflagmanager

Keyword arguments:
infile -- Name of input SD dataset
default: ''. example: infile='ngc5921.asap'
mode -- Flag version operation
default: 'list'; to list existing flagtables
'save' will save flag column from infile to a specified flag file
'restore' will place the specified flag file into infile
'delete' will delete specified flag file
'rename' will rename a specified flag file

>>> mode expandable parameters
versionname -- Flag version name
default: none; example: versionname='original_data'
No imbedded blanks in the versionname
comment -- Short description of a versionname, when mode is 'save'
or 'rename'
default: ''; example: comment='Clip above 1.85'
comment = versionname
oldname -- When mode='rename', the flag file to rename
merge -- Merge operation
DESCRIPTION:

These flag version files are copies of the flag column for a Measurement Set. They can be restored to the data set to obtain a previous flag version. It is wise to save a flag version at the beginning or after serious editing.

8.2.1.9 sdfit

Keyword arguments:

infile -- name of input SD dataset
  default: none - must input file name
  example: 'mysd.asap'
  See sdreduce for allowed formats.

antenna -- antenna name or id (only effective for MS input).

fluxunit -- units for line flux
  options: (str) 'K','Jy',''
  default: '' (keep current fluxunit)
  WARNING: For GBT data, see description below.

>>> fluxunit expandable parameter

  telescopeparm -- the telescope characteristics
    options: (str) name or (list) list of gain info
    default: '' (none set)
  example: if telescopeparm='', it tries to get the telescope name from the data.
    Full antenna parameters (diameter,ap.eff.) known to ASAP are
    'ATPKSMB', 'ATPKSHOH', 'ATMOPRA', 'DSS-43',
    'CEDUNA','HOBART'. For GBT, it fixes default fluxunit to 'K' first then convert to a new fluxunit.
  telescopeparm=[104.9,0.43] diameter(m), ap.eff.
  telescopeparm=[0.743] gain in Jy/K
  telescopeparm='FIX' to change default fluxunit
  see description below

 specunit -- units for spectral axis
  options: (str) 'channel','km/s','GHz','MHz','kHz','Hz',''
  default: '' (=current)
  example: this will be the units for maskline

>>> specunit expandable parameters

  restfreq -- rest frequency
    available type includes float, int, string, list of float,
    list of int, list of string, and list of dictionary. the
default unit of restfreq in case of float, int, or string without unit is Hz. String input can be a value only (treated as Hz) or a value followed by unit for which 'GHz', 'MHz', 'kHz', and 'Hz' are available.

A list can be used to set different rest frequencies for each IF. The length of list input must be nIF. Dictionary input should be a pair of molecule name and frequency with keys of 'name' and 'value', respectively. Values in the dictionary input follow the same manner as for single float or string input.

Example: 345.796

'1420MHz'

[345.8, 347.0, 356.7]

['345.8MHz', '347.0MHz', '356.7MHz']

[{'name': 'CO', 'value': 345}]

Frame -- Frequency frame for spectral axis
Options: (str) 'LSRK', 'REST', 'TOPO', 'LSRD', 'BARY', 'GEO', 'GALACTIC', 'LGROUP', 'CMB'
Default: currently set frame in scantable
WARNING: frame='REST' not yet implemented

Doppler -- Doppler mode
Options: (str) 'RADIO', 'OPTICAL', 'Z', 'BETA', 'GAMMA'
Default: currently set doppler in scantable

Scanlist -- List of scan numbers to process
Default: [] (use all scans)
Example: [21, 22, 23, 24]

Field -- Selection string for selecting scans by name
Default: '' (no name selection)
Example: 'FLS3a*
This selection is in addition to scanlist, iflist, and pollist

Iflist -- List of IF id numbers to select
Default: [] (use all IFs)
Example: [15]

Pollist -- List of polarization id numbers to select
Default: [] (use all polarizations)
Example: [1]

Fitfunc -- Function for fitting
Options: (str) 'gauss', 'lorentz'
Default: 'gauss'

Fitmode -- Mode for fitting
Options: (str) 'list', 'auto', 'interact'
Default: 'auto'
Example: 'list' will use maskline to define regions to fit for lines with nfit in each
'auto' will use the linefinder to fit for lines
using the following parameters
   'interact' allows adding and deleting mask regions by drawing rectangles on the plot with mouse. Draw a rectangle with LEFT-mouse to ADD the region to the mask and with RIGHT-mouse to DELETE the region.

>>> fitmode expandable parameters
    thresh -- S/N threshold for linefinder
       default: 5
       example: a single channel S/N ratio above which the channel is considered to be a detection
    min_nchan -- minimum number of consecutive channels for linefinder
       default: 3
       example: minimum number of consecutive channels required to pass threshold
    avg_limit -- channel averaging for broad lines
       default: 4
       example: a number of consecutive channels not greater than this parameter can be averaged to search for broad lines
    box_size -- running mean box size
       default: 0.2
       example: a running mean box size specified as a fraction of the total spectrum length
    edge -- channels to drop at beginning and end of spectrum
       default: 0
       example: [1000] drops 1000 channels at beginning AND end [1000,500] drops 1000 from beginning and 500 from end

Note: For bad baselines threshold should be increased, and avg_limit decreased (or even switched off completely by setting this parameter to 1) to avoid detecting baseline undulations instead of real lines.

maskline -- list of mask regions to INCLUDE in LINE fitting
   default: all
   example: maskline=[[3900,4300]] for a single region, or
           maskline=[[3900,4300],[5000,5400]] for two, etc.
invertmask -- invert mask (EXCLUDE masklist instead)
   options: (bool) True, False
   default: False
   example: invertmask=True, then will make one region that is the exclusion of the maskline regions
nfit -- list of number of gaussian/lorentzian lines to fit in in maskline region (ignored when fitmode='auto')
   default: 0 (no fitting)
   example: nfit=[1] for single line in single region,
nfit=[2] for two lines in single region,
nfit=[1,1] for single lines in each of two regions, etc.

outfile -- name of output file for fit results
  default: no output fit file
  example: 'mysd.fit'
overwrite -- overwrite the outfile if already exists
  options: (bool) True, False
  default: False
plotlevel -- control for plotting of results
  options: (int) 0=none, 1=some, 2=more
  default: 0 (no plotting)
  example: plotlevel=1 plots fit
           plotlevel=2 plots fit and residual
           no hardcopy available for fitter
WARNING: be careful plotting OTF data with lots of fields

Returns a Python dictionary of line statistics
  keys:  'peak','cent','fwhm','nfit'
  example: each value is a list of lists with one list of
           2 entries [fitvalue,error] per component.
           e.g. xstat['peak']=[[234.9, 4.8],[234.2, 5.3]]
           for 2 components.

DESCRIPTION:

Task sdfit is a basic line-fitter for single-dish spectra. It assumes that the spectra have been
 calibrated in sdcal or sdreduce.

Furthermore, it assumes that any selection of scans, IFs, polarizations, and time and channel
 averaging/smoothing has also already been done (in other sd tasks) as there are no controls for
 these. Note that you can use sdsave to do selection and write out a new scantable.

Note that multiple scans and IFs can in principle be handled, but we recommend that you use
 scanlist, field, and iflist to give a single selection for each fit.

Currently you can choose Gaussian or Lorentzian profile as a fitting model.

Interactive mask selection for spectral line fitting is enabled with fitmode='interact'.

For complicated spectra, sdfit does not do a good job of "auto-guessing" the starting model for
 the fit. We recommend you use sd.fitter in the toolkit which has more options, such as fixing
 components in the fit and supplying starting guesses by hand.

See the sdcal description for information on fluxunit conversion and the telescopeparm parameter. Also, see the sdcal description for note on GBT raw SDFITS format data.
8.2.1.10 sdgrid

Keyword arguments:
infiles -- name of input SD dataset. can be list.
   example: 'testimage.asap'
   ['testimage1.asap','testimage2.asap']
antenna -- select data based on antenna name(s) or id(s)
   default: -1
   example: 0, 'DV01'
scanlist -- list of scan numbers to process
   default: [] (use all scans)
   example: [21,22,23,24]
ifno -- IFNO to be gridded
   default: -1 (only process IFNO in the first row)
   example: 1
pollist -- POLNO to be gridded
   default: [] (all polarizations)
   example: 1,[0,1]
gridfunction -- gridding function
   options: 'BOX' (Box-car), 'SF' (Spheroidal),
   'GAUSS' (Gaussian), 'PB' (Primary-beam)
   default: 'BOX'
   example: 'SF'
   >>> gridfunction expandable parameter:
   width -- width of convolution kernel, not available
   for BOX gridding
   default: -1 (use default for each gridfunction)
   example: 3
weight -- weight type (both lower-case and upper-case are
   acceptable)
   options: 'UNIFORM',
   'TSYS' (1/Tsys**2 weighted)
   'TINT' (integration time weighted)
   'TINTSYS' (Tint/Tsys**2)
   default: 'UNIFORM'
clipminmax -- do min/max clipping if True
   default: False
outfile -- output data name
   default: '' (outfile will be set to infile+.grid')
   example: 'mydata.asap.grid'
overwrite -- overwrite option for outfile
   default: False (not overwrite)
   options: True, False
   example: if True, existing file will be overwritten
npix -- x and y image size in pixels, symmetric for single value
default: -1 (automatically calculated from cell size and the data)
  example: npix=200 (equivalent to [200,200])

cell -- x and y cell size. default unit arcsec
  default: '' (automatically calculated from npix if it is set, otherwise '1.0arcmin')
  example: cell=[0.2arcmin, 0.2arcmin']
  cell='0.2arcmin' (equivalent to example above)
  cell=12.0 (interpreted as '12.0arcsec'='0.2arcmin')

center -- grid center
  default: '' (automatically calculated from the data)
  example: 'J2000 13h44m00 -17d02m00'
    [05:34:48.2', '-05.22.17.7'] (in J2000 frame)
    [1.46, -0.09] (interpreted as radian in J2000 frame)

plot -- Plot result or not
  default: False (not plot)
  example: if True, result will be plotted

DESCRIPTION:

The sdgrid task performs spatial gridding according to the user specification of spatial grid, convolution function, etc.

For grid configuration, the task supplements necessary information by referring input data if any of gridding parameter (npix, cell, or center) is not specified by the user. If center is default value (empty string), central position of the grid will be set to the center of observed area, i.e. \( x = 0.5 (x_{\text{max}} + x_{\text{min}}) \), \( y = 0.5 (y_{\text{max}} + y_{\text{min}}) \). If either cell or npix is set, unspecified one will be calculated from the others. In that case, total extent of the grid will be set to cover all observed position. If neither cell nor npix is set, cell size will be set to 1.0 arcmin and number of pixel will be calculated based on that cell size.

Currently, only J2000 frame is supported.

The parameter gridfunction sets gridding function for imaging. Currently, the task supports 'BOX' (Box-car), 'SF' (Prolate Spheroidal Wave Function), 'GAUSS' (Gaussian), and 'PB' (Primary Beam, not implemented yet). For 'PB', correct antenna informations should be included in input file. The width parameter specifies width of the convolution kernel in pixel unit. For Gaussian gridding, width is treated as HWHM and actual width (the width that convolution function has non-zero value) is set to 4HWHM to take into account contribution from Gaussian tail. Otherwise, width is treated as actual width of the convolution function.

The parameter gridfunction sets gridding function for imaging. Currently, the task supports 'BOX' (Box-car), 'SF' (Prolate Spheroidal Wave Function), 'GAUSS' (Gaussian), 'GJINC' (Gaussian*Jinc), where Jinc(x) = \( J_1 (\pi x / c) / (\pi x / c) \) with a first order Bessel function \( J_1 \), and 'PB' (Primary Beam, not implemented yet). For 'PB', correct antenna informations should be included in input file.

There are four subparameters for gridfunction: convsupport, truncate, gwidth, and jwidth. The convsupport is an integer specifying cut-off radius for 'SF' in units of pixel. By default (convsupport=-
1), the cut-off radius is set to 3 pixels. The truncate is a cut-off radius for 'GAUSS' or 'GJINC'. It accepts integer, float, and string values of numeric plus unit. Allowed units are angular units such as 'deg', 'arcmin', 'arcsec', and 'pixel'. Default unit is 'pixel' so that string without unit or numerical values (integer or float) will be interpreted as radius in pixel. Default value for truncate, which is used when negative radius is set, is 3*HWHM for 'GAUSS' and radius at first null for 'GJINC'. The gwidth is the HWHM of gaussian for 'GAUSS' and 'GJINC'. Default value is $\sqrt{\log 2}$ pixel for 'GAUSS' and 2.52$\sqrt{\log 2}$ pixel for 'GJINC'. The jwidth specifies width of the jinc function (parameter 'c' in the definition above). Default is 1.55 pixel. Both gwidth and jwidth allows integer, float, or string of numeric plus unit. Default values for gwidth and jwidth are taken from Mangum et al. (2007). Formula for 'GAUSS' and 'GJINC' are taken from Table 1 in the paper, and are written as below using gwidth and jwidth:

GAUSS: \[ \exp \left( -\frac{|r|}{gwidth}^2 \right) \]

GJINC: \[ \frac{J_1(\pi|r|/jwidth)}{\pi|r|/jwidth} \exp \left( -\frac{|r|}{gwidth}^2 \right) \]

Boolean parameter plot controls whether gridded result is plotted or not. If True, color map of gridded data will be shown. Pixel center and observed position are overlayed as blue dot and red dot, respectively. Currently, channel averaged value will be plotted.


8.2.1.11 sdimage

Keyword arguments:

infile -- name of input SD (MS) dataset

specunit -- units for spectral axis

options: (str) 'channel', 'km/s', 'GHz', 'MHz', 'kHz', 'Hz'

default: 'channel'

eyexample: this will be the units for nchan, start, and step

restfreq -- rest frequency

default: '' (refer input data)

eyexample: 1.0e11, '100GHz'

scanlist -- list of scan numbers to process

default: [] (use all scans)

eyexample: [21,22,23,24]

this selection is in addition to field and spw

field -- field id or selection string for selecting scans by name

default: -1 (all fields)

eyexample: 'FLS3a', 0

this selection is in addition to scanlist and spw

spw -- spectral window id

default: 0

eyexample: 1

this selection is in addition to scanlist and field
antenna -- select data based on antenna name(s) or id(s)
  default: -1 (all baselines, i.e. all antenna in case of auto data)
  example: 0, 'DV01'

stokes -- select data based on stokes or polarization type
  default: '' (use all polarizations)
  example: 'XX'

gridfunction -- gridding function for imaging
  options: 'BOX' (Box-car), 'SF' (Spheroidal), 'PB' (Primary-beam), 'GAUSS' (Gaussian), 'GJINC' (Gaussian*Jinc)
  default: 'BOX'
  example: 'SF'

```
>>> gridfunction expandable parameter:
```
  convsupport -- convolution support for 'SF'
    default: -1 (use default for each gridfunction)
    example: 3
  truncate -- truncation radius of convolution kernel.
    effective only for 'GAUSS' and 'GJINC'.
    default: '-1' (use default for each gridfunction)
    example: 3, '20arcsec', '3pixel'
  gwidth -- HWHM for gaussian. Effective only for 'GAUSS' and 'GJINC'.
    default: '-1' (use default for each gridfunction)
    example: 3, '20arcsec', '3pixel'
  jwidth -- Width of jinc function. Effective only for 'GJINC'.
    default: '-1' (use default for each gridfunction)
    example: 3, '20arcsec', '3pixel'

outfile -- output image name
  default: none
  example: 'mySDimage.im'

overwrite -- overwrite option for outfile
  default: False (not overwrite)
  options: True, False
  example: if True, existing file will be overwritten

imsizer -- x and y image size in pixels, symmetric for single value
  default: [256,256]
  example: imsize=200 (equivalent to [200,200])

cell -- x and y cell size. default unit arcmin
  default: ['1.0arcmin', '1.0arcmin']
  example: cell=[0.2arcmin, 0.2arcmin]
    cell='0.2arcmin' (equivalent to example above)

dochannelmap -- channel map image or total power image
  default: False (total power)
  options: True (channel map), False
CHAPTER 8. SINGLE DISH DATA PROCESSING

>>> dochannelmap=True expandable parameters
    nchan -- number of spectral channel for created image
        default: 1
        options: to do total power imaging, set -1
    start -- reference value of start channel (in units of specunit)
        default: 0 (0th channel if specunit='channel')
        example: 100
    step -- width of each spectral channel for created image
        default: 1 (channel width of 1 channel if specunit='channel')
        example: 100
    phasecenter -- image phase center: direction measure or fieldid
        default: 0
        example: 'J2000 13h44m00 -17d02m00', 'AZEL -123d48m29 15d41m41'
    ephemsrcref -- ephemeris source name for moving source
        default: ''
        if the source name in the data matches one of the known
        solar objects by the system, this task automatically set
        the source name.
        example: 'moon'
    pointingcolumn -- pointing data column to use
        option: 'direction', 'target', 'pointing_offset', 'source_offset', 'encoder'
        default: 'direction'

DESCRIPTION:

Task sdimaging creates an image from input single-dish data. The input can be either total power
or spectral data. Currently, this task directly accesses the Measurement Set data only because of
the data access efficiently. It differs from other single-dish tasks that mostly operate on the ASAP
scantable data format.

Units of spectral axis can be specified via a parameter specunit. Allowed values for specunit are
'channel', 'GHz', 'MHz', 'kHz', 'Hz', and 'km/s'. This parameter is also used as the units of the
parameter start and step that specify reference value of start channel and width of each spectral
channel for channel map, respectively.

Selection of the antennas can be made by setting antennaid(s) or antenna name(s) in string (e.g.
'0', 'DV01', etc.). Default value, -1, means that the task selects data from all baseline, i.e., data
from all antenna when data only contains auto-correlation.

The parameter gridfunction sets gridding function for imaging. Currently, the task supports 'BOX'
(Box-car), 'SF' (Prolate Spheroidal Wave Function), 'GAUSS' (Gaussian), 'GJINC' (Gaussian* Jinc),
where \( J_1 \left( \frac{2x}{c} \right) \) with a first order Bessel function \( J_1 \), and 'PB' (Primary Beam,
not implemented yet). For 'PB', correct antenna informations should be included in input file.

There are four subparameters for gridfunction: convsupport, truncate, gwidth, and jwidth. The
convsupport is an integer specifying cut-off radius for 'SF' in units of pixel. By default (convsupport=-1),
the cut-off radius is set to 3 pixels. The truncate is a cut-off radius for 'GAUSS' or 'GJINC'.
It accepts integer, float, and string values of numeric plus unit. Allowed units are angular units such as 'deg', 'arcmin', 'arcsec', and 'pixel'. Default unit is 'pixel' so that string without unit or numerical values (integer or float) will be interpreted as radius in pixel. Default value for truncate, which is used when negative radius is set, is $3\times$HWHM for 'GAUSS' and radius at first null for 'GJINC'. The gwidth is the HWHM of gaussian for 'GAUSS' and 'GJINC'. Default value is $\sqrt{\log 2}$ pixel for 'GAUSS' and $2.52\sqrt{\log 2}$ pixel for 'GJINC'. The jwidth specifies width of the jinc function (parameter 'c' in the definition above). Default is 1.55 pixel. Both gwidth jwidth allows integer, float, or string of numeric plus unit. Default values for gwidth and jwidth are taken from Mangum et al. (2007). Formula for 'GAUSS' and 'GJINC' are taken from Table 1 in the paper, and are written as below using gwidth and jwidth:

\[
\text{GAUSS: } \exp \left[ -\left( \frac{|r|}{\text{gwidth}} \right)^2 \right]
\]
\[
\text{GJINC: } \frac{J_1(\pi |r|/\text{jwidth})}{(\pi |r|/\text{jwidth})} \exp \left[ -\left( \frac{|r|}{\text{gwidth}} \right)^2 \right]
\]


**R4.1 New Feature:**

When phasecenter is empty string, position of the map center will be automatically calculated.

### 8.2.1.12 sdlist

**Keyword arguments:**

- **infile** -- name of input SD dataset
- **antenna** -- antenna name or id (only effective for MS input).
- **scanaverage** -- average integrations within scans
  - options: (bool) True, False
  - default: False
  - example: if True, this happens in read-in
  - For GBT, set False!
- **outfile** -- Name of output file for summary list
  - default: '' (no output file)
  - example: 'mysd_summary.txt'
- **overwrite** -- overwrite the output file if already exists
  - options: (bool) True, False
  - default: False

**DESCRIPTION:**

Task sdlist lists the scan summary of the dataset after importing as a scantable into ASAP. It will optionally output this summary as file.

See the sdcal description for note on GBT raw SDFITS format data.
8.2.1.13  **sdmath**

Keyword arguments:

- **expr** -- Mathematical expression using scantables
- **varlist** -- Dictionary of variables in expr and their values.
  - Keys must be coincide with variables used in expr.
  - Values are substituted in each value in expr.
- **antenna** -- antenna name or id (only effective for MS input).
- **fluxunit** -- units for line flux
  - Options: 'K', 'Jy', ''
  - Default: '' (keep current fluxunit)
  - WARNING: For GBT data, see description below.

```plaintext
>>> fluxunit expandable parameter
```  
- **telescopeparm** -- the telescope characteristics
  - Options: (str) name or (list) list of gain info
  - Default: '' (none set)
  - Example: if telescopeparm='', it tries to get the telescope name from the data.

- **specunit** -- units for spectral axis
  - Options: (str) 'channel', 'km/s', 'GHz', 'MHz', 'kHz', 'Hz'
  - Default: '' (=current)
  - Example: this will be the units for masklist

- **frame** -- frequency frame for spectral axis
  - Options: (str) 'LSRK', 'REST', 'TOPO', 'LSRD', 'BARY', 'GEO', 'GALACTO', 'LGROUP', 'CMB'
  - Default: currently set frame in scantable
  - WARNING: frame='REST' not yet implemented

- **doppler** -- doppler mode
  - Options: (str) 'RADIO', 'OPTICAL', 'Z', 'BETA', 'GAMMA'
  - Default: currently set doppler in scantable

- **scanlist** -- list of scan numbers to process
  - Default: [] (use all scans)
  - Example: [21, 22, 23, 24]
  - This selection is in addition to field, iflist, and pollist

- **field** -- selection string for selecting scans by name
default: '' (no name selection)  
example: 'FLS3a*'  
this selection is in addition to scanlist, iflist, and pollist  
iflist -- list of IF id numbers to select  
default: [] (use all IFs)  
example: [15]  
this selection is in addition to scanlist, field, and pollist  
pollist -- list of polarization id numbers to select  
default: [] (use all polarizations)  
example: [1]  
this selection is in addition to scanlist, field, and iflist  
outfile -- Name of output file  
default: ' ' (<infile>_cal)  
outform -- format of output file  
options: 'ASCII','SDFITS','MS','ASAP'  
default: 'ASAP'  
example: the ASAP format is easiest for further sd  
        processing; use MS for CASA imaging.  
        If ASCII, then will append some stuff to  
        the outfile name  
overwrite -- overwrite the output file if already exists  
options: (bool) True,False  
default: False  
WARNING: if outform='ASCII', this parameter is ignored

DESCRIPTION:

Task **sdmath** executes a mathematical expression for single dish spectra. The spectral data file can be any of the formats supported by ASAP (scantable, MS, rpfits, and SDFITS). In the expression, these file names should be put inside of single or double quotes. You can use variables in the expression. If you want to use, you must define varlist dictionary. Name of variables should be simple, e.g. V0, V1, etc., to avoid unexpected error. Keys of varlist must be name of variables that you used in the expression, and their values will be substituted for variables in the expression. Allowed type for value is numerical values, one- or two-dimensional lists (either Python list or numpy.ndarray), and filename strings that indicate spectral data or ASCII text, which is space-separated list of numerical values consisting of adequate number of rows and columns.

The **fluxunit**, **specunit**, and **frame** can be set, otherwise, the current settings of the first spectral data in the expression are used. Other selections (e.g. scan No, IF, Pol) also apply to all the spectral data in the expression, so if any of the data are not selected, the task will produce no output.

See the **sdcal** description for note on GBT raw SDFITS format data.

Example:

```bash
    # do on-off/off calculation
```
expr='("orion_on_data.asap"-"orion_off_data.asap")/"orion_off_data.asap"
outfile='orion_cal.asap'
sdmath()

# do on-off/off calculation using varlist
expr='V0/V1-V2'
varlist['V0']='orion_on_data.asap'
varlist['V1']='orion_off_data.asap'
varlist['V2']=1.0
outfile='orion_cal.asap'
sdmath()

# interpretation of ASCII file value for varlist
If the contents of input ASCII file is shown as,

```
0.5 0.3 0.2
1.0 0.2 0.9
```

it is interpreted as a list, `[0.5,0.3,0.2],[1.0,0.2,0.9]`.

---

8.2.1.14 sdplot

Keyword arguments:

infile -- name of input SD dataset
antenna -- antenna name or id (only effective for MS input).
fluxunit -- units for line flux
options: 'K','Jy',''
default: '' (keep current fluxunit)
WARNING: For GBT data, see description below.

>>> fluxunit expandable parameter
telescopeparm -- the telescope characteristics
options: (str) name or (list) list of gain info
default: '' (none set)
example: if telescopeparm='', it tries to get the telescope
name from the data.
Full antenna parameters (diameter,ap.eff.) known
to ASAP are
‘CEDUNA’,‘HOBART’. For GBT, it fixes default fluxunit
to 'K' first then convert to a new fluxunit.
telescopeparm=[104.9,0.43] diameter(m), ap.eff.
telescopeparm=[0.743] gain in Jy/K
telescopeparm='FIX' to change default fluxunit
see description below
specunit -- units for spectral axis
options: (str) 'channel', 'km/s', 'GHz', 'MHz', 'kHz', 'Hz'
default: '' (=current)
example: this will be the units for masklist
>>> specunit expandable parameter
restfreq -- rest frequency
default: '' (use current setting)
example: 4.6e10 (float value in Hz),
'46GHz' (string with unit),
['345.8GHz', 347.0e9, 356.7e9] (for each IF)
[{'name': 'CO', 'value': 345e9}] (a value with name)
frame -- frequency frame for spectral axis
options: (str) 'LSRK', 'REST', 'TOPO', 'LSRD', 'BARY',
'GEO', 'GALACTO', 'LGROUP', 'CMB'
default: currently set frame in scantable
WARNING: frame='REST' not yet implemented
doppler -- doppler mode
options: (str) 'RADIO', 'OPTICAL', 'Z', 'BETA', 'GAMMA'
default: currently set doppler in scantable
scanlist -- list or string of scan numbers to process
default: [] (use all scans)
example: [21, 22, 23, 24], or "21~24"
this selection is in addition to field, iflist, pollist, and beamlist
field -- selection string for selecting scans by name
default: '' (no name selection)
example: 'FLS3a*
this selection is in addition to scanlist, iflist, pollist, and beamlist
iflist -- list or string of IF id numbers to select
default: [] (use all IFs)
example: [15]
this selection is in addition to scanlist, field, pollist, and beamlist
pollist -- list or string of polarization id numbers to select
default: [] (use all polarizations)
example: [1]
this selection is in addition to scanlist, field, iflist, and beamlist
beamlist -- list or string of beam id numbers to select
default: [] (use all beams)
example: [1]
this selection is in addition to scanlist, field, iflist, and pollist
scanaverage -- average integers within scans
  options: (bool) True, False
  default: False

timeaverage -- average times for multiple scan cycles
  options: (bool) True, False
  default: False
  example: if True, this happens after calibration
  >>> timeaverage expandable parameter
  tweight -- weighting for time average
  options: 'var' (1/var(spec) weighted)
            'tsys' (1/Tsys**2 weighted)
            'int' (integration time weighted)
            'tintsys' (Tint/Tsys**2)
            'median' (median averaging)
  default: 'tintsys'

polaverage -- average polarizations
  options: (bool) True, False
  default: False
  >>> polaverage expandable parameter
  pweight -- weighting for polarization average
  options: 'var' (1/var(spec) weighted)
            'tsys' (1/Tsys**2 weighted)
  default: 'tsys'

kernel -- type of spectral smoothing
  options: 'hanning', 'gaussian', 'boxcar', 'none'
  default: 'none'
  >>> kernel expandable parameter
  kwidth -- width of spectral smoothing kernel
  options: (int) in channels
  default: 5
  example: 5 or 10 seem to be popular for boxcar
           ignored for hanning (fixed at 5 chans)
           (0 will turn off gaussian or boxcar)

plottype -- type of plot
  options: 'spectra', 'totalpower', 'pointing', 'azel', 'grid'
  default: 'spectra'
  >>> plottype expandable parameters
  stack -- code for stacking on single plot for spectral plotting
  options: 'p', 'b', 'i', 't', 's', 'r' or
            'pol', 'beam', 'if', 'time', 'scan', 'row'
  default: 'p'
  example: maximum of 16 stacked spectra
           stack by pol, beam, if, time, scan
           Note stack selection is ignored when panel='r'.

panel -- code for splitting into multiple panels for spectral plotting
options: 'p', 'b', 'i', 't', 's', 'r' or 'pol', 'beam', 'if', 'time', 'scan', 'row'
default: 'i'
example: maximum of 16 panels
panel by pol, beam, if, time, scan
Note panel selection is ignored when stack='r'.

flrange -- range for flux axis of plot for spectral plotting
options: (list) [min, max]
default: [] (full range)
example: flrange=[-0.1, 2.0] if 'K'
assumes current fluxunit

sprange -- range for spectral axis of plot
options: (list) [min, max]
default: [] (full range)
example: sprange=[42.1, 42.5] if 'GHz'
assumes current specunit

linecat -- control for line catalog plotting for spectral plotting
options: (str) 'all', 'none' or by molecule
default: 'none' (no lines plotted)
example: linecat='SiO' for SiO lines
linecat='*OH' for alcohols
uses sprange to limit catalog
WARNING: specunit must be in frequency (*Hz)
to plot from the line catalog!
and must be 'GHz' or 'MHz' to use
sprange to limit catalog

linedop -- doppler offset for line catalog plotting (spectral plotting)
options: (float) doppler velocity (km/s)
default: 0.0
example: linedop=-30.0

center -- the central direction of gridding
default: '' (map center)
example: 'J2000 19h30m00 -40d00m00'
Note currently only supports 'J2000' as direction frame

cell -- x and y cell size of gridding
default: [] (map extent divided by # of subplots in x and y)
example: cell=['1.0arcmin', '1.0arcmin']
cell='1.0arcmin' (equivalent to the example above)
Note default number of subplots is 1 x 1 in plottype='grid'.

subplot -- number of subplots (row and column) on a page
NOTICE plotter will slow down when a large number is specified
default: -1 (auto. for plottype='spectra', 1x1 for plottype='grid')
example: 23 (2 rows by 3 columns)

colormap -- the colours to be used for plot lines.
default: None
example: colormap="green red black cyan magenta" (html standard)
colormap="g r k c m" (abbreviation)
colormap="#008000 #00FFFF #FF0090" (RGB tuple)
The plotter will cycle through these colours when lines are overlaid (stacking mode).

linestyles -- the linestyles to be used for plot lines.
default: None
example: linestyles="line dashed dotted dashdot dashdotdot dashdashdot".
The plotter will cycle through these linestyles when lines are overlaid (stacking mode).
WARNING: Linestyles can be specified only one color has been set.

linewidth -- width of plotted lines.
default: 1
example: linewidth=1 (integer)
linewidth=0.75 (double)

histogram -- plot histogram
options: (bool) True, False
default: False

scanpattern -- plot additional lines on the plot to indicate scan patterns when plottype='pointing'
options: (bool) True, False
default: False

header -- print header information on the plot
options: (bool) True, False
default: True
The header information is printed only on the logger when plottype = 'azel' and 'pointing'.

>>> header expandable parameter

headsize -- header font size
options: (int)
default: 9

plotstyle -- customise plot settings
options: (bool) True, False
default: False

>>> plotstyle expandable parameter

margin -- a list of subplot margins in figure coordinate (0-1), i.e., fraction of the figure width or height.
The order of elements should be:
[left, bottom, right, top, horizontal space btw panels, vertical space btw panels]
example: margin = [0.125, 0.1, 0.9, 0.9, 0.2, 0.2]

legendloc -- legend location on the axes (0-10)
options: (integer) 0 -10
see help of "sd.plotter.set_legend" for the detail of location. Note that 0 ('best')
CHAPTER 8. SINGLE DISH DATA PROCESSING

is very slow.

default: 1 ('upper right')

outfile -- file name for hardcopy output
options: (str) filename.eps,.ps,.png
default: '' (no hardcopy)
exmple: 'specplot.eps','specplot.png'
Note this autodetects the format from the suffix (.eps,.ps,.png).

overwrite -- overwrite the output file if already exists
options: (bool) True,False
default: False

DESCRIPTION:

Task *sdplot* displays single-dish spectra, total power, or pointing direction of input data. It assumes that the spectra have been calibrated. It does allow selection of scans, IFs, polarizations, and some time and channel averaging/smoothing options also, but does not write out this data.

This task adds an additional toolbar to Matplotlib plotter. See the cookbook for details of its capability.

*** Data selection ***

This task allows data selection via field name, scan, IF, polarization and beam IDs. Selection of field allows pattern matching using asterisk, e.g., 'FLS3a*'. Selection of scans, IFs, polarizations, and beams, is possible either by a list of IDs or by a CASA type selection syntax using a string of comma separated numbers with operators, i.e., '>', '>=', '<', and '<='. For example, the following two selections are equivalent:

\[
\text{scanlist} = [0, 1, 2, 7, 8, 9, 15] \\
\text{scanlist} = '<3,7~9,15'
\]

*** control of plot lines in 'spectra' and 'grid' plottype ***

Note that colormap and linestyles cannot be controlled at a time. The linestyles is ignored if both of them are specified. Some plot options, like changing titles, legends, fonts, and the like are not supported in this task. You should use *sd.plotter* from the ASAP toolkit directly for this.

*** available plottypes ***

- **plottype = 'spectra'** plots single dish spectra. Multiple scans, IFs, polarizations, and beams can be handles through stacking and panelling. This task uses the JPL line catalog as supplied by ASAP. If you wish to use a different catalog, or have it plot the line IDs from top or bottom (rather than alternating), then you will need to explore the sd toolkit also.

- **plottype = 'grid'** plots spectra based on their pointing direction. The spectra are gridded by direction before plotting. Multiple IFs and polarizations are not handled in this mode. Only the first IF and polarization is gridded and plotted if data includes multiple IDs after selections are applied. Hence, over plotting is not available.

Currently most of the parameters are ignored in the following modes.
• `plottype='totalpower'` is used to plot the total power data, and only plot option is amplitude versus data row number.

• `plottype='azel'` plots azimuth and elevation tracks of the source.

• `plottype='pointing'` plots antenna pointings.

See the `sdcal` description for information on the `fluxunit` conversion and the `telescopeparm` parameter. Also, see the `sdcal` description for note on GBT raw SDFITS format data.

**WARNING:** be careful plotting otf data with lots of fields!

### R4.1 New Features:
A couple of new capabilities are added to `plottype = 'pointing'`.

- color variation of plot symbols by the source type, scan, IF, polarization, or beam IDs.
- overplotting scan patterns when `scanpattern = True`.

### GUI Plot Control on ASAP Plotter
The principal ways to plot single dish spectra are using the `sdplot` task and `sd.plotter` toolkit. These task and toolkit load ASAP Plotter which uses the `matplotlib` plotting library to display plots. You can find information on `matplotlib` at [http://matplotlib.sourceforge.net/](http://matplotlib.sourceforge.net/)

---

**Figure 8.3:** The toolbars on ASAP plotter. The **bottom set of buttons** are the standard `matplotlib` toolbar. See the caption of Figure 3.4 for detailed descriptions. The **upper set of buttons** are: 1) **notation**. Press this to begin editing notes on the plotter. 2) **statistics**. Press this to begin printing statistics to the logger. 3,4) +, −. Click to move to the next or previous page in a series of iterated plots. The page counter on their left shows the current page number. Finally, the **Quit** is on the bottom right.

---

The ASAP Plotter has two rows of buttons at the bottom to control interactive operations as shown in Figure 8.3. When none of the button is depressed, the ASAP Plotter is in spectral value mode. Click on a spectrum to select it and drag the mouse to print the spectral value at the channel position of mouse. The value is printed to the bottom right corner of plotter window.

The buttons on the lower row are the standard `matplotlib` navigation buttons. See § 3.3.2.1 about details of their capabilities.

In a row above it, there are a set of the other buttons (left to right):
• **notation** — If depressed lets you edit texts on the plotter. See below for details of text edition. Clicking the button again will un-depress it and go back to the default spectral value mode.

• **statistics** — If depressed lets you print statistics of a selected region of scantable to the logger. See below for details of region selection. Clicking the button again will un-depress it and go back to the default spectral value mode.

• **+ and −** — Step to the next or previous plot in an iteration. The page counter on their left shows the current page number.

• **Quit** — Click this to close ASAP Plotter.

### Editing texts on the plotter

When the **notation** button is depressed, it lets you edit texts on the plotter. Left-click at a position on the plotter to print a new text, and the **Notation window** is loaded (Figure 8.4). Type the arbitrary text in the text box, select an anchor, and press the **print** button to print it at the position you clicked. There are three choices of anchors: **figure**, **panel**, and **data**. The **figure** or **panel** locates the text at a fixed position in the figure or subplot, respectively. Its relative position to the figure or subplot boundaries doesn’t change when you resize the plotter. On the other hand, the text is fixed on a position in the data coordinate of subplot, when **data** is selected as the anchor. The text moves along with plotted spectra as you pan the subplot.

You can modify or delete texts you added on the plotter. To do it, right-click on a text to show a menu with **Modify** and **Delete**. When **Modify** is selected, the **Notation window** is loaded to modify the selected text. Click on **Delete** and confirm the operation in a pop-up dialog to delete the text. Clicking the **notation** button again will un-depress it and go back to the default spectral value mode.

### Printing statistics of scantable

When **statistics** button is depressed, it lets you print statistics of a selected channel region of the scantable plotted. The statistics values are printed to the logger. You can select a channel region
by left- or right-clicking and dragging the mouse to draw a rectangle. Draw it with left-mouse to print statistics within the region, while do with right-mouse to print statistics excluding the region. Clicking the statistics button again will un-depress it and go back to the default spectral value mode.

### 8.2.1.15 sdsave

Keyword arguments:

- **infile**-- name of input SD dataset
- **antenna**-- antenna name or id (only effective for MS input).
- **getpt**-- fill DIRECTION column properly, or reuse POINTING table in original MS (only effective for MS input)
  - default: True
  - options: True (fill DIRECTION column properly)
    - False (reuse POINTING table in original MS)
- **rowlist**-- list of row numbers to process
  - default: [] (use all rows)
  - example: [0,2,4,6]
  - For expert users only!
  - this selection is applied first, and then followed by the selection with scans, fields, ifs, and polarizations.
- **scanlist**-- list of to process
  - default: [] (use all scans)
  - example: [21,22,23,24]
  - this selection is in addition to field, iflist, and pollist
- **field**-- selection string for selecting scans by name
  - default: '' (no name selection)
  - example: 'FLS3a*'
  - this selection is in addition to scanlist, iflist, and pollist
- **iflist**-- list of IF id numbers to select
  - default: [] (use all IFs)
  - example: [15]
  - this selection is in addition to scanlist, field, and pollist
- **pollist**-- list of polarization id numbers to select
  - default: [] (use all polarizations)
  - example: [1]
  - this selection is in addition to scanlist, field, and iflist
- **scanaverage**-- average integrations within scans
  - options: (bool) True,False
  - default: False
  - example: if True, average integrations before it is saved
- **timeaverage**-- average times for multiple scan cycles
  - options: (bool) True,False
  - default: False
CHAPTER 8. SINGLE DISH DATA PROCESSING

>>>timeaverage expandable parameter
tweight -- weighting for time average
options: 'none'
  'var' (1/var(spec) weighted)
  'tsys' (1/Tsys**2 weighted)
  'tint' (integration time weighted)
  'tintsys' (Tint/Tsys**2)
  'median' (median averaging)
default: 'none'

polaverage -- average polarizations
options: (bool) True,False
default: False

>>>polaverage expandable parameter
pweight -- weighting for polarization average
options: 'none'
  'var' (1/var(spec) weighted)
  'tsys' (1/Tsys**2 weighted)

restfreq -- rest frequencies of output data
Available types are a number, string, a list of numbers or strings (see examples below), and list of dictionaries. The default unit of restfreq is Hz, if not specified. A list can be used to set different rest frequencies to each IF. The length of list input must be nIF. Dictionary input should be a pair of molecule name and frequency with keys of 'name' and 'value', respectively. The 'value's in the dictionary input follows the same manner as for single float or string input.
default: '' (use current setting)
example: 4.6e10 (float value in Hz),
  '46GHz' (string with unit),
  ['345.8GHz', '347.0GHz', 356.7e9] (for each IF)
  [{'name':'CO','value':345e9}] (a value with name)

outfile -- name of output dataset
default: ''

outform -- output data format
default: 'ASAP'
Options: 'ASAP', 'MS2', 'SDFITS', 'ASCII'

overwrite -- overwrite the output file if already exists
options: (bool) True,False
default: False
WARNING: if outform='ASCII', this parameter is ignored

DESCRIPTION:
Task `sdsave` writes the single dish data to a disk file in specified format (ASAP, MS2, SDFITS, ASCII). It is possible to save the subset of the data by selecting row numbers, scan numbers, IF ids and field names. The ASAP (scantable) format is recommended for further analysis using sd tool. For further imaging using imager, save the data to the Measurement Set (MS2).

Note that setting `getpt=False` needs a lot of attention. If you set `getpt=False`, the task retrieves pointing direction from MS’s FIELD table, which might not be correct for single dish observation, instead to check MS’s POINTING table, which is the default behavior of the task (`getpt=True`). To compensate this, absolute path to MS’s POINTING table is stored, and it will be used for POINTING table when the data is converted back to MS format. In general, `getpt=False` is faster especially for large data. However, MS created from Scantable cannot have correct POINTING table if original MS’s POINTING table doesn’t exist. Such situation will happen when original MS is removed or renamed, or imported Scantable is moved to other computer alone.

See the `sdcalen` description for note on GBT raw SDFITS format data.

**WARNING:** The parameter `rowlist` enables you to make data selection based on row number in the Measurement Set or scantable for data saving. Note that data should be treated carefully when applying row based selection, since row numbers can be changed easily by sorting, prior selection, etc. Therefore, this parameter is expected to be used by expert users only.

**R4.1 New Feature:**

When scantable is imported from MS, its frequency reference frame is taken from input MS, while it was forcibly set to LSRK in the previous releases.

### 8.2.1.16 sdscale

**Keyword arguments:**

infile -- name of input SD dataset

antenna -- antenna name or id (only effective for MS input).

factor -- scaling factor. float or one- or two-dimensional float list.
  default: 1 (no scaling)

scaletsys -- scaling of associated Tsys
  default: True

outfile -- output file name
  default: `{infile}_scaled{factor}`

overwrite -- overwrite the output file if already exists
  options: (bool) True,False
  default: False

**DESCRIPTION:**

Task `sdscale` performs scaling of single-dish spectra. By setting `scaletsys = True`, associated Tsys is also scaled. Tsys information are written into the file 'sdscale.log' as well as they are
CHAPTER 8. SINGLE DISH DATA PROCESSING

displayed in the terminal window. The \texttt{infile} can be any of ASAP, MS, SDFITS, or RPFITS format. If \texttt{outfile} name is given or \texttt{outfile=''} (default), the scaled data is written to a new file with the same format as the input data (Note: in case of the RPFITS format input data, it will be written to SDFITS format).

The scaling factor, \texttt{factor}, accepts both scalar type and list type value. The list must be one or two dimensional. If \texttt{factor} is one dimensional, its length must coincide with a number of spectral channel. If \texttt{factor} is two dimensional, its shape must be \((n,1)\) or \((n,m)\), where \(n\) is a number of spectrum, while \(m\) is a number of channel for each spectrum. \(m\) can be variable for each spectrum. In addition, the \texttt{factor} can be an ASCII filename that stores a space-separated list of scaling factor consisting of adequate number of rows and columns. For example, if the content of input ASCII file is shown as,

\begin{verbatim}
0.5 0.3 0.2
1.0 0.2 0.9
\end{verbatim}

it is interpreted as a list \([\[0.5,0.3,0.2\],[1.0,0.2,0.9]]\).

See the \texttt{sdcal} description for note on GBT raw SDFITS format data.

\subsection{sdstat}

Keyword arguments:
\begin{description}
\item[infile] name of input SD dataset
  \begin{description}
  \item[default] none - must input file name
  \item[example] 'mysd.asap'
  \end{description}
  See sdreduce for allowed formats.
\item[antenna] antenna name or id (only effective for MS input).
\item[fluxunit] units for line flux
  \begin{description}
  \item[options] (str) 'K','Jy',''
  \item[default] '' (keep current fluxunit)
  \end{description}
  WARNING: For GBT data, see description below.
\item[fluxunit expandable parameter]
\end{description}
telescopeparm='FIX' to change default fluxunit
see description below

**specunit** -- units for spectral axis
  options: (str) 'channel', 'km/s', 'GHz', 'MHz', 'kHz', 'Hz', ''
  default: '' (=current)
>>> specunit expandable parameter

**restfreq** -- rest frequency
  default: '' (use current setting)
  example: 4.6e10 (float value in Hz),
            '46GHz' (string with unit),
            ['345.8GHz', 347.0e9, 356.7e9] (for each IF)
            [{'name': 'CO', 'value': 345e9}] (a value with name)

**frame** -- frequency frame for spectral axis
  options: (str) 'LSRK', 'REST', 'TOPO', 'LSRD', 'BARY',
            'GEO', 'GALACTO', 'LGROUP', 'CMB'
  default: currently set frame in scantable
  WARNING: frame='REST' not yet implemented

**doppler** -- doppler mode
  options: (str) 'RADIO', 'OPTICAL', 'Z', 'BETA', 'GAMMA'
  default: currently set doppler in scantable

**scanlist** -- list of scan numbers to process
  default: [] (use all scans)
  example: [21, 22, 23, 24]
  this selection is in addition to field, iflist, and pollist

**field** -- selection string for selecting scans by name
  default: '' (no name selection)
  example: 'FLS3a*'
  this selection is in addition to scanlist, iflist, and pollist

**iflist** -- list of IF id numbers to select
  default: [] (use all IFs)
  example: [15]
  this selection is in addition to field, scanlist, and pollist

**pollist** -- list of polarization id numbers to select
  default: [] (use all pols)
  example: [1]
  this selection is in addition to field, scanlist, and iflist

**masklist** -- list of mask regions to INCLUDE in stats
  default: [] (whole spectrum)
  example: [4000, 4500] for one region
            [[1000, 3000], [5000, 7000]]
            these must be pairs of [lo, hi] boundaries

**invertmask** -- invert mask (EXCLUDE masklist instead)
  options: (bool) True, False
  default: false
interactive -- determines interactive masking
  options: (bool) True,False
  default: False
  example: interactive=True allows adding and deleting mask
           regions by drawing rectangles on the plot with mouse.
           Draw a rectangle with LEFT-mouse to ADD the region to
           the mask and with RIGHT-mouse to DELETE the region.

outfile -- name of output file for line statistics
  default: '' (no output statistics file)
  example: 'stat.txt'

format -- format string to print statistic values
  default: '3.3f'

overwrite -- overwrite the statistics file if already exists
  options: (bool) True,False
  default: False

Returns: a Python dictionary of line statistics
  keys: 'rms','stddev','max','min','max_abscissa',
        'min_abscissa','sum','median','mean','totint','eqw'
  example: xstat=sdstat(); print "rms = ",xstat['rms']
     these can be used for testing in scripts or
     for regression

     'max_abscissa' and 'min_abscissa' refer to the abscissa
     (channel/frequency/velocity) of max and min intensity.
     'totint' is the integrated intensity (sum*dx)
     where dx is the abscissa interval in 'specunit'.
     'eqw' is equivalent width (totint/mag) where mag
     is either max or min depending on which has
     greater magnitude.
     Note that 'max_abscissa', 'min_abscissa', 'totint'
     and 'eqw' are quantities (python dictionaries with
     keys, 'unit' and 'value').

DESCRIPTION:

Task sdstat computes basic statistics (rms,mean,median,sum) for single-dish spectra. It assumes
that the spectra have been calibrated. Furthermore, it assumes that any time and channel aver-
ing/smoothing has also already been done as there are no controls for these. Note that you can
run sddreduce with calmode='none' and do selection, writing out a new scantable. The calculated
statistics are written into a file specified by outfile. Interactive mask specification is possible with
interactive=True. Integrated intensity will be shown on the screen and will be included in the
saved outfile (but not yet available in the returned dictionary).
Note that multiple scans and IFs can in principle be handled, but we recommend that you use scanlist, field, iflist, and pollist to give a single selection for each run.

See the sdcal description for information on the fluxunit conversion and the telescopeparm parameter. Also, see the sdcal description for note on GBT raw SDFITS format data.

WARNING: If you do have multiple scantable rows, then xstat values will be lists.

8.2.1.18 sdtpimaging

Keyword arguments:
- infile -- name of input SD (MS) dataset
- calmode -- calibration mode (currently only baseline subtraction)
  options: 'baseline','none'
  default: 'none'
  example: choose mode 'none' if you have already calibrated and want to do plotting nd/or imaging
  >>> calmode='baseline' expandable parameters
- masklist -- mask in numbers of rows from each edge of each scan to be included for baseline fitting
  default: none
  example: [30,30] or [30]
  used first 30 rows and last 30 rows of each scan for the baseline
- blpoly -- polynomial order for the baseline fit
  default: 1
- backup -- set True to create backup for input data
  default: True
- flaglist -- list of scan numbers to flag (ranges can be accepted)
  default: [] (use all scans)
  example: [[0,3],80]
  flag the scan range [0,3] = [0,1,2,3] and scan 80
- antenna -- select data based on antenna name(s) or id(s) in string
  default: '' (use all antennas)
  example: '0,1', 'DV01'
  WARNING: currently baseline subtraction properly only one of the antennas.
- stokes -- select data based on stokes or polarization type
  default: '' (use all polarizations)
  example: 'XX'
- createimage -- do imaging?
  default: False
  >>> createimage=True expandable parameters
- outfile -- output image name
CHAPTER 8. SINGLE DISH DATA PROCESSING

imsize -- x and y image size in pixels, symmetric for single
value
default: [256,256]
example: imsize=200 (equivalent to [200,200])

cell -- x and y cell size. default unit arcmin
default: '1.0arcmin'
example: cell=['0.2arcmin', '0.2arcmin']
cell='0.2arcmin' (equivalent to example above)

phasedcenter -- image phase center: direction measure or fieldid
default: 0
example: 'J2000 13h44m00 -17d02m00', 'AZEL -123d48m29 15d41m41'

ephemsrcname -- ephemeris source name to proper shifting to
center on the moving source for imaging
default: '

if the source name in the data matches one of the
known solar objects by the system, this task
automatically set the source name.
example: 'moon'

pointingcolumn -- pointing data column to use
option: 'direction', 'target', 'pointing_offset',
'source_offset', 'encoder'
default: 'direction'

gridfunction -- gridding function for imaging
options: 'BOX' (Box-car), 'SF' (Spheroidal),
'PB' (Primary-beam), 'GAUSS' (Gaussian),
'GJINC' (Gaussian*Jinc)
default: 'BOX'
example: 'SF'

plotlevel -- control for plotting of results
options: (int) 0=none, 1=some, 2=more, <0=hardcopy
default: 0 (no plotting)
example: plotlevel<0 as abs(plotlevel), e.g.

1: hardcopy plot
(will be named <infile>_scans.eps)

2: plot raw data, progressively display baseline
fitting for each scan, and final calibrated data
(for calmode='baseline')
DESCRIPTION:

Task sdtpimaging performs data selection, calibration, and imaging for single-dish totalpower raster scan data. This is a still experimental task made to work for the data taken at the ALMA Testing Facility (ATF) and OSF. Currently, this task directly accesses the Measurement Set data because of the data access efficiency. So it differs from other single-dish tasks that mostly operate on the ASAP scannable data format. By setting calmode='none', one can run sdtpimaging to plot the data (raw or calibrated, if exists) and further imaging by setting createimage=True. The calibration available at this moment is just a simple baseline subtraction for each scan. The fitted regions set by masklist are the common for all the scans. Selection of the antennas can be made by setting antenna ID(s) or antenna name(s) in string (e.g. '0', '0,1', 'DV01', etc.). For baseline subtraction, it currently works properly for a single antenna selection. So a separate sdtpimaging task needs to be run for each antenna. It currently assumes that the data has a single spw(=0) and fieldid(=0). By setting flaglist, one can set flag by scan numbers to be excluded from imaging. (Note: 'scan numbers' are determined from state id and related to SUB_SCAN column in STATE subtable and they are typically different from SCAN_NUMBER in MS.) By default, baseline subtraction stage overwrites (FLOAT_)DATA column of input data. You can keep original data by setting backup parameter to True. In this case, the task make a copy of input data specified by infile parameter. Name of backup file is <infile>.sdtpimaging.bak.<timestamp>. The selection of polarizations can be made by specifying the polarization name in stokes, such as 'XX' or 'YY' for linear polarizations. For example, with createimage=True, stokes='XXYY' will produces an image cube with each plane contains the image of one of the polarizations while stokes='I' or stokes='I' will produces a 'total intensity' or Stokes I image.

Among the imaging sub-parameters, ephemsrcname is used to set the name of a moving source such as planets to produce a stationary image (can be omitted), and pointingcolumn is used to specify which pointing data column to use for imaging. Convolution kernel for imaging can be specified by using gridfunction. Available options are 'Box' (Box-car), 'SF' (Spheroidal), 'PB' (Primary-beam), 'GAUSS' (Gaussian), and 'GJINC' (Gaussian*Jinc), where \( J_1 \left( \frac{\pi x}{c} \right) / \left( \frac{\pi x}{c} \right) \) with a first order Bessel function \( J_1 \). Sub-parameters for convolution functions cannot be specified in this task. To customize your convolution function, please do imaging using sdimaging task or imager tool.

8.2.1.19 sdimprocess

Keyword arguments:
infles -- name of input SD (FITS or CASA) image
mode -- processing mode
   default: 'basket'
   options: 'basket', 'press'

>>>mode expandable parameter
   direction -- scan direction in unit of degree
   default: []
   example: [0.0,90.0]
   masklist -- mask width for Basket-Weaving on percentage
default: 1.0 (1.0\% of map size)
numpoly -- order of polynomial fit in Presssed-out
  default: 2
beamsize -- beam size
  default: 0.0
  example: 10.0 (interpreted as '10arcsec'), '1arcmin'
smoothsize -- smoothing beam in Presssed-out
  default: 2.0 (interpreted as 2.0 * beamsize)
  example: '1arcmin' (set smoothsize directly)
tmax -- maximum value used for process
  default: 0.0 (no threshold in maximum)
  example: 10.0 (mask data larger value than 10.0)
tmin -- minimum value used for process
  default: 0.0 (no threshold in minimum)
  example: -10.0 (mask data smaller value than -10.0)
outfile -- output CASA image name
  default: '' (use default name)
  example: 'output.im'
overwrite -- overwrite option for outfile
  default: False (not overwrite)
  options: True, False
  example: if True, existing file will be overwritten

DESCRIPTION:

Task \texttt{sdimprocess} is used to remove a scanning noise that appears as a striped noise pattern along the scan direction in a raster scan data.

By default, the scanning noise is removed by using the 'Basket-Weaving' method (Emerson & Grave 1988) that requires multiple images that observed exactly the same area with different scanning direction. If only one image is available, the 'Pressed-out' method (Sofue & Reich 1979) can be used to remove the scanning effect.

For 'Basket-Weaving', scanning directions must have at least two different values. Normally, the scanning direction should be specified for each input image. Otherwise, specified scanning directions will be used iteratively. The \texttt{masklist} is a width of masking region in the Fourier plane. It is specified as a fraction (percentage) of the image size.

For 'Pressed-out', the scanning direction must be unique. There are two ways to specify a size of smoothing beam used for process. One is to specify smoothing size directly, where \texttt{smoothsize} is specified as string that consists of a numerical value and an unit (e.g. '10.0arcsec'). The value of \texttt{beamsize} will be ignored in this case. Another way to specify smoothing size is to set an observed beam size and indicate them smoothing size as a scale factor of the observed beam. In this case, the \texttt{beamsize} is interpreted as the observed beam size, and the \texttt{smoothsize} is the scale factor. If the \texttt{beamsize} is provided as float value, its unit is assumed to have 'arcsec' units. It is also possible
to set the `beamsize` as string consisting of the numerical value and the unit. The `smoothsize` must
be float value.

The `infiles` only allows an image data (CASA or FITS), and does not work with MS or Scantable.
The `direction` is an angle with respect to the horizontal direction in degree units. Any value may
be interpreted properly, but the value ranging from 0.0 to 180.0 will be secure. The `tmax` and the
`tmin` is used to specify a threshold that defines a range of spectral values used for processing. The
data point that has the value larger than `tmax` or smaller than `tmin` will be excluded from the
processing. The default (0.0) is no threshold. The `outfile` specifies an output CASA image name.
If the `outfile` is empty, the default name (`'sdimprocess.out.im'`) will be used.

8.2.1.20  `msmoments`

Keyword arguments:

infile -- Name of input MS data
  default: none; example: `infile="OrionS_rawACSmod"

moments -- List of moments you would like to compute
  default: 0 (integrated spectrum); example: `moments=[0,1]`

antenna -- antenna name or id that the user wants to compute moments
  default: '' (all antennae)

field -- field name or id that the user wants to compute moments
  default: '' (all fields)

spw -- spectral window id that the user wants to compute moments
  default: '' (all spectral windows)

includemask -- List of masks to include
  default: [-1] (include all channels); example=[2,100]

excludemask -- List of masks to exclude
  default: [-1] (don't exclude channels); example=[100,200]

outfile -- Output MS file name (or root for multiple moments)
  default: '' (input+auto-determined suffix); example: `outfile='source_moment'

overwrite -- Overwrite existing output files
  default: false

Task `msmoments` computes moments from spectral data stored in MS. The task is defined in analogy
with `immoments` task, so that you can calculate any moments that is available for `immoments` task.
Currently, the task only accepts MS with FLOAT_DATA column.

The spectral moment distributions at each row in input MS are determined. Input MS must have
FLOAT_DATA column, i.e. autocorrelation data. See the cookbook and User Reference Manual
for mathematical details.

The main control of the calculation is given by parameter `moments`:

- `moments=-1` - mean value of the spectrum
CHAPTER 8. SINGLE DISH DATA PROCESSING

- moments=0 - integrated value of the spectrum
- moments=1 - intensity weighted coordinate; traditionally used to get 'velocity fields'
- moments=2 - intensity weighted dispersion of the coordinate; traditionally used to get "velocity dispersion"
- moments=3 - median of I
- moments=4 - median coordinate
- moments=5 - standard deviation about the mean of the spectrum
- moments=6 - root mean square of the spectrum
- moments=7 - absolute mean deviation of the spectrum
- moments=8 - maximum value of the spectrum
- moments=9 - coordinate of the maximum value of the spectrum
- moments=10 - minimum value of the spectrum
- moments=11 - coordinate of the minimum value of the spectrum

Note that includemask and excludemask cannot set simultaneously.

Example for finding the 1-moment, intensity-weighted coordinate, often used for finding velocity fields.

\[ \texttt{msmoments( infile="mydata", moment=1, outfile="velocityfields" )} \]

8.2.2 Single Dish Analysis Use Cases With SDTasks

8.2.2.1 GBT Position Switched Data Analysis

As an example, the following illustrates the use of the SDtasks for the Orion data set, which contains the HCCCN line in one of its IFs. This walk-through contains comments about setting parameter values and some options during processing.
# for using the SDtasks on a
test dataset.
#

#####################################
import time
import os
#

# This is the environment variable
# pointing to the head of the CASA
# tree that you are running
casapath=os.environ['AIPSPATH']

#
# This bit removes old versions of the output files
os.system('rm -rf sdusecase_orions* ')
#
# This is the path to the OrionS GBT ms in the data repository
datapath=casapath+'/data/regression/ATST5/OrionS/OrionS_rawACSmod'
#
# The following will remove old versions of the data and
# copy the data from the repository to your
# current directory. Comment this out if you already have it
# and don't want to recopy
os.system('rm -rf OrionS_rawACSmod')
copystring='cp -r '+datapath+' .'
os.system(copystring)

# Now is the time to set some of the more useful
# ASAP environment parameters (the ones that the
# ASAP User Manual claims are in the .asaprc file).
# These are in the Python dictionary sd.rcParams
# You can see what's in it by typing:
sd.rcParams
# One of them is the 'verbose' parameter which tells
# ASAP whether to spew lots of verbiage during processing
# or to keep quiet. The default is
#sd.rcParams['verbose']=True
# You can make ASAP run quietly (with only task output) with
#sd.rcParams['verbose']=False

# Another key one is to tell ASAP to save memory by
# going off the disk instead. The default is
#sd.rcParams['scantable.storage']='memory'
# but if you are on a machine with small memory, do
#sd.rcParams['scantable.storage']='disk'

# You can reset back to defaults with
#sd.rcdefaults

############################
# ORION-S HC3N
# Position-Switched data
#
############################
startTime=time.time()
startProc=time.clock()

############################
# List data
############################
# List the contents of the dataset
# First reset parameter defaults (safe)
default('sdlist')

# You can see its inputs with
#inp('sdlist')
# or just
#inp
# now that the defaults('sdlist') set the
# taskname='sdlist'
#
# Set the name of the GBT ms file
infile = 'OrionS_rawACSmod'

# Set an output file in case we want to
# refer back to it
outfile = 'sdusecase_orions_summary.txt'
sdlist()

# You could also just type
#go

# You should see something like:
#
# ################################################################################
# Scan Table Summary
# ################################################################################
# Project: AGBT06A_018_01
# Obs Date: 2006/01/19/01:45:58
# Observer: Joseph McMullin
# Antenna Name: GBT@GREENBANK
# Data Records: 512 rows
# Obs. Type: OffOn:PSWITCHOFF:TPWCAL
# Beams: 1
# IFs: 8
# Polarisations: 2 (circular)
# Channels: 8192
# Flux Unit: K
# Abscissa: Channel
# Selection: none

# Scan Source Time range Int[s] Record SrcType FreqIDs MolIDs
# Beam Position (J2000)
# --------------------------------------------------------------------------------
# 20 OrionS 2006/01/19/01:45:58.0 - 01:47:58.2 30.03 64 [PSOFF, PSOFF:CALON] [0, 1, 2, 3] [0]
# 0 05:15:13.5 -05.24.08.6
# 21 OrionS 2006/01/19/01:48:38.0 - 01:50:38.2 30.03 64 [PSON, PSON:CALON] [0, 1, 2, 3] [0]
# 0 05:35:13.4 -05.24.07.8
# 22 OrionS 2006/01/19/01:51:21.0 - 01:53:21.2 30.03 64 [PSOFF, PSOFF:CALON] [0, 1, 2, 3] [0]
# 0 05:15:13.6 -05.24.08.5
# 23 OrionS 2006/01/19/01:54:01.0 - 01:56:01.2 30.03 64 [PSON, PSON:CALON] [0, 1, 2, 3] [0]
# 0 05:35:13.4 -05.24.08.1
# 24 OrionS 2006/01/19/02:01:47.0 - 02:03:47.2 30.03 64 [PSOFF, PSOFF:CALON] [4, 5, 6, 7] [1]
# 0 05:15:13.5 -05.24.08.5
# 25 OrionS 2006/01/19/02:04:27.0 - 02:06:27.2 30.03 64 [PSON, PSON:CALON] [4, 5, 6, 7] [1]
# 0 05:35:13.4 -05.24.08.1
# 26 OrionS 2006/01/19/02:07:10.0 - 02:09:10.2 30.03 64 [PSOFF, PSOFF:CALON] [4, 5, 6, 7] [1]
# 0 05:15:13.5 -05.24.08.4
# 27 OrionS 2006/01/19/02:09:51.0 - 02:11:51.2 30.03 64 [PSON, PSON:CALON] [4, 5, 6, 7] [1]
# 0 05:35:13.3 -05.24.08.1
# --------------------------------------------------------------------------------
# FREQUENCIES: 4
# ID IFNO Frame RefVal RefPix Increment Channels POLNUs
# 0 0 LSRK 4.5489351e+10 4095.5 6104.233 8192 [0, 1]
# 1 1 LSRK 4.5300782e+10 4095.5 6104.233 8192 [0, 1]
# 2 2 LSRK 4.4074926e+10 4095.5 6104.233 8192 [0, 1]
# 3 3 LSRK 4.4166212e+10 4095.5 6104.233 8192 [0, 1]
# 4 12 LSRK 4.3962123e+10 4095.5 6104.233 8192 [0, 1]
# 5 13 LSRK 4.2645417e+10 4095.5 6104.233 8192 [0, 1]
# 6 14 LSRK 4.1594977e+10 4095.5 6104.233 8192 [0, 1]
# 7 15 LSRK 4.342282e+10 4095.5 6104.233 8192 [0, 1]
# --------------------------------------------------------------------------------
# MOLECULES:
# ID RestFreq Name
# 0 [4.54903e+10] []
# 1 [4.3963e+10] []
# --------------------------------------------------------------------------------

# The HC3N and CH3OH lines are in IFs 0 and 2 respectively
# of scans 20,21,22,23. We will pull these out in our
# calibration.

###########################################################################
# Calibrate data
###########################################################################
# We will use the sdreduce task to calibrate the data.
# Set the defaults
default('sdreduce')

# You can see the inputs with
# inp

# Set our infile (which would have been set from our run of
# sdlist if we were not cautious and reset defaults).
infile = 'OrionS_rawACSmod'
fluxunit = 'K'

# Lets leave the spectral axis in channels for now
specunit = 'channel'

# This is position-switched data so we tell sdreduce this
calmode = 'ps'

# For GBT data, it is safest to not have scantable pre-average
# integrations within scans.
average = True
scanaverage = False

default('sdreduce')

# We do want sdreduce to average up scans and polarization after
# calibration however. The averaging of scans are weighted by
# integration time and Tsys, and the averaging of polarization
# by Tsys.
timeaverage = True
tweight = 'tintsys'
polaverage = True
pweight = 'tsys'

# Do an atmospheric optical depth (attenuation) correction
# Input the zenith optical depth at 43 GHz
tau = 0.09

# Select our scans and IFs (for HC3N)
scanlist = [20, 21, 22, 23]
iflist = [0]

# We do not require selection by field name (they are all
# the same except for on and off)
field = ''

# We will do some spectral smoothing
# For this demo we will use boxcar smoothing rather than
# the default
#kernel='hanning'
# We will set the width of the kernel to 5 channels
kernel = 'boxcar'
width = 5

# We wish to fit out a baseline from the spectrum
# The GBT has particularly nasty baselines :)!
# We will let ASAP use auto_poly_baseline mode
# but tell it to drop the 1000 edge channels from
# the beginning and end of the spectrum.
# A 2nd-order polynomial will suffice for this test.
# You might try higher orders for fun.
blmode = 'auto'
blpoly = 2
edge = [1000]

# We will not give it regions as an input mask
# though you could, with something like
#masklist=[[1000,3000],[5000,7000]]
masklist = []

# By default, we will not get plots in sdreduce (but
# can make them using splot).
plotlevel = 0
# But if you wish to see a final spectrum, set
#plotlevel = 1
# or even
#plotlevel = 2
# to see intermediate plots and baselining output.

# Now we give the name for the output file
outfile = 'sdusecase_orions_hc3n.asap'

# We will write it out in ASAP scantable format
outform = 'asap'

# You can look at the inputs with
#inp

# Before running, lets save the inputs in case we want
# to come back and re-run the calibration.
saveinputs('sdreduce','sdreduce.orions.save')
# These can be recovered by
#execfile 'sdreduce.orions.save'

# We are ready to calibrate
sdreduce()

# Note that after the task ran, it produced a file
# sdreduce.last which contains the inputs from the last
# run of the task (all tasks do this). You can recover
# this (anytime before sdreduce is run again) with
# execfile 'sdreduce.last'

# List data
# List the contents of the calibrated dataset
# Set the input to the just created file
infile = outfile
outfile = ''
sdlist()

# You should see:

# Scanned Table Summary
# Project: AGBT06A_018_01
# Obs Date: 2006/01/19/01:45:58
# Observer: Joseph McMullin
# Antenna Name: GBT@GREENBANK
# Data Records: 1 rows
# Obs. Type: OffOn:PSWITCHOFF:TPWCAL
# Beams: 1
# IFs: 8
# Polarisations: 1 (stokes)
# Channels: 8192
# Flux Unit: K
# Abscissa: Channel
# Selection: none

# Scan Source Time range Int[s] Record SrcType FreqIDs MolIDs
# Beam Position (J2000)
# 0 OrionS 2006/01/19/02:04.6 - 02:00:05.1 480.48 1 [PSW] [0] [0]
# 0 05:35:13.4 -05:24.07.8

# Frequencies: 1
# ID IFNO Frame RefVal RefPix Increment Channels POLNOs
# 0 LSRK 4.5489351e+10 4095.5 6104.233 8192 [0]

# Molecules:
# ID RestFreq Name
# 0 [4.54903e+10] []
# 1 [4.3963e+10] []
# Note that our scans are now collapsed (timeaverage=True) but we still have our IF 0

# The file we produced after calibration (if we hadn't reset defaults it would have been set - note that sdplot, sdfit, sdstat use infile as the input file, which is the output file of sdreduce).
infile = 'sdusecase_orions_hc3n.asap'

# Lets just go ahead and plot it up as-is
sdplot()

# Looks ok. Plot with x-axis in GHz
specunit='GHz'
sdplot()

# Note that the rest frequency in the scantable is set correctly to the HCCCN line at 45.490 GHz. So you can plot the spectrum in km/s
specunit='km/s'
sdplot()

# Zoom in
sprange=[-100,50]
sdplot()

# Lets plot up the lines to be sure
# We have to go back to GHz for this (known deficiency in ASAP)
specunit='GHz'
sprange=[45.48,45.51]
linecat='all'
sdplot()

# Too many lines! Focus on the HC3N ones
linecat='HCCCN'
sdplot()

# Finally, we can convert from K to Jy
# using the aperture efficiencies we have
# coded into the sdtasks
# For GBT data, do not set telescopeparm
fluxunit='Jy'
telescopeparm=''
sdplot()

# Lets save this plot
outfile='sdusecase_orions_hc3n.eps'
sdplot()

##########################
# Off-line Statistics
##########################
# Now do some region statistics
# First the line-free region
# Set parameters
default('sdsstat')
infile = 'sdusecase_orions_hc3n.asap'

# Keep the default spectrum and flux units
# K and channel
fluxunit = ''
specunit = ''

# Pick out a line-free region
# You can bring up a default sdplot again
# to check this
masklist = [[5000, 7000]]

# This is a line-free region so we don’t need
# to invert the mask
invertmask = False

# You can check with
#inp

# sdsstat returns some results in
# the Python dictionary. You can assign
# this to a variable
off_stat=sdsstat()

# and look at it
off_stat
# which should give
CHAPTER 8. SINGLE DISH DATA PROCESSING

# You see it has some keywords for the various stats. We want the standard deviation about
# the mean, or 'stddev'
print "The off-line std. deviation = ", off_stat['stddev']
# which should give
# The off-line std. deviation = 0.0474953278899

# or better formatted (using Python I/O formatting)
print "The off-line std. deviation = %5.3f K" %
    (off_stat['stddev'])
# which should give
# The off-line std. deviation = 0.047 K

# On-line Statistics
# Now do the line region
# Continue setting or resetting parameters
masklist = [[3900,4200]]

line_stat = sdstat()

# look at these
line_stat
# which gives
# {'eqw': 73.335154614280981,
# 'max': 0.92909121513366699,
# 'mean': 0.22636228799819946,
# 'median': 0.10317134857177734,
# 'min': -0.13283586502075195,
# 'rms': 0.35585442185401917,
# 'stddev': 0.27503398060798645,
# 'sum': 68.135047912597656}

# of particular interest are the max value
print "The on-line maximum = %5.3f K" % (line_stat['max'])
# which gives
# The on-line maximum = 0.929 K

# and the estimated equivalent width (in channels)
# which is the sum/max
print "The estimated equivalent width = %5.1f channels" %
   (line_stat['eqw'])
# which gives
# The estimated equivalent width = 73.3 channels

# Line Fitting
# Now we are ready to do some line fitting
# Default the parameters
default('sdfit')

# Set our input file
infile = 'sdusecase_orions_hc3n.asap'

# Stick to defaults
# fluxunit = 'K', specunit = 'channel'
fluxunit = ''
specunit = ''

# We will try auto-fitting first
fitmode = 'auto'
# A single Gaussian
nfit = [1]
# Leave the auto-parameters to their defaults for
# now, except ignore the edge channels
edge = [1000]

# Lets see a plot while doing this
plotlevel = 1

# Save the fit output in a file
outfile = 'sdusecase_orions_hc3n.fit'

# Go ahead and do the fit
fit_stat=sdfit()

# If you had verbose mode on, you probably saw something
# like:
# 0: peak = 0.811 K, centre = 4091.041 channel, FWHM = 72.900 channel
# area = 62.918 K channel

# The fit is output in the dictionary

fit_stat =
#
# {'cent': [[4091.04052734375, 0.72398632764816284]],
# 'fwhm': [[72.899894714355469, 1.7048574686050415]],
# 'nfit': 1,
# 'peak': [[0.81080442667007446, 0.016420882195234299]]}
#
# So you can write them out or test them:
print "The line-fit parameters were:",
print " maximum = %6.3f +/- %6.3f K" \n(fit_stat['peak'][0][0],fit_stat['peak'][0][1])
print " center = %6.1f +/- %6.1f channels" \n(fit_stat['cent'][0][0],fit_stat['cent'][0][1])
print " FWHM = %6.2f +/- %6.2f channels" \n(fit_stat['fwhm'][0][0],fit_stat['fwhm'][0][1])
#
# Which gives:
# The line-fit parameters were:
# maximum = 0.811 +/- 0.016 K
# center = 4091.0 +/- 0.7 channels
# FWHM = 72.90 +/- 1.70 channels

# We can do the fit in km/s also
specunit = 'km/s'
# For some reason we need to help it along with a mask
maskline = [-50,0]

outfile = 'sdusecase_orions_hc3n_kms.fit'
fit_stat_kms = sdfit()
# Should give (if in verbose mode)
# 0: peak = 0.811 K, centre = -27.134 km/s, FWHM = 2.933 km/s
# area = 2.531 K km/s
#
#
# with
fit_stat_kms
# giving
CHAPTER 8. SINGLE DISH DATA PROCESSING

# The line-fit parameters were:
max = 0.811 +/- 0.009 K
cent = -27.13 +/- 0.02 km/s
FWM = 2.9329 +/- 0.0388 km/s

8.2.2.2 Imaging of Total Power Raster Scans

This example illustrates the use of sdtpimaging for the total power raster scans of the Moon taken at ATF.

# The data used here (uid__X1e1__X3197__X1.ms) is the total power raster scans of the Moon taken at ATF (with both antennas).
# It is in MS format which was converted from the ASDM format.

# Do data plotting only
default(sdtpimaging)
inp()
plotlevel=2
# select antenna 1 (Vertex antenna)
antenna='1'
infile='uid__X1e1__X3197__X1.ms'
sdtpimaging()

# Now, rerun sdtpimaging to do actual data reduction (applying
Figure 8.5: Total power data display using sdtpimaging, with calmode='baseline'. The top panel shows uncalibrated data versus row numbers. The middle panel shows baseline fitting of each scan (only shown here the last scan). The bottom panel shows the calibrated (baseline subtracted) data.

```python
# baseline subtraction from each scan, and then do imaging).
#
# Do baseline subtraction
# calmode='baseline'
# masklist=[30] # use 30 data points from each end of scan for fitting
# Do imaging
createimage=True
outfile='moon.im'
imagesize=[200,200]
cell=[0.2] # in arcmin
```
CHAPTER 8. SINGLE DISH DATA PROCESSING

phasecenter='AZEL 187d54m22s 41d03m0s'
ephemsrcname='moon' # specify ephemeris source name (can be omitted)
plotlevel=1
#plotlevel=2 to see progress of each fitting
sdtpimaging()

8.3 Using The ASAP Toolkit within CASA

ASAP is included with the CASA installation/build. It is loaded upon start-up, and the ASAP functionality is under the Python 'sd' tool. Note: This means that if you are following the ASAP cookbook or documentation, all of the commands should be invoked with a 'sd.' before the native ASAP command.

The ASAP interface is essentially the same as that of the CASA toolkit, that is, there are groups of functionality (aka tools) which have the ability to operate on your data. Type:

```
CASA <4>: sd.<TAB>
```

```
sd.___builtins__  sd.___validate_bool  sd._list_scans
sd.___class__    sd.___validate_int  sd._mask_and
sd.___date__     sd._asapfitter      sd._mask_not
sd.___delattr__  sd._asaplinefind   sd._mask_or
sd.___dict__     sd._asaplog         sd._merge
sd.___doc__      sd._asapplotbase   sd._os
sd.___file__     sd._asapplotgui    sd._plf
sd.___getattribute__ sd._asapmath     sd._plotter
sd.___hash__     sd._asapplotter    sd._print_log
sd.___init__     sd._asapreader     sd._quotient
sd.___name__     sd._average_time   sd._rc
sd.___new__      sd._calods         sd._rcParams
sd.___path__     sd._calnod          sd._rcParamsDefault
sd.___reduce__   sd._calps           sd._rc_params
sd.___reduce_ex__ sd._casapath       sd._rcdefaults
sd.___repr__     sd._commands       sd._reader
sd.___revision__ sd._defaultParams  sd._revinfo
sd.___setattr__  sd._dosigref       sd._scatable
sd.___str__      sd._dototalpower   sd._selector
sd.___version__  sd._fitter          sd._simple_math
sd._asap         sd._interactivemask sd._sys
sd._asap_fname   sd._is_ipython     sd._unique
sd._asaplog      sd._linecatalog    sd._version
sd._is_sequence_or_number sd._linefinder sd._welcome
sd._n_bools      sd._list_files     sd._xyplothter
```

...to see the list of tools.

In particular, the following are essential for most reduction sessions:
CHAPTER 8. SINGLE DISH DATA PROCESSING

- **sd.scantable** - the data structure for ASAP and the core methods for manipulating the data; allows importing data, making data selections, basic operations (averaging, baselines, etc) and setting data characteristics (e.g., frequencies, etc).

- **sd.selector** - selects a subset of data for subsequent operations

- **sd.fitter** - fit data

- **sd.plotter** - plotting facilities (uses matplotlib)

The **scantable** functions are used most often and can be applied to both the initial scantable and to any spectrum from that scan table. Type

```
sd.scantable.<TAB>
```

(using TAB completion) to see the full list.

### 8.3.1 Environment Variables

The **asaprc** environment variables are stored in the Python dictionary **sd.rcParams** in CASA. This contains a number of parameters that control how ASAP runs, for both tools and tasks. You can see what these are set to by typing at the CASA prompt:

```
CASA <2>: sd.rcParams
Out[2]:
{'insitu': True,
 'plotter.colours': '',
 'plotter.decimate': False,
 'plotter.ganged': True,
 'plotter.gui': True,
 'plotter.histogram': False,
 'plotter.linestyles': '',
 'plotter.panelling': 's',
 'plotter.papertype': 'A4',
 'plotter.stacking': 'p',
 'scantable.autoaverage': True,
 'scantable.freqframe': 'LSRK',
 'scantable.save': 'ASAP',
 'scantable.storage': 'memory',
 'scantable.verbosesummary': False,
 'useplotter': True,
 'verbose': True}
```

The use of these parameters is described in detail in the ASAP Users Guide.

These parameters can be changed through the **sd.rc** function. Use is described in **help sd.rc**:
help(sd.rc)
Help on function rc in module asap:

rc(group, **kwargs)
   Set the current rc params. Group is the grouping for the rc, eg
   for scantable.save the group is 'scantable', for plotter.stacking, the
   group is 'plotter', and so on. kwargs is a list of attribute
   name/value pairs, eg

   rc('scantable', save='SDFITS')

   sets the current rc params and is equivalent to

   rcParams['scantable.save'] = 'SDFITS'

   Use rcdsafed to restore the default rc params after changes.

Important Note:
User must use sd.rcParams['scantable.storage']='disk' with care when you call any tool level
functions since some functions may overwrite original data even if you set sd.rcParams['insitu']=False,
which tells the system not to overwrite original data (in contrast, setting sd.rcParams['insitu']
to True forces to overwrite original data). Relevant methods, which may overwrite original data in
the above case, are as follows:

* sd.average_time
* sd.merge
* four operations (+, -, *, /) of sd.scantable instance with scalar or array
* sd.scantable.add
* sd.scantable.clip
* sd.scantable.flag
* sd.scantable.flag_nans
* sd.scantable.flag_row
* sd.scantable.scale
* sd.scantable.recalc_azel
* any setter functions of sd.scantable class (both set_xxx and _setxxx functions)

8.3.2 Import

Data can be loaded into ASAP by using the scantable function which will read a variety of
recognized formats (RPFITS, varieties of SDFITS, the CASA Measurement Set, and NRO data
format). For example:

CASA <1>: scans = sd.scantable('OrionS_rawACSmod', average=False)
Importing OrionS_rawACSmod...
Use the `summary` function to examine the data and get basic information:

```python
CASA <8>: print scans.summary()
```

---

**Scan Table Summary**

---

<table>
<thead>
<tr>
<th>Project:</th>
<th>AGBT06A_018_01</th>
</tr>
</thead>
<tbody>
<tr>
<td>Obs Date:</td>
<td>2006/01/19/01:45:58</td>
</tr>
<tr>
<td>Observer:</td>
<td>Joseph McMullin</td>
</tr>
<tr>
<td>Antenna Name:</td>
<td>GBT@GREENBANK</td>
</tr>
<tr>
<td>Data Records:</td>
<td>512 rows</td>
</tr>
<tr>
<td>Obs. Type:</td>
<td>OffOn:PSWITCHOFF:TPWCAL</td>
</tr>
<tr>
<td>Beams:</td>
<td>1</td>
</tr>
<tr>
<td>IFs:</td>
<td>8</td>
</tr>
<tr>
<td>Polarisations:</td>
<td>2 (circular)</td>
</tr>
<tr>
<td>Channels:</td>
<td>8192</td>
</tr>
<tr>
<td>Flux Unit:</td>
<td>K</td>
</tr>
<tr>
<td>Abscissa:</td>
<td>Channel</td>
</tr>
<tr>
<td>Selection:</td>
<td>none</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Scan Source</th>
<th>Time range</th>
<th>Int[s]</th>
<th>Record</th>
<th>SrcType</th>
<th>FreqIDs</th>
<th>MolIDs</th>
</tr>
</thead>
<tbody>
<tr>
<td>20 OrionS</td>
<td>2006/01/19/01:45:58.0 - 01:47:58.2</td>
<td>30.03</td>
<td>64</td>
<td>[PSOFF, PSOFF:CALON] [0, 1, 2, 3] [0]</td>
<td></td>
<td></td>
</tr>
<tr>
<td>21 OrionS</td>
<td>2006/01/19/01:48:38.0 - 01:50:38.2</td>
<td>30.03</td>
<td>64</td>
<td>[PSON, PSON:CALON] [0, 1, 2, 3] [0]</td>
<td></td>
<td></td>
</tr>
<tr>
<td>22 OrionS</td>
<td>2006/01/19/01:51:21.0 - 01:53:21.2</td>
<td>30.03</td>
<td>64</td>
<td>[PSOFF, PSOFF:CALON] [0, 1, 2, 3] [0]</td>
<td></td>
<td></td>
</tr>
<tr>
<td>23 OrionS</td>
<td>2006/01/19/01:54:01.0 - 01:56:01.2</td>
<td>30.03</td>
<td>64</td>
<td>[PSON, PSON:CALON] [0, 1, 2, 3] [0]</td>
<td></td>
<td></td>
</tr>
<tr>
<td>24 OrionS</td>
<td>2006/01/19/02:01:47.0 - 02:03:47.2</td>
<td>30.03</td>
<td>64</td>
<td>[PSOFF, PSOFF:CALON] [4, 5, 6, 7] [1]</td>
<td></td>
<td></td>
</tr>
<tr>
<td>25 OrionS</td>
<td>2006/01/19/02:04:27.0 - 02:06:27.2</td>
<td>30.03</td>
<td>64</td>
<td>[PSON, PSON:CALON] [4, 5, 6, 7] [1]</td>
<td></td>
<td></td>
</tr>
<tr>
<td>26 OrionS</td>
<td>2006/01/19/02:07:10.0 - 02:09:10.2</td>
<td>30.03</td>
<td>64</td>
<td>[PSOFF, PSOFF:CALON] [4, 5, 6, 7] [1]</td>
<td></td>
<td></td>
</tr>
<tr>
<td>27 OrionS</td>
<td>2006/01/19/02:09:51.0 - 02:11:51.2</td>
<td>30.03</td>
<td>64</td>
<td>[PSON, PSON:CALON] [4, 5, 6, 7] [1]</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

**FREQUENCIES:** 4

<table>
<thead>
<tr>
<th>ID</th>
<th>IFNO</th>
<th>Frame</th>
<th>RefVal</th>
<th>RefPix</th>
<th>Increment</th>
<th>Channels</th>
<th>POLNIDs</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>0</td>
<td>LSRK</td>
<td>4.5489351e+10 4095.5</td>
<td>6104.233</td>
<td>8192 [0, 1]</td>
<td></td>
<td></td>
</tr>
<tr>
<td>1</td>
<td>1</td>
<td>LSRK</td>
<td>4.5500782e+10 4095.5</td>
<td>6104.233</td>
<td>8192 [0, 1]</td>
<td></td>
<td></td>
</tr>
<tr>
<td>2</td>
<td>2</td>
<td>LSRK</td>
<td>4.5700782e+10 4095.5</td>
<td>6104.233</td>
<td>8192 [0, 1]</td>
<td></td>
<td></td>
</tr>
<tr>
<td>3</td>
<td>3</td>
<td>LSRK</td>
<td>4.5500782e+10 4095.5</td>
<td>6104.233</td>
<td>8192 [0, 1]</td>
<td></td>
<td></td>
</tr>
<tr>
<td>4</td>
<td>12</td>
<td>LSRK</td>
<td>4.5900782e+10 4095.5</td>
<td>6104.233</td>
<td>8192 [0, 1]</td>
<td></td>
<td></td>
</tr>
<tr>
<td>5</td>
<td>13</td>
<td>LSRK</td>
<td>4.5450214e+10 4095.5</td>
<td>6104.233</td>
<td>8192 [0, 1]</td>
<td></td>
<td></td>
</tr>
<tr>
<td>6</td>
<td>14</td>
<td>LSRK</td>
<td>4.5500782e+10 4095.5</td>
<td>6104.233</td>
<td>8192 [0, 1]</td>
<td></td>
<td></td>
</tr>
<tr>
<td>7</td>
<td>15</td>
<td>LSRK</td>
<td>4.5422828e+10 4095.5</td>
<td>6104.233</td>
<td>8192 [0, 1]</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

**MOLECULES:**

<table>
<thead>
<tr>
<th>ID</th>
<th>RestFreq</th>
<th>Name</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>[4.54903e+10]</td>
<td>[]</td>
</tr>
<tr>
<td>1</td>
<td>[4.3963e+10]</td>
<td>[]</td>
</tr>
</tbody>
</table>
8.3.2.1 General descriptions

The following are some cautions when using import feature.

- It is important to specify the \texttt{antenna} parameter when importing Measurement Set. For example:

  \begin{verbatim}
  CASA<1>: scans = sd.scantable( 'OrionS_rawACSmod', average=False, antenna=0 )
  \end{verbatim}

  The value of the \texttt{antenna} parameter can be either id (integer) or name (string). The default value for \texttt{antenna} parameter is 0.

- It is important to use the \texttt{average=False} parameter setting as the calibration routines supporting GBT data require all of the individual times and phases.

- GBT data may need some pre-processing prior to using ASAP. In particular, the program which converts GBT raw data into CASA Measurement Sets tends to proliferate the number of spectral windows due to shifts in the tracking frequency; this is being worked on by GBT staff.

- Identification of observing modes or reference and source data are changed from the name assignment to the identification number assignment. Position switched (’ps’), Nod (’nod’), and frequency switched (’fs’) data are assigned their id number as 0, 2, and 3, respectively. The corresponding reference data (name with ‘r’) for position switched and frequency switched modes are assigned as 1 and 4, respectively. These identification number is stored as SRCTYPE in the scantable.

- Importing of Nobeyama Radio Observatory (NRO) data (in both OTF and NEWSTAR format) is available. However, it is still experimental and only tested to work from toolkit level.

8.3.2.2 Handling ALMA data

- Using \texttt{importasdm} task, ASDM data can be imported to ASAP directly. To do that, you should set \texttt{singledish=True} and specify id or name of the antenna by the \texttt{antenna} parameter (see §\ref{sec:import}). This functionality is still under testing. You can use previous two step process (import ASDM as MS using \texttt{importasdm} task first, then import MS as ASAP format) to import ASDM as ASAP format if you have any problem during direct import.

- If the MS data contain data from multiple single dish antennas you need either, to specify the \texttt{antenna} parameter when importing data (\texttt{sd.scantable}) or, to split the data by antenna using \texttt{sd.splitant} for further processing in ASAP since ASAP scantable cannot properly store the data from multiple antennas. The method \texttt{sd.splitant} splits a Measurement Set by
antenna ID and save the tables as scantables containing data from each antenna. The names of output scantables are defined as prefix specified by users (with parameter `outprefix`) + '.' + antenna name. For example, if you split Measurement Set, foo.ms, which contains data from antA and antB, with `outprefix='splitted'`, i.e., `sd.splitant('foo.ms', outprefix='splitted')`, the names of scantables are 'splitted.antA' and 'splitted.antB'. The returned value of the method is a list of scantable names.

- From 4.1, frequency reference frame of imported scantables takes from that of MS or ASDM (usually TOPO), while it was forcibly set to LSRK in previous release.

- It is possible to read the 2-element interferometric data taken by the ALMA telescopes as a single dish data to further examine it using ASAP Toolkit and the SDtasks. The usage is the same as importing single dish data. For example, to load the ALMA interferometry data, `myOSFint.ms`

  ```python
  s=sd.scantable('myOSFint.ms', 'False')
  ```

It is still experimental and limited to data obtained with a two-element array.

- In ALMA, Tsys measurement is done in a specific spectral window for calibration so that it is necessary to transfer Tsys to the spectral window for target scan. This can be done using `filltsys` module or `sdcal2` task. Usage of `filltsys` is as follows:

  ```python
  import filltsys
  filltsys.fillTsys( filename='mydata.asap', specif=5, tsysif=1, mode='linear' )
  ```

  The parameter `filename` specifies a name of the data to be processed. Data must be in ASAP format. The spectral windows (=IFs) for target scan and calibration scan should be set using `specif` and `tsysif`, respectively. You can identify those informations using `sdlist` task. The `mode` is an interpolation mode along frequency axis. Available options are 'linear', 'nearest', 'zero', 'slinear', 'quadratic', 'cubic', and any integer specifying an order of the spline interpolation. Note that `filltsys` will overwrite the data specified by `filename`. See §8.2.1.2 if you want to use `sdcal2`.

### 8.3.2.3 Importing NRO data

Importing NRO data is available. Here are some notes on NRO data import.

- Both NEWSTAR and NOSTAR format are supported.

- Dual-polarization data is supported.

- IFNO is assigned for each array such that you can identify which IFNO corresponds to which array number. If you use A01, A03, and A05, their IFNOs will be 0, 1, and 2, respectively.

- Development mainly focuses on recent data, especially for new correlator. Although older data (using AOS) can be imported, there may be an inconsistency with original data.
• `freqref` parameter controls how frequency reference frame is set. Default is 'rest'. Other option is 'vref'. If `freqref` is 'vref', frequency reference frame takes from VREF field in input NRO data. This parameter is only available for tool level, i.e. `sd.scantable`.

• There is a problem on imaging multi-beam data.

### 8.3.3 Scantable Manipulation

Within ASAP, data is stored in a `scantable`, which holds all of the observational information and provides functionality to manipulate the data and information. The building block of a `scantable` is an integration which is a single row of a scantable. Each row contains just one spectrum for each beam, IF and polarization.

Once you have a `scantable` in ASAP, you can select a subset of the data based on scan numbers, sources, or types of scan; note that each of these selections returns a new 'scantable' with all of the underlying functionality:

```
CASA <5>: scan27=scans.get_scan(27)    # Get the 27th scan
CASA <6>: scans20to24=scans.get_scan(range(20,25)) # Get scans 20 - 24
CASA <7>: scans_on=scans.get_scan('*_ps') # Get ps scans on source
CASA <8>: scansOrion=scans.get_scan('Ori*') # Get all Orion scans
```

To copy a scantable, do:

```
CASA <15>: ss=scans.copy()
```

#### 8.3.3.1 Data Selection

In addition to the basic data selection above, data can be selected based on IF, beam, polarization, scan number as well as values such as Tsys. To make a selection create a `selector` object choose among various selection functions, e.g.,

```
sel = sd.selector()    # initialize a selector object
    # sel.<TAB> will list all options
sel.set_ifs(0)    # select only the first IF of the data
scans.set_selection(sel) # apply the selection to the data
print scans     # shows just the first IF
```

#### 8.3.3.2 State Information

Some properties of a scantable apply to all of the data, such as spectral units, frequency frame, or Doppler type. This information can be set using the `scantable.set_xxxx` methods. These are currently:
CASA <1>: sd.scantable.set_<TAB>
sd.scantable.set_dirframe  sd.scantable.set_restfreqs
sd.scantable.set_doppler   sd.scantable.set_selection
sd.scantable.set_feedtype sd.scantable.set_sourcetype
sd.scantable.set_fluxunit sd.scantable.set_spectrum
sd.scantable.set_freqframe sd.scantable.set_unit
sd.scantable.set_instrument

For example, sd.scantable.set_fluxunit sets the default units that describe the flux axis:

```
scans.set_fluxunit('K')  # Set the flux unit for data to Kelvin
```

Choices are 'K' or 'Jy'. Note: the sd.scantable.set_fluxunit function only changes the name of the current fluxunit. To change fluxunits, use sd.antennatable.convert_flux as described in §8.3.4.2 instead (currently it is necessary to do some gymnastics for non-AT telescopes).

Use sd.scantable.set_unit to set the units to be used on the spectral axis:

```
scans.set_unit('GHz')  # Use GHz as the spectral axis for plots
```

The choices for the units are 'km/s', 'channel', or '*Hz' (e.g. 'GHz', 'MHz', 'kHz', 'Hz'). This does the proper conversion using the current frame and Doppler reference as can be seen when the spectrum is plotted.

Set the frame in which the frequency (spectral) axis is defined by sd.scantable.set_freqframe:

CASA <2>: help(sd.scantable.set_freqframe)
Help on method set_freqframe in module asap.scantable:

```
set_freqframe(self, frame=None) unbound asap.scantable.scantable method
    Set the frame type of the Spectral Axis.
    Parameters:
        frame:  an optional frame type, default 'LSRK'. Valid frames are:
                'REST', 'TOPO', 'LSRD', 'LSRK', 'BARY',
                'GEO', 'GALACTIC', 'LGROUP', 'CMB'
    Examples:
        scan.set_freqframe('BARY')
```

The most useful choices here are frame = 'LSRK' (the default for the function) and frame = 'TOPO' (what the GBT actually observes in). Note that the 'REST' option is not yet available.

The Doppler frame is set with sd.scantable.set_doppler:

CASA <3>: help(sd.scantable.set_doppler)
Help on method set_doppler in module asap.scantable:

```
set_doppler(self, doppler='RADIO') unbound asap.scantable.scantable method
    Set the doppler for all following operations on this scantable.
    Parameters:
        doppler:  One of 'RADIO', 'OPTICAL', 'Z', 'BETA', 'GAMMA'
```
Finally, there are a number of functions to query the state of the scantable. These can be found in the usual way:

CASA <4>: sd.scantable.get<TAB>
sd.scantable.get_abcissa     sd.scantable.get_parangle
sd.scantable.get_antennaname sd.scantable.get_restfreqs
sd.scantable.get_azimuth     sd.scantable.get_rms
sd.scantable.get_column_names sd.scantable.get_row
sd.scantable.get_coordinate  sd.scantable.get_row_selector
sd.scantable.get_direction   sd.scantable.get_scan
sd.scantable.get_directionval sd.scantable.get_selection
sd.scantable.get_elevation   sd.scantable.get_sourcename
sd.scantable.get_fit         sd.scantable.get_spectrum
sd.scantable.get_fluxunit    sd.scantable.get_time
sd.scantable.get_inttime     sd.scantable.get_tsys
sd.scantable.get_mask        sd.scantable.get_tsysspectrum
sd.scantable.get_mask_indices sd.scantable.get_unit
sd.scantable.get_masklist    sd.scantable.get_weather

These include functions to get the current values of the states mentioned above, as well as methods to query the number of scans, IFs, and polarizations in the scantable and their designations. See the inline help of the individual functions for more information.

8.3.3.3 Masks

Several functions (fitting, baseline subtraction, statistics, etc) may be run on a range of channels (or velocity/frequency ranges). You can create masks of this type using the `create_mask` function:

```
# spave = an averaged spectrum
spave.set_unit('channel')
rmsmask=spave.create_mask([5000,7000])  # create a region over channels 5000-7000
rms=spave.stats(stat='rms',mask=rmsmask)  # get rms of line free region

rmsmask=spave.create_mask([3000,4000],invert=True)  # choose the region
          # *excluding* the specified channels
```

The mask is stored in a simple Python variable (a list) and so may be manipulated using an Python facilities.

8.3.3.4 Scantable Management

`scantables` can be listed via:

CASA <33>: sd.list_scans()
The user created scantables are:
['scans20to24', 's', 'scan27']
As every scantable will consume memory, if you will not use it any longer, you can explicitly remove it via:

```
del <scantable name>
```

### 8.3.3.5 Scantable Mathematics

It is possible to do simple mathematics directly on scantables from the CASA command line using the `+`, `-`, `*`, `/` operators as well as their cousins `+=`, `-=` , `*=` , `/=`.

```
CASA <10>: scan2=scan1+2.0 # add 2.0 to data  
CASA <11>: scan *= 1.05  # scale spectrum by 1.05
```

Operands can be a numerical value and one- or two-dimensional Python list. For list operand, its shape should be conform with the shape of spectral data stored in the scantable. Mathematics between two scantables is also available. In that case, scantables must be conform with each other.

**NOTE:** In scantable mathematics, scantable must be put on the left. For example:

```
CASA<12>: scan2=scan1+2.0  # this works  
CASA<13>: scan2=2.0+scan1  # this causes an error
```

### 8.3.3.6 Scantable Save and Export

ASAP can save scantables in a variety of formats, suitable for reading into other packages. The formats are:

- **ASAP** – This is the internal format used for ASAP. It is the only format that allows the user to restore the data, fits, etc., without losing any information. As mentioned before, the ASAP scantable is a CASA Table (memory-based table). This function just converts it to a disk-based table. You can access it with the CASA `browsetable` task or any other CASA table tasks.

- **SDFITS** – The Single Dish FITS format. This format was designed for interchange between packages but few packages can actually read it.

- **ASCII** – A simple text based format suitable for the user to process using Python or other means.

- **Measurement Set (V2: CASA format)** – Saves the data in a Measurement Set. All CASA tasks which use an MS should work with this format.

```
scans.save('output_filename','format'), e.g.,  
CASA <19>: scans.save('FLS3a_calfs','MS2')
```
8.3.4 Calibration

For some observatories, the calibration happens transparently as the input data contains the Tsys measurements taken during the observations. The nominal 'Tsys' values may be in Kelvin or Jansky. The user may wish to apply a Tsys correction or apply gain-elevation and opacity corrections.

8.3.4.1 Tsys scaling

If the nominal Tsys measurement at the telescope is wrong due to incorrect calibration, the scale function allows it to be corrected.

\[
\text{scans.scale}(1.05, \text{tsys=True}) \quad \# \text{by default only the spectra are scaled}
\]
\[
\quad \# \text{(and not the corresponding Tsys) unless tsys=True}
\]

8.3.4.2 Flux and Temperature Unit Conversion

To convert measurements in Kelvin to Jansky (and vice versa), the convert_flux function may be used. This converts and scales the data to the selected units. The user may need to supply the aperture efficiency, telescope diameter, or the Jy/K factor.

\[
\text{scans.convert_flux}(\eta=0.48, d=35.) \quad \# \text{Unknown telescope}
\]
\[
\text{scans.convert_flux}(\text{jypk}=15) \quad \# \text{Unknown telescope (alternative)}
\]
\[
\text{scans.convert_flux}() \quad \# \text{known telescope (mostly AT telescopes)}
\]
\[
\text{scans.convert_flux}(\eta=0.48) \quad \# \text{if telescope diameter known}
\]

8.3.4.3 Gain-Elevation and Atmospheric Optical Depth Corrections

At higher frequencies, it is important to make corrections for atmospheric opacity and gain-elevation effects. **NOTE:** Currently, the MS to scantable conversion does not adequately populate the azimuth and elevation in the scantable. As a result, one must calculate these via:

\[
\text{scans.recalc_azel}()
\]

Computed azimuth/elevation using

Position: [882590, -4.92487e+06, 3.94373e+06]
\[
\text{Time: 01:48:38 Direction: 05:35:13.5 -05.24.08.2}
\]
\[
\Rightarrow \text{azel: 154.696 43.1847 (deg)}
\]
\[
\text{Time: 01:48:38 Direction: 05:35:13.5 -05.24.08.2}
\]
\[
\Rightarrow \text{azel: 154.696 43.1847 (deg)}
\]
\[
\text{Time: 01:48:38 Direction: 05:35:13.5 -05.24.08.2}
\]
\[
\Rightarrow \text{azel: 154.696 43.1847 (deg)}
\]
\[
\text{Time: 01:48:38 Direction: 05:35:13.5 -05.24.08.2}
\]
\[
\Rightarrow \text{azel: 154.696 43.1847 (deg)}
\]
\[
\text{Time: 01:48:38 Direction: 05:35:13.5 -05.24.08.2}
\]
\[
\Rightarrow \text{azel: 154.696 43.1847 (deg)}
\]
With the correct Az/El, it can be corrected for a known opacity by:

```python
scans.opacity(tau=0.09)  # Opacity from which the correction factor:
# exp(tau*zenith-distance)
```

### 8.3.4.4 Calibration of GBT data

Data from the GBT are uncalibrated and come as sets of integrations representing the different phases of a calibration cycle (e.g., on source, calibration on, on source, calibration off, on reference, calibration on; on reference, calibration off). Currently, there are a number of routines emulating the standard GBT calibration (in GBTIDL):

- **calps** - calibrate position switched data
- **calfs** - calibrate frequency switched data
- **calnod** - calibration nod (beam switch) data

All these routines calibrate the spectral data to antenna temperature adopting the GBT calibration method as described in the GBTIDL calibration document available at:


There are two basic steps:

First, determine system temperature using a noise tube calibrator (**sd.dototalpower()**)

For each integration, the system temperature is calculated from CAL noise on/off data as:

\[
T_{\text{sys}} = T_{\text{cal}} \times \frac{<\text{ref}_{\text{caloff}}>-<\text{ref}_{\text{calon}}>-\text{caloff}>}{2} + \frac{T_{\text{cal}}}{2}
\]

*ref* which refers to reference data and the spectral data are averaged across the bandpass. Note that the central 80% of the spectra are used for the calculation.

Second, determine antenna temperature (**sd.dosigref()**)

The antenna temperature for each channel is calculated as:

\[
T_a(\nu) = T_{\text{sys}} \times \frac{\text{sig}(\nu)-\text{ref}(\nu)}{\text{ref}(\nu)}
\]

where \( \text{sig} = \frac{1}{2}(\text{sig}_{\text{calon}} + \text{sig}_{\text{caloff}}) \), \( \text{ref} = \frac{1}{2}(\text{ref}_{\text{calon}} + \text{ref}_{\text{caloff}}) \).

Each calibration routine may be used as:

```python
scans=sd.scantable('inputdata',False)  # create a scantable called 'scans'
calibrated_scans = sd.calps(scans,[scanlist])  # calibrate scantable with position-switched scheme
```

**Note:** For calps and calnod, the **scanlist** must be scan pairs in correct order as these routines only do minimal checking.
8.3.4.5 Comprehensive calibration function

A new function `calibrate` is introduced for more comprehensive calibration. This function calls appropriate calibration scheme by referring the antenna name in the metadata. The user just specify input scantable and calmode parameter that indicates calibration mode ('ps', 'nod', 'fs', 'otf', or 'otfraster'). For GBT data, `calibrate` function calls one of the functions listed in the above section depending upon the value of `calmode`. For APEX data, `apexcal` function is called, while for ALMA data, that contains string 'ALMA' or 'OSF' in its antenna name, `almacal` function is called. Calibration scheme for these two telescopes are essentially same, and can be expressed as,

\[ T_A^* = T_{sys} \times \frac{(ON - OFF)}{OFF}, \]

where OFF scans are interpolated in time if possible.

8.3.5 Averaging

One can average polarizations in a scantable using the `sd.scantable.average.pol` function:

```python
averaged_scan = scans.average_pol(mask, weight)
```

where:

**Parameters:**
- `mask`: An optional mask defining the region, where the averaging will be applied. The output will have all specified points masked.
- `weight`: Weighting scheme. 'none' (default), 'var' (1/var(spec) weighted), or 'tsys' (1/Tsys**2 weighted)

**Example:**

```python
spave = stave.average_pol(weight='tsys')
```

One can also average scans over time using `sd.average_time`:

```python
sd.average_time(scantable, mask, scanav, weight, align)
```

where:

**Parameters:**
- one scan or comma separated scans
- `compel`: if True, enable averaging of multi-resolution spectra.
- `mask`: an optional mask (only used for 'var' and 'tsys' weighting)
- `scanav`: True averages each scan separately, False (default) averages all scans together,
- `weight`: Weighting scheme.
- 'none' (mean no weight)
`var` (1/var(spec) weighted)
`tsys` (1/Tsys**2 weighted)
`tint` (integration time weighted)
`tintsys` (Tint/Tsys**2)
`median` (median averaging)

align: align the spectra in velocity before averaging. It takes the time of the first spectrum in the first scantable as reference time.

Example:

```python
stave = sd.average_time(scans, weight='tintsys')
```

Note that alignment of the velocity frame should be done before averaging if the time spanned by the scantable is long enough. This is done through the `align=True` option in `sd.average_time`, or explicitly through the `sd.scantable.freq_align` function, e.g.

```python
CASA <62>: sc = sd.scantable('orions_scan20to23_if0to3.asap', False)
CASA <63>: sc.freq_align()
Aligned at reference Epoch 2006/01/19/01:49:23 (UTC) in frame LSRK
CASA <64>: av = sd.average_times(sc)
```

The time averaging can also be applied to multiple scantables. For example, such data might have been taken on different days. The `sd.average_time` function takes multiple scantables as input. However, if they are taken at significantly different times (different days for example), then `sd.scantable.freq_align` must be used to align the velocity scales to the same time, e.g.

```python
CASA <65>: sc1 = sd.scantable('orions_scan21_if0to3.asap', False)
CASA <66>: sc2 = sd.scantable('orions_scan23_if0to3.asap', False)
CASA <67>: sc1.freq_align()
Aligned at reference Epoch 2006/01/19/01:49:23 (UTC) in frame LSRK
CASA <68>: sc2.freq_align(reftime='2006/01/19/01:49:23')
Aligned at reference Epoch 2006/01/19/01:54:46 (UTC) in frame LSRK
CASA <69>: scav = sd.average_times(sc1, sc2)
```

### 8.3.6 Spectral Smoothing

Smoothing on data can be done as follows:

```python
scantable.smooth(kernel, # type of smoothing: 'hanning' (default), 'gaussian', 'boxcar'
width, # width in pixls (ignored for hanning); FWHM for gaussian.
insitu) # if False (default), do smoothing in-situ; otherwise,
# make new scantable
```

Example:

```python
# spave is an averaged spectrum
spave.smooth('boxcar', 5) # do a 5 pixel boxcar smooth on the spectrum
sd.plotter.plot(spave) # should see smoothed spectrum
```
8.3.7 Baseline Fitting

CASA offers a variety of functions for baseline fitting: polynomial, cubic spline, Chebyshev polynomial and sinusoid are available.

The function `sd.scantable.poly_baseline` carries out a baseline fit, given a mask of channels (if desired):

```python
msk=scans.create_mask([100,400],[600,900])
sans.poly_baseline(msk,order=1)
```

This will fit a first order polynomial to the selected channels and subtract this polynomial from the full spectrum.

The `auto_poly_baseline` function can be used to automatically baseline your data without specifying channel ranges for the line-free data. It automatically figures out the line-free emission and fits a polynomial baseline to that data. The user can use masks to fix the range of channels or velocity range for the fit as well as mark the band edge as invalid:

```python
scans.auto_poly_baseline(mask,order,insitu,edge,threshold,chan_avg_limit,plot,...):
```

Parameters:

- **mask**: an optional mask retrieved from scantable
- **order**: the order of the polynomial (default is 0)
- **insitu**: if False a new scantable is returned. Otherwise, the scaling is done in-situ
  - The default is taken from .asaprc (False)
- **clipthresh**: Clipping threshold. (default is 3.0, unit: sigma)
- **clipniter**: maximum number of iteration of 'clipthresh'-sigma clipping (default is 0: no clipping)
- **edge**: an optional number of channel to drop at the edge of spectrum. If only one value is specified, the same number will be dropped from both sides of the spectrum. Default is to keep all channels. Nested tuples represent individual edge selection for different IFs (a number of spectral channels can be different)
- **threshold**: the threshold used by line finder. It is better to keep it large as only strong lines affect the baseline solution.
- **chan_avg_limit**: the maximum number of consecutive spectral channels to average during the search of weak and broad lines. The default is no averaging (and no search for weak lines). If such lines can affect the fitted baseline (e.g. a high order polynomial is fitted), increase this parameter (usually values up to 8 are reasonable). Most users of this method should find the default value sufficient.
- **plot**: plot the fit and the residual. In this each
individual fit has to be approved, by typing 'y'
or 'n'

getresidual: if False, returns best-fit values instead of
residual (default is True)

showprogress:
show progress status for large data.
default is True.

minnrow: minimum number of input spectra to show progress
status. default is 1000.

outlog: Output the coefficients of the best-fit
function to logger (default is False)

blfile: Name of a text file in which the best-fit
parameter values to be written
(default is "": no file/logger output)

csvformat: if True blfile is csv-formatted. default is False.

bltable: name of a baseline table where fitting results
(coefficients, rms, etc.) are to be written.
if given, fitting results will NOT be output to
scantable (insitu=True) or None will be returned
(insitu=False). default is "." (no bltable output)

Example:
scans.auto_poly_baseline(order=2,threshold=5)

The parameters edge, threshold, and chan_avg_limit can be used in common for all the baseline
fitting functions that use linefinder (auto_*.baseline).

The functions chebyshev_baseline and auto_chebyshev_baseline are for baselining using the
Chebyshev polynomials with or without linefinder, respectively.

The functions cspline_baseline and auto_cspline_baseline are for cubic spline fitting with or
without using linefinder, respectively. The unique parameters for these are as follows:

npiece: Number of pieces. (default is 2)

The functions sinusoid_baseline and auto.sinusoid_baseline are for sinusoidal fitting with or
without using linefinder, respectively. The unique parameters for these are as follows:

nwave: the maximum wave number of sinusoids within a range
of spectral width multiplied by maxwavelength.
The default is 3 (i.e., sinusoids with wave
number of 0(constant), 1, 2, and 3 are
used for fitting). Also it is possible to
explicitly specify all the wave numbers to
be used, by giving a list including them
(e.g., [0, 1, 2, 15, 16]).

maxwavelength: the longest sinusoidal wavelength. The
default is 1.0 (unit: spectral range)
In CASA 4.1, these tool functions to fit/subtract baseline get significantly (2-10 times) faster compared with CASA 4.0.

Note that the parameters `clipthresh` and `clipniter` can now be used for all the available baseline functions.

Other new features and functionalities in CASA 4.1 include:

- Baseline function type and parameters can be independently specified for each spectrum in a Scantable. A new sd tool function `sd.scantable.sub_baseline` is offered to do that.

- Baseline fitting results can be stored as a baseline table, a CASA Table containing baseline function type, parameters, fitting results (coefficients, rms, etc.) and so on. Specifying table name in a new parameter `bltable` for `sd.scantable.*_baseline` enables you to store fitting results in an independent table outside scantable.

- Applying an existing baseline table to fit/subtract baseline is also available via `sd.scantable.apply_bltable`.

- The 'goodness' of baseline fitting can be evaluated. A new sd tool function `sd.scantable.calc_aic` is available to calculate several values known as model selection criteria for a given spectrum and a baseline function. It can calculate Akaike Information Criterion (AIC), the corrected Akaike Information Criterion (AICc), Bayesian Information Criterion (BIC) and the Generalised Cross Validation (GCV).

Just as CASA 4.0, The parameter `plot` remains ignored (always set False) for cubic spline and sinusoidal fitting.

### 8.3.8 Line Fitting

Multi-component Gaussian fitting is done by creating a fitting object, specifying fit parameters and finally fitting the data. Fitting can be done on a scantable selection or an entire scantable using the `auto_fit` function.

```python
# spave is an averaged spectrum
f = sd.fitter()  # create fitter object
msk = spave.create_mask([3928, 4255])  # create mask region around line
f.set_function(gauss=1)  # set a single gaussian component
f.set_scan(spave, msk)  # set the scantable and region

# Automatically guess start values
f.fit()  # fit
f.plot(residual=True)  # plot residual
f.get_parameters()  # retrieve fit parameters

# 0: peak = 0.786 K, centre = 4091.236 channel, FWHM = 70.586 channel
#  area = 59.473 K channel
f.store_fit('orions_hc3n_fit.txt')  # store fit
```
f.set_function(gauss=1)
f.set_gauss_parameters(0.4,4100,200, component=0)

# To specify an initial guess:
# set a single gaussian component
# set initial guesses for Gaussian
# for first component (0)
# (peak,center,fwhm)

# For multiple components set
# initial guesses for each, e.g.,
# set two gaussian components
# set initial guesses for Gaussian
# for first component (0)
# set initial guesses for Gaussian
# for second component (1)

f.set_function(gauss=2)
f.set_gauss_parameters(0.4,4100,200, component=0)
f.set_gauss_parameters(0.1,4200,100, component=1)

8.3.9 Plotting

8.3.9.1 ASAP plotter

The ASAP plotter uses the same Python matplotlib library as in CASA (for x-y plots). It is accessed via the:

sd.plotter<TAB> # see all functions (omitted here)
sd.plotter.plot(scans) # the workhorse function
sd.plotter.set<TAB>
 sd.plotter.set_abcissa    sd.plotter.set_layout    sd.plotter.set_panelling
 sd.plotter.set_colors    sd.plotter.set_linestyles   sd.plotter.set_selection
 sd.plotter.set_data      sd.plotter.set_mask       sd.plotter.set_stacking
 sd.plotter.set_font      sd.plotter.set_mode       sd.plotter.set_title

Spectra can be plotted at any time when refresh = True (default) is selected, and it will attempt to do the correct layout depending on whether it is a set of scans or a single scan. You can switch off verbose plotting by refresh = False in tool parameters for faster plotting in scripts:

sd.plotter.set_data(scan,refresh=False)  # set scantable to plot
    # this should be done at first.
sd.plotter.set_mode(stacking='time',panelling='if',refresh=False)
sd.plotter.set_range(ystart=-1.0,yend=5.0,refresh=False)
sd.plotter.plot()                 # actual plotting

The details of the plotter display (matplotlib) are detailed in the earlier section.
8.3.9.2 Line Catalog

ASAP allows loading a custom line catalog in ASCII format. The ASCII text file must have at least 4 columns with Molecule name, frequency in MHz, frequency error and intensity (any units). If the molecule name contains any spaces, they must be wrapped in quotes "". A sample of the ASCII catalog is shown below.

```
H2D+  3955.2551  228.8818  -7.1941
H2D+  12104.7712 177.1558  -6.0769
H2D+  45809.2731 118.3223  -3.9494
CH    701.6811   .0441    -7.1641
CH    724.7709   .0456    -7.3912
CH    3263.7940   .1000   -6.3501
CH    3335.4810   .1000   -6.0304
```

You can load the ASCII line catalog, for example, if it is called my_custom_linecat.txt, by following command.

```
mycatlog = sd.linecatlog('my_custom_linecat.txt')
```

Use `sd.plotter.plot_line` to overlay the line catalog on the plot. (Currently overplotting line catalog works only spectra plotted in frequency.)

```
scans.set_unit('GHz')
sd.plotter.plot(scans)
sd.plotter.plot_line(mycatlog)
```

The following are some useful functions to control the line catalog access. See ASAP User Guide for more complete descriptions.

```
mycatlog.save('my_custom_linecat.tbl')  # save to the internal table format
mycatlog.set_frequency_limits(100,115,'GHz')  #set a frequency range for line selection
mycatlog.set_name('*OH')  # select all alcohols
```

8.3.10 Setting/Getting Rest Frequencies

The rest frequencies used in the data can be retrieved by `sd.scantable.get_restfreqs()` and set to new values by `sd.scantable.set_restfreqs()`. The CASA version of ASAP now can store multiple rest frequencies for each IF.

```
scans.get_restfreqs()  #retrieve current rest frequencies
#0:  [45490258000.0]
```
CHAPTER 8. SINGLE DISH DATA PROCESSING

All of the rest frequencies currently set to the data are listed in python dictionary for each MOLECULE_ID.

Here is an example of setting multiple rest frequencies for spectra of a particular IF:

```
#Select IFs, then set rest frequencies,
sel=sd.selector()
sel.setifs(0)
scans.set_selection(sel)
scans.set_restfreqs([45490258000.0,45590258000.0,45690258000.0])
```

NOTE: there is no functionality yet to select a specific rest frequency to apply to a specific line, etc. Currently, the first one in the list of the rest frequencies is used for such calculation.

8.3.11 Single Dish Spectral Analysis Use Case With ASAP Toolkit

Below is a script that illustrates how to reduce single dish data using ASAP within CASA. First a summary of the dataset is given and then the script.

```
# MeasurementSet Name: /home/rohir3/jocular/SD/OrionS_rawACSmod MS Version 2
# Project: AGBT06A_018_01
# Observation: GBT(1 antennas)
# Data records: 256    Total integration time = 1523.13 seconds
#   Observed from 01:45:58 to 02:11:21
# Fields: 4
#   ID  Name  Right Ascension  Declination  Epoch  
#   0   OrionS  05:15:13.45  -05:24.08.20 J2000
#   1   OrionS  05:35:13.45  -05:24.08.20 J2000
#   2   OrionS  05:15:13.45  -05:24.08.20 J2000
#   3   OrionS  05:35:13.45  -05:24.08.20 J2000
# Spectral Windows: (8 unique spectral windows and 1 unique polarization setups)
#   SpwID  Chans  Frame  Ch1(MHz)  Resoln(kHz)  TotBW(kHz)  Ref(MHz)  Corrs
#   0    8192   LSRK  45464.3506  6.10423298  50005.8766  45489.3536  RR LL HC3N
#   1    8192   LSRK  45275.7825  6.10423298  50005.8766  45300.7854  RR LL HN15CO
#   2    8192   LSRK  44049.9264  6.10423298  50005.8766  44074.9293  RR LL CH3OH
#   3    8192   LSRK  44141.2121  6.10423298  50005.8766  44166.2151  RR LL HC3N
#   12   8192   LSRK  43937.1232  6.10423298  50005.8813  43962.1261  RR LL HNCO
#   13   8192   LSRK  42620.4173  6.10423298  50005.8813  42645.4203  RR LL H15NCO
#   14   8192   LSRK  41569.9768  6.10423298  50005.8813  41594.9797  RR LL HNC18O
#   15   8192   LSRK  43397.8198  6.10423298  50005.8813  43422.8227  RR LL SiO
# Scans: 21-24  Setup 1 HC3N et al
# Scans: 25-28  Setup 2 SiO et al
```
casapath=os.environ['AIPSPATH']

# ASAP script
#-------------------------------------- -----------------------------------------------
import asap as sd
# Orion-S (SiO line reduction only)
# Notes:
# scan numbers (zero-based) as compared to GBTIDL
# changes made to get to OrionS_rawACSmod
# modifications to label sig/ref positions

os.environ['AIPSPATH']=casapath
# set this environment variable back - ASAP changes it

s=sd.scantable('OrionS_rawACSmod',False)# load the data without averaging

Figure 8.6: Multi-panel display of the scantable. Subpanels are displayed per scan. There are two spectra in each scan indicating two polarization (RR and LL).

s.summary()
# summary info
s.set_fluxunit('K')
# make 'K' default unit
scal=sd.calps(s,[20,21,22,23])
# Calibrate HC3N scans

scal.recalc_azel()
# recalculate az/el to
CHAPTER 8. SINGLE DISH DATA PROCESSING

Figure 8.7: Two panel plot of the calibrated spectra. The GBT data have a separate scan for the SOURCE and REFERENCE positions so scans 20, 21, 22 and 23 result in these two spectra.

```python
scal.opacity(0.09)  # do opacity correction
sel=sd.selector()  # Prepare a selection
sel.set_ifs(0)  # select HC3N IF
scal.set_selection(sel)  # get this IF
stave=sd.average_time(scal, weight='tintsys')  # average in time
spave=stave.average_pol(weight='tsys')  # average polarizations; Tsys-weighted (1/Tsys**2) average
sd.plotter.plot(spave)  # plot
spave.smooth('boxcar', 5)  # boxcar 5
spave.auto_poly_baseline(order=2)  # baseline fit order=2
sd.plotter.plot(spave)  # plot
spave.set_unit('GHz')
sd.plotter.plot(spave)
sd.plotter.set_histogram(hist=True)  # draw spectrum using histogram
sd.plotter.axhline(color='r', linewidth=2)  # zline
sd.plotter.save('orions_hc3n_reduced.eps')  # save postscript spectrum

spave.set_unit('channel')
rmsmask=spave.create_mask([5000, 7000])  # get rms of line free regions
rms=spave.stats(stat='rms', mask=rmsmask)  # rms
```
Figure 8.8: Calibrated spectrum with a line at zero (using histograms).

```python
# Scan[0] (OrionS_ps) Time[2006/01/19/01:52:05]:
# IF[0] = 0.048
#----------------------------------------------
# LINE
linemask = spave.create_mask([3900, 4200])
max = spave.stats('max', linemask)  # IF[0] = 0.918
sum = spave.stats('sum', linemask)  # IF[0] = 64.994
median = spave.stats('median', linemask)  # IF[0] = 0.091
mean = spave.stats('mean', linemask)  # IF[0] = 0.210

# Fitting
spave.set_unit('channel')  # set units to channel
sd.plotter.plot(spave)  # plot spectrum
f = sd.fitter()
msk = spave.create_mask([3928, 4255])  # create region around line
f.set_function(gauss=1)  # set a single gaussian component
f.set_scan(spave, msk)  # set the data and region for the fitter
f.fit()  # fit
f.plot(residual=True)  # plot residual
```
CHAPTER 8. SINGLE DISH DATA PROCESSING

f.get_parameters()  # retrieve fit parameters
# 0: peak = 0.786 K, centre = 4091.236 channel, FWHM = 70.586 channel
# area = 59.473 K channel
f.store_fit('orions_hc3n_fit.txt')  # store fit
# Save the spectrum
spave.save('orions_hc3n_reduced','ASCII',True)  # save the spectrum

8.4 Single Dish Imaging

Single dish imaging is supported within CASA using standard tasks and tools. The data must be in the Measurement Set format. Once there, you can use the im (imager) tool to create images:

Tool example:

```python
scans.save('outputms','MS2')  # Save your data from ASAP into an MS
im.open('outputms')  # open the data set
im.selectvis(nchan=901,start=30,step=1, spwid=0,field=0)  # choose a subset of the data
# (just the key emission channels)
dir='J2000 17:18:29 +59.31.23'  # set map center
im.defineimage(nx=150,cellx='1.5arcmin', phasecenter=dir, mode='channel',start=30, nchan=901,step=1)  # define image parameters
# (note it assumes symmetry if ny,celly aren't specified)
im.setoptions(ftmachine='sd',cache=100000000)  # choose SD gridding
im.setsdoptions(convsupport=4)  # use this many pixels to support the gridding function used
# (default=prolate spheroidal wave function)
im.makeimage(type='singledish', image='FLS3a_HI.image')  # make the image
```

8.4.1 Single Dish Imaging Use Case With ASAP Toolkit

The data summary and the script are given below.

```plaintext
# Project: AGBT02A_007_01
# Observation: GBT(1 antennas)
#
# Telescope Observation Date Observer Project
# GBT [ 4.57539e+09, 4.5754e+09]Lockman AGBT02A_007_01
# GBT [ 4.57574e+09, 4.57575e+09]Lockman AGBT02A_007_02
# GBT [ 4.5831e+09, 4.58313e+09]Lockman AGBT02A_031_12
#
# Thu Feb 1 23:15:15 2007 NORMAL ms::summary:
# Data records: 76860 Total integration time = 7.74277e+06 seconds
# Observed from 22:05:41 to 12:51:56
```
CHAPTER 8. SINGLE DISH DATA PROCESSING

# Thu Feb 1 23:15:15 2007 NORMAL ms::summary:
# Fields: 2
#  ID  Name     Right Ascension  Declination  Epoch
#   0  FLS3a   17:18:00.00   +59.30.00.00  J2000
#   1  FLS3b   17:18:00.00   +59.30.00.00  J2000
#
# Thu Feb 1 23:15:15 2007 NORMAL ms::summary:
# Spectral Windows: (2 unique spectral windows and 1 unique polarization setups)
#  SpwID #Chans Frame   Ch1(MHz)  Resoln(kHz)  TotBW(kHz)  Ref(MHz)  Corrs
#   0  1024 LSRK 1421.89269  2.44140625  2500  1420.64269  XX YY
#   1  1024 LSRK 1419.39269  2.44140625  2500  1418.14269  XX YY

# FLS3 data calibration
# this is calibration part of FLS3 data
#
casapath=os.environ['AIPSPATH']
import asap as sd
os.environ['AIPSPATH']=casapath

print '---Import---'
s=sd.scantable('FLS3_all_newcal_SP',false) # read in MeasurementSet

print '---Split---'
# splitting the data for each field
s0=s.get_scan('FLS3a*') # split the data for the field of interest
s0.save('FLS3a_HI.asap') # save this scantable to disk (asap format)
del s0 # free up memory from scantable

print '---Calibrate---'
s=sd.scantable('FLS3a_HI.asap') # read in scantable from disk (FLS3a)
s.set_fluxunit('K') # set the brightness units to Kelvin
scanns = s.getscannos() # get a list of scan numbers
sn=list(scanns) # convert it to a list
print "No. scans to be processed: ", len(scanns)
res=sd.calfs(s,sn) # calibrate all scans listed using frequency

print '---Save calibrated data---'
res.save('FLS3a_calfs', 'MS2') # Save the dataset as a MeasurementSet

print '---Image data---'
im.open('FLS3a_calfs') # open the data set
im.selectvis(nchan=901,start=30,step=1, # choose a subset of the data
spwid=0,field=0) # (just the key emission channels)
dir='J2000 17:18:29 +59.31.23' # set map center
im.defineimage(nx=150,cellx='1.5arcmin', # define image parameters
phasecenter=dir,mode='channel',start=30,
nchan=901,step=1)  # (note it assumes symmetry if ny,celly
# aren't specified)

im.setoptions(ftmachine='sd',cache=1000000000) # choose SD gridding
im.setsdoptions(convsupport=4) # use this many pixels to support the
# gridding function used
# (default=prolate spheroidal wave function)
im.makeimage(type='singledish',image='FLS3a_HI.image') # make the image

Figure 8.9: FLS3a HI emission. The display illustrates the visualization of the data cube (left) and
the profile display of the cube at the cursor location (right); the Tools menu of the Viewer Display
Panel has a Spectral Profile button which brings up this display. By default, it grabs the left-mouse
button. Pressing down the button and moving in the display will show the profile variations.
8.5 Known Issues, Problems, Deficiencies and Features

The Single-Dish calibration and analysis package within CASA is still very much under development. Not surprisingly, there are a number of issues with ASAP and the SDtasks that are known and under repair. Some of these are non-obvious "features" by the way ASAP and sd are implemented, or limitations of the current Python tasking environment. Some are functions that have yet to be implemented. These currently include:

1. sd.plotter
   The method, `sd.plotter.set_range()` sets the same range for multiple panels, while we would like it to be able to set the range for each independently, including the default ranges.
   The `sd.plotter` object remembers things throughout the session and thus can easily get confused. For example, one must reset the range `sd.plotter.set_range()` if set manually. This behaviour is not always expected, but is a consequence of having `sd.plotter` be its own object that is fed data and commands.
   Eventually we would like the capability to interactively set things using the plots, like select frequency ranges, identify lines, start fitting.

2. sd.selector
   The selector object only allows one selection of each type. It would be nice to be able to make a union of selections (without resorting to query) for the `set_name`. Note that the others like scans and IFs work off lists, which is fine. We should make `set_name` work off lists of names.

3. sd.scantable
   The `scantable.verbosesummary` asaprc parameter (e.g. in `sd.rcParams`) does nothing.
   GBT data has an undefined parameter fluxunit (\"\" that should be \"K\"), an incorrect freqframe (\"LSRK\" that is is really \"TOPO\"), and reference frequency (set to that of the first IF only).
   The `sd.scantable.freq_align` does not yet work correctly.

4. sd general issues
   There should be a `sdhelp` equivalent of `toolhelp` and `tasklist` for the sd tools and tasks.
   The current output of ASAP is verbose and controlled by setting `sd.rcParams[\'verbose\']`=`False` (or `True`). We will make some of the output less cryptic.
   We will strip off leading and trailing whitespace on string parameters.

5. SDtasks general issues
   The SDtasks work with files saved onto disk in one of the scantable supported formats. It might be useful to work with scantables in memory (passing the objects) but this would require changes to the tasking system. Note that this behavior is consistent throughout the casapy tasks.
6. **sdcal** (and **sdreduce**)

   `averageall=True` is still experimental since the test was insufficient because of a lack of test data.

7. **sdfit**

   Only way to handle multi-IFs is to set `fitmode='auto'` (linefinder is applied for each spectra and derives initial guesses). For `fitmode='list'`, there are no way to give initial guesses for each IFs by hand.

8. **sdplot**

   Only handles the included JPL line catalog. Also, see **sd.plotter** issues above.

9. GBT raw SDFITS data

   The SDtasks and **sd.scantable** are able to handle GBT raw SDFITS data format (version 1.3) data since the data filler is available. However, the functionality is not well tested yet, so that there may be unknown bugs.
Chapter 9

Simulation

New in 4.1: Task simalma uses feather to combine interferometer and total power data sets.

The tasks available for simulating observations are:

- **simobserve** — simulate an interferometer or total power observation (§ 9.1)
- **simanalyze** — image and analyze simulated data sets (§ 9.1)
- **simalma** — (experimental) simulate an ALMA observation including the 12-m interferometric array, the 7-m ACA, and total power measurements. Generate a combined image from the simulated data sets (§ 9.2)

The capability of simulating observations and data sets from the JVLA and ALMA are an important use-case for CASA. This not only allows one to get an idea of the capabilities of these instruments for doing science, but also provides benchmarks for the performance and utility of the software to process “realistic” data sets (with atmospheric and instrumental effects). Simulations can also be used to tune parameters of the data reduction and therefore help optimizing the process. CASA can calculate visibilities (create a measurement set) for any interferometric array, and calculate and apply calibration tables representing some of the most important corrupting effects. **simobserve** can also simulate total power observations, which can be combined with interferometric data in simanalyze (i.e. one would run simobserve twice, simanalyze once). The task simalma is an experimental task to simulate an ALMA observation, including ALMA 12-m, ACA 7-m and total power arrays, and generate a combined image.

CASA’s simulation capabilities continue to be improved with each CASA release. For the most current information, please refer to [http://www.casaguides.nrao.edu](http://www.casaguides.nrao.edu) and click on “Simulating Observations in CASA”. Following general CASA practice, the greatest flexibility and richest functionality is at the Toolkit level. The most commonly used procedures for interferometric and single dish simulation are encapsulated in the **simobserve** task.

Inside the Toolkit:

The simulator methods are in the **sm** tool. Many of the other tools are also helpful when constructing and analyzing simulations.
CHAPTER 9. SIMULATION

ALERT: Antenna configurations of ALMA in Cycle 2 are under discussion, and the configuration files for Cycle 2 are not yet distributed within CASA 4.1 package. The configuration files and the way to simulate Cycle 2 observations will be provided in CASA Guide home page, once the details of observation settings of Cycle 2 is defined.

9.1 Simulating ALMA observations with simobserve and simanalyze

The simobserve inputs are (submenus expand slightly differently for thermalnoise=manual and single dish observing):

```plaintext
project = 'sim' # root prefix for output file names
skymodel = '' # model image to observe
inbright = '' # scale surface brightness of brightest pixel e.g. "1.2Jy/pixel"
indirection = '' # set new direction e.g. "J2000 19h00m00 -40d00m00"
incell = '' # set new cell/pixel size e.g. "0.0arcsec"
incenter = '' # set new frequency of center channel e.g. "89GHz" (required even for 2D model)
inwidth = '' # set new channel width e.g. "10MHz" (required even for 2D model)
complist = '' # componentlist to observe
compwidth = '8GHz' # bandwidth of components
setpointings = True
integration = '10s' # integration (sampling) time
direction = '' # "J2000 19h00m00 -40d00m00" or "" to center on model
mapsize = ['', ''] # angular size of map or "" to cover model
maptype = 'ALMA' # hexagonal, square (raster), ALMA, etc
pointingspacing = '' # spacing in between pointings or "0.25PB" or "" for Nyquist
obsmode = 'int' # observation mode to simulate
# [int(interferometer)|sd(singledish)|""(none)]
antennalist = 'alma.out10.cfg' # interferometer antenna position file
refdate = '2014/05/21' # date of observation - not critical unless concatenating
# simulations
hourangle = 'transit' # hour angle of observation center e.g. -3:00:00, or "transit"
totaltime = '7200s' # total time of observation or number of repetitions
caldirection = '' # pt source calibrator [experimental]
calflux = '1Jy'
thermalnoise = 'tsys-atm' # add thermal noise: [tsys-atm|tsys-manual|""]
user_pwv = 1.0 # Precipitable Water Vapor in mm
t_ground = 269.0 # ambient temperature
seed = 11111 # random number seed
leakage = 0.0 # cross polarization (interferometer only)
graphics = 'both' # display graphics at each stage to [screen|file|both|none]
verbose = False
overwrite = True # overwrite files starting with $project
async = False # If true the taskname must be started using simobserve(...)```

...
CHAPTER 9. SIMULATION

This task takes an input model image or list of components, plus a list of antennas (locations and sizes), and simulates a particular observation (specified by mosaic setup and observing cycles and times). The output is a measurement set suitable for further analysis in CASA.

The simanalyze inputs are:

```
project = 'sim'          # root prefix for output file names
image = True             # (re)image $project.*.ms to $project.image
vis = 'default'          # Measurement Set(s) to image
modelimage = ''          # prior image to use in clean e.g. existing single dish image
imsize = 0               # output image size in pixels (x,y) or 0 to match model
imdirection = ''         # set output image direction, (otherwise center on the model)
cell = ''                # cell size with units or "" to equal model
niter = 500              # maximum number of iterations (0 for dirty image)
threshold = '0.1mJy'     # flux level (+units) to stop cleaning
weighting = 'natural'    # weighting to apply to visibilities
mask = []                # Cleanbox(es), mask image(s), region(s), or a level
outertaper = []          # uv-taper on outer baselines in uv-plane
stokes = 'I'             # Stokes params to image
analyzefile = True       # (only first 6 selected outputs will be displayed)
showuv = True            # display uv coverage
showpsf = True           # display synthesized (dirty) beam (ignored in single dish simulation)
showmodel = True         # display sky model at original resolution
showconvolved = False    # display sky model convolved with output beam
showclean = True         # display the synthesized image
showresidual = False     # display the clean residual image (ignored in single dish simulations)
showdifference = True    # display difference between output cleaned image and input model sky image convolved with output clean beam
showfidelity = True      # display fidelity
graphics = 'both'        # display graphics at each stage to [screen|file|both|none]
verbose = False          # If true the taskname must be started using simanalyze(...) overwrite = True # overwrite files starting with $project
async = False # If true the taskname must be started using simanalyze(...)```

This task analyzes one or more measurement sets - interferometric and/or single dish. The output is a synthesized image created from those visibilities, a difference image between the synthesized image and your sky model convolved with the output synthesized beam, and a fidelity image. (see ALMA memo 398 for description of fidelity, which is approximately the output image divided by the difference between input and output)

9.2 Simulating ALMA observations with simalma

The task simalma simulates an ALMA observation by ALMA 12-m, ACA-7m and total power arrays. It takes an input model image or a list of components, plus configurations of ALMA antennas (locations and sizes), and simulates a particular ALMA observation (specified by mosaic
setup and observing cycles and times). The outputs are measurement sets. The task optionally generates synthesized images from the measurement sets as simanalyze does.

Technically speaking, simalma internally calls simobserve and simanalyze as many times as necessary to simulate and analyze an ALMA observation. Some of the simulation (simobserve) and imaging (simanalyze) parameters are automatically set to values typical of ALMA observations in simalma (see §9.2.1 for more details). Thus, it has a simpler task interface compared to simobserve plus simanalyze at the cost of limited flexibility. If you want to have more control on simulation setup, it is available by manually running simobserve and simanalyze multiple times or by using sm tools.

**ALERT:** Note that simalma is an experimental task. Simulation settings in detail may differ from the actual observations in Cycle 1 and 2, as the optimal strategy for combining ALMA 12-m, ACA-7m and total power array data is under investigation.

The simalma inputs are:

```bash
project = '' # root prefix for output file names
skymodel = '' # model image to observe
inbright = '' # scale surface brightness of brightest pixel e.g. "1.2Jy/pixel"
indirection = '' # set new direction e.g. "J2000 19h00m00 -40d00m00"
inell = '' # set new cell/pixel size e.g. "0.1arcsec"
incenter = '' # set new frequency of center channel e.g. "89GHz"
# (required even for 2D model)
inwidth = '' # set new channel width e.g. "10MHz" (required even
# for 2D model)
complist = '' # componentlist to observe
compwidth = '8GHz' # bandwidth of components
setpointings = True # integration (sampling) time
direction = '' # "J2000 19h00m00 -40d00m00" or "" to center on model
mapsize = ['',''] # angular size of map or "" to cover model
antennalist = 'alma_cycle1_1.cfg' # antenna position file of ALMA 12m array
hourangle = 'transit' # hour angle of observation center e.g. -3:00:00, or "transit"
totaltime = '7200s' # total time of observation or number of repetitions
acaratio = 3.0 # Ratio of the total observation time for ACA in
# relation to 12-m array or 0 for no ACA
acaconfig = '' # Antenna configuration of ACA 7-m array
# [""|"cycle1"|"i"|"ns"]
pwv = 0.0 # Precipitable Water Vapor in mm. 0 for noise-free
# simulation
image = True # image $project.*.ms to $project.image
imsize = 0 # output image size in pixels (x,y) or 0 to match model
indirection = '' # set output image direction, (otherwise center on the model)
cell = '' # cell size with units or "" to equal model
niter = 500 # maximum number of iterations (0 for dirty image)
threshold = '0.1mJy' # flux level (+units) to stop cleaning
```
CHAPTER 9. SIMULATION

```plaintext
graphics  = 'both'  # display graphics at each stage to [screen|file|both|none]
verbose   = False
overwrite = False  # overwrite files starting with $project
async     = False   # If true the taskname must be started using simalma(...)
```

The task `simalma` is designed as a task that is invoked only once for a simulation setup. It always sets up skymodel and pointings, and invokes a simulated observation of ALMA 12-m array. That means that `simalma` is not supposed to be run multiple times for a project, unlike `simobserve` and `simanalyze`. The task `simalma` may ignore or overwrite the old results when it is run more than once with the same project name.

There are options in `simalma` to simulate observation of ACA 7-m and total power arrays, to apply thermal noise, and/or to generate images from simulated measurement sets. Observations of ACA 7-m and total power arrays are simulated when `acaratio > 0`, while they are skipped and only ALMA 12-m array is simulated when `acaratio = 0`. Thermal noise is added to visibilities when `pwv > 0`. The ATM atmospheric model is constructed from the characteristics of the ALMA site and a user defined Precipitable Water Vapour (`pwv`) value. Set `pwv = 0` to omit the thermal noise. Finally, when `image = True`, synthesized images are generated from the simulated measurement sets.

9.2.1 Implementation of `simalma` in CASA 4.1.0

As mentioned in the previous section, `simalma` automatically sets some of the simulation and imaging parameters to values typical of ALMA observations. The implementations of antenna configurations, pointings, integration time, and imaging in CASA 4.1.0 are described in this section.

Antenna Configuration:

The configuration of the ALMA 12-m array is defined by the `antennalist` parameter. As with `simobserve`, you can specify either the name of an antenna configuration file or a desired resolution, e.g., `alma-cycle1;5arcsec`. When observations by ACA are requested (`acaratio > 0`), the configuration of the ACA 7-m array is defined by the `acaconfig` parameter. Available configurations are, ‘’ (default), ‘cycle1’ (to use `aca_cycle1.cfg`), ‘i’ (`aca.i.cfg`), or ‘ns’ (`aca.ns.cfg`). The default configuration of the ACA 7-m array is set to `aca_cycle1.cfg` when the ALMA 12-m array (`antennalist`) is in one of the Cycle 1 configurations, or to `aca.i.cfg` otherwise. Finally, the location of the ACA total power array is taken from a file, `aca.tp.cfg`, and only the first antenna in the list is simulated.

Field Setup:

There are two ways to setup pointings, i.e., Rectangle Setup and Multi-Pointing.

In the Rectangle Setsups, pointings are automatically calculated from the pointing centre (`direction`) and the map size. A rectangular map region is covered by a hexagonal grid (`maptype = 'alma'`) with Nyquist sampling, i.e., 0.48 PB spacing (where PB $\equiv 1.2 \lambda/D$), in both ALMA 12-m and ACA 7-m array simulations. A slightly larger area is mapped in ACA total power simulations.
for later combination with interferometer visibilities. The map area is extended by 1 PB in each
direction and covered by a lattice grid with 0.225 PB spacing.

In Multi-Pointing, a list of pointings is defined in the direction parameter or read from a file (when
setpointings = False). The ALMA 12-m and ACA 7-m arrays observe the specified directions.
The ACA total power simulations map either (1) square regions of 2 PB extent centred at each of
the pointings, or (2) a rectangle region that covers all the pointings. Either (1) or (2), whichever
can be done with the smaller number of points, is selected. The pointing spacing in total power
simulations is, again, 0.225 PB in lattice grids.

Integration time:

The total observation time of the ALMA 12-m array is defined by the totaltime parameter,
while that of the ACA 7-m and total power arrays is defined by totaltime × acaratio. Set
acaratio = 0 or 3 for Cycle 1 simulations. In general, the integration time (dump interval) of
simulations is defined by the integration parameter with an exception. Since the ACA total
power array always observes larger areas compared to the ALMA 12-m and ACA 7-m arrays, it is
possible that the ACA total power array can not cover all pointings in the given observation time
(totaltime × acaratio). In such a case, the integration time in total power simulation is scaled
so that the all pointings are observed at least once in its observation time, i.e., integration,TP =
totaltime × acaratio / (the number of total power pointings).

Imaging and combination of ALMA with ACA:

The CLEAN algorithm is used in simalma to generate images from visibilities. The visibilities are
weighted to UV-plane using Briggs weighting.

When ACA observations are simulated, visibilities of ACA 7-m are weighted by the relative sen-
sitivities to ALMA 12-m visibilities, and both data sets are concatenated before imaging. The
relative weight of ACA 7-m visibilities is defined in proportion to the difference of beam area, i.e.,
\((7/12)^2 = 0.34\). This is because simalma uses a bandwidth and an integration time common to
both ALMA 12-m and ACA 7-m simulations.

The interferometer and total power images are combined using feather task when acaratio > 0.
The total power image is scaled by the interferometer primary beam coverage before combination.
The final image product is the combined image corrected for the interferometer primary beam
coverage. The output image of the feather task is divided by the interferometer primary beam
coverage in the final step.
Chapter 10

Parallel Processing in CASA

Since CASA 4.0.0, a parallelized execution of a full data analysis from data import to imaging is possible. This functionality continues to be under development and should still be regarded as experimental but users are encouraged to try this feature if they have access to computers with a solid state disk (SSD) or RAID arrays with a Lustre file system or other fast file systems. On normal SATA disks, there is no benefit from parallelization as the file system cannot feed more than one CASA instance.

The following deal with the handling of visibility data. For imaging with pclean, see §5.10.

10.1 The CASA parallelization scheme

In order to run one analysis on multiple processors, one can parallelize the work by dividing the data into several parts ("partitioning") and then run a CASA instance on each part or have non-trivially parallelized algorithms which make use of several processors within a single CASA instance. Non-trivial parallelization is presently only implemented in certain sections of the imaging code of CASA based on OpenMP.

All other parallelization is achieved by partitioning the MeasurementSet (MS) of interest using the task partition. The resulting partitioned MS is called a "multi-MS" or "MMS". Logically, an MMS has the same structure as an MS but internally it is a group of several MSs which are virtually concatenated. Virtual concatenation of several MSs or MMSs into an MMS can also be achieved via the new (in CASA 4.0) task virtualconcat.

Due to the virtual concatenation, the main table of an MMS appears like the union of the main tables of all the member MSs such that when the MMS is accessed like a normal MS, processing can proceed sequentially as usual. Each member MS or "subMS" of an MMS, however, is at the same time a valid MS on its own and can be processed as such. This is what happens when the MMS is accessed by a parallelized task. The partitioning of the MMS is recognized and work is started in parallel on the separate subMSs.

The internal structure of an MMS can be inspected using the new task listpartition.
10.2 Multi-MS-compatible tasks in CASA 4.1

The following tasks in CASA 4.1 have been tested to work with MMSs as input:

- applycal
- bandpass
- clean
- concat (produces an output MS, not an MMS)
- fixplanets
- flagdata
- flagmanager
- fluxscale
- gaincal
- gencal
- listobs
- listpartition
- listvis
- listhistory
- partition (repartitioning of an MMS is also possible)
- pclean
- plotms
- setjy
- split (produces MS by default, an MMS if parameter keepmms=True)
- uvcontsub (produces an MMS)
- virtualconcat (produces an MMS)
- vishead
- wvrgcal

Of these, the following tasks will work in a parallelized way on MMSs to speed up processing:
• applycal
• flagdata
• partition (repartitioning of an MMS is also possible)
• pclean
• setjy (when parameter usescratch=True)
• split (when parameter keepmms=True)
• uvcontsub

You can find an example of a parallelized analysis in the regression script

alma-m100-analysis-hpc-regression.py

in a subdirectory of your CASA distribution.

10.3 Parallelization control

10.3.1 Requirements

The following requirements are necessary for all the nodes to be included in the cluster:

• Password-less ssh access from the controller (user) machine into all the hosts to be included in the cluster
  NOTE: This is not necessary when using only localhost, i.e. if the cluster is deployed only on the machine where casapy is running.

• All the input files must be located in a shared file-system, accessible from all the nodes comprising the cluster, and mounted in the same path of the file-system

• Mirrored CASA installation w.r.t. the CASA installation in the controller (user) machine, so that the following environmental variables are pointing to valid installations: PATH, LD_LIBRARY_PATH, IPYTHONDIR, CASAPATH, CASAARCH, PYTHONHOME, _CASAPY_PYTHONDIR, PGPLOT_DEV, PGPLOT_DIR, PGPLOT_FONT.
10.3.2 Configuration and Start-Up

The “cluster”, i.e. the collection of CASA instances which will run the jobs from parallelized tasks, is set up automatically when it is used the first time, typically when running `partition`. The setup of this default cluster is derived from the properties of the host on which CASA is running. Presently the settings are such that up to 90% of the processors and the available RAM is used. There has to be at least 512 MB per CASA engine. But even if there are not enough resources available, at least one engine is deployed. In that case, the cluster is bypassed and jobs are simply run sequentially.

If the user wants to override these settings, this is possible by creating a “cluster configuration file” with one line per host to be used in the following format:

```
<hostname>, <number of engines>, <work directory>, <RAM usage>, <RAM per engine>
```

The comma-separated parameters have the following meaning:

1. **hostname**: Hostname of the target node where the cluster is deployed
   
   **NOTE**: The hostname has to be provided w/o quotes

2. **number of engines**: Supports in turns 3 different formats
   
   - If provided as an integer ≥1: It is interpreted as the actual user-specified maximum number of engines
   - If provided as an integer =0: It will deploy as maximum engines as possible according to the idle CPU capacity available at the target node
   - If provided as a float between 0 and 1: It is interpreted as the percentage of idle CPU capacity that the cluster can use in total at the target node

3. **work directory**: Area in which the cluster will put intermediate files such as log files, configuration files, and monitoring files
   
   **NOTE1**: This area has to be accessible from the controller (user) machine, and mounted in the same path of the filesystem
   
   **NOTE2**: The path name has to be provided w/o quotes

4. **RAM usage**: (optional) can be given in three different formats

   - If provided as an integer =0 or not at all (default): will deploy as many engines as possible using up to 90% of the free RAM available at target node
   - If provided as an integer >1: interpreted as the actual user-specified maximum amount of RAM (MB) to be used in total at the target node
   - If provided as a float between 0 and 1: interpreted as the percentage of free RAM that the cluster can use in total at the target node
5. **RAM per engine**: (optional) integer, the required memory per engine in MB (default is 512MB)

It is also possible to add comments, by using the `#` character at the beginning of the line.

Example:

```
# CASA cluster configuration file
orion, 10, /home/jdoe/test/myclusterhome1
m42, 4, /home/jdoe/test/myclusterhome2, 0.6, 1024
antares, 0.6, /home/jdoe/test/myclusterhome3, 0, 2048
```

Will set up a cluster comprised of three nodes, deploying the engines per node as follows:

- At host “orion” up to 10 engines will be deployed with working directory `/home/jdoe/test/myclusterhome1` and using as much free RAM available as possible (up to 90% by default), taking into account that each engine can use up to 512 MB (the default and minimum)

- At host “m42”: It will deploy up to 4 engines, with working directory `/home/jdoe/test/myclusterhome2`, and using at the most 60% of the free RAM available, taking into account that each engine can use up to 1024 MB.

- At host “antares”: It will deploy as many engines as possible, with working directory `/home/jdoe/test/myclusterhome3`, using up to 60% of the idle CPU capacity / cores, and as much free RAM available as possible (up to 90% by default), taking into account that each engine can use up to 2048 MB.

Using such a configuration file named, say, “cluster-config.txt”, the cluster can then be created after CASA startup using the commands

```python
from simple_cluster import *
s = simple_cluster()
s.init_cluster('cluster-config.txt', 'mycluster')
```

It will be used by all subsequent calls to parallelized tasks.

To stop an existing cluster without exiting casa type

```python
sc.stop_cluster()
```

Otherwise, any cluster will be terminated anyway when CASA exits.
10.3.3 Monitoring

The CASA cluster framework comes with a monitoring service that produces a monitoring.log file, in the same directory where the controller instance (user CASA terminal) is started.

This file is updated whilst the cluster is actively carrying out tasks, and shows information per engine, and total per host included in the cluster.

Therefore, it is possible to monitor the cluster by screening this file in a separated terminal, e.g. using the operating system command `watch`:

```
watch cat monitoring.log
```

will result in the screen output

```
<table>
<thead>
<tr>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>hpc01</td>
<td>0</td>
<td>running</td>
<td>75</td>
<td>2</td>
<td>28</td>
<td>334</td>
<td>2</td>
<td></td>
<td>11</td>
<td>flagdata X54.0005.ms</td>
<td></td>
</tr>
<tr>
<td>hpc01</td>
<td>1</td>
<td>running</td>
<td>61</td>
<td>2</td>
<td>9</td>
<td>197</td>
<td>0</td>
<td></td>
<td>21</td>
<td>flagdata X54.0007.ms</td>
<td></td>
</tr>
<tr>
<td>hpc01</td>
<td>2</td>
<td>running</td>
<td>74</td>
<td>2</td>
<td>28</td>
<td>386</td>
<td>3</td>
<td></td>
<td>13</td>
<td>flagdata X54.0003.ms</td>
<td></td>
</tr>
<tr>
<td>hpc01</td>
<td>3</td>
<td>scheduled</td>
<td>24</td>
<td>1</td>
<td>0</td>
<td>1</td>
<td>0</td>
<td></td>
<td>0</td>
<td>flagdata X54.0012.ms</td>
<td></td>
</tr>
<tr>
<td>hpc01</td>
<td>4</td>
<td>running</td>
<td>82</td>
<td>2</td>
<td>28</td>
<td>386</td>
<td>3</td>
<td></td>
<td>13</td>
<td>flagdata X54.0001.ms</td>
<td></td>
</tr>
<tr>
<td>hpc01</td>
<td>5</td>
<td>scheduled</td>
<td>21</td>
<td>1</td>
<td>0</td>
<td>13</td>
<td>0</td>
<td></td>
<td>0</td>
<td>flagdata X54.0011.ms</td>
<td></td>
</tr>
<tr>
<td>hpc01</td>
<td>Total</td>
<td></td>
<td>337</td>
<td>10</td>
<td>1318</td>
<td>8</td>
<td>61</td>
<td>0</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
```
Appendix A

Obtaining, Installing, and Customizing CASA

A.1 Installation On Linux

To install CASA for Linux, we have packaged up a binary distribution of CASA which is available as a downloadable tar file. We believe this binary distribution works with most Linux distributions. While the binary distribution is the only supported public distribution, most CASA developers use RPMs for many third-party packages installed with yum to do development on RedHat Enterprise Linux. Installing the developer RPMs requires root access and we only provide developer support for organizations which have a cooperative agreement to participate in the development of CASA. We are currently working on the development of a distribution for developers similar to our standard binary distribution, but it is not yet ready for testing.

A.1.1 Installation

You do not have to have root or sudo permission, you can easily install CASA, delete it, move it, and it works for many versions of Linux. The one caveat is that CASA on Linux currently will not run if the Security-Enhanced Linux option of the linux operating system is set to enforcing. For the non-root install to work. SElinux must be set to disabled or permissive (in /etc/selinux/config) or you must run (as root):

```
setsebool -P allow_execheap=1
```

Otherwise, you will encounter errors like:

```
casapy: error while loading shared libraries: /opt/casa/casapy-20.0.5653-001/lib/liblapack.so.3.1.1: cannot restore segment prot after reloc: Permission denied
```

The non-root installation is thought to work on a wide variety of linux platforms, see Sect.1.2 for the latest supported OSs.
A.1.1.1 Using more than one Linux version of CASA

Up to CASA 3.3.0, CASA .rpm files prohibited installing more than one CASA release at a time. Starting with CASA 3.4.0, CASA .rpm files allow previously installed CASA releases to remain installed.

To start a specific CASA version, type

```
casapy --release <VERSION>
```

or

```
casapy -r <VERSION>
```

where `"<VERSION>"` is a placeholder for the CASA version to be invoked, e.g. 3.3.0.

Also, starting with CASA 3.4.0, the programs asdm2ms, casabrowser, casalogger, casaplotms, casapy, casapyinfo, and casaviewer all take the two new command line options: `"-r"` and `"--release"`. These options allow users to select a CASA program to run from the installed CASA releases.

A.1.2 Unsupported platforms

The non-root install may work on other platforms not listed, please let us know if you find that this binary distribution of CASA works on other linux platforms. Also note, that the plotting tasks like plotxy and plotcal are the ones that typically give problems for new platforms, so a check of these after attempting an unsupported platform installation is advisable.

A.1.3 Download & Unpack

You can download the distribution tar file from

```
http://casa.nrao.edu/casa_obtaining.shtml
```

This directory will contain two tar files one will be the 32-bit version of CASA and the other will be the 64-bit version of CASA. The file name of the 64-bit version ends with `-64b.tar.gz`. After downloading the appropriate tar file, untar it with

```
tar -zxf casapy-*.tar.gz
```

This will extract a directory with the same basename as the tar file. Change to that directory and add it to your path with, for example,

```
PATH=‘pwd’:
```

After that, you should be able to start CASA by running

```
casapy
```
A.2 Installation on Mac OS

CASA for Macintosh is distributed as self-contained Macintosh application. For installation purposes, this means that you can install CASA by simply dragging the application to your hard disk. It should be as easy as copying a file.

1. Download the CASA disk image for your OS version from our download site [http://casa.nrao.edu/casa_obtaining.shtml]
2. Open the disk image file (if your browser does not do so automatically).
3. Drag the CASA application to the Applications folder of your hard disk.
4. Eject the CASA disk image.
5. Double-click the CASA application to run it for the first time. This ensures everything is properly updated if you had installed a previous version.

You may need to unload the dbus before the copy will work

```
launchctl remove org.freedesktop.dbus-session
launchctl remove org.freedesktop.dbus-system
```

Versions after 12115 are 64bit only and will not work on older mac intel machines. The first time you launch the CASA application, it will prompt you to set up an alias to the casapy command. You will be taken through the process of creating several casapy symbolic links, it is advisable to do so as this will allow you to run casapy from a terminal window by typing casapy. Additionally, the viewer (casaviewer), table browser (casabrowser), plotms (casaplotms), and buildmytasks will also be available via the command line. Creating the symbolic links will require that you have administrator privileges.

A.2.0.1 Using more than one Mac version of CASA

By dragging the CASA.app into the Applications folder, any previous version of CASA will be replaced. If one would like to keep older versions, one can simply rename them, e.g., to CASA-3.3.0.app. Double clicking any of the CASA*.app applications will prompt to update the symlinks to that specific CASA version. So any startup of casapy, casaviewer, casaplotms will point to that version. If one decides to switch to a different version, just double click the respective CASA*.app and follow the instructions to update the symlinks.

A.3 Startup

in a terminal type
APPENDIX A. APPENDIX: OBTAINING, INSTALLING, AND CUSTOMIZING CASA

and the world of CASA will open its doors for you.

There are a number of options to casapy (see casapy --help): Options are:

```
--rcdir directory
--logfile logfilename specify the name of the log file if other than casapy-DATE.log
--maclogger will use the Mac Console program for the logger
--log2term output the logger text in the terminal
--nologger run without launching the logger
--nologfile does not create a logfile
--nogui will not open the logger GUI
--colors=[NoColor|Linux|LightBG] selects color theme for prompt task inputs
--release <VERSION> launches CASA version <VERSION> when installed as Linux rpm
-r <VERSION> alias for --release
-c filename-or-expression execute a CASA python script from the command line
--help print this text and exit
```

E.g. you can execute a CASA script `script.py` directly with the command

```
casapy -c script.py
```

You can also launch the `plotms` and `viewer` GUIs separately without starting CASA itself. To do so, type:

```
casaplotms
casaviewer
```

for the `viewer`.

### A.4 Startup Customization

There are two initialization files that are loaded upon startup. The first is loaded very early in the startup of casapy:

```
~/casa/prelude.py
```

This allows for limited customization of the casapy environment, e.g. setting the path to an alternate logger. The second startup file should be used for most purposes:
APPENDIX A. APPENDIX: OBTAINING, INSTALLING, AND CUSTOMIZING CASA

`.casa/init.py`

This file is loaded just before the casapy prompt is display. This is the place where users can load their own python modules and casa tasks. For example `.casa/init.py` might contain:

```python
import os
sys.path.insert(1, os.environ['HOME'] + os.sep + "python")
import analysisUtils as aU
```

and `analysisUtils.py` might contain:

```python
import numpy as np
from mpfit import mpfit
from pylab import *
from numpy.fft import fft
from scipy import polyfit
import taskinit as ti
from importasdm import importasdm
```

Many options can also be set in the file

`~/.casarc`

E.g.

````
# # Set these so that bug(), ask(), etc. know who you are
#
userinfo.name: Sheila User
userinfo.email: suser@nrao.edu
userinfo.org: NRAO

#NOTE: Fill this value in as appropriate - the units are MB
#It is important that you not set this value larger than your actual
#physical memory
#system.resources.memory: 2000
#help.popup.type: mb3long

#catalog
catalog.gui.auto: T
catalog.confirm: T
catalog.view.PostScript: ghostview
catalog.edit.ascii: xterm -e vi
```

#logger
A.5 Updating the data repository

Each CASA release for linux comes with an up to date data repository (containing information such as observatory coordinates, calibrator models, leap second tables, etc.). However, the files that make up the data repository are updated regularly. Therefore, if you install (or have installed) a release that is a few weeks to a month old, it makes sense to update the data repository because it is very easy. On a Mac, the data repository is updated every time you run `casapy`. For Linux, you just change to the `data` directory in the installation root and run "svn update". This will sync your local copy of the CASA data repository with the repository maintained by the CASA group, e.g.

```bash
cd /usr/lib64/casapy/data/
svn update
```

will start syncing:

```
bash-3.2$ svn update
U  geodetic/IERSep97/table.f0
U  geodetic/IERSep97/table.dat
U  geodetic/IERSep97/table.lock
```
U geodetic/Observatories/table.f0
U geodetic/Observatories/table.f1
U geodetic/Observatories/table.dat
...

Appendix B

Python and CASA

CASA uses Python, IPython and matplotlib within the package. IPython is an enhanced, interactive shell to Python which provides many features for efficient command line interaction, while matplotlib is a Python 2-D plotting library for publication quality figures in different hardcopy formats.

From www.python.org: "Python is an interpreted, interactive, object-oriented programming language". Python is used as the underlying command line interface/scripting language to CASA. Thus, CASA inherits the features and the annoyances of Python. For example, since Python is inherently 0-based in its indexing of arrays, vectors, etc, CASA is also 0-based; any Index inputs (e.g., start (for start channel), fieldIndex, antennaID, etc) will start with 0. Another example is that indenting of lines means something to Python, of which users will have to be aware.

Currently, CASA uses python 2.6 (2.5 for the Mac OS 10.5 version). Some key links to python are:

- [http://python.org](http://python.org) – Main Python page
- [http://docs.python.org/release/2.6.5/tutorial/index.html](http://docs.python.org/release/2.6.5/tutorial/index.html) – Python Reference
- [http://docs.python.org/release/2.6.5/reference/index.html](http://docs.python.org/release/2.6.5/reference/index.html) – Python Tutorial
- [http://ipython.scipy.org](http://ipython.scipy.org) – IPython page

Each of the features of these components behave in the standard way within CASA. In the following sections, we outline the key elements for analysis interactions; see the Python references and the IPython page for the full suite of functionality.

B.1 Python Packages

The following python packages are included in CASA: ipython, nose, pyfits, pytz, dbus, numpy, scientific python, twisted, zope.interface, foolscap, matplotlib, scipy. For their version numbers, please
B.2 Automatic parentheses

Automatic parenthesis is enabled for calling functions with argument lists; this feature is intended to allow less typing for common situations. IPython will display the interpretation of the line, beneath the one typed, as indicated by the '-------->'. Default behavior in CASA is to have automatic parenthesis enabled.

B.3 Indentation

Python pays attention to indentation of lines in scripts or when you enter them interactively. It uses indentation to determine the level of nesting in loops. Be careful when cutting and pasting, if you get the wrong indentation, then unpredictable things can happen (usually it just gives an error).

A blank line can be used to return the indentation to a previous level. For example, expanded parameters in tasks cause indentation in subsequent lines in the interface. For example, the following snippet of inputs from clean can be cut and pasted without error due to the blank line after the indented parameters:

```python
mode = 'channel'  # Type of selection
nchan = -1        # Number of channels to select
start = 0         # Start channel
step = 1          # Increment between channels/velocity
width = 1         # Channel width
alg = 'clark'     # Algorithm to use
```

If the blank line were not there, an error would result if you pasted this at the casapy prompt.

B.4 Lists and Ranges

Sometimes, you need to give a task a list of indices. For example, some tasks and tools expect a comma-separated Python list, e.g.

```python
scanlist = [241, 242, 243, 244, 245, 246]
```

You can use the Python range function to generate a list of consecutive numbers, e.g.

```python
scanlist = range(241, 247)
```

giving the same list as above, e.g.
APPENDIX B. APPENDIX: PYTHON AND CASA

CASA <1>: scanlist=range(241,247)
CASA <2>: print scanlist
[241, 242, 243, 244, 245, 246]

Note that range starts from the first limit and goes to one below the second limit (Python is 0-based, and range is designed to work in loop functions). If only a single limit is given, the first limit is treated as 0, and the one given is used as the second, e.g.

CASA <3>: iflist=range(4)
CASA <4>: print iflist
[0, 1, 2, 3]

You can also combine multiple ranges by summing lists

CASA <5>: scanlist=range(241,247) + range(251,255)
CASA <6>: print scanlist
[241, 242, 243, 244, 245, 246, 251, 252, 253, 254]

B.5 Dictionaries

Python dictionaries are data structures that contain key:value pairs, sort of like a hash array. These are useful to store mini-databases of things. In CASA, the parameter values are kept in a dictionary behind the scenes.

To initialize a dictionary, say we call it mydict, for use:

CASA <7>: mydict = {}

To add members:

CASA <8>: mydict['source'] = '0137+331'
CASA <9>: mydict['flux'] = 5.4

To see its contents:

CASA <10>: mydict
Output: {'source': '0137+331', 'flux': 5.4000000000000004}
CASA <11>: print mydict
{'source': '0137+331', 'flux': 5.4000000000000004}

To access a specific entry:

CASA <12>: print mydict['flux']
5.4
B.5.1 Saving and Reading Dictionaries

To save a simple dictionary to a file:

```plaintext
CASA <13>: dictfile = open('mydictfile.py','w')
CASA <14>: print >>dictfile,"mydict = ",mydict
CASA <15>: dictfile.close()
CASA <16>: !cat mydictfile.py
IPython system call: cat mydictfile.py
mydict = {'source': '0137+331', 'flux': 5.4000000000000004}
CASA <17>: mydict = {}
CASA <18>: run mydictfile.py
CASA <19>: mydict
Out[19]: {'flux': 5.4000000000000004, 'source': '0137+331'}
```

More complex dictionaries, like those produced by `imstat` that contain NumPy arrays, require a different approach to save. The `pickle` module lets you save general data structures from Python. For example:

```plaintext
CASA <20>: import pickle
CASA <21>: xstat
Out[21]:
{'blc': array([0, 0, 0, 0]),
 'blcf': '15:24:08.404, +04.31.59.181, I, 1.41281e+09Hz',
 'flux': array([ 4.0795296]),
 'max': array([ 0.05235516]),
 'maxpos': array([134, 134, 0, 38]),
 'maxposf': '15:21:53.976, +05.05.29.998, I, 1.41374e+09Hz',
 'mean': array([ 1.60097857e-05]),
 'medabsdevmed': array([ 0.00127436]),
 'median': array([-1.17422514e-05]),
 'min': array([-0.0104834]),
 'minpos': array([160, 1, 0, 30]),
 'minposf': '15:21:27.899, +04.32.14.923, I, 1.41354e+09Hz',
 'npts': array([ 3014656.]),
 'quartile': array([ 0.00254881]),
 'rms': array([ 0.00202226]),
 'sigma': array([ 0.00202222]),
 'sum': array([ 48.26399646]),
 'sumsq': array([12.32857318]),
 'trc': array([255, 255, 0, 45]),
 'trcf': '15:19:52.390, +05.35.44.246, I, 1.41391e+09Hz'}
CASA <22>: mydict
Out[22]: {'flux': 5.4000000000000004, 'source': '0137+331'}
```

CASA <23>: pickfile = 'myxstat.pickle'
CASA <24>: f = open(pickfile,'w')
CASA <25>: p = pickle.Pickler(f)
The dictionaries are now saved in pickle file myxstat.pickle in the current directory.

To retrieve:

```casa
CASA <29>: xstat2 = {}
CASA <30>: mydict2 = {}
CASA <31>: f = open(pickfile)
CASA <32>: u = pickle.Unpickler(f)
CASA <33>: xstat2 = u.load()
CASA <34>: mydict2 = u.load()
CASA <35>: f.close()
CASA <36>: xstat2
Out[36]:
{'blc': array([0, 0, 0, 0]),
 'blcf': '15:24:08.404, +04.31.59.181, I, 1.41281e+09Hz',
 'flux': array([ 4.0795296]),
 'max': array([ 0.05235516]),
 'maxpos': array([134, 134, 0, 38]),
 'maxposf': '15:21:53.976, +05.05.29.998, I, 1.41374e+09Hz',
 'mean': array([1.60097857e-05]),
 'medabsdevmed': array([0.00127436]),
 'median': array([-1.17422514e-05]),
 'min': array([-0.0104834]),
 'minpos': array([160, 1, 0, 30]),
 'minposf': '15:21:27.899, +04.32.14.923, I, 1.41354e+09Hz',
 'npts': array([3014656.]),
 'quartile': array([0.00254881]),
 'rms': array([0.00202226]),
 'sigma': array([0.00202222]),
 'sum': array([48.26399646]),
 'sumsq': array([12.32857318]),
 'trc': array([255, 255, 0, 45]),
 'trcf': '15:19:52.390, +05.35.44.246, I, 1.41391e+09Hz'}
CASA <37>: mydict2
Out[37]: {'flux': 5.4000000000000004, 'source': '0137+331'}
```

Thus, you can make scripts that save information and use it later, like for regressions.

Note that these examples use Python file-handling and IO, as well as importing modules such as pickle. See your friendly Python reference for more on this kind of stuff. Its fairly obvious how it works.
B.6 Control Flow: Conditionals, Loops, and Exceptions

There are a number of ways to control the flow of execution in Python, including conditionals (if), loops (for and while), and exceptions (try). We will discuss the first two below.

B.6.1 Conditionals

The standard if block handles conditional execution or branches in Python:

```
if <expression>:
    <statements>
elif <expression>:
    <statements>
elif <expression>:
    <statements>
...
else:
    <statements>
```

Insert a pass statement if you want no action to be taken for a particular clause. The <expression> should reduce down to True or False.

For example,

```python
if ( importmode == 'vla' ):
    # Import the data from VLA Export to MS
    default('importvla')
    print "Use importvla to read VLA Export and make an MS"
    archivefiles = datafile
    vis = msfile
    bandname = exportband
    autocorr = False
    antnamescheme = 'new'
    project = exportproject
    importvla()
elif ( importmode == 'fits' ):
    # Import the data from VLA Export to MS
    default('importuvfits')
    print "Use importuvfits to read UVFITS and make an MS"
    fitsfile = datafile
    vis = msfile
    async = False
    importuvfits()
```
else:
    # Copy from msfile
    print "Copying "+datafile+" to "+msfile
    os.system('cp -r "+datafile+' '+msfile)
    vis = msfile

chooses branches based on the value of the importmode Python variable (set previously in script).

### B.6.2 Loops

The `for` loop

```python
for iter in seq:
    <statements>
```

iterates over elements of a sequence `seq`, assigning each in turn to `iter`. The sequence is usually a list of values.

For example,

```python
splitms = 'polcal_20080224.cband.all.split.ms'
srclist = ['0137+331','2136+006','2202+422','2253+161','0319+415','0359+509']
spwlist = ['0','1']

for src in srclist:
    for spwid in spwlist:
        imname = splitms + '.' + src + '.' + spwid + '.clean'
        clean(vis=splitms,field=src,spw=spwid,imagename=imname,
              stokes='IQUV',psfmode='hogbom',imagermode='csclean',
              imsize=[288,288],cell=[0.4,0.4],niter=1000,
              threshold=1.3,mask=[134,134,154,154])
```

# Done with spw

# Done with sources

As usual, blocks are closed by blank lines of the previous indentation level.

You can use the `range` (§ B.4) Python function to generate a numerical loop:

```python
vis = 'polcal_20080224.cband.all.ms'
for i in range(0,6):
    fld = str(i)
    plotxy(vis,field=fld,xaxis='uvdist',yaxis='amp')
```

# Done with fields [0, 1, 2, 3, 4, 5]
There is also a `while` loop construct

```python
while <expression>:
    <statements>
```

which executes the statement block while the `<expression>` is `True`. The `while` loop can also take an `else` block.

For example,

```python
# Do an explicit set of clean iterations down to a limit
prevrms = 1.e10
while rms > 0.001 :
    clean(vis=splitms,field=src,spw=spwid,imagename=imname,
          stokes='IQUV',psfmode='hogbom',imagermode='csclean',
          imsize=[288,288],cell=[0.4,0.4],niter=200,
          threshold=1.3,mask=[134,134,154,154])

    offstat=imstat(imname+'*.residual',box='224,224,284,284')
    rms=offstat['sigma'][0]
    if rms > prevrms:
        break # the rms has increased, stop

    prevrms = rms

# Clean until the off-source rms residual, reaches 0.001 Jy
```

Note that you can exit a loop using the `break` statement, as we have here when the rms increases.

### B.7 System shell access

For scripts, the `os.system` methods are the preferred way to access system shell commands (see §[B.7.1](#)).

In interactive mode, any input line beginning with a `!' character is passed verbatim (minus the `!' ) to the underlying operating system. Several common commands (`ls, pwd, less`) may be executed with or without the `!' . Note that the `cd` command must be executed without the `!' , and the `cp` command must use `!' as there is a conflict with the `cp` tool in `casapy`.

For example:

```
CASA [1]: pwd
/export/home/corsair-vml/jmcmulli/data
CASA [2]: ls n*
ngc5921.ms ngc5921.py
CASA [3]: !cp -r ../*.py .
```
B.7.1 Using the os.system methods

To use this, you need the os package. This should be loaded by default by casapy, but if not you can use

    import os

in your script.

For example, in our scripts we use this to clean up any existing output files

    # The prefix to use for all output files
    prefix='ngc5921.usecase'

    # Clean up old files
    os.system('rm -rf '+prefix+'*')

Note that the os package has many useful methods. You can see these by using tab-completion:

CASA <2>: os.<tab>

```
  os.EX_CANTCREAT  os.__Environ  os.fdatasync  os.remove
  os.EX_CONFIG    os.__all__    os.fopen      os.removedirs
  os.EX_DATAERR   os.__builtins__ os.fork      os.rename
  os.EX_IOERR     os.__class__  os.forkpty    os.renames
  os.EX_NOHOST    os.__delattr__ os.fpathconf  os.rmdir
  os.EX_NOINPUT   os.__dict__   os.fstat      os.sep
  os.EX_NOPERM    os.__doc__    os.fstatvfs   os.setegid
  os.EX_NOUSER    os.__file__   os.fsync      os.seteuid
  os.EX_OK        os.__getattribute__ os.ftruncate os.setgid
  os.EX_OSERR     os.__hash__   os.getcwd     os.setgroups
  os.EX_OFILE     os.__init__   os.getcwdu    os.setpgid
  os.EX_PROTOCOL  os.__name__   os.getegid    os.setpgrp
  os.EX_SOFTWARE  os.__new__    os.getenv     os.setregid
  os.EX_TEMPFAIL  os.__reduce__ os.geteuid    os.setreuid
  os.EX_UNAVAILABLE os.__reduce_ex__ os.getgid    os.session
  os.EX_USAGE     os.__repr__   os.getgroups  os.setuid
  os.F_OK         os.__setattr__ os.getloadavg os.spawn
  os.NGROUPS_MAX  os._copy_reg os.getlogin   os.spawnl
  os.O_APPEND     os._exists    os.getpgid    os.spawnlp
  os.O_CREAT      os._get_exports_list os.getpgrp   os.spawnlpe
  os.O_DIRECT     os._make_stat_result os.getsid    os.spawnvp
  os.O_DSYNC      os._make_statvfs_result os.getspgid os.spawnve
  os.O_DIRECTORY  os._pickle_stat_result os.getspgid os.spawnvpe
  os.O_EXCL       os._pickle_statvfs_result os.kill    os.stat
  os.O_LARGEFILE  os._spawnvef  os.killpg     os.stat_result
  os.O_NONBLOCK   os.abort      os.lchown     os.statvfs
  os.O_NOCTTY     os.lchmod      os.linesep    os.statvfs_result
  os.O_NOFOLLOW  os.link        os.stat    os.strerror
```
B.7.2 Directory Navigation

In addition, filesystem navigation is aided through the use of bookmarks to simplify access to frequently-used directories:

CASA [4]: cd /home/ballista/jmcmulli/other_data
CASA [4]: pwd
/home/ballista/jmcmulli/other_data
CASA [5]: bookmark other_data
CASA [6]: cd /export/home/corsair-vml/jmcmulli/data
CASA [7]: pwd
/export/home/corsair-vml/jmcmulli/data
CASA [8]: cd -b other_data
(bookmark: data) -> /home/ballista/jmcmulli/other_data

For python scripts, there is a special command to change a directory.

```python
os.system('cd ~/directory')
```

will NOT work but the following will:
B.7.3 Shell Command and Capture

See also §B.9 for the use of the command history.

1. sx shell_command, !!shell_command - this captures the output to a list

```python
CASA [1]: sx pwd # stores output of 'pwd' in a list
   Out[1]: ['/home/basho3/jmcmulli/pretest']

CASA [2]: !!pwd # !! is a shortcut for 'sx'
   Out[2]: ['/home/basho3/jmcmulli/pretest']

CASA [3]: sx ls v* # stores output of 'pwd' in a list
   Out[3]: ['vla_calplot.jpg',
              'vla_calplot.png',
              'vla_msplot_cals.jpg',
              'vla_msplot_cals.png',
              'vla_plotcal_bpass.jpg',
              'vla_plotcal_bpass.png',
              'vla_plotcal_fcal.jpg',
              'vla_plotcal_fcal.png',
              'vla_plotvis.jpg',
              'vla_plotvis.png']

CASA [4]: x=_ # remember '_' is a shortcut for the output from the last command

CASA [5]: x
   Out[5]: ['vla_calplot.jpg',
              'vla_calplot.png',
              'vla_msplot_cals.jpg',
              'vla_msplot_cals.png',
              'vla_plotcal_bpass.jpg',
              'vla_plotcal_bpass.png',
              'vla_plotcal_fcal.jpg',
              'vla_plotcal_fcal.png',
              'vla_plotvis.jpg',
              'vla_plotvis.png']

CASA [6]: y=Out[2] # or just refer to the enumerated output

CASA [7]: y
   Out[7]: ['/home/basho3/jmcmulli/pretest']
```

2. sc - captures the output to a variable; options are '-l' and '-v'

```python
CASA [1]: sc x=pwd # capture output from 'pwd' to the variable 'x'
```
B.8 Logging

There are two components to logging within CASA. Logging of all command line inputs is done via IPython.

Upon startup, CASA will log all commands to a file called `ipython.log`. This file can be changed via the use of the `/.casa/ipython/ipythonrc` file. This log file can be edited and re-executed as appropriate using the `execfile` feature (§B.12).

Logging can be turned on and off using the `logon`, `logoff` commands.

The second component is the output from applications which is directed to the file `./casapy.log`. See §1.5.2 for more on the `casalogger`.

B.9 History and Searching

Numbered input/output history is provided natively within IPython. Command history is also maintained on-line.

```python
CASA [11]: x
Out[11]: 1

CASA [12]: y=3*x

CASA [13]: z=x**2+y**2

CASA [14]: x
Out[14]: 1
```
Command history can be accessed via the 'hist' command. The history is reset at the beginning of every CASA session, that is, typing 'hist' when you first start CASA will not provide any commands from the previous session. However, all of the commands are still available at the command line and can be accessed through the up or down arrow keys, and through searching.

```
CASA [22]: hist
1 : __IP.system("vi temp.py") # Note: shell commands are designated in this way
2 : ipmagic("run -i temp.py") # Note: magic commands are designated in this way
3 : ipmagic("hist ")
4 : more temp.py
5 : __IP.system("more temp.py")
6 : quickhelp()              # Note: autoparenthesis are added in the history
7 : im.open('ngc5921.ms')
8 : im.summary()
9 : ipmagic("pdoc im.setdata")
10: im.close()
11: quickhelp()
12: ipmagic("logstate ")
13: x=1
14: y=3*x
15: z=x**2+y**2
16: x
17: y
18: z
19: Out[16]
20: _17
21: ___
```

The history can be saved as a script or used as a macro for further use:

```
CASA [24]: save script.py 13:16
File 'script.py' exists. Overwrite (y/[N])? y
The following commands were written to file 'script.py':
  x=1
```
\begin{verbatim}
y=3*x
z=x**2+y**2
CASA [25]: !more script.py
x=1
y=3*x
z=x**2+y**2
\end{verbatim}

Note that the history commands will be saved up to, but not including the last value (i.e., history commands 13-16 saves commands 13, 14, and 15).

There are two mechanisms for searching command history:

1. Previous/Next: use Ctrl-p (previous,up) and Ctrl-n (next,down) to search through only the history items that match what you have typed so far (min-match completion). If you use Ctrl-p or Ctrl-n at a blank prompt, they behave just like the normal arrow keys.

2. Search: Ctrl-r opens a search prompt. Begin typing and the system searches your history for lines that contain what you’ve typed so far, completing what it can. For example:

\begin{verbatim}
CASA [37]: <Cntl-r>
(reverse-i-search)'':
Typing anything after the colon will provide you with the last command matching the characters, for example, typing 'op' finds:
(reverse-i-search)'op': im.open('ngc5921.ms')
Subsequent hitting of Ctrl-r will search for the next command matching the characters.
\end{verbatim}

\section*{B.10 Macros}

Macros can be made for easy re-execution of previous commands. For example to store the commands 13-15 to the macro 'example':

\begin{verbatim}
CASA [31]: macro example 13:16
Macro 'example' created. To execute, type its name (without quotes).
Macro contents:
x=1
y=3*x
z=x**2+y**2
CASA [32]: z
Out[32]: 6
CASA [33]: z=10
\end{verbatim}
APPENDIX B. APPENDIX: PYTHON AND CASA

B.11 On-line editing

You can edit files on-line in two ways:

1. Using the shell access via '!vi'

2. Using the ed function; this will edit the file but upon closing, it will try to execute the file; using the 'script.py' example above:

    CASA [13]: ed script.py # this will bring up the file in your chosen editor
                  # when you are finished editing the file,
                  # it will automatically
                  # execute it (as though you had done a
                  # execfile 'script.py'
    Editing... done. Executing edited code...

B.12 Executing Python scripts

Python scripts are simple text files containing lists of commands as if typed at the keyboard. Note: the auto-parentheses feature of IPython can not be used in scripts, that is, you should make sure all function calls have any opening and closing parentheses.

    # file is script.py
    # My script to plot the observed visibilities
    plotxy('ngc5921.ms','uvdist') #yaxis defaults to amplitude

This can be done by using the execfile command to execute this script. execfile will execute the script as though you had typed the lines at the CASA prompt.
If you don’t want to launch CASA and execute your script from the command line, you can use the 'c' option:

```
unix$ casapy -c 'script.py'
```

**B.13 How do I exit from CASA?**

You can exit CASA by using the `quit` command. This will bring up the query

```
Do you really want to exit ([y]/n)?
```

to give you a chance in case you did not mean to exit. You can also quit using `%exit` or `CTRL-D`.

If you don’t want to see the question "Do you really want to exit [y]/n?", then just type `Exit` or `exit` followed by return, and CASA will stop right then and there.
Appendix C

Appendix: Models, Conventions, and Reference Frames

This appendix lists the available parameters, conventions, reference frames, and information on flux standards used in CASA.

C.1 Flux Density Models for setjy

setjy adds a source model given the source name, frequency, a standard (really, a set of models), and possibly a time. At cm wavelengths the flux density (FD) calibrators are typically one of several bright extragalactic sources. These objects are comparatively faint and less well characterized at shorter wavelengths, so for (sub)mm astronomy it is common to use Solar System objects.

Reliably setting the FD scale with astronomical calibrators requires that they be bright, not too resolved, and have simple dependencies on frequency and time. These criteria are somewhat mutually exclusive, so the number of calibrator sources supported by setjy is fairly small, although it could certainly be added to. This appendix is for describing the models that setjy uses. Choosing a FD calibrator of course has to be done before the observation and the observatory may provide additional information.

C.1.1 Long wavelength calibration

Synchrotron sources can vary over a light crossing time, so ones used as FD calibrators must have most of their emission coming from an extended region. The additional requirement that they be nearly unresolved therefore forces them to be distant, meaning that candidates which also have high apparent fluxes are quite rare. The following standards mostly share the same set of objects, and monitor their FDs every few years to account for variations. No interpolation is done between epochs, though - you are encouraged to choose the standard which observed your FD calibrator closest to the time you observed it at. The measurements are interpolated in frequency, however, using second to fourth degree polynomials of the frequency’s logarithm.
Table C.1: Recognized Flux Density Calibrators. Note that the VLA uses J2000 calibrator names. CASA accepts all strings that contain the names below. E.g. 'PKS 1934-638' will be recognized

<table>
<thead>
<tr>
<th>3C Name</th>
<th>B1950 Name</th>
<th>J2000 Name</th>
<th>Alt. J2000 Name</th>
<th>Standards</th>
</tr>
</thead>
<tbody>
<tr>
<td>3C48</td>
<td>0134+329</td>
<td>0137+331</td>
<td>J0137+3309</td>
<td>1,3,4,5,6</td>
</tr>
<tr>
<td>3C123</td>
<td>0433+295</td>
<td>0437+296</td>
<td>J0437+2940</td>
<td>2</td>
</tr>
<tr>
<td>3C138</td>
<td>0518+165</td>
<td>0521+166</td>
<td>J0521+1638</td>
<td>1,3,4,5,6</td>
</tr>
<tr>
<td>3C147</td>
<td>0538+498</td>
<td>0542+498</td>
<td>J0542+4951</td>
<td>1,3,4,5,6</td>
</tr>
<tr>
<td>3C196</td>
<td>0809+483</td>
<td>0813+482</td>
<td>J0813+4813</td>
<td>1,2</td>
</tr>
<tr>
<td>3C286</td>
<td>1328+307</td>
<td>1331+305</td>
<td>J1331+3030</td>
<td>1,2,3,4,5,6</td>
</tr>
<tr>
<td>3C295</td>
<td>1409+524</td>
<td>1411+522</td>
<td>J1411+5212</td>
<td>1,2,3,4,5,6</td>
</tr>
<tr>
<td>–</td>
<td>1934-638</td>
<td>–</td>
<td>J1939-6342</td>
<td>1,3,4,5,6</td>
</tr>
</tbody>
</table>


C.1.1.1 Baars

The only standard to not have the year in the name. It is 1977.

The models are second order polynomials in $\log(\nu)$, valid between 408 MHz and 15 GHz.


C.1.1.2 Perley 90


C.1.1.3 Perley-Taylor 95


C.1.1.4 Perley-Taylor 99

C.1.1.5 Perley-Butler 2010


C.1.1.6 Perley-Butler 2013

Flux scale for the constant flux sources 3C123, 3C196, 3C286, and 3C295.


C.1.2 Short wavelength calibration

The usual approach in this regime is to use models that are, to first order, thermal sources in the Solar System. Their apparent brightness of course varies in time with their distance from the Earth (and Sun), and orientation if they are not perfect spheres with zero obliquity. However, most of them have almost constant surface properties, so once those properties are measured their apparent brightness distributions can in principle be predicted for any time, given an ephemeris. Planets, in particular, however, have more complex spectra and effects such as atmospheric lines, magnetic fields, seasons, polar caps and surface features need to be taken into account when they are available and significant. In CASA the Solar System objects supported by setjy are available through the ‘Butler-JPL-Horizons 2010’, and ’Butler-JPL-Horizons 2012’ standards. The models are described in ALMA Memo 594 available on https://science.nrao.edu/facilities/alma/aboutALMA/Technology/ALMA_Memo_Series/alma594/abs594

C.2 Velocity Reference Frames

CASA supported velocity frames are listed in Table C.2

C.2.1 Doppler Types

CASA supported Doppler types are listed in Table C.3

C.3 Time Reference Frames

CASA supported time reference frames are listed in Table C.4
Table C.2: Velocity frames in CASA

<table>
<thead>
<tr>
<th>Name</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>REST</td>
<td>Laboratory</td>
</tr>
<tr>
<td>LSRK</td>
<td>local standard of rest (kinematic)</td>
</tr>
<tr>
<td>LSRD</td>
<td>local standard of rest (dynamic)</td>
</tr>
<tr>
<td>BARY</td>
<td>barycentric</td>
</tr>
<tr>
<td>GEO</td>
<td>geocentric</td>
</tr>
<tr>
<td>TOPO</td>
<td>topocentric</td>
</tr>
<tr>
<td>GALACTO</td>
<td>galactocentric</td>
</tr>
<tr>
<td>LGROUP</td>
<td>Local Group</td>
</tr>
<tr>
<td>CMB</td>
<td>cosmic microwave background dipole</td>
</tr>
</tbody>
</table>

Table C.3: Doppler types in CASA

<table>
<thead>
<tr>
<th>Name</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>RADIO</td>
<td></td>
</tr>
<tr>
<td>Z</td>
<td></td>
</tr>
<tr>
<td>RATIO</td>
<td></td>
</tr>
<tr>
<td>BETA</td>
<td></td>
</tr>
<tr>
<td>GAMMA</td>
<td></td>
</tr>
<tr>
<td>OPTICAL</td>
<td></td>
</tr>
<tr>
<td>TRUE</td>
<td></td>
</tr>
<tr>
<td>RELATIVISTIC</td>
<td></td>
</tr>
</tbody>
</table>

C.4 Coordinate Frames

CASA supported time coordinate frames are listed in Table C.5.

Note that TOPO refers to a time stamp at a given observation date. If more than one observation is concatenated this may lead to vastly erroneous values. Any conversion from TOPO to other frames such as BARY and LSRK should be performed for each individual observation, prior to concatenation or simultaneous imaging.

C.5 Physical Units

CASA also recognizes physical units. They are listed in Tables C.6, C.7, and C.8.
### Table C.4: Time reference frames in CASA

<table>
<thead>
<tr>
<th>Name</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>LAST</td>
<td></td>
</tr>
<tr>
<td>LMST</td>
<td></td>
</tr>
<tr>
<td>GMST1</td>
<td></td>
</tr>
<tr>
<td>GAST</td>
<td></td>
</tr>
<tr>
<td>UT1</td>
<td></td>
</tr>
<tr>
<td>UT2</td>
<td></td>
</tr>
<tr>
<td>UTC</td>
<td></td>
</tr>
<tr>
<td>TAI</td>
<td></td>
</tr>
<tr>
<td>TDT</td>
<td></td>
</tr>
<tr>
<td>TCG</td>
<td></td>
</tr>
<tr>
<td>TDB</td>
<td></td>
</tr>
<tr>
<td>TCB</td>
<td></td>
</tr>
<tr>
<td>IAT</td>
<td></td>
</tr>
<tr>
<td>GMST</td>
<td></td>
</tr>
<tr>
<td>TT</td>
<td></td>
</tr>
<tr>
<td>ET</td>
<td></td>
</tr>
<tr>
<td>UT</td>
<td></td>
</tr>
</tbody>
</table>

### C.6 Physical Constants

The physical constants included in CASA can be found in Table C.9.
Table C.5: Coordinate frames in CASA

<table>
<thead>
<tr>
<th>Name</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>J2000</td>
<td>mean equator and equinox at J2000.0 (FK5)</td>
</tr>
<tr>
<td>JNAT</td>
<td>geocentric natural frame</td>
</tr>
<tr>
<td>JMEAN</td>
<td>mean equator and equinox at frame epoch</td>
</tr>
<tr>
<td>JTRUE</td>
<td>true equator and equinox at frame epoch</td>
</tr>
<tr>
<td>APP</td>
<td>apparent geocentric position</td>
</tr>
<tr>
<td>B1950</td>
<td>mean epoch and ecliptic at B1950.0</td>
</tr>
<tr>
<td>B1950_VLA</td>
<td>mean epoch(1979.9) and ecliptic at B1950.0</td>
</tr>
<tr>
<td>BMEAN</td>
<td>mean equator and equinox at frame epoch</td>
</tr>
<tr>
<td>BTRUE</td>
<td>true equator and equinox at frame epoch</td>
</tr>
<tr>
<td>GALACTIC</td>
<td>Galactic coordinates</td>
</tr>
<tr>
<td>HADEC</td>
<td>topocentric HA and declination</td>
</tr>
<tr>
<td>AZEL</td>
<td>topocentric Azimuth and Elevation (N through E)</td>
</tr>
<tr>
<td>AZELSW</td>
<td>topocentric Azimuth and Elevation (S through W)</td>
</tr>
<tr>
<td>AZELNE</td>
<td>topocentric Azimuth and Elevation (N through E)</td>
</tr>
<tr>
<td>AZELGEO</td>
<td>geodetic Azimuth and Elevation (N through E)</td>
</tr>
<tr>
<td>AZELSWGEO</td>
<td>geodetic Azimuth and Elevation (S through W)</td>
</tr>
<tr>
<td>AZELNEGEO</td>
<td>geodetic Azimuth and Elevation (N through E)</td>
</tr>
<tr>
<td>ECLIPTC</td>
<td>ecliptic for J2000 equator and equinox</td>
</tr>
<tr>
<td>MECLIPTIC</td>
<td>ecliptic for mean equator of date</td>
</tr>
<tr>
<td>TECLIPTIC</td>
<td>ecliptic for true equator of date</td>
</tr>
<tr>
<td>SUPERGAL</td>
<td>supergalactic coordinates</td>
</tr>
<tr>
<td>ITRF</td>
<td>coordinates wrt ITRF Earth frame</td>
</tr>
<tr>
<td>TOPO</td>
<td>apparent topocentric position</td>
</tr>
<tr>
<td>ICRS</td>
<td>International Celestial reference system</td>
</tr>
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Table C.6: Prefixes

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<tr>
<th>Prefix</th>
<th>Name</th>
<th>Value</th>
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<tbody>
<tr>
<td>Y</td>
<td>(yotta)</td>
<td>(10^{24})</td>
</tr>
<tr>
<td>Z</td>
<td>(zetta)</td>
<td>(10^{21})</td>
</tr>
<tr>
<td>E</td>
<td>(exa)</td>
<td>(10^{18})</td>
</tr>
<tr>
<td>P</td>
<td>(peta)</td>
<td>(10^{15})</td>
</tr>
<tr>
<td>T</td>
<td>(tera)</td>
<td>(10^{12})</td>
</tr>
<tr>
<td>G</td>
<td>(giga)</td>
<td>(10^{9})</td>
</tr>
<tr>
<td>M</td>
<td>(mega)</td>
<td>(10^{6})</td>
</tr>
<tr>
<td>k</td>
<td>(kilo)</td>
<td>(10^{3})</td>
</tr>
<tr>
<td>h</td>
<td>(hecto)</td>
<td>(10^{2})</td>
</tr>
<tr>
<td>da</td>
<td>(deka)</td>
<td>(10)</td>
</tr>
<tr>
<td>d</td>
<td>(deci)</td>
<td>(10^{-1})</td>
</tr>
<tr>
<td>c</td>
<td>(centi)</td>
<td>(10^{-2})</td>
</tr>
<tr>
<td>m</td>
<td>(milli)</td>
<td>(10^{-3})</td>
</tr>
<tr>
<td>u</td>
<td>(micro)</td>
<td>(10^{-6})</td>
</tr>
<tr>
<td>n</td>
<td>(nano)</td>
<td>(10^{-9})</td>
</tr>
<tr>
<td>p</td>
<td>(pico)</td>
<td>(10^{-12})</td>
</tr>
<tr>
<td>f</td>
<td>(femto)</td>
<td>(10^{-15})</td>
</tr>
<tr>
<td>a</td>
<td>(atto)</td>
<td>(10^{-18})</td>
</tr>
<tr>
<td>z</td>
<td>(zepto)</td>
<td>(10^{-21})</td>
</tr>
<tr>
<td>y</td>
<td>(yocto)</td>
<td>(10^{-24})</td>
</tr>
</tbody>
</table>
Table C.7: SI Units

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<thead>
<tr>
<th>Unit</th>
<th>Name</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>$</td>
<td>(currency)</td>
<td>1 _</td>
</tr>
<tr>
<td>%</td>
<td>(percent)</td>
<td>0.01</td>
</tr>
<tr>
<td>%%</td>
<td>(permille)</td>
<td>0.001</td>
</tr>
<tr>
<td>A</td>
<td>(ampere)</td>
<td>1 A</td>
</tr>
<tr>
<td>AE</td>
<td>(astronomical unit)</td>
<td>149597870659 m</td>
</tr>
<tr>
<td>AU</td>
<td>(astronomical unit)</td>
<td>149597870659 m</td>
</tr>
<tr>
<td>Bq</td>
<td>(becquerel)</td>
<td>1 s⁻¹</td>
</tr>
<tr>
<td>C</td>
<td>(coulomb)</td>
<td>1 s A</td>
</tr>
<tr>
<td>F</td>
<td>(farad)</td>
<td>1 m⁻² kg⁻¹ s⁴ A²</td>
</tr>
<tr>
<td>Gy</td>
<td>(gray)</td>
<td>1 m² s⁻²</td>
</tr>
<tr>
<td>H</td>
<td>(henry)</td>
<td>1 m² kg s⁻² A⁻²</td>
</tr>
<tr>
<td>Hz</td>
<td>(hertz)</td>
<td>1 s⁻¹</td>
</tr>
<tr>
<td>J</td>
<td>(joule)</td>
<td>1 m² kg s⁻²</td>
</tr>
<tr>
<td>Jy</td>
<td>(jansky)</td>
<td>10⁻²⁶ kg s⁻²</td>
</tr>
<tr>
<td>K</td>
<td>(kelvin)</td>
<td>1 K</td>
</tr>
<tr>
<td>L</td>
<td>(litre)</td>
<td>0.001 m³</td>
</tr>
<tr>
<td>M0</td>
<td>(solar mass)</td>
<td>1.98891944407×10³⁰ kg</td>
</tr>
<tr>
<td>N</td>
<td>(newton)</td>
<td>1 m kg s⁻²</td>
</tr>
<tr>
<td>Ohm</td>
<td>(ohm)</td>
<td>1 m² kg s⁻³ A⁻²</td>
</tr>
<tr>
<td>Pa</td>
<td>(pascal)</td>
<td>1 m⁻¹ kg s⁻²</td>
</tr>
<tr>
<td>S</td>
<td>(siemens)</td>
<td>1 m⁻² kg⁻¹ s³ A²</td>
</tr>
<tr>
<td>S0</td>
<td>(solar mass)</td>
<td>1.98891944407×10³⁰ kg</td>
</tr>
<tr>
<td>Sv</td>
<td>(sievert)</td>
<td>1 m² s⁻²</td>
</tr>
<tr>
<td>T</td>
<td>(tesla)</td>
<td>1 kg s⁻² A⁻¹</td>
</tr>
<tr>
<td>UA</td>
<td>(astronomical unit)</td>
<td>149597870659 m</td>
</tr>
<tr>
<td>V</td>
<td>(volt)</td>
<td>1 m² kg s⁻³ A⁻¹</td>
</tr>
<tr>
<td>W</td>
<td>(watt)</td>
<td>1 m² kg s⁻³</td>
</tr>
<tr>
<td>Wb</td>
<td>(weber)</td>
<td>1 m² kg s⁻² A⁻¹</td>
</tr>
<tr>
<td>_</td>
<td>(undimensioned)</td>
<td>1 _</td>
</tr>
</tbody>
</table>
Table C.7: SI Units – continued

<table>
<thead>
<tr>
<th>Unit</th>
<th>Name</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>a</td>
<td>(year)</td>
<td>31557600 s</td>
</tr>
<tr>
<td>arcmin</td>
<td>(arcmin)</td>
<td>0.000290888208666 rad</td>
</tr>
<tr>
<td>arcsec</td>
<td>(arcsec)</td>
<td>4.8481368111 \times 10^{-6} rad</td>
</tr>
<tr>
<td>as</td>
<td>(arcsec)</td>
<td>4.8481368111e \times 10^{-6} rad</td>
</tr>
<tr>
<td>cd</td>
<td>(candela)</td>
<td>1 cd</td>
</tr>
<tr>
<td>cy</td>
<td>(century)</td>
<td>3155760000 s</td>
</tr>
<tr>
<td>d</td>
<td>(day)</td>
<td>86400 s</td>
</tr>
<tr>
<td>deg</td>
<td>(degree)</td>
<td>0.0174532925199 rad</td>
</tr>
<tr>
<td>g</td>
<td>(gram)</td>
<td>0.001 kg</td>
</tr>
<tr>
<td>h</td>
<td>(hour)</td>
<td>3600 s</td>
</tr>
<tr>
<td>l</td>
<td>(litre)</td>
<td>0.001 m(^3)</td>
</tr>
<tr>
<td>lm</td>
<td>(lumen)</td>
<td>1 cd sr</td>
</tr>
<tr>
<td>lx</td>
<td>(lux)</td>
<td>1 m(^{-2}) cd sr</td>
</tr>
<tr>
<td>m</td>
<td>(metre)</td>
<td>1 m</td>
</tr>
<tr>
<td>min</td>
<td>(minute)</td>
<td>60 s</td>
</tr>
<tr>
<td>mol</td>
<td>(mole)</td>
<td>1 mol</td>
</tr>
<tr>
<td>pc</td>
<td>(parsec)</td>
<td>3.08567758065 \times 10^{16} m</td>
</tr>
<tr>
<td>rad</td>
<td>(radian)</td>
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<td>(second)</td>
<td>1 s</td>
</tr>
<tr>
<td>sr</td>
<td>(steradian)</td>
<td>1 sr</td>
</tr>
<tr>
<td>t</td>
<td>(tonne)</td>
<td>1000 kg</td>
</tr>
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</table>
Table C.8: Custom Units

<table>
<thead>
<tr>
<th>Unit</th>
<th>Name</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>&quot;</td>
<td>(arcsec)</td>
<td>$4.8481368111 	imes 10^{-6}$ rad</td>
</tr>
<tr>
<td>&quot;_2</td>
<td>(square arcsec)</td>
<td>$2.35044305391 	imes 10^{-11}$ sr</td>
</tr>
<tr>
<td>'</td>
<td>(arcmin)</td>
<td>$0.000290888208666$ rad</td>
</tr>
<tr>
<td>&quot;</td>
<td>(arcsec)</td>
<td>$4.8481368111 	imes 10^{-6}$ rad</td>
</tr>
<tr>
<td>&quot;_2</td>
<td>(square arcsec)</td>
<td>$2.35044305391 	imes 10^{-11}$ sr</td>
</tr>
<tr>
<td>'_2</td>
<td>(square arcmin)</td>
<td>$8.46159499408 	imes 10^{-8}$ sr</td>
</tr>
<tr>
<td>:</td>
<td>(hour)</td>
<td>$3600$ s</td>
</tr>
<tr>
<td>::</td>
<td>(minute)</td>
<td>$60$ s</td>
</tr>
<tr>
<td>::::</td>
<td>(second)</td>
<td>$1$ s</td>
</tr>
<tr>
<td>Ah</td>
<td>(ampere hour)</td>
<td>$3600$ s A</td>
</tr>
<tr>
<td>Angstrom</td>
<td>(angstrom)</td>
<td>$1e-10$ m</td>
</tr>
<tr>
<td>Btu</td>
<td>(British thermal unit (Int))</td>
<td>$1055.056$ m$^2$ kg s$^{-2}$</td>
</tr>
<tr>
<td>CM</td>
<td>(metric carat)</td>
<td>$0.0002$ kg</td>
</tr>
<tr>
<td>Cal</td>
<td>(large calorie (Int))</td>
<td>$4186.8$ m$^2$ kg s$^{-2}$</td>
</tr>
<tr>
<td>FU</td>
<td>(flux unit)</td>
<td>$10^{-26}$ kg s$^{-2}$</td>
</tr>
<tr>
<td>G</td>
<td>(gauss)</td>
<td>$0.0001$ kg s$^{-2}$ A$^{-1}$</td>
</tr>
<tr>
<td>Gal</td>
<td>(gal)</td>
<td>$0.01$ m s$^{-2}$</td>
</tr>
<tr>
<td>Gb</td>
<td>(gilbert)</td>
<td>$0.795774715459$ A</td>
</tr>
<tr>
<td>Mx</td>
<td>(maxwell)</td>
<td>$10^{-8}$ m$^2$ kg s$^{-2}$ A$^{-1}$</td>
</tr>
<tr>
<td>Oe</td>
<td>(oersted)</td>
<td>$79.5774715459$ m$^{-1}$ A</td>
</tr>
<tr>
<td>R</td>
<td>(mile)</td>
<td>$0.000258$ kg$^{-1}$ s A</td>
</tr>
<tr>
<td>St</td>
<td>(stokes)</td>
<td>$0.0001$ m$^2$ s$^{-1}$</td>
</tr>
<tr>
<td>Torr</td>
<td>(torr)</td>
<td>$133.322368421$ m$^{-1}$ kg s$^{-2}$</td>
</tr>
<tr>
<td>USfl_oz</td>
<td>(fluid ounce (US))</td>
<td>$2.95735295625 	imes 10^{-5}$ m$^3$</td>
</tr>
<tr>
<td>USgal</td>
<td>(gallon (US))</td>
<td>$0.003785411784$ m$^3$</td>
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</table>
### Table C.8: Custom Units – continued

<table>
<thead>
<tr>
<th>Unit</th>
<th>Name</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>WU</td>
<td>(WSRT flux unit)</td>
<td>$5 \times 10^{-29} \text{kg s}^{-2}$</td>
</tr>
<tr>
<td>abA</td>
<td>(abampere)</td>
<td>10 A</td>
</tr>
<tr>
<td>abC</td>
<td>(abcoulomb)</td>
<td>10 s A</td>
</tr>
<tr>
<td>abF</td>
<td>(abfarad)</td>
<td>$10^9 \text{m}^{-2} \text{kg s}^{-1} \text{A}^2$</td>
</tr>
<tr>
<td>abH</td>
<td>(abhenry)</td>
<td>$10^{-9} \text{m}^2 \text{kg s}^{-2} \text{A}^{-2}$</td>
</tr>
<tr>
<td>abOhm</td>
<td>(abohtm)</td>
<td>$10^{-9} \text{m}^2 \text{kg s}^{-3} \text{A}^{-2}$</td>
</tr>
<tr>
<td>abV</td>
<td>(abvolt)</td>
<td>$10^{-8} \text{m}^2 \text{kg s}^{-3} \text{A}^{-1}$</td>
</tr>
<tr>
<td>ac</td>
<td>(acre)</td>
<td>4046.8564224 m²</td>
</tr>
<tr>
<td>arcmin_2</td>
<td>(square arcmin)</td>
<td>$8.46 \times 10^{-8} \text{sr}$</td>
</tr>
<tr>
<td>arcsec_2</td>
<td>(square arcsec)</td>
<td>$2.35 \times 10^{-11} \text{sr}$</td>
</tr>
<tr>
<td>ata</td>
<td>(technical atmosphere)</td>
<td>98066.5 m⁻¹.kg.s⁻²</td>
</tr>
<tr>
<td>atm</td>
<td>(standard atmosphere)</td>
<td>101325 m⁻¹.kg.s⁻²</td>
</tr>
<tr>
<td>bar</td>
<td>(bar)</td>
<td>100000 m⁻¹.kg.s⁻²</td>
</tr>
<tr>
<td>beam</td>
<td>(undefined beam area)</td>
<td>1 m²</td>
</tr>
<tr>
<td>cal</td>
<td>(calorie (Int))</td>
<td>4.1868 m² kg s⁻²</td>
</tr>
<tr>
<td>count</td>
<td>(count)</td>
<td>1 m²</td>
</tr>
<tr>
<td>cwt</td>
<td>(hundredweight)</td>
<td>50.80234544 kg</td>
</tr>
<tr>
<td>deg_2</td>
<td>(square degree)</td>
<td>0.000304617419787 sr</td>
</tr>
<tr>
<td>dyn</td>
<td>(dyne)</td>
<td>$10^{-5} \text{m kg s}^{-2}$</td>
</tr>
<tr>
<td>eV</td>
<td>(electron volt)</td>
<td>$1.60217733 \times 10^{-19} \text{m}^2 \text{kg s}^{-2}$</td>
</tr>
<tr>
<td>erg</td>
<td>(erg)</td>
<td>$10^{-7} \text{m}^2 \text{kg s}^{-2}$</td>
</tr>
<tr>
<td>fl_oz</td>
<td>(fluid ounce (Imp))</td>
<td>$2.84130488996 \times 10^{-5} \text{m}^3$</td>
</tr>
<tr>
<td>ft</td>
<td>(foot)</td>
<td>0.3048 m</td>
</tr>
<tr>
<td>fu</td>
<td>(flux unit)</td>
<td>$10^{-26} \text{kg s}^{-2}$</td>
</tr>
<tr>
<td>fur</td>
<td>(furlong)</td>
<td>201.168 m</td>
</tr>
<tr>
<td>gal</td>
<td>(gallon (Imp))</td>
<td>0.00454608782394 m³</td>
</tr>
</tbody>
</table>
Table C.8: Custom Units – continued

<table>
<thead>
<tr>
<th>Unit</th>
<th>Name</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>ha</td>
<td>(hectare)</td>
<td>10000 m²</td>
</tr>
<tr>
<td>hp</td>
<td>(horsepower)</td>
<td>745.7 m² kg s⁻³</td>
</tr>
<tr>
<td>in</td>
<td>(inch)</td>
<td>0.0254 m</td>
</tr>
<tr>
<td>kn</td>
<td>(knot (Imp))</td>
<td>0.514773333333 m s⁻¹</td>
</tr>
<tr>
<td>lambda</td>
<td>(lambda)</td>
<td>1 s⁻¹</td>
</tr>
<tr>
<td>lb</td>
<td>(pound (avoirdupois))</td>
<td>0.45359237 kg</td>
</tr>
<tr>
<td>ly</td>
<td>(light year)</td>
<td>9.46073047 × 10¹⁵ m</td>
</tr>
<tr>
<td>mHg</td>
<td>(metre of mercury)</td>
<td>133322.387415 m⁻¹ kg s⁻²</td>
</tr>
<tr>
<td>mile</td>
<td>(mile)</td>
<td>1609.344 m</td>
</tr>
<tr>
<td>n_mile</td>
<td>(nautical mile (Imp))</td>
<td>1853.184 m</td>
</tr>
<tr>
<td>oz</td>
<td>(ounce (avoirdupois))</td>
<td>0.028349523125 kg</td>
</tr>
<tr>
<td>pixel</td>
<td>(pixel)</td>
<td>1 sq °</td>
</tr>
<tr>
<td>sb</td>
<td>(stilb)</td>
<td>10000 m⁻² cd</td>
</tr>
<tr>
<td>sq_arcmin</td>
<td>(square arcmin)</td>
<td>8.46159499408 × 10⁻⁸ sr</td>
</tr>
<tr>
<td>sq_arcsec</td>
<td>(square arcsec)</td>
<td>2.35044305391 × 10⁻¹¹ sr</td>
</tr>
<tr>
<td>sq_deg</td>
<td>(square degree)</td>
<td>0.000304617419787 sr</td>
</tr>
<tr>
<td>statA</td>
<td>(statampere)</td>
<td>3.33564095198 × 10⁻¹⁰ A</td>
</tr>
<tr>
<td>statC</td>
<td>(statcoulomb)</td>
<td>3.33564095198 × 10⁻¹⁰ s A</td>
</tr>
<tr>
<td>statF</td>
<td>(statfarad)</td>
<td>1.11188031733 × 10⁻¹² m⁻² kg⁻¹ s⁻¹ A³</td>
</tr>
<tr>
<td>statH</td>
<td>(stathenry)</td>
<td>899377374000 m² kg s⁻² A⁻²</td>
</tr>
<tr>
<td>statOhm</td>
<td>(statohm)</td>
<td>899377374000 m² kg s⁻³ A⁻²</td>
</tr>
<tr>
<td>statV</td>
<td>(statvolt)</td>
<td>299.792458 m² kg s⁻³ A⁻¹</td>
</tr>
<tr>
<td>u</td>
<td>(atomic mass unit)</td>
<td>1.661 × 10⁻²⁷ kg</td>
</tr>
<tr>
<td>yd</td>
<td>(yard)</td>
<td>0.9144 m</td>
</tr>
<tr>
<td>yr</td>
<td>(year)</td>
<td>31557600 s</td>
</tr>
</tbody>
</table>
Table C.9: Physical Constants

<table>
<thead>
<tr>
<th>Constant</th>
<th>Name</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>pi</td>
<td>3.14..</td>
<td>3.14159</td>
</tr>
<tr>
<td>ee</td>
<td>2.71..</td>
<td>2.71828</td>
</tr>
<tr>
<td>c</td>
<td>light vel.</td>
<td>2.99792×10^8 m s(^{-1})</td>
</tr>
<tr>
<td>G</td>
<td>grav. const</td>
<td>6.67259×10^{11} N m^2 kg(^{-2})</td>
</tr>
<tr>
<td>h</td>
<td>Planck const</td>
<td>6.62608×10^{-34} J s</td>
</tr>
<tr>
<td>HI</td>
<td>HI line</td>
<td>1420.41 MHz</td>
</tr>
<tr>
<td>R</td>
<td>gas const</td>
<td>8.31451 J K(^{-1}) mol(^{-1})</td>
</tr>
<tr>
<td>NA</td>
<td>Avogadro #</td>
<td>6.02214×10^{23} mol(^{-1})</td>
</tr>
<tr>
<td>e</td>
<td>electron charge</td>
<td>1.60218×10^{-19} C</td>
</tr>
<tr>
<td>mp</td>
<td>proton mass</td>
<td>1.67262×10^{-27} kg</td>
</tr>
<tr>
<td>mp/me</td>
<td>mp/me</td>
<td>1836.15</td>
</tr>
<tr>
<td>mu0</td>
<td>permeability vac.</td>
<td>1.25664×10^{-6} H m(^{-1})</td>
</tr>
<tr>
<td>eps0</td>
<td>permittivity vac.</td>
<td>1.60218×10^{-19} C</td>
</tr>
<tr>
<td>k</td>
<td>Boltzmann const</td>
<td>1.38066×10^{-23} J K(^{-1})</td>
</tr>
<tr>
<td>F</td>
<td>Faraday const</td>
<td>96485.3 C mol(^{-1})</td>
</tr>
<tr>
<td>me</td>
<td>electron mass</td>
<td>9.10939×10^{-31} kg</td>
</tr>
<tr>
<td>re</td>
<td>electron radius</td>
<td>2.8179e×10^{-15} m</td>
</tr>
<tr>
<td>a0</td>
<td>Bohrs radius</td>
<td>5.2918×10^{-11} m</td>
</tr>
<tr>
<td>R0</td>
<td>solar radius</td>
<td>6.9599×10^8 m</td>
</tr>
<tr>
<td>k2</td>
<td>IAU grav. const(^2)</td>
<td>0.000295912 AU^3 d^{-2} S0^{-1}</td>
</tr>
</tbody>
</table>
Appendix D

Appendix: CASA Region File Format

The CASA region file format provides a flexible, easily edited set of region definitions which are accepted across CASA tasks. Region files may be written by hand or using the CASA viewer.

Alert: Whereas the region format is supported by all the data processing tasks, the viewer implementation is still limited to rectangles, ellipses, and some markers.

For a file to be recognized as a valid CASA region text file, the first line must contain the string:

```
#CRTF
```

"CRTF" stands for "CASA Region Text Format". One may also include an optional version number at the end of the string, so it reads #CRTFv0; this indicates the version of the format definition.

Region files have two different kinds of definitions, "regions" and "annotations", each of which is one line long. To indicate an annotation, a line must begin with "ann". Lines that begin with the comment character (#) are not considered for processing or display.

The second line of a file may define global parameters that are to be used for all regions and annotations in that file, in which case the line starts with "global". The parameters set here may also be overridden by keywords in a specific line, in which case the keywords pertain only to that one line.

- **Regions**: all regions are considered by tasks. They will be displayed by visualization tasks as well as used to create masks, etc., as appropriate.

- **Annotations**: these are used by display tasks, and are for visual reference only.

D.1 Region definitions

All regions lines will follow this general arrangement:
The possible parameter/value pairs are described in more detail below. Note that most parameters beyond the shape and its coordinates can be defined globally.

Possible units for coordinates are:

- *sexagesimal*, e.g. 18h12m24s for right ascension or -03.47.27.1 for declination
- *decimal degrees*, e.g. 140.0342deg for both RA and Dec
- *radians*, e.g. 2.37666rad for both RA and Dec
- *pixels*, e.g. 204pix

Possible units of length are:

- *degrees*, e.g. 23deg
- *arcminutes*, e.g. 23arcmin
- *arcseconds*, e.g. 23arcsec
- *radians*, e.g. 0.00035rad
- *pixels*, e.g. 23pix

Units must always be included when defining a region.

### D.2 Allowed shapes

- **Rectangular box**: the two coordinates are two opposite corners:

  box[[x1, y1], [x2, y2]]

- **Center box**: [x, y] define the center point of the box and [x_width, y_width] the width of the sides:

  centerbox[[x, y], [x_width, y_width]]

- **Rotated box**: [x, y] define the center point of the box; [x_width, y_width] the width of the sides; rotang the rotation angle:

  rotbox[[x, y], [x_width, y_width], rotang]
• **Polygon**: there could be many \([x, y]\) corners; note that the last point will connect with the first point to close the polygon:

\[
\text{poly}[[x_1, y_1], [x_2, y_2], [x_3, y_3], \ldots]
\]

• **Circle**: center of the circle \([x, y]\), \(r\) is the radius:

\[
\text{circle}[[x, y], r]
\]

• **Annulus**: center of the circle is \([x, y]\), \([r_1, r_2]\) are inner and outer radii:

\[
\text{annulus}[[x, y], [r_1, r_2]]
\]

• **Ellipse**: center of the ellipse is \([x, y]\); semi-major and semi-minor axes are \([b_{maj}, b_{min}]\); position angle of the major axis is \(p_a\):

\[
\text{ellipse}[[x, y], [b_{maj}, b_{min}], p_a]
\]

### D.3 Annotation definitions

In addition to the definitions for regions [above], the following are always treated as annotations:

• **Line**: coordinates define the end points of the line:

\[
\text{line}[[x_1, y_1], [x_2, y_2]]
\]

• **Vector**: coordinates define end points; second coordinate pair is location of tip of arrow:

\[
\text{vector}[[x_1, y_1], [x_2, y_2]]
\]

• **Text**: coordinates define leftmost point of text string:

\[
\text{text}[[x, y], 'my text']
\]

• **Symbol**: coordinates define location of symbol (see Sec.|D.7.1| for a list of allowed symbols):

\[
\text{symbol}[[x, y], \{\text{symbol}\}]
\]
D.4 Global definitions

Definitions to be used throughout the region file are placed on a line beginning with ‘global’, usually at the top of the file. These definitions may also be used on any individual region or annotation line; in this case, the value defined on that line will override the predefined global (but only for that line). If a ‘global’ line occurs later in the file, subsequent lines will obey those definitions.

- **Coordinate reference frame:**
  - Possible values: J2000, JMEAN, JTRUE, APP, B1950, B1950_VLA, BMEAN, BTRUE, GALACTIC, HADEC, AZEL, AZELSW, AZELNE, AZELGEO, AZELSWGEO, AZELNEGEO, JNAT, ECLIPTIC, MECLIPTIC, TECLIPTIC, SUPERGAL, ITRF, TOPO, ICRS
  - Default: image value

  \[
  \text{coord} = \text{J2000}
  \]

- **Frequency/velocity axis:**
  - Possible values: REST, LSRK, LSRD, BARY, GEO, TOPO, GALACTO, LGROUP, CMB
  - Default: image value

  frame=TOPO

- **Frequency/velocity range:**
  - Possible units: GHz, MHz, kHz, km/s, Hz, channel, chan (=channel)
  - Default: image range

  range=\([\text{min}, \text{max}]\)

- **Correlation axis:**
  - Possible values: I, Q, U, V, RR, RL, LL, XX, XY, YX, YY, RX, RY, LX, LY, XR, XL, YR, YL, PP, PQ, QP, QQ, RCircular, LCircular, Linear, Ptotal, Plinear, PFtotal, PFlinear, Pangle
  - Default: all planes present in image

  corr=[X, Y]

- **Velocity calculation:**
  - Possible values: RADIO, OPTICAL, Z, BETA, GAMMA
- Default: image value

veltype=RADIO

- **Rest frequency:**

- Default: image value

restfreq=1.42GHz

- **Line characteristics:**

- Possible values: any line style recognized by matplotlib: ‘-’=solid, ‘--’=dashed, ‘:’=dotted
- Default: linewidth=1, linestyle=’-’

 linewidth=1
 linestyle=’-’

- **Symbol characteristics:**

- Symbol syze and thickness:

 symsize = 1
 symthick = 1

- **Region, symbol, and text color:**

- Possible values: any color recognized by matplotlib, including hex values
- Default: color=green

 color=red

- **Text font characteristics:**

- Possible values: see Sect. D.7.2
- ’usetex’ is a boolean parameter that determines whether or not the text line should be interpreted as LaTeX, and would require working LaTeX, dvipng, and Ghostscript installations (equivalent to the text.usetex parameter in matplotlib).

 font=Helvetica
 fontsize=10pt
 fontstyle=bold
 usetex=True/False
• **Label position:**
  
  – Possible values: 'left', 'right', 'top', 'bottom'
  – Default: 'top'
    
    \[
    \text{labelpos='right'}
    \]

• **Label color:**
  
  – Default: color of associated region.
  – Allowed values: same as values for region colors.
    
    \[
    \text{labelcolor='green'}
    \]

• **Label offset:**
  
  – Default: [0,0].
  – Allowed values: any positive or negative number, in units of pixels.
    
    \[
    \text{labeloff=[1, 1]}
    \]

### D.5 Allowed additional parameters

These must be defined per region line:

• **Labels:** text label for a region; should be placed so text does not overlap with region boundary
  
  \[
  \text{label='string'}
  \]

• **"OR/NOT" operators:** A "+" at the beginning of a line will flag it with a boolean "OR" (default), and a "-" will flag it with a boolean "NOT". Overlapping regions will be treated according to their sequence in the file; i.e., (((entireImage OR line1) OR line2) NOT line3) OR line4). This allows some flexibility in building "non-standard" regions. Note that a task (e.g., clean) will still consider all lines: if one wishes to remove a region from consideration, it should be commented out ("#`).
  
  • Default: OR (+)

### D.6 Examples

A file with both global definitions and per-line definitions:

```
#CRTFv0
global coord=B1950_VLA, frame=BARY, corr=[I, Q], color=blue
```
# A simple circle region:
circle[[18h12m24s, -23d11m00s], 2.3arcsec]

# A box region, this one only for annotation:
ann box[[140.0342deg, -12.34243deg], [140.0360deg, -12.34320deg]]

# A rotated box region, for a particular range of velocities:
rotbox[[12h01m34.1s, 12d23m33s], [3arcmin, 1arcmin], 12deg], range=[-1240km/s, 1240km/s]

# An annular region, overriding some of the global defaults:
annulus[[17h51m03.2s, -45d17m50s], [0.10deg, 4.12deg]], corr=[I,Q,U,V], color=red, label='My label here'

# Cuts an ellipse out of the previous regions, but only for Q and a particular frequency range:
-ellipse[[17:51:03.2, -45.17.50], [0.25deg, 1.34deg], 45rad], range=[1.420GHz, 1.421GHz], corr=[Q], color=green, label='Removed this'

# A diamond marker, in J2000 coordinates:
symbol[[32.1423deg, 12.1412deg], D], linewidth=2, coord=J2000, symsize=2

D.7 Fonts and Symbols

D.7.1 Allowed symbols

', point marker
', pixel marker
'o' circle marker
'v' triangle_down marker
'^' triangle_up marker
'<' triangle_left marker
'>' triangle_right marker
'1' tri_down marker
'2' tri_up marker
'3' tri_left marker
'4' tri_right marker
's' square marker
'p' pentagon marker
'*' star marker
'h' hexagon1 marker
'H' hexagon2 marker
'+' plus marker
'x' x marker
'D' diamond marker
d' thin_diamond marker
'l' vline marker
D.7.2 Allowed fonts

D.7.2.1 Allowed fonts for Linux


D.7.2.2 Allowed fonts for MacOS X

APPENDIX D. APPENDIX: CASA REGION FILE FORMAT

Appendix E

The Measurement Equation and Calibration

The visibilities measured by an interferometer must be calibrated before formation of an image. This is because the wavefronts received and processed by the observational hardware have been corrupted by a variety of effects. These include (but are not exclusive to): the effects of transmission through the atmosphere, the imperfect details amplified electronic (digital) signal and transmission through the signal processing system, and the effects of formation of the cross-power spectra by a correlator. Calibration is the process of reversing these effects to arrive at corrected visibilities which resemble as closely as possible the visibilities that would have been measured in vacuum by a perfect system. The subject of this chapter is the determination of these effects by using the visibility data itself.

E.1 The HBS Measurement Equation

The relationship between the observed and ideal (desired) visibilities on the baseline between antennas i and j may be expressed by the Hamaker-Bregman-Sault Measurement Equation:

\[ \vec{V}_{ij} = J_{ij} \vec{V}_{ij}^{\text{IDEAL}} \]

where \( \vec{V}_{ij} \) represents the observed visibility, \( \vec{V}_{ij}^{\text{IDEAL}} \) represents the corresponding ideal visibilities, and \( J_{ij} \) represents the accumulation of all corruptions affecting baseline \( ij \). The visibilities are indicated as vectors spanning the four correlation combinations which can be formed from dual-polarization signals. These four correlations are related directly to the Stokes parameters which fully describe the radiation. The \( J_{ij} \) term is therefore a 4×4 matrix.

Most of the effects contained in \( J_{ij} \) (indeed, the most important of them) are antenna-based, i.e., they arise from measurable physical properties of (or above) individual antenna elements in a synthesis array. Thus, adequate calibration of an array of \( N_{\text{ant}} \) antennas forming \( N_{\text{ant}}(N_{\text{ant}} - 1)/2 \) baseline visibilities is usually achieved through the determination of only \( N_{\text{ant}} \) factors, such that

\( J_{ij} = J_i \otimes J_j^* \). For the rest of this chapter, we will usually assume that \( J_{ij} \) is factorable in this way, unless otherwise noted.

As implied above, \( J_{ij} \) may also be factored into the sequence of specific corrupting effects, each having their own particular (relative) importance and physical origin, which determines their unique algebra. Including the most commonly considered effects, the Measurement Equation can be written:

\[
\vec{V}_{ij} = M_{ij} B_{ij} G_{ij} D_{ij} E_{ij} P_{ij} T_{ij} \vec{V}_{ij}^{\text{IDEAL}}
\]

where:

- \( T_{ij} \) = Polarization-independent multiplicative effects introduced by the troposphere, such as opacity and path-length variation.
- \( P_{ij} \) = Parallactic angle, which describes the orientation of the polarization coordinates on the plane of the sky. This term varies according to the type of the antenna mount.
- \( E_{ij} \) = Effects introduced by properties of the optical components of the telescopes, such as the collecting area’s dependence on elevation.
- \( D_{ij} \) = Instrumental polarization response. "D-terms" describe the polarization leakage between feeds (e.g. how much the R-polarized feed picked up L-polarized emission, and vice versa).
- \( G_{ij} \) = Electronic gain response due to components in the signal path between the feed and the correlator. This complex gain term \( G_{ij} \) includes the scale factor for absolute flux density calibration, and may include phase and amplitude corrections due to changes in the atmosphere (in lieu of \( T_{ij} \)). These gains are polarization-dependent.
- \( B_{ij} \) = Bandpass (frequency-dependent) response, such as that introduced by spectral filters in the electronic transmission system
- \( M_{ij} \) = Baseline-based correlator (non-closing) errors. By definition, these are not factorable into antenna-based parts.

Note that the terms are listed in the order in which they affect the incoming wavefront (\( G \) and \( B \) represent an arbitrary sequence of such terms depending upon the details of the particular electronic system). Note that \( M \) differs from all of the rest in that it is not antenna-based, and thus not factorable into terms for each antenna.

As written above, the measurement equation is very general; not all observations will require treatment of all effects, depending upon the desired dynamic range. E.g., bandpass need only be considered for continuum observations if observed in a channelized mode and very high dynamic range is desired. Similarly, instrumental polarization calibration can usually be omitted when observing (only) total intensity using circular feeds. Ultimately, however, each of these effects occurs at some level, and a complete treatment will yield the most accurate calibration. Modern high-sensitivity instruments such as ALMA and JVLA will likely require a more general calibration.
APPENDIX E. APPENDIX: THE MEASUREMENT EQUATION AND CALIBRATION

577
treatment for similar observations with older arrays in order to reach the advertised dynamic ranges on strong sources.

In practice, it is usually far too difficult to adequately measure most calibration effects absolutely (as if in the laboratory) for use in calibration. The effects are usually far too changeable. Instead, the calibration is achieved by making observations of calibrator sources on the appropriate timescales for the relevant effects, and solving the measurement equation for them using the fact that we have \( N_{\text{ant}}(N_{\text{ant}} - 1)/2 \) measurements and only \( N_{\text{ant}} \) factors to determine (except for \( M \) which is only sparingly used). (Note: By partitioning the calibration factors into a series of consecutive effects, it might appear that the number of free parameters is some multiple of \( N_{\text{ant}} \), but the relative algebra and timescales of the different effects, as well as the the multiplicity of observed polarizations and channels compensate, and it can be shown that the problem remains well-determined until, perhaps, the effects are direction-dependent within the field of view. Limited solvers for such effects are under study; the calibrator tool currently only handles effects which may be assumed constant within the field of view. Corrections for the primary beam are handled in the imager tool.) Once determined, these terms are used to correct the visibilities measured for the scientific target. This procedure is known as cross-calibration (when only phase is considered, it is called phase-referencing).

The best calibrators are point sources at the phase center (constant visibility amplitude, zero phase), with sufficient flux density to determine the calibration factors with adequate SNR on the relevant timescale. The primary gain calibrator must be sufficiently close to the target on the sky so that its observations sample the same atmospheric effects. A bandpass calibrator usually must be sufficiently strong (or observed with sufficient duration) to provide adequate per-channel sensitivity for a useful calibration. In practice, several calibrators are usually observed, each with properties suitable for one or more of the required calibrations.

Synthesis calibration is inherently a bootstrapping process. First, the dominant calibration term is determined, and then, using this result, more subtle effects are solved for, until the full set of required calibration terms is available for application to the target field. The solutions for each successive term are relative to the previous terms. Occasionally, when the several calibration terms are not sufficiently orthogonal, it is useful to re-solve for earlier types using the results for later types, in effect, reducing the effect of the later terms on the solution for earlier ones, and thus better isolating them. This idea is a generalization of the traditional concept of self-calibration, where initial imaging of the target source supplies the visibility model for a re-solve of the gain calibration (\( G \) or \( T \)). Iteration tends toward convergence to a statistically optimal image. In general, the quality of each calibration and of the source model are mutually dependent. In principle, as long as the solution for any calibration component (or the source model itself) is likely to improve substantially through the use of new information (provided by other improved solutions), it is worthwhile to continue this process.

In practice, these concepts motivate certain patterns of calibration for different types of observation, and the calibrator tool in CASA is designed to accommodate these patterns in a general and flexible manner. For a spectral line total intensity observation, the pattern is usually:

1. Solve for \( G \) on the bandpass calibrator
2. Solve for \( B \) on the bandpass calibrator, using \( G \)
3. Solve for $G$ on the primary gain (near-target) and flux density calibrators, using $B$ solutions just obtained

4. Scale $G$ solutions for the primary gain calibrator according to the flux density calibrator solutions

5. Apply $G$ and $B$ solutions to the target data

6. Image the calibrated target data

If opacity and gain curve information are relevant and available, these types are incorporated in each of the steps (in future, an actual solve for opacity from appropriate data may be folded into this process):

1. Solve for $G$ on the bandpass calibrator, using $T$ (opacity) and $E$ (gain curve) solutions already derived.

2. Solve for $B$ on the bandpass calibrator, using $G$, $T$ (opacity), and $E$ (gain curve) solutions.

3. Solve for $G$ on primary gain (near-target) and flux density calibrators, using $B$, $T$ (opacity), and $E$ (gain curve) solutions.

4. Scale $G$ solutions for the primary gain calibrator according to the flux density calibrator solutions

5. Apply $T$ (opacity), $E$ (gain curve), $G$, and $B$ solutions to the target data

6. Image the calibrated target data

For continuum polarimetry, the typical pattern is:

1. Solve for $G$ on the polarization calibrator, using (analytical) $P$ solutions.


3. Solve for $G$ on primary gain and flux density calibrators, using $P$ and $D$ solutions.

4. Scale $G$ solutions for the primary gain calibrator according to the flux density calibrator solutions.

5. Apply $P$, $D$, and $G$ solutions to target data.

6. Image the calibrated target data.

For a spectro-polarimetry observation, these two examples would be folded together.

In all cases the calibrator model must be adequate at each solve step. At high dynamic range and/or high resolution, many calibrators which are nominally assumed to be point sources become slightly resolved. If this has biased the calibration solutions, the offending calibrator may be imaged at any point in the process and the resulting model used to improve the calibration. Finally, if sufficiently strong, the target may be self-calibrated as well.
E.2 General Calibrater Mechanics

The calibrater tasks/tool are designed to solve and apply solutions for all of the solution types listed above (and more are in the works). This leads to a single basic sequence of execution for all solves, regardless of type:

1. Set the calibrator model visibilities
2. Select the visibility data which will be used to solve for a calibration type
3. Arrange to apply any already-known calibration types (the first time through, none may yet be available)
4. Arrange to solve for a specific calibration type, including specification of the solution timescale and other specifics
5. Execute the solve process
6. Repeat 1-4 for all required types, using each result, as it becomes available, in step 2, and perhaps repeating for some types to improve the solutions

By itself, this sequence doesn’t guarantee success; the data provided for the solve must have sufficient SNR on the appropriate timescale, and must provide sufficient leverage for the solution (e.g., D solutions require data taken over a sufficient range of parallactic angle in order to separate the source polarization contribution from the instrumental polarization).
Appendix F

Annotated Example Scripts

The annotated scripts are available on the CASA homepage:

http://casa.nrao.edu/casa_scripts.shtml

These will be removed shortly, however, as the casaguides contain newer version of data reduction tutorials:

http://casaguides.nrao.edu
Appendix G

CASA Dictionaries

BETA ALERT: These tend to become out of date as we add new tasks or change names.

G.1 AIPS – CASA dictionary

In Table G.1 we provide a comparison of CASA and AIPS commands. The data reduction recipes and break-down of jobs in individual tasks, however, is not the same in both packages. Nevertheless, the table may give AIPS users a good start if they search for functionality in CASA.

G.2 MIRIAD – CASA dictionary

Table G.2 provides a list of common Miriad tasks, and their equivalent CASA tool or tool function names. The two packages differ in both their architecture and calibration and imaging models, and there is often not a direct correspondence. However, this index does provide a scientific user of CASA who is familiar with MIRIAD, with a simple translation table to map their existing data reduction knowledge to the new package.

G.3 CLIC – CASA dictionary

Table G.3 provides a list of common CLIC tasks, and their equivalent CASA tool or tool function names. The two packages are very similar since the CASA software to reduce IRAM data is based on the CLIC reduction procedures.
<table>
<thead>
<tr>
<th><strong>AIPS Task</strong></th>
<th><strong>CASA task/tool</strong></th>
<th><strong>Description</strong></th>
</tr>
</thead>
<tbody>
<tr>
<td>APROPOS</td>
<td>taskhelp</td>
<td>List tasks with a short description of their purposes</td>
</tr>
<tr>
<td>BLCAL</td>
<td>blcal</td>
<td>Calculate a baseline-based gain calibration solution</td>
</tr>
<tr>
<td>BLCHN</td>
<td>blcal</td>
<td>Calculate a baseline-based bandpass calibration solution</td>
</tr>
<tr>
<td>BPASS</td>
<td>bandpass</td>
<td>Calibrate bandpasses</td>
</tr>
<tr>
<td>CALIB</td>
<td>gaincal</td>
<td>Calibrate gains (amplitudes and phases)</td>
</tr>
<tr>
<td>CLCAL</td>
<td>applycal</td>
<td>Apply calibration to data</td>
</tr>
<tr>
<td>COMB</td>
<td>immath</td>
<td>Combine images</td>
</tr>
<tr>
<td>CPASS</td>
<td>bandpass</td>
<td>Calibrate bandpasses by polynomial fitting</td>
</tr>
<tr>
<td>DBCON</td>
<td>concat</td>
<td>Concatenate u-v datasets</td>
</tr>
<tr>
<td>DEFAULT</td>
<td>default</td>
<td>Load a task with default parameters</td>
</tr>
<tr>
<td>FILLM</td>
<td>importvla</td>
<td>Import old-format VLA data</td>
</tr>
<tr>
<td>FITLD</td>
<td>importuvtfits</td>
<td>Import a u-v dataset which is in FITS format</td>
</tr>
<tr>
<td>FITLDD</td>
<td>importfits</td>
<td>Import an image which is in FITS format</td>
</tr>
<tr>
<td>FITTP</td>
<td>exportuvtfits</td>
<td>Write a u-v dataset to FITS format</td>
</tr>
<tr>
<td>FITTP</td>
<td>exportfits</td>
<td>Write an image to FITS format</td>
</tr>
<tr>
<td>FRING</td>
<td>—</td>
<td>Calibrate group delays and phase rates.</td>
</tr>
<tr>
<td>GETJY</td>
<td>fluxscale</td>
<td>Determine flux densities for other cals</td>
</tr>
<tr>
<td>GO</td>
<td>go</td>
<td>Run a task</td>
</tr>
<tr>
<td>HELP</td>
<td>help</td>
<td>Display the help page for a task</td>
</tr>
<tr>
<td>IMAGR</td>
<td>clean</td>
<td>Image and deconvolve</td>
</tr>
<tr>
<td>IMFIT</td>
<td>imfit</td>
<td>Fit gaussian components to an image</td>
</tr>
<tr>
<td>IMHEAD</td>
<td>vishead</td>
<td>View header for u-v data</td>
</tr>
<tr>
<td>IMHEAD</td>
<td>imhead</td>
<td>View header for an image</td>
</tr>
<tr>
<td>IMLIN</td>
<td>imcontsub</td>
<td>Subtract continuum in image plane</td>
</tr>
<tr>
<td>IMLOD</td>
<td>importfits</td>
<td>Import a FITS image</td>
</tr>
<tr>
<td>IMSTAT</td>
<td>imstat</td>
<td>Measure statistics on an image</td>
</tr>
<tr>
<td>INP</td>
<td>inp</td>
<td>View task parameters</td>
</tr>
<tr>
<td>JMFIT</td>
<td>imfit</td>
<td>Fit gaussian components to an image</td>
</tr>
<tr>
<td>LISTR</td>
<td>listobs</td>
<td>Print basic data</td>
</tr>
<tr>
<td>MCAT</td>
<td>ls</td>
<td>List image data files</td>
</tr>
<tr>
<td>MOMNT</td>
<td>immoments</td>
<td>Compute moments from an image</td>
</tr>
<tr>
<td>OHGEO</td>
<td>imregrid</td>
<td>Regrids an image onto another image’s geometry</td>
</tr>
<tr>
<td>PBCOR</td>
<td>immath</td>
<td>Correct an image for the primary beam</td>
</tr>
<tr>
<td>PCAL</td>
<td>polcal</td>
<td>Calibrate polarization</td>
</tr>
<tr>
<td>POSSM</td>
<td>plotcal</td>
<td>Plot bandpass calibration tables</td>
</tr>
<tr>
<td>POSSM</td>
<td>plotms</td>
<td>Plot spectra</td>
</tr>
<tr>
<td>PRTAN</td>
<td>listobs</td>
<td>Print antenna locations</td>
</tr>
<tr>
<td>PRTAN</td>
<td>plotants</td>
<td>Plot antenna locations</td>
</tr>
<tr>
<td>QUACK</td>
<td>flagdata</td>
<td>Remove first integrations from scans</td>
</tr>
<tr>
<td>RENAME</td>
<td>mv</td>
<td>Rename an image or dataset</td>
</tr>
<tr>
<td>SETJY</td>
<td>setjy</td>
<td>Set flux densities for flux cals</td>
</tr>
<tr>
<td>SMOOTH</td>
<td>imsmooth</td>
<td>Smooth an image</td>
</tr>
<tr>
<td>SNPLT</td>
<td>plotcal</td>
<td>Plot gain calibration tables</td>
</tr>
<tr>
<td>SPFLG</td>
<td>viewer</td>
<td>Flag raster image of time v. channel</td>
</tr>
<tr>
<td>SPLIT</td>
<td>split</td>
<td>Write out u-v files for individual sources</td>
</tr>
<tr>
<td>TASK</td>
<td>inp</td>
<td>Load a task with current parameters</td>
</tr>
<tr>
<td>TGET</td>
<td>tget</td>
<td>Load a task with parameters last used for that task</td>
</tr>
<tr>
<td>TVALL</td>
<td>viewer</td>
<td>Display image</td>
</tr>
<tr>
<td>MIRIAD Task</td>
<td>Description</td>
<td>CASA task/tool</td>
</tr>
<tr>
<td>-------------</td>
<td>--------------------------------------------------</td>
<td>---------------------------------</td>
</tr>
<tr>
<td>blflag</td>
<td>Interactive baseline based editor/flagger</td>
<td>mp raster displays</td>
</tr>
<tr>
<td>cgcurc</td>
<td>Interactive image analysis</td>
<td>viewer</td>
</tr>
<tr>
<td>cgdisp</td>
<td>Image display, overlays</td>
<td>viewer</td>
</tr>
<tr>
<td>clean</td>
<td>Clean an image</td>
<td>clean</td>
</tr>
<tr>
<td>fits</td>
<td>FITS image filler</td>
<td>importfits, exportfits, importuvfits, exportuvfits</td>
</tr>
<tr>
<td>gpboot</td>
<td>Set flux density scale</td>
<td>fluxscale</td>
</tr>
<tr>
<td>gpchal</td>
<td>Polarization leakage and gain calibration</td>
<td>gaincal</td>
</tr>
<tr>
<td>gpcopy</td>
<td>copy calibration tables</td>
<td>not needed</td>
</tr>
<tr>
<td>gpplt</td>
<td>Plot calibration solutions</td>
<td>plotcal</td>
</tr>
<tr>
<td>imcomb</td>
<td>Image combination</td>
<td>immaths</td>
</tr>
<tr>
<td>imfit</td>
<td>Image-plane component fitter</td>
<td>imfit</td>
</tr>
<tr>
<td>impol</td>
<td>Create polarization images</td>
<td>clean</td>
</tr>
<tr>
<td>imstat</td>
<td>Image statistics</td>
<td>immath</td>
</tr>
<tr>
<td>imsub</td>
<td>Extract sub-image</td>
<td>bandpass</td>
</tr>
<tr>
<td>invert</td>
<td>Synthesis imaging</td>
<td>clean</td>
</tr>
<tr>
<td>linmos</td>
<td>linear mosaic combination of images</td>
<td>clean</td>
</tr>
<tr>
<td>maths</td>
<td>Calculations involving images</td>
<td>clean</td>
</tr>
<tr>
<td>mfcal</td>
<td>Bandpass and gain calibration</td>
<td>clean</td>
</tr>
<tr>
<td>prthd</td>
<td>Print header of image or uvdata</td>
<td>clean</td>
</tr>
<tr>
<td>restor</td>
<td>Restore a clean component model</td>
<td>clean</td>
</tr>
<tr>
<td>selfcal</td>
<td>selfcalibration of visibility data</td>
<td>clean, gaincal, etc.</td>
</tr>
<tr>
<td>tvclip</td>
<td>automated flagging based on clip levels</td>
<td>flagdata, msview</td>
</tr>
<tr>
<td>tvdisp</td>
<td>Load image to TV display</td>
<td>msview</td>
</tr>
<tr>
<td>tvflag</td>
<td>Interactive TB data editing</td>
<td>msview</td>
</tr>
<tr>
<td>uvaver</td>
<td>Average/select data, apply calibration</td>
<td>applycal, split</td>
</tr>
<tr>
<td>uvfit</td>
<td>uv-plane component fitter</td>
<td>uvmodelfit</td>
</tr>
<tr>
<td>uvflag</td>
<td>Command-based flagging</td>
<td>flagdata</td>
</tr>
<tr>
<td>uvgen</td>
<td>Simulator</td>
<td>simobserve, simanalyze</td>
</tr>
<tr>
<td>uvlist</td>
<td>List uv-data</td>
<td>listvis</td>
</tr>
<tr>
<td>uvmodel</td>
<td>Source model computation</td>
<td>ft</td>
</tr>
<tr>
<td>uvplt</td>
<td>uv-data plotting</td>
<td>plotms</td>
</tr>
<tr>
<td>uvsplit</td>
<td>split uv file in sources and spectral windows</td>
<td>split</td>
</tr>
</tbody>
</table>
Table G.3: CLIC–CASA dictionary

<table>
<thead>
<tr>
<th>CLIC Function</th>
<th>Description</th>
<th>CASA task/tool</th>
</tr>
</thead>
<tbody>
<tr>
<td>load</td>
<td>Load data</td>
<td>importfits, importasdm, importuvfits</td>
</tr>
<tr>
<td>print</td>
<td>Print text summary of data</td>
<td>listobs</td>
</tr>
<tr>
<td>flag</td>
<td>Flag data</td>
<td>plotms, flagdata, viewer</td>
</tr>
<tr>
<td>phcor</td>
<td>Atmospheric phase correction</td>
<td>gaincal</td>
</tr>
<tr>
<td>rf</td>
<td>Radio frequency bandpass</td>
<td>gaincal</td>
</tr>
<tr>
<td>phase</td>
<td>Phase calibration</td>
<td>gaincal</td>
</tr>
<tr>
<td>flux</td>
<td>Absolute flux calibration</td>
<td>setjy, fluxscale</td>
</tr>
<tr>
<td>ampl</td>
<td>Amplitude calibration</td>
<td>gaincal</td>
</tr>
<tr>
<td>table</td>
<td>Split out calibrated data (uv table)</td>
<td>split</td>
</tr>
</tbody>
</table>
Appendix H

Writing Tasks

**ALERT:** This prescription for writing and incorporating tasks in CASA is for the power-user. This procedure is also likely to change in future releases.

It is possible to write your own task and have it appear in casapy. For example, if you want to create a task named “yourtask”, then must create two files, `yourtask.xml` and a `task_yourtask.py`. The `.xml` file is used to describe the interface to the task and the `task_yourtask.py` does the actual work. The argument names must be the same in both the `yourtask.xml` and `task_yourtask.py` file. The `yourtask.xml` file is used to generate all the interface files so `yourtask` will appear in the casapy system. It is easiest to start from one of the existing tasks when constructing these. You would make the name of the function in the `yourtask.py` be “yourtask” in this example.

We have provided the `buildmytasks` command in order to assemble your Python and XML into a loadable Python file. Thus, the steps you need to execute (again for an example task named “yourtask”):

- Create python code for task as `task_yourtask.py`
- Create xml for task as `yourtask.xml`
- Execute buildmytasks from the casapy prompt: `!buildmytasks`
- Initialize your new task inside casapy: `execfile 'mytasks.py'`

After this, you should see the help and inputs inside casapy, e.g. `inp yourtask` should work. Note that for the final step you invoke the file called `mytasks.py`, regardless of what you named the actual task. You now have a shiny new task `yourtask` that you can run and use in the same way as all other CASA tasks.

Note that if multiple custom tasks are stored in the same directory, they will all be built by `!buildmytasks` and will all be initialized by executing `mytasks.py`. To build and initialize only a single task, instead use `!buildmytasks taskname`; you are then free to rename `mytasks.py` (e.g. `load_taskname.py`) and repeat this procedure for your other tasks. Our recommendation, for those of you who are managing multiple custom tasks, is to have each task live in its own directory. The
mytasks.py file need not be in the current working directory to initialize your task, since you can provide the full path upon initialization (e.g. `execfile '/full_path_to_my_task/mytasks.py').

H.1 The XML file

The key to getting your task into casapy is constructing a task interface description XML file. Some XML basics, an xml element begins with `<element>` and ends with `</element>`. If an XML element contains no other XML element you may specify it via `<element/>`. An XML element may have zero or more attributes which are specified by attribute="attribute value". You must put the attribute value in quotes, i.e. `<element myattribute="attribute value">`.

All task xml files must start with this header information.

```xml
<?xml version="1.0" encoding="UTF-8"?>
<?xml-stylesheet type="text/xsl" ?>
<casaxml xmlns="http://casa.nrao.edu/schema/psetTypes.html"
    xmlns:xsi="http://www.w3.org/2001/XMLSchema-instance"
    xsi:schemaLocation="http://casa.nrao.edu/schema/casa.xsd
    file:///opt/casa/code/xmlcasa/xml/casa.xsd">
```

and the file must have the end tag

```xml
</casaxml>
```

Inside a `<task>` tags you will need to specify the following elements.

```xml
<task>
  <Attributes>
    <type required, allowed value is "function">
    <name required>
  </Attributes>
  <Subelements>
    <shortdescription required>
    <description required>
    <input optional>
    <output optional>
    <returns optional>
    <constraints optional>
  </Subelements>
  <shortdescription> - required by <task>; A short one-line description describing your task
  <Attributes>
```
None
Subelements
None
<description> - required] by <task>, Also used by <param>a; A longer description describing your task with multiple lines

Attributes
None
Subelements
None
<input> - optional element used by <task>; An input block specifies which parameters are used for input

Attributes
None
Subelements
<param> , optional
<output> - optional An output element that contains a list of parameters that are "returned" by the task.

Attributes
None
Subelements
<param> , optional
<returns> - optional Value returned by the task

Attributes
type optional; as specified in <param>
Subelements
<description> , optional
<constraints> - optional A constraints element that lets you constrain params based on the values of other params.

Attributes
None
Subelements
<when> , required.

<param> - optional The input and output elements consist of param elements.
Attributes

- **type**, required; allowed values are record, variant, string, int, double, bool, intArray, doubleArray, boolArray, stringArray
- **name**, required;
- **subparam**, optional; allowed values True, False, Yes or No.
- **kind**, optional;
- **mustexist**, optional; allowed values True, False, Yes or No.

All param elements require name and type attributes.

Subelements

- `<description>`, required;
- `<value>`, optional;
- `<allowed>`, optional;

`<value>` - optional Value returned by the task

Attributes

- **type**, required; as specified in `<param>` attributes.

Subelements

- `<value>`, optional

`<allowed>` - optional; Block of allowed values

Attributes

- **enum**, required; maybe enum or range. If specified as enum only specific values are allowed If specified as range then the value tags may have min and max attributes.

Subelements

- `<value>`, optional

`<when>` - optional When blocks allow value specific handling for parameters

Attributes

- **param**, required; Specifies special handling for a `<param>`

Subelements

- `<equals>`, optional
- `<notequals>`, optional

`<equals>` - optional Reset parameters if equal to the specified value

Attributes

- **value**, required; the value of the parameter

Subelements

- `<default>`, required
<notequals> - optional  Reset specified parameters if not equal to the specified value

  Attributes
  value , required; The value of the parameter

  Subelements
  <default> , optional

<default> - optional  Resets default values for specified parameters

  Attributes
  param , required; Name of the <param> to be reset.

  Subelements
  <value> , required, the revised value of the <param>.

<example> - optional  An example block, typically in python

  Attributes
  lang optional; specifies the language of the example, defaults to python.

  Subelements
  None

H.2  The task_yourtask.py file

You must write the python code that does the actual work. The task_* .py file function call sequence must be the same as specified in the XML file. We may relax the requirement that the function call sequence exactly match the sequence in the XML file in a future release.

The task_* .py file should contain the following preamble

  import os
  from taskinit import *

  plus any other global function imports you will need such as

  import time

followed by the task function def. See Sect. II.3.2 for an example.

H.3  Example: The clean task

Note that the following is for illustration only and does not reflect the current implementation of clean – a task that is always developing further on a quick pace.
H.3.1 File clean.xml

Clean.xml gives a fairly comprehensive example of how to construct the XML file.

```xml
<?xml version="1.0" encoding="UTF-8"?>
<?xml-stylesheet type="text/xsl" ?>
<casaxml xmlns="http://casa.nrao.edu/schema/psetTypes.html"
xmlns:xsi="http://www.w3.org/2001/XMLSchema-instance"
xsi:schemaLocation="http://casa.nrao.edu/schema/casa.xsd
file:///opt/casa/code/xmlcasa/xml/casa.xsd">

<!-- This is the param set for clean -->
<!-- This does the equivalent of -->
<!-- imgr:=imager('anyfile.ms'); -->
<!-- imgr.setdata(mode='channel',nchan=100,start=1,step=1,fieldid=1) -->
<!-- imgr.setimage(nx=512,ny=,cellx='1arcsec',celly='1arcsec',stokes='I',-->
<!-- mode='channel',start=35,step=1,nchan=40, -->
<!-- fieldid=[1]) -->
<!-- imgr.weight('natural'); -->
<!-- imgr.clean(algorithm='csclean',niter=500,model='field1') -->

<task type="function" name="clean">
    <shortdescription>Deconvolve an image with selected algorithm</shortdescription>
    <description>
    Form images from visibilities. Handles continuum and spectral line cubes.
    </description>
    <input>
        <param type="string" name="vis" kind="ms" mustexist="true">
            <description>name of input visibility file</description>
            <value></value>
        </param>
        <param type="string" name="imagename">
            <description>Pre-name of output images</description>
            <value></value>
        </param>
        <param type="string" name="field">
            <description>Field Name</description>
            <value></value>
        </param>
    </input>
</casaxml>
```
<param type="any" name="spw">
  <description>Spectral windows: channels: \'\' is all</description>
  <any type="variant"/>
  <value type="string"></value>
</param>

<param type="bool" name="selectdata">
  <description>Other data selection parameters</description>
  <value>False</value>
</param>

<param type="string" name="timerange" subparam="true">
  <description>Range of time to select from data</description>
  <value></value>
</param>

<param type="string" name="uvrange" subparam="true">
  <description>Select data within uvrange</description>
  <value></value>
</param>

<param type="string" name="antenna" subparam="true">
  <description>Select data based on antenna/baseline</description>
  <value></value>
</param>

<param type="string" name="scan" subparam="true">
  <description>Scan number range</description>
  <value></value>
</param>

<param type="string" name="mode">
  <description>Type of selection (mfs, channel, velocity, frequency)</description>
  <value>mfs</value>
  <allowed kind="enum">
    <value>mfs</value>
    <value>channel</value>
    <value>velocity</value>
    <value>frequency</value>
  </allowed>
</param>
<param type="int" name="niter">
    <description>Maximum number of iterations</description>
    <value>500</value>
</param>

<param type="double" name="gain">
    <description>Loop gain for cleaning</description>
    <value>0.1</value>
</param>

<param type="double" name="threshold" units="mJy">
    <description>Flux level to stop cleaning. Must include units</description>
    <value>0.0</value>
</param>

<!-- Getting rid of this
<param type="bool" name="csclean">
    <description>Use Cotton-Schwab style reconciliation with UV-data</description>
    <value>False</value>
</param>
-->

<param type="string" name="psfmode">
    <description>method of PSF calculation to use during minor cycles</description>
    <value>clark</value>
    <allowed kind="enum">
        <value>clark</value>
        <value>hogbom</value>
    </allowed>
</param>

<param type="string" name="imagermode">
    <description>Use csclean or mosaic. If ", use psfmode</description>
    <value></value>
    <allowed kind="enum">
        <value></value>
        <value>csclean</value>
        <value>mosaic</value>
    </allowed>
</param>

</param>

<param type="string" name="ftmachine" subparam="true"
<description>Gridding method for the image</description>
<value>mosaic</value>
<allowed kind="enum">
    <value>mosaic</value>
    <value>ft</value>
    <value>sd</value>
    <value>both</value>
</allowed>
</param>

<param type="bool" name="mosweight" subparam="true">
    <description>Individually weight the fields of the mosaic</description>
    <value>False</value>
</param>

<param type="string" name="scaletype" subparam="true">
    <description>Controls scaling of pixels in the image plane.
        default=\'SAULT\';
        example: scaletype=\'PBCOR\'
        Options: \'PBCOR\', \'SAULT\'</description>
    <value>SAULT</value>
    <allowed kind="enum">
        <value>SAULT</value>
        <value>PBCOR</value>
    </allowed>
</param>

<param type="intArray" name="multiscale">
    <description>set deconvolution scales (pixels),
        default: multiscale=[] (standard CLEAN)</description>
    <value type="vector">
        <value></value>
    </value>
</param>

<param type="int" name="negcomponent" subparam="true">
    <description>
        Stop cleaning if the largest scale finds this number of neg components
    </description>
    <value>0</value>
</param>

<param type="bool" name="interactive">
    <description>use interactive clean (with GUI viewer)</description>
    <value>False</value>
</param>
<param type="any" name="mask">
    <description>cleanbox(es), mask image(s), and/or region(s) used in cleaning</description>
    <any type="variant"/>
    <value type="stringArray"></value>
</param>

<param type="int" name="nchan" subparam="true">
    <description>Number of channels (planes) in output image</description>
    <value>1</value>
</param>

<param type="any" name="start" subparam="true">
    <description>First channel in input to use</description>
    <any type="variant"/>
    <value type="int">0</value>
</param>

<param type="any" name="width" subparam="true">
    <description>Number of input channels to average</description>
    <any type="variant"/>
    <value type="int">1</value>
</param>

<param type="intArray" name="imsize">
    <description>x and y image size in pixels, symmetric for single value</description>
    <value type="vector">
        <value>256</value><value>256</value>
    </value>
</param>

<param type="doubleArray" name="cell" units="arcsec">
    <description>x and y cell size. default unit arcsec</description>
    <value type="vector">1.0</value><value>1.0</value>
</param>

<param type="any" name="phasecenter">
    <description>Image phase center: position or field index</description>
    <any type="variant"/>
    <value type="string"></value>
</param>
<param type="string" name="restfreq">
   <description>rest frequency to assign to image (see help)</description>
   <value></value>
</param>

<param type="string" name="stokes">
   <description>Stokes params to image (eg I,IV, QU, IQUV)</description>
   <value>I</value>
   <allowed kind="enum">
      <value>I</value>
      <value>IV</value>
      <value>QU</value>
      <value>IQUV</value>
      <value>RR</value>
      <value>LL</value>
      <value>RRLL</value>
      <value>XX</value>
      <value>YY</value>
      <value>XXYY</value>
   </allowed>
</param>

<param type="string" name="weighting">
   <description>Weighting to apply to visibilities</description>
   <value>natural</value>
   <allowed kind="enum">
      <value>natural</value>
      <value>uniform</value>
      <value>briggs</value>
      <value>briggsabs</value>
      <value>radial</value>
      <value>superuniform</value>
   </allowed>
</param>

<param type="double" name="robust" subparam='true'>
   <description>Briggs robustness parameter</description>
   <value>0.0</value>
</param>
<param type="stringArray" name="outertaper" subparam="true">
  <description>uv-taper on outer baselines in uv-plane</description>
  <value type="vector">
    <value></value>
  </value>
</param>

<param type="stringArray" name="innertaper" subparam="true">
  <description>uv-taper in center of uv-plane</description>
  <value>1.0</value>
</param>

<param type="string" name="modelimage">
  <description>Name of model image(s) to initialize cleaning</description>
  <value></value>
</param>

<param type="stringArray" name="restoringbeam">
  <description>Output Gaussian restoring beam for CLEAN image</description>
  <value></value>
</param>

<param type="bool" name="pbcor">
  <description>Output primary beam-corrected image</description>
  <value>False</value>
</param>

<param type="double" name="minpb">
  <description>Minimum PB level to use</description>
  <value>0.1</value>
</param>

<param type="any" name="noise" subparam='true'>
  <description>noise parameter for briggs abs mode weighting</description>
  <any type="variant"/>
<value type="string">1.0Jy</value>
</param>

<param type="int" name="npixels" subparam='true'>
  <description>number of pixels for superuniform or briggs weighting
  </description>
  <value>0</value>
</param>

<param type="int" name="npercycle" subparam='true'>
  <description>Number of iterations before interactive prompt</description>
  <value>100</value>
</param>

<param type="double" name="cyclefactor" subparam='true'>
  <description>change depth in between of cscllean cycle</description>
  <value>1.5</value>
</param>

<param type="int" name="cyclespeedup" subparam='true'>
  <description>Cycle threshold doubles in this number of iteration</description>
  <value>-1</value>
</param>

<constraints>
  <when param="selectdata">
    <equals type="bool" value="False"/>
    <equals type="bool" value="True">
      <default param="timerange"><value type="string"></value>
    </default>
    <default param="uvrange"><value type="string"></value>
    </default>
    <default param="antenna"><value type="string"></value>
    </default>
    <default param="scan"><value type="string"></value>
    </default>
  </equals>
</when>

<when param="multiscale">
  <notequals type="vector" value="[]"/>
  <default param="negcomponent"><value>-1</value>
</default>
</when>

<notequals>
</when>
<when param="mode">
  <equals value="mfs"/>
  <equals value="channel">
    <default param="nchan">1</default>
    <default param="start">0</default>
    <description>first input channel to use</description>
  </default>
  <default param="width">1</default>
</equals>
<equals value="velocity">
  <default param="nchan">1</default>
  <default param="start">0.0 km/s</default>
  <description>Velocity of first image channel: e.g. '0.0 km/s'</description>
</default>
<default param="width">1 km/s</default>
<description>image channel width in velocity units: e.g. '-1.0 km/s'</description>
</equals>
<equals value="frequency">
  <default param="nchan">1</default>
  <default param="start">1.4 GHz</default>
  <description>Frequency of first image channel: e.g. '1.4 GHz'</description>
</default>
<default param="width">10 kHz</default>
<description>Image channel width in frequency units: e.g. '1.0 kHz'</description>
</equals>
</when>

<when param="weighting">
  <equals value="natural"/>
  <equals value="uniform"/>
  <equals value="briggs">
    <default param="robust">0.0</default>
    <default param="npixels">0</default>
    <description>number of pixels to determine uv-cell size
      0=&gt; field of view</description>
  </default>
</equals>
<equals value="briggsabs">
  <default param="robust"><value>0.0</value></default>
  <default param="noise"><value type="string">1.0Jy</value></default>
  <default param="npixels"><value>0</value>
    <description>number of pixels to determine uv-cell size
      0=&gt; field of view</description>
  </default>
</equals>

<equals value="superuniform">
  <default param="npixels"><value>0</value>
    <description>number of pixels to determine uv-cell size
      0=&gt; +/-3pixels</description>
  </default>
</equals>

<when param="uvtaper">
  <equals type="bool" value="False"/>
  <equals type="bool" value="True">
    <default param="outertaper"><value type="vector"></value></default>
    <default param="innertaper"><value type="vector"></value></default>
  </equals>
</when>

<when param="interactive">
  <equals type="bool" value="False"/>
  <equals type="bool" value="True">
    <default param="npercycle"><value>100</value></default>
  </equals>
</when>

<when param="imagermode">
  <equals value="/">
    <equals value="csclean">
      <default param="cyclefactor"><value>1.5</value></default>
      <default param="cyclespeedup"><value>-1</value></default>
    </equals>
    <equals value="mosaic">
      <default param="mosweight"><value>False</value></default>
      <default param="ftmachine"><value type="string">mosaic</value>
        <default param="scalestype"><value type="string">SAULT</value>
          <default param="cyclefactor"><value>1.5</value></default>
          <default param="cyclespeedup"><value>-1</value></default>
        </default>
    </equals>
  </equals>
</when>

<!--Get rid of that soon-->
<when param="mosaicmode">
  <equals type="bool" value="False"/>
  <equals type="bool" value="True">
    <default param="mosweight"><value>False</value></default>
    <default param="ftmachine"><value type="string">mosaic</value></default>
    <default param="scaletype"><value type="string">SAULT</value></default>
  </equals>
</when>

The main clean deconvolution task. It contains many functions

1) Make 'dirty' image and 'dirty' beam (psf)
2) Multi-frequency-continuum images or spectral channel imaging
3) Full Stokes imaging
4) Mosaicking of several pointings
5) Multi-scale cleaning
6) Interactive clean boxing
7) Initial starting model

vis -- Name of input visibility file
  default: none; example: vis='ngc5921.ms'
imagename -- Pre-name of output images:
  default: none; example: imagename='m2'
  output images are:
    m2.image; cleaned and restored image
    With or without primary beam correction
    m2.psf; point-spread function (dirty beam)
    m2.flux; relative sky sensitivity over field
    m2.model; image of clean components
    m2.residual; image of residuals
    m2.interactive.mask; image containing clean regions
field -- Select fields in mosaic. Use field id(s) or field name(s).
  ['go listobs' to obtain the list id’s or names]
  default: ''=all fields
  If field string is a non-negative integer, it is assumed to
  be a field index otherwise, it is assumed to be a
field name
field='0~2'; field ids 0,1,2
field='0,4,5~7'; field ids 0,4,5,6,7
field='3C286,3C295'; field named 3C286 and 3C295
field = '3,4C*'; field id 3, all names starting with 4C

spw -- Select spectral window/channels

NOTE: This selects the data passed as the INPUT to mode
default: ’’=all spectral windows and channels

spw='0~2,4'; spectral windows 0,1,2,4 (all channels)
spw='0:5~61'; spw 0, channels 5 to 61
spw='&lt;2'; spectral windows less than 2 (i.e. 0,1)
spw='0,10,3:3~45'; spw 0,10 all channels, spw 3,
    channels 3 to 45.
spw='0~2:2~6'; spw 0,1,2 with channels 2 through 6 in each.
spw='0:0~10,15~60'; spectral window 0 with channels
    0-10,15-60
spw='0:0~10,1:20~30,2:1;2;3'; spw 0, channels 0-10,
    spw 1, channels 20-30, and spw 2, channels, 1,2 and 3

selectdata -- Other data selection parameters

default: True

&gt;&gt; selectdata=True expandable parameters

See help par.selectdata for more on these

timerange -- Select data based on time range:
default = ’’ (all); examples,
timerange = 'YYYY/MM/DD/hh:mm:ss~YYYY/MM/DD/hh:mm:ss'
Note: if YYYY/MM/DD is missing date defaults to first
day in data set
timerange='09:14:0~09:54:0’ picks 40 min on first day
timerange= '25:00:00~27:30:00' picks 1 hr to 3 hr
    30min on NEXT day
timerange='09:44:00’ pick data within one integration
    of time
timerange='&gt;10:24:00’ data after this time

uvrange -- Select data within uvrange (default units meters)
default: ’’ (all); example:
    uvrange='0~1000klambda'; uvrange from 0-1000 kilo-lambda
    uvrange='&gt;4klambda';uvranges greater than 4 kilo lambda

antenna -- Select data based on antenna/baseline
default: ’’ (all)
If antenna string is a non-negative integer, it is
    assumed to be an antenna index, otherwise, it is
    considered an antenna name.
antenna='5&amp;6'; baseline between antenna index 5 and
    index 6.
antenna='VA05&amp;VA06'; baseline between VLA antenna 5
and 6.
antenna='5&6;7&8'; baselines 5-6 and 7-8
antenna='5'; all baselines with antenna index 5
antenna='05'; all baselines with antenna number 05
   (VLA old name)
antenna='5,6,9'; all baselines with antennas 5,6,9
index numbers

scan -- Scan number range.
default: '' (all)
example: scan='1~5'
   Check 'go listobs' to insure the scan numbers are in order.

mode -- Frequency Specification:
NOTE: See examples below:
default: 'mfs'
   mode = 'mfs' means produce one image from all
   specified data.
   mode = 'channel'; Use with nchan, start, width to specify
   output image cube. See examples below
   mode = 'velocity', means channels are specified in
   velocity.
   mode = 'frequency', means channels are specified in
   frequency.

>&gt;&gt;&gt; mode expandable parameters (for modes other than 'mfs')
Start, width are given in units of channels, frequency
or velocity as indicated by mode, but only channel
is complete.
nchan -- Number of channels (planes) in output image
default: 1; example: nchan=3
start -- Start input channel (relative-0)
default=0; example: start=5
width -- Output channel width in units of the input
   channel width (&gt;1 indicates channel averaging)
default=1; example: width=4

examples:
spw = '0,1'; mode = 'mfs'
   will produce one image made from all channels in spw
   0 and 1
spw='0:5~28~2'; mode = 'mfs'
   will produce one image made with channels
   (5,7,9,...,25,27)
spw = '0'; mode = 'channel': nchan=3; start=5; width=4
   will produce an image with 3 output planes
   plane 1 contains data from channels (5+6+7+8)
   plane 2 contains data from channels (9+10+11+12)
plane 3 contains data from channels (13+14+15+16)
spw = '0:0~63^3'; mode='channel'; nchan=21; start = 0;
width = 1
will produce an image with 20 output planes
Plane 1 contains data from channel 0
Plane 2 contains data from channel 2
Plane 21 contains data from channel 61
spw = '0:0~40^2'; mode = 'channel'; nchan = 3; start = 5; width = 4
will produce an image with three output planes
plane 1 contains channels (5,7)
plane 2 contains channels (13,15)
plane 3 contains channels (21,23)

psfmode -- method of PSF calculation to use during minor cycles:
default: 'clark': Options: 'clark','hogbom'
'clark' use smaller beam (faster, usually good enough)
'hogbom' full-width of image (slower, better for poor
uv-coverage)
Note: psfmode will be used to clean is imagermode = '

imagermode -- Advanced imaging e.g mosaic or Cotton-Schwab clean
default: imagermode='': Options: '', 'csclean', 'mosaic'
default '' =&gt; psfmode cleaning algorithm used
&gt;&gt;&gt; imagermode='mosaic' expandable parameter(s):
Image as a mosaic of the different pointings (uses csclean
style too)

mosweight -- Individually weight the fields of the mosaic
default: False; example: mosweight=True
This can be useful if some of your fields are more
sensitive than others (i.e. due to time spent
on-source); this parameter will give more weight to
higher sensitivity fields in the overlap regions.

ftmachine -- Gridding method for the image;
Options: ft (standard interferometric gridding), sd
(standard single dish) both (ft and sd as appropriate),
mosaic (gridding use PB as convolution function)
default: 'mosaic'; example: ftmachine='ft'
scaletype -- Controls scaling of pixels in the image plane.
(Not fully implemented...for now only controls
what is seen if interactive=True...but in the future will
control the image on which clean components are searched)
default='SAULT'; example: scaletype='PBCOR'
Options: 'PBCOR', 'SAULT'
'SAULT' when interactive=True shows the residual
with constant noise across the mosaic. If
pbcor=False, the final output image is NOT
corrected for the PB pattern, and therefore is not "flux correct". Division of SAULT
image by the .image will produce a "flux correct image", can also
be achieved by setting pbcor=True.

'PBCOR' uses the SAULT scaling scheme for
deconvolution, but if interactive=True shows the
primary beam corrected image; the final PBCOR
image is "flux correct" if pbcor=True.

imagermode='csclean' expandable parameter(s): Image using the
Cotton-Schwab algorithm in between major cycles
cyclefactor -- Change the threshold at which
the deconvolution cycle will stop, degrid
and subtract from the visibilities. For
poor PSFs, reconcile often (cyclefactor=4 or 5); For good PSFs, use cyclefactor 1.5 to
2.0. Note: threshold = cyclefactor * max
sidelobe * max residual.
default: 1.5; example: cyclefactor=4
cyclespeedup -- Cycle threshold doubles in this
number of iterations default: -1;
example: cyclespeedup=3
try cyclespeedup = 50 to speed up cleaning
multiscale -- set of scales to use in deconvolution. If set,
cleans with several resolutions using hdbogm clean. The
scale sizes are in units of cellsize. So if
cell='2arcsec', a multiscale scale=10 = 20arcsec. First
scale should always be 0 (point), we suggest second on
the order of synthesized beam, third 3-5 times
synthesized beam, etc. For example if synthesized beam
is 10" and cell=2", try multscale = [0,5,15]. Note,
multiscale is currently a bit slow.
default: multiscale=[] (standard CLEAN using psfmode algorithm,
no multi-scale). Example: multscale = [0,5,15]
negcomponent -- Stop
component search when the largest scale has found this
number of negative components; -1 means continue
component search even if the largest component is
negative. default: -1; example: negcomponent=50
imsize -- Image pixel size (x,y)
default = [256,256]; example: imsize=[350,350]
imsize = 500 is equivalent to [500,500]
cell -- Cell size (x,y)
default= '1.0arcsec';
example: cell=['0.5arcsec','0.5arcsec'] or
cell=[‘1arcmin’, ‘1arcmin’]
cell = ‘1arcsec’ is equivalent to [‘1arcsec’,’1arcsec’]
NOTE:cell = 2.0 =gt; [‘2arcsec’, ‘2arcsec’]

phasecenter -- direction measure or fieldid for the mosaic center
default: ‘’ =gt; first field selected ; example: phasecenter=6
or phasecenter=’J2000 19h30m00 -40d00m00’

restfreq -- Specify rest frequency to use for output image
default=’’ Occasionally it is necessary to set this (for
example some VLA spectral line data). For example for
NH_3 (1,1) put restfreq=’23.694496GHz’

stokes -- Stokes parameters to image
default=’I’; example: stokes=’IQUV’;
Options: ‘I’,’IV’’QU’,’IQUV’,’RR’,’LL’,’XX’,’YY’,’RRLL’,’XXYY’

niter -- Maximum number iterations,
if niter=0, then no CLEANing is done (”invert” only)
default: 500; example: niter=5000

gain -- Loop gain for CLEANing
default: 0.1; example: gain=0.5

threshold -- Flux level at which to stop CLEANing
default: ’0.0mJy’;
example: threshold=’2.3mJy’ (always include units)
threshold = ‘0.0023Jy’
threshold = ‘0.0023Jy/beam’ (okay also)

interactive -- use interactive clean (with GUI viewer)
default: interactive=False
esample: interactive=True

interactive clean allows the user to build the cleaning
mask interactively using the viewer. The viewer will
appear every npercycle iteration, but modify as needed
The final interactive maks is saved in the file
imagename_interactive.mask. The initial masks use the
union of mask and cleanbox (see below)

interactive= True expandable parameter npercycle -- this is the
number of iterations between each clean to update mask
interactively. Set to about niter/5, but can also be
changed interactively.

mask -- Specification of cleanbox(es), mask image(s), and/or
region(s) to be used for CLEANing. As long as the image has
the same shape (size), mask images from a previous
interactive session can be used for a new execution. NOTE:
the initial clean mask actually used is the union of what
is specified in mask and imagename_mask_default: [] (no
masking); Possible pecification types: (a) Explicit
cleanbox pixel ranges example: mask=[110,110,150,145] clean
region with blc=110,100; trc=150,145 (pixel values) (b)
Filename with cleanbox pixel values with ascii format:
example: mask='mycleanbox.txt' &lt;fieldid blc-x blc-y
trc-x trc-y&gt; on each line
1 45 66 123 124
2 23 100 300 340
(c) Filename for image mask example: mask='myimage.mask'
(d) Filename for region specification (e.g. from viewer)
example: mask='myregion.rgn' (e) Combinations of any of the
above example: mask=[[110,110,150,145],’mycleanbox.txt’,
’myimage.mask’,’myregion.rgn’]

tvtaper -- Apply additional uv tapering of the visibilities.
default: uvtaper=False; example: uvtaper=True

outertaper -- uv-taper on outer baselines in uv-plane
[bmaj, bmin, bpa] taper Gaussian scale in uv or
angular units. NOTE: uv taper in (klambda) is roughly on-sky
FWHM(arcsec/200)
default: outertaper=[]; no outer taper applied
example: outertaper=['5klambda'] circular taper
     FWHM=5 kilo-lambda
     outertaper=['5klambda','3klambda','45.0deg']
     outertaper=['10arcsec'] on-sky FWHM 10"
     outertaper=['300.0'] default units are meters
     in aperture plane

innertaper -- uv-taper in center of uv-plane
[bmaj,bmin,bpa] Gaussian scale at which taper falls to
zero at uv=0
default: innertaper=[]; no inner taper applied
NOT YET IMPLEMENTED

modelimage -- Name of model image(s) to initialize cleaning. If
multiple images, then these will be added together to
form initial staring model NOTE: these are in addition
to any initial model in the &lt;imagename&gt;.model image file
default: '' (none); example: modelimage='orion.model'
modelimage=['orion.model','sdorion.image'] Note: if the
units in the image are Jy/beam as in a single-dish
image, then it will be converted to Jy/pixel as in a
model image, using the restoring beam in the image
header

weighting -- Weighting to apply to visibilities:
default='natural'; example: weighting='uniform';
      ‘superuniform’, ‘briggsabs’, ‘radial’

Weighting expandable parameters
For weighting='briggs' and ‘briggsabs’
robust -- Brigg’s robustness parameter
  default=0.0; example: robust=0.5;
  Options: -2.0 to 2.0; -2 (uniform)/+2 (natural)
For weighting='briggsabs'
  noise -- noise parameter to use for Briggs "abs" weighting
  example noise='1.0mJy'
For superuniform/briggs/briggsabs weighting
  npixels -- number of pixels to determine uv-cell size
  for weight calculation
  example npixels=7
restoringbeam -- Output Gaussian restoring beam for CLEAN image
  [bmaj, bmin, bpa] elliptical Gaussian restoring beam
  default units are in arc-seconds for bmaj,bmin, degrees
  for bpa default: restoringbeam=[]; Use PSF calculated
  from dirty beam.
  example: restoringbeam=['10arcsec'] circular Gaussian
            FWHM 10'' example:
            restoringbeam=['10.0', '5.0', '45.0deg'] 10''x5''
            at 45 degrees
pbcor -- Output primary beam-corrected image
  default: pbcor=False; output un-corrected image
  example: pbcor=True; output pb-corrected image (masked outside
  minpb) Note: if you set pbcor=False, you can later
  recover the pbcor image by dividing by the .flux image
  (e.g. using immath)
minpb -- Minimum PB level to use default=0.1; example:
  minpb=0.01 Note: this minpb is always in effect
  (regardless of pbcor=True/False)
async -- Run asynchronously
  default = False; do not run asynchronously

</example>
</task>
</casaxml>

H.3.2 File task_clean.py

Task clean implementation file.
import os
from taskinit import *
from cleanhelper import *

def clean(vis, imagename, field, spw, selectdata, timerange, uvrange, antenna, 
          scan, mode, niter, gain, threshold, psfmode, imagermode, ftmachine, 
          mosweight, scateype, multiscale, negcomponent, interactive, mask, 
          nchan, start, width, imsize, cell, phasecenter, restfreq, stokes, 
          weighting, robust, uvtaper, outertaper, innertaper, modelimage, 
          restoringbeam, pbcor, minpb, noise, npixels, npercycle, cyclefactor, 
          cyclespeedup):

    # Python script
    casalog.origin('clean')

    maskimage=''
    if((mask==[]) or (mask=='')):
        mask=['']
    if (interactive):
        if( (mask=='') or (mask==['']) or (mask==[]):)
            # try:
            if(1):
                imCln=imtool.create()
                imset=cleanhelper(imCln, vis)

    if((len(imagename)==0) or (imagename.isspace())):
        raise Exception, 'Cannot proceed with blank imagename'
    casalog.origin('clean')

    imset.defineimages(imsize=imsize, cell=cell, stokes=stokes, 
                      mode=mode, spw=spw, nchan=nchan, 
                      start=start, width=width, 
                      restfreq=restfreq, field=field, 
                      phasecenter=phasecenter)

    imset.datselweightfilter(field=field, spw=spw, 
                             timerange=timerange, 
                             uvrange=uvrange, 
                             antenna=antenna, scan=scan, 
                             wgttype=weighting, 
                             robust=robust, 
                             noise=noise, npixels=npixels, 
                             mosweight=mosweight,
innertaper=innertaper,
outertaper=outertaper)

if(maskimage==' '):
    maskimage=imagename+' .mask'
imset.makemaskimage(outputmask=maskimage,imagename=imagename,
    maskobject=mask)

###define clean alg
alg=psfmode
if(multiscale==[0]):
    multiscale=[]
if((type(multiscale)==list) and (len(multiscale)>0)):
    alg='multiscale'
imCln.setscales(scalemethod='uservector',
    uservector=multiscale)

if(imagermode=='csclean '):
    alg='mf'+alg
if(imagermode=='mosaic '):
    if(alg.count('mf') <1):
        alg='mf'+alg
    imCln.setoptions(ftmachine=ftmachine, padding=1.0)
imCln.setvp(dovp=True)

###PBCOR or not
sclt='SAULT'
if((scaletype=='PBCOR') or (scaletype=='pbcor')):
    sclt='NONE'
imCln.setvp(dovp=True)
else:
    if(imagermode != 'mosaic '):
        ##make a pb for flux scale
        imCln.setvp(dovp=True)
        imCln.makeimage(type='pb', image=imagename+' .flux')
imCln.setvp(dovp=False)

##restoring
imset.setrestoringbeam(restoringbeam)

###model image
imset.convertmodelimage(modelimages=modelimage,
    outputmodel=imagename+' .model')

###after all the mask shenanigans...make sure to use the
###last mask
APPENDIX H. APPENDIX: WRITING TASKS IN CASA

610

maskimage=imset.outputmask
if((imagermode==’mosaic’)):
imCln.setmfcontrol(stoplargenegatives=negcomponent,scaletype=sclt,
minpb=minpb,cyclefactor=cyclefactor,
cyclespeedup=cyclespeedup,
fluxscale=[imagename+’.flux’])
else:
imCln.setmfcontrol(stoplargenegatives=negcomponent,
cyclefactor=cyclefactor, cyclespeedup=cyclespeedup)
imCln.clean(algorithm=alg,niter=niter,gain=gain,
threshold=qa.quantity(threshold,’mJy’),
model=[imagename+’.model’],
residual=[imagename+’.residual’],
image=[imagename+’.image’],
psfimage=[imagename+’.psf’],
mask=maskimage, interactive=interactive,
npercycle=npercycle)
imCln.close()
presdir=os.path.realpath(’.’)
newimage=imagename
if(imagename.count(’/’) > 0):
newimage=os.path.basename(imagename)
os.chdir(os.path.dirname(imagename))
result
= ’\’’ + newimage + ’.image’ + ’\’’;
fluxscale_image = ’\’’ + newimage + ’.flux’ + ’\’’;
if (pbcor):
if(sclt != ’NONE’):
##otherwise its already divided
ia.open(newimage+’.image’)
pixmask = fluxscale_image+’>’+str(minpb);
ia.calcmask(pixmask,asdefault=True);
pixels=’iif(’+ fluxscale_image+’>’+str(minpb)+’,’
+ result+’/’+fluxscale_image+’, 0)’
ia.calc(pixels=pixels)
ia.close()
else:
## people has imaged the fluxed corrected image
## but want the
## final image to be non-fluxed corrected
if(sclt==’NONE’):
ia.open(newimage+’.image’)
result=newimage+’.image’


fluxscale_image=newimage+'.flux'
pixels=result+'*'+fluxscale_image
ia.calc(pixels=pixels)
ia.close()

os.chdir(presdir)

del imCln

# except Exception, instance:
#     print '*** Error *** ',instance
#     raise Exception, instance